

# ML Supervised Learning 3

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- ▶ Introduction to Supervised Learning
- ▶ Some foundational aspects of ML

Rewind

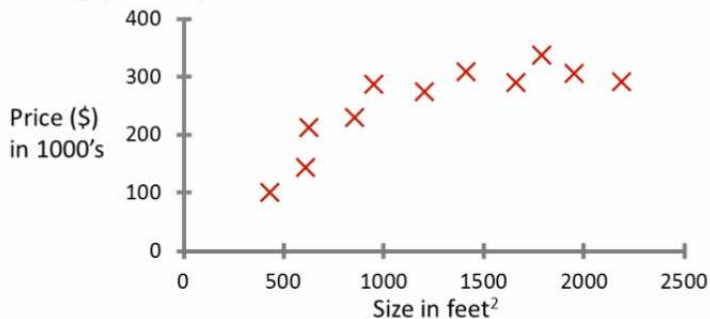
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- ▶ General introduction to ML and what it can and cannot
- ▶ Some understanding of what is data and model
- ▶ Machine learning work-flow (very important)
- ▶ How can we construct simple classifiers using “distance”
- ▶ Introduction to Bayes decision theory

# Supervised Learning

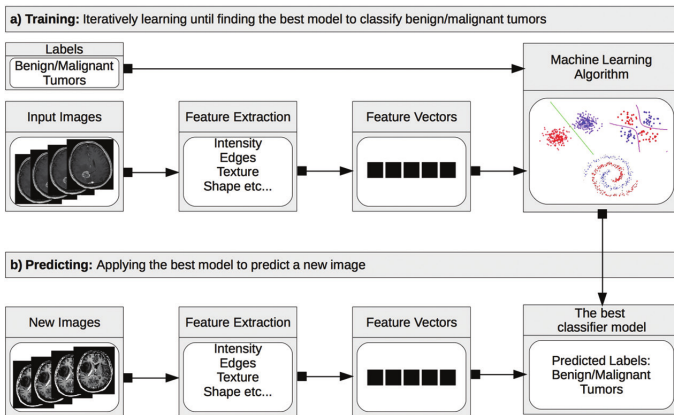
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### Housing price prediction.



*Supervised Learning: Predicting housing prices*

# Classification: Example



*Supervised Learning in Action for Medical Image Diagnosis<sup>1</sup>*

<sup>1</sup>Image is taken from Erickson et al, Machine Learning for Medical Imaging, Radio Graphics, 2017

# Who supervises “Learning”?

**Answer:** Ground-truth or labels.

- ▶ In supervised learning along with input feature vector  $x$  there a groundtruth or response  $y$  associated with it.
  - ▶ If  $y$  takes only two values or at most finitely many values it is a classification problem
  - ▶ If  $y$  takes any real number it is a regression problem
- ▶ Aim is to build a system  $f$  (or a function) such a way that
  - ▶ given  $x$  predict  $y$  as accurately as possible

**How do we measure the accuracy?**

# Supervised Learning: Setting

A set of **labeled** training examples are given.

$$\mathcal{D} = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$$

- ▶ Each  $x_n$  can be an image or a document or a time series etc.
- ▶ Each  $x_n$  it self is  $D$ -dimensional vector. That is each  $x_n$  is of the form

$$x_n = (x_{n1}, x_{n2}, \dots, x_{nD})$$

- ▶  $x_{n1}, x_{n2}, \dots, x_{nD}$  are called features of  $x_n$
- ▶ Note that we represent  $x_n$  either as a vector or a column matrix.

**Output:**  $y_n$  denotes a label or ground-truth or response



## Supervised Learning: Setting (Cont...)

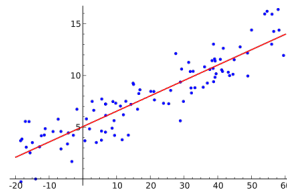
**Objective:** To learn a function  $f_\theta$  that:

- ▶ Closely mimics the examples in training set ( $f_\theta(x_n) \approx y_n$ ), *i.e.*, has low *training error*
- ▶ Generalizes to unseen examples, *i.e.*, has low *test error*

$\theta$  refers to *learnable parameters* of the function  $f_\theta$

# Supervised Learning - Regression

- ▶ **Objective:** To learn a function mapping input features  $x$  to scalar target  $y$
- ▶ Linear regression is the most common form - assumes that  $f_{\theta}$  is linear in  $\theta$
- ▶ **Examples:**
  - ▶ Predicting temperature in a room based on other physical measurements
  - ▶ Predicting location of gaze using image of an eye
  - ▶ Predicting remaining life expectancy of a person based on current health records
  - ▶ Predicting return on investment based on market status



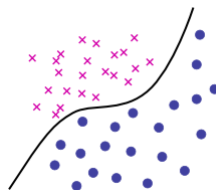
*Example - Linear Regression*

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<sup>1</sup>Image source: [https://en.wikipedia.org/wiki/Linear\\_regression](https://en.wikipedia.org/wiki/Linear_regression)

# Supervised Learning - Classification

- ▶ **Objective:** To learn a function that maps input features  $x$  to one of the  $K$  classes
- ▶ The classes may be (and usually are) unordered



*Example - Classification*

- ▶ **Examples:**
  - ▶ Classifying images based on objects being depicted
  - ▶ Classifying market condition as favorable or unfavorable
  - ▶ Classifying pixels based on membership to object/background for segmentation
  - ▶ Predicting the next word based on a sequence of observed words

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<sup>1</sup>Image source: <https://www.hact.org.uk>

### Some popular techniques:

- ▶ Logistic regression
- ▶ Random forests
- ▶ Bayesian logistic regression
- ▶ Support vector machines
- ▶ Neural networks
- ▶ etc.

## Supervised Learning Setup: Notation

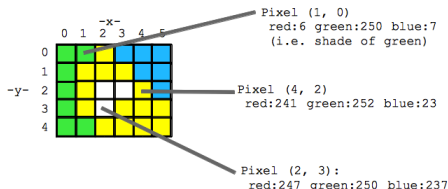
- ▶ The number of data samples that are available to us is  $N$
- ▶ That is the samples are  $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$ 
  - ▶ For example,  $x_1, x_2, \dots, x_N$  denote medical images and,
  - ▶  $y_1, y_2, \dots, y_N$  represent ground-truth diagnosis say  $-1$  or  $+1$ .
- ▶ Note that the data can be noisy
  - ▶ Scanner itself may introduce this noise
  - ▶ Doctors can make some mistake in their diagnosis

# Supervised Learning Setup: Dimension

- ▶ Dimension is the size of the input data i.e  $x_n$  we denote this by  $D$
- ▶ We write  $x_n = (x_{n1}, \dots, x_{nD}) \in \mathbb{R}^D$ 
  - ▶ If a grey scale image size is say  $16 \times 16$  then  $D = 16 \times 16$
  - ▶ If it is RGB then  $D = 16 \times 16 \times 3$  and each  $x_{nd}$  takes value between 0 and 255.
- ▶ The dimension of  $x_1, x_2, \dots, x_N$  is typically very high
- ▶ Why?

## Supervised Learning Setup: Dimension (Contd...)

- ▶ Number of pixels in an image 800 pixel wide, 600 pixels high:  
 $800 \times 600 = 480000$ . Which is 0.48 megapixels
- ▶ Typically digital images are 4 – 20 megapixels



*Pixels in RGB images<sup>2</sup>*

- ▶ Now what is the dimension of  $800 \times 600$  image?

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<sup>2</sup>Taken from web

## Supervised Learning Setup: Dimension (Contd...)

- ▶ Note that in some applications dimension of each sample can be varying, for example:
  - ▶ sentences in text
  - ▶ protein sequence data
- ▶ What about the response  $y$ ?
  - ▶ Dimension of  $y$  is much much less than  $x$
  - ▶  $y$  can be structured and it leads to structure prediction learning
- ▶ A major issue in machine learning: **High dimensionality of data**



## Supervised Learning: Formal Definition

**Problem:** Given the data  $(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)$ , aim is to find a function.

$$f : \mathcal{X} \rightarrow \mathcal{Y}$$

that approximate the relation between  $X$  and  $Y$ .

- ▶ There are small letters, capitol letters, script letters. What are they?
- ▶  $X$  and  $Y$  denotes the random variables and  $\mathcal{X}$  and  $\mathcal{Y}$  denotes the sets from where  $X$  and  $Y$  take values.

**Random Variables?** Why are we talking about probability here?

# Some Foundational aspects of Machine Learning

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# On Statistical Approach to Machine Learning

Assumption behind the statistical approach to Machine Learning:

Data is assumed to be sampled from a underlying probability distribution

## On Statistical Approach to Machine Learning (contd...)

- ▶ Suppose we are given  $N$  samples  $x_1, \dots, x_N$
- ▶ Our assumption is that there is a hypothetical underlying distribution  $P$  from which these samples are drawn
  - ▶ The problem is that we do not know this distribution
  - ▶ Some machine learning algorithms try to estimate this distribution, some try to solve problems without estimating this distribution

- ▶ Recall, class conditional densities  $P(x|y_1)$  and  $P(x|y_2)$ 
  - ▶ In the Bayes classifier uses these distributions
  - ▶ We are given only data, from which we need to estimate these distributions (How?)
    - ▶ Maximum likelihood estimation
    - ▶ Maximum a posteriori estimation

How complicated this underlying distribution can be?

# Loss Function

We need some guiding mechanism that will tell us how good our predictions are given an input.

- ▶  $\ell(y, f(x))$  denotes the loss when  $x$  is mapped to  $f(x)$ , while the actual value is  $y$ .

## Note

- ▶  $\ell$  and  $f$  are specific to the problems and a method.
- ▶ For example,  $\ell(\cdot)$  can be a squared loss and  $f(x)$  is linear function i.e  $f = w^\top x$ .

## Objective

Given a loss function  $\ell$ , aim is to find  $f$  such that,

$$L(f) = \mathbb{E}_{(x,y) \sim P}[\ell(Y, f(X))]$$

is minimum

- ▶ Here  $X$  and  $Y$  are random variables.
- ▶  $L$  is the true loss or expected loss or Risk.
- ▶ As we mentioned before we assume that the data is generated from a joint distribution  $P(X, Y)$ .
- ▶ When we try to learning this distribution it is called generative modelling leads to so called Generative AI.



- ▶ Remember, broad aim of ML is to understand a phenomenon or (and) solve some downstream problems related to it
- ▶ When we make assumptions about existence of  $P$  that means assume that we capture the phenomenon by  $P$
- ▶ The available data represents the partial information that we have about the phenomenon or  $P$
- ▶ That is data is nothing but samples drawn from distribution  $P$

## Diversion: Probability Basics

- ▶ Random variable is nothing but a function that maps outcome to a number
  - ▶ Consider a coin tossing experiment: Outcomes are H and T
  - ▶ Random variable  $X$  can map H to 1 and can map T to 0
- ▶ Now let us assign probabilities
  - ▶ Suppose  $P(X = 1) = \frac{1}{4}$  and  $P(X = 0) = \frac{3}{4}$
  - ▶ That is probability mass function of  $X$  is  $(\frac{1}{4}, \frac{3}{4})$
- ▶ Let us calculate expectation of a random variable

$$E_P X = \sum_{i=1}^2 x_i p_i = 1 \left( \frac{1}{4} \right) + 0 \left( \frac{3}{4} \right)$$

**Problem:** We cannot estimate the true loss as we do not know  $P$ .

**Some Relief:** But we have some samples that are drawn from  $P$ .

## Empirical Risk

Instead of minimizing the true loss find  $f$  that minimizes empirical risk

$$L_{emp}(f) = \frac{1}{N} \sum_{n=1}^N \ell(y_n, f(x_n))$$

$$i.e. \quad f^* = \arg \min_f \frac{1}{N} \sum_{n=1}^N \ell(y_n, f(x_n))$$

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- ▶ Here  $\ell(y_n, f(x_n))$  is the per sample loss
- ▶  $L_{emp}(f)$  is the overall loss given the data  $\{(x_n, y_n)\}_{n=1}^N$
- ▶  $N$  is the number of samples and we need “reasonably many” samples so that Empirical Risk is close to the True Risk
- ▶ Why do we need Empirical Risk to be closer to the True Risk?

How well the learned function work on the unseen data?

- ▶ We want  $f$  not only work on the training data but also it should work on the unseen data.
- ▶ For this the general principle:

The model should be simple

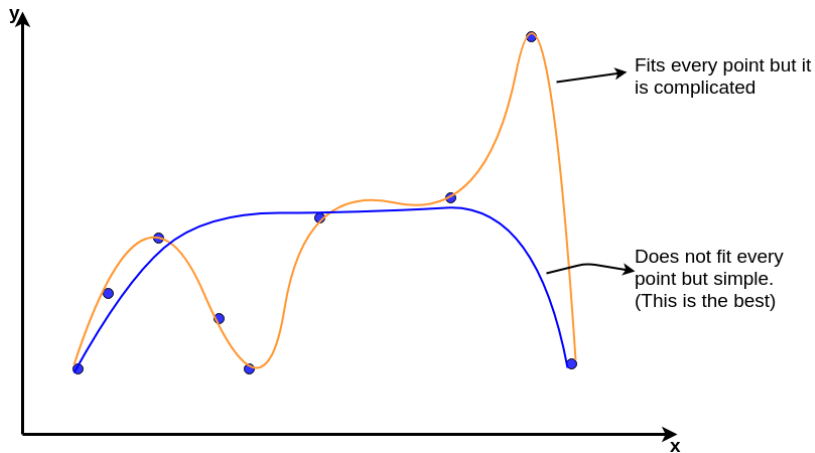
- ▶ Regularizer

$$f^* = \arg \min_f \frac{1}{N} \sum_{n=1}^N \ell(y_n, f(x_n)) + \lambda R(f)$$

- ▶  $\lambda$  controls how much regularization one needs.
- ▶  $R$  measures complexity of  $f$ .
- ▶ This is regularized risk minimization.

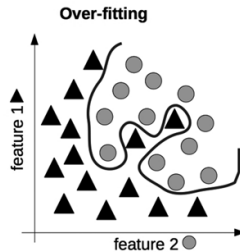
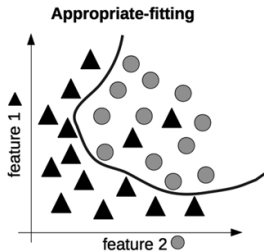
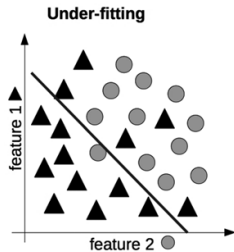
- ▶ What we want to achieve.
  - ▶ Small empirical error on training data, and at the same time,
  - ▶  $f$  needs to be simple.
- ▶ There is a trade off between these two goals
  - ▶  $\lambda$  is a hyperparameter that tries to achieve this.

## Generalizing Capacity(cont...)



*The blue curve has better generalization capacity. The orange curve overfits the data*

## Generalizing Capacity(cont...)





We have the following optimization problem "find  $f$  such that ... "

- ▶ Is it any  $f$  ?
- ▶ No, The choice  $f$  cannot be from a arbitrary set.
- ▶ First we fix  $\mathcal{F}$ : the set of all possible functions that describe relation between  $X$  and  $Y$  given training data  $\{(x_n, y_n)\}_{n=1}^N$
- ▶ Now our objective is

$$f^* = \arg \min_{f \in \mathcal{F}} \sum_{n=1}^N \ell(y_n, f(x_n)) + \lambda R(f)$$

- ▶ For example, If  $\mathcal{F}$  is set of all linear functions then we call it linear regression.

## What we have learned?

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- ▶ Beware! there are some underlying assumptions and approximations
- ▶ There is no rule book. Practitioners have to make some decisions while designing the algorithms and methods
- ▶ What is the Challenge? We want our algorithms work well on the unseen data.
- ▶ How do we evaluate performance of ML algorithms?