

# Deep Statistical Solvers

Course Project — DS303: Machine Learning

## **Team AlphaSolvers**

Sai Aneesh Suryadevara - 190100125

Bhargav Rongali - 190100102

Indian Institute of Technology, Bombay

April 22, 2022

# Overview

1. Problem Statement
2. Before Midterm review
3. Midterm Review
4. Work Done after Midterm Review
5. Experiments & Results
6. Conclusions
7. Future Directions
8. Team Contributions

# Problem Statement

- **Optimization Problem:** The elementary question is to solve the following optimization problem for a given Interaction Graph  $G$

$$U^*(G) = \arg \min_{U \in \mathcal{U}} L(U, G)$$

- **Learning Goal:** Because the above optimization problem is not easy to solve, we want to learn a single solver that best approximates the mapping  $G \rightarrow U^*(G)$  for all  $G$ .

$$\hat{U}(G) = \text{Solver}(G) \quad \text{where, } \hat{U} \text{ is an approximation of } U^*$$

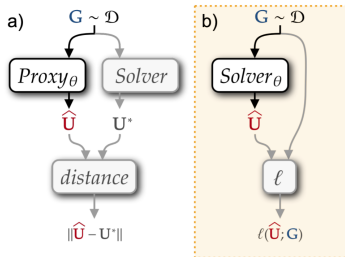


Figure: Proxy approach (a) vs. DSS (b)

# Graph Neural Network implementation of a DSS

- **Node Embedding:** For each node,  $H_i$  is an embedding of actual state  $U_i$ , which is used for training and prediction
- **Message passing:** This step performs  $\bar{k}$  updates on the latent state variable  $\mathbf{H}$  using an **UPDATE** function  $M_\theta^k$  and **AGGREGATE** function  $\Psi$

$$\phi_{\rightarrow,i}^k = \sum_{j \in \mathcal{N}^*(i; \mathbf{G})} \Phi_{\rightarrow, \theta}^k(H_i^{k-1}, A_{ij}, H_j^{k-1}) \quad \text{outgoing edges}$$

$$\phi_{\leftarrow,i}^k = \sum_{j \in \mathcal{N}^*(i; \mathbf{G})} \Phi_{\leftarrow, \theta}^k(H_i^{k-1}, A_{ji}, H_j^{k-1}) \quad \text{ingoing edges}$$

$$\phi_{\odot,i}^k = \Phi_{\odot, \theta}^k(H_i^{k-1}, A_{ii}) \quad \text{self loop}$$

Latent states  $H_i^k$  are then computed using trainable mapping  $\Psi_\theta^k$ , in a ResNet-like fashion:

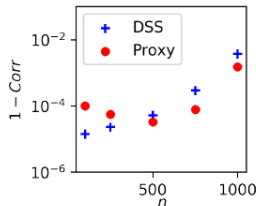
$$\mathbf{H}^k = \mathbf{M}_\theta^k(\mathbf{H}^{k-1}, \mathbf{G}) := (H_i^k)_{i \in [n]}, \text{ with } H_i^k = H_i^{k-1} + \Psi_\theta^k(H_i^{k-1}, B_i, \phi_{\rightarrow,i}^k, \phi_{\leftarrow,i}^k, \phi_{\odot,i}^k)$$

# Linear Solver Experiment

- We had seen how temperature distribution for a 2D domain can be obtained by solving Poisson equation using the DSS
- Following were its results

Method	DSS	Proxy	LU
Correlation w/ LU	> 99.99%	> 99.99%	-
NRMSE w/ LU	1.6e-3	1.1e-3	-
Time per instance (ms) * Inference time divided by batch size	1.8*	1.8*	2.4
Loss 10 <sup>th</sup> percentile	3.9e-4	7.0e-3	4.5e-27
Loss 50 <sup>th</sup> percentile	1.2e-3	1.6e-2	6.1e-26
Loss 90 <sup>th</sup> percentile	4.1e-3	4.0e-2	6.3e-25

- Next we had analyzed how well trained model is able to generalize to a distribution that is different from the training distribution



# Comments on Midterm Presentation

- Motivation could have been more elaborate and clear
- For the past work only the name of the approach or method is mentioned, could have covered a brief theme of these approaches
- Skipped a part on universal approximation property
- More emphasis regarding the performance metric (correlation between two solvers) could have been discussed as it is not a common performance metric.
- For future work: Include a code walkthrough of replication of work.

# Addressing the Comments

- **Universal approximation property** now explained in detail
- The performance metrics used **Pearson Correlation Coefficient** and NRMSE have been discussed in detail and also explained during the code demonstration
- Code has now been discussed properly and a code walkthrough has been included
- We learnt about **GRNN** and made an attempt to incorporate it in the code

# Universal Approximation Property

Let us say that all the interaction graphs,  $G$  are sampled from a given distribution  $\mathcal{D}$ . Let  $\text{supp}(\mathcal{D})$  (support of  $\mathcal{D}$ ) follow four hypotheses:

- **Permutation Invariance:** For any  $G \in \text{supp}(\mathcal{D})$  and  $\sigma \in \Sigma_n$ ,  $\sigma \star G \in \text{supp}(\mathcal{D})$
- **Compactness:**  $\text{supp}(\mathcal{D})$  is a compact subset
- **Connectivity:** For any  $G \in \text{supp}(\mathcal{D})$ ,  $\tilde{G}$  has only one connected component.
- **Seperability of external inputs:** There exist  $\delta > 0$  such that for any  $G = (n, A, B) \in \text{supp}(\mathcal{D})$  and any  $i \neq j \in \{1, 2, \dots, n\}$ ,  $\|B_i - B_j\| \geq \delta$

and let  $l$  be a continuous and permutation-invariant loss function such that for any  $G \in \text{supp}(\mathcal{D})$ , our problem has a unique minimizer  $U^*(G)$ , continuous w.r.t  $G$ . Then  $\forall \epsilon > 0 \exists \text{Solver}_\theta$ , such that

$$\|\text{Solver}_\theta(G) - U^*(G)\| \leq \epsilon$$



# Normalization - Change of Variables (For Poisson Equation)

- In the Poisson case study, the nodes at the boundary are constrained (i.e.  $A_{ii} = 1$  and  $A_{ij} = 0$  if  $i \neq j$ ), and the interior nodes are not
- Also, the coefficients of matrix  $A$  at these interior nodes satisfy a conservation equality ( $A_{ii} = -\sum_{j \in [n] \setminus i} A_{ij}$ )
- Due to this, the distributions of their respective  $B_i$  are very different

To overcome this issue we use change of variables as follows:

$$B'_i = \begin{cases} [B_i, 0, 0], & \text{if node } i \text{ is not constrained} \\ [0, 1, B_i], & \text{otherwise} \end{cases}$$

$$A'_{ij} = \begin{cases} A_{ij}, & \text{if } i \neq j \\ 0, & \text{otherwise} \end{cases}$$

# Normalization and Evaluation Metric

So the now the loss function  $l(U, G) = \sum_{i=1}^n (-B_i + \sum_{j=1}^n A_{ij} U_j)^2$  takes the form,

$$l'(U, G') = \sum_{i=1}^n \left( (1 - B_i'^2)(-B_i'^1) + B_i'^2(U_i - B_i'^3) + \sum_{j=1}^n A'_{ij}(U_j - U_i) \right)^2$$

where  $B_i'^p$  denotes the  $p^{th}$  component of vector  $B_i$

**Pearson Correlation Metric:** The correlation metric used by the authors is known as the Pearson correlation. It is defined as follows,

$$r_{12} = \frac{\sum_{i=1}^n (U_i^1 - \bar{U}^1)(U_i^2 - \bar{U}^2)}{\sqrt{\sum_{i=1}^n (U_i^1 - \bar{U}^1)^2} \sqrt{\sum_{i=1}^n (U_i^2 - \bar{U}^2)^2}}$$

# AC power flow experiments

The second SSP example is the AC power flow prediction. Here, We know

- The amount of power being produced & consumed throughout the grid - encoded into B
- The way power lines are interconnected and their physical properties - encoded into A
- Our goal is to compute the voltage defined at each electrical node - encoded in state U

Let's consider a power grid with n nodes. We define the complex voltage at node i

$$V_i = |V_i|e^{j\theta_i}$$

The real part of the power consumed is denoted by  $P_{d,i}$  and the imaginary part by  $Q_{d,i}$ .

Current State-of-the-art AC power flow computation uses the **Newton-Raphson** method

# Loss Function : Kirchhoff's laws

The system of equations that govern the power grid are the following:

$$\forall i \in [n] \setminus \{i_s\}, \quad P_{g,i} - P_{d,i} = \sum_{j \in [n]} |V_i| |V_j| (\operatorname{Re}(Y_{ij}) \cos(\theta_i - \theta_j) + \operatorname{Im}(Y_{ij}) \sin(\theta_i - \theta_j))$$

$$\forall i \in I_{PQ}, \quad -Q_{d,i} = \sum_{j \in [n]} |V_i| |V_j| (\operatorname{Re}(Y_{ij}) \sin(\theta_i - \theta_j) - \operatorname{Im}(Y_{ij}) \cos(\theta_i - \theta_j))$$

$$\forall i \in I_{PV}, \quad |V_i| = V_{g,i}$$

This set of complex equations can be converted into a SSP using A, B and U and loss function-

$$\begin{aligned} \ell(\mathbf{U}, \mathbf{G}) = & \sum_{i \in [n]} (1 - B_i^5) \left( -B_i^1 + U_i^1 \sum_{j \in [n]} A_{ij}^1 U_j^1 \cos(U_i^2 - U_j^2 - A_{ij}^2) \right)^2 \\ & + \sum_{i \in [n]} B_i^3 \left( -B_i^2 + U_i^1 \sum_{j \in [n]} A_{ij}^1 U_j^1 \sin(U_i^2 - U_j^2 - A_{ij}^2) \right)^2 + \lambda \sum_{i \in [n]} (1 - B_i^3) (U_i^1 - B_i^4)^2 \end{aligned}$$

# Details of Experiments

- Experiments are conducted on two standard benchmarks ( $n = 14$ ) and ( $n = 118$ ).
- For case 14 (resp. case 118), the dataset is split into 16064/2008/2008 (resp. 18432/2304/2304).

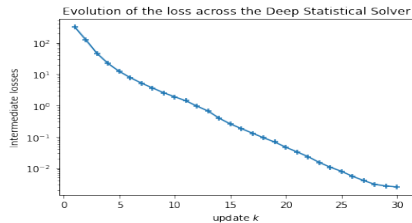
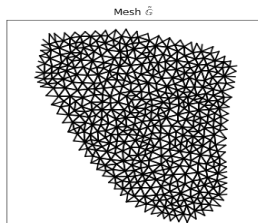
## Neural Network Details

- Each NN block : single hidden layer of dimension  $d = 10$  & leaky-ReLU non linearity
- Xavier Initialization, Adam Optimizer and Gradient Clipping were used
- For case  $n = 14$ ,  $\bar{k}$  was set to 10 ; we have  $\alpha = 10^{-2}$ ,  $lr = 3 * 10^{-3}$  and  $\gamma = 0.9$
- For case  $n = 118$ ,  $\bar{k}$  was set to 30 ; we have  $\alpha = 3 * 10^{-4}$ ,  $lr = 3 * 10^{-3}$  and  $\gamma = 0.9$
- The number of weights is 1,722 for each of the  $\bar{k}$  (M, D) blocks

# Results

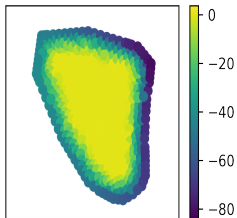
Dataset		IEEE 14 nodes			IEEE 118 nodes		
Method		DSS	Proxy	NR	DSS	Proxy	NR
Corr. w/ NR	$ V_i $	99.93%	> <b>99.99%</b>	-	99.79%	> <b>99.99%</b>	-
	$\theta_i$	99.86%	> <b>99.99%</b>	-	81.31%	> <b>99.99%</b>	-
	$P_{ij}$	> <b>99.99%</b>	> <b>99.99%</b>	-	> <b>99.99%</b>	> <b>99.99%</b>	-
	$Q_{ij}$	> <b>99.99%</b>	> <b>99.99%</b>	-	> <b>99.99%</b>	> <b>99.99%</b>	-
NRMSE w/ NR	$ V_i $	2.0e-3	<b>4.9e-4</b>	-	1.4e-3	<b>1.2e-3</b>	-
	$\theta_i$	7.1e-3	<b>1.7e-3</b>	-	5.7e-2	<b>4.5e-3</b>	-
	$P_{ij}$	6.2e-4	<b>2.6e-4</b>	-	1.0e-3	<b>3.9e-4</b>	-
	$Q_{ij}$	4.2e-4	<b>2.0e-4</b>	-	1.1e-4	<b>1.7e-4</b>	-
Time per instance (ms) * Inference time divided by batch size		<b>1e-2*</b>	<b>1e-2*</b>	2e1	<b>2e-1*</b>	2e-1*	2e1
Loss 10 <sup>th</sup> percentile		<b>4.2e-6</b>	2.3e-5	1.4e-12	<b>1.3e-6</b>	6.2e-6	2.9e-14
Loss 50 <sup>th</sup> percentile		<b>1.0e-5</b>	4.0e-5	2.1e-12	<b>1.7e-6</b>	8.3e-6	4.2e-14
Loss 90 <sup>th</sup> percentile		<b>4.4e-5</b>	1.2e-4	3.3e-12	<b>2.5e-6</b>	1.3e-5	6.4e-14

# Replication of results -Linear Systems

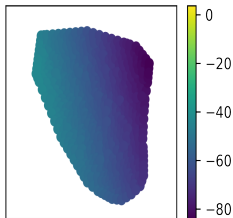


Intermediate predictions of State U and latent state H evolution

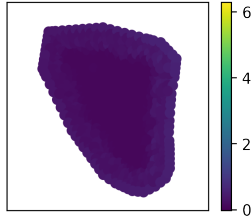
Intermediate prediction  $\hat{U}^5$



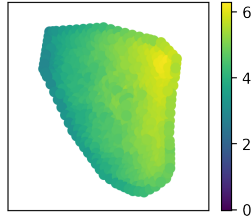
Intermediate prediction  $\hat{U}^{31}$



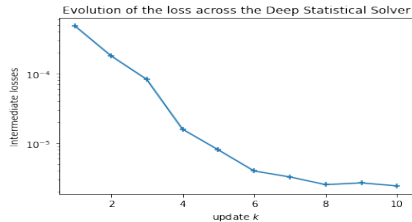
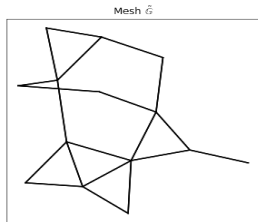
$H^5 - \text{component2}$



$H^{31} - \text{component2}$

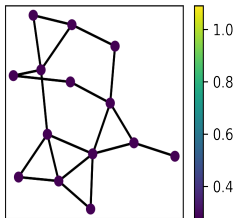


# Replication of results - AC Power Flow Prediction

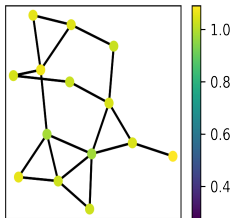


## Intermediate predictions of Voltage and Phase Angle

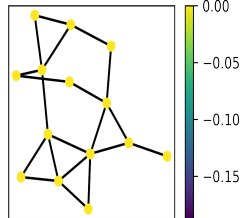
Intermediate prediction  $\hat{\mathbf{U}}^1$



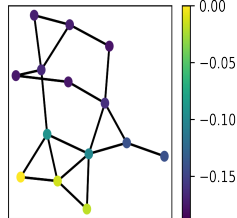
Intermediate prediction  $\hat{\mathbf{U}}^{11}$



Intermediate prediction  $\hat{\mathbf{U}}^0$



Intermediate prediction  $\hat{\mathbf{U}}^{10}$



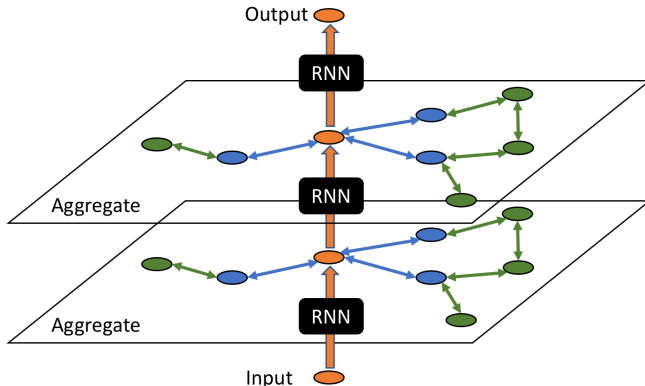


# Conclusions

- We have performed an in-depth analysis of the Deep Statistical Solvers and in doing so we also learnt about Graph Neural Networks(GNN) which are widely used for physics based simulations.
- We covered the Universal Approximation Property of DSS. This property gives a theoretical backup to the network hence justifying its use in various domains.
- The effectiveness of DSSs was also experimentally demonstrated on two problems. We saw that the accuracy on power flow computations matches that of state-of-the-art approaches while speeding up calculations by 2 to 3 orders of magnitude.
- Another application of DSS is that it can be used as an initialization heuristic for classical optimization algorithms.

# Extensions to the Work

- **Modification - Using Recurrent Graph Neural Networks (GRNN) :**  
In the paper authors have used GNN model of a limited depth. Instead, we can use **GNN with recurrent graph layers**. This will help in building deeper GNNs, without increasing the complexity of the training phase, while improving on the predictive performances.



# Team Contributions

## 1. Aneesh:

- Replicated the code for both Linear Systems and AC power flow and verified the results
- Ideated on the inclusion of Recurrent modules to the existing GNN architecture
- Learnt about GNNs and GRNNs using Reference [4],[6]
- Read the entire Deep Statistical Solver paper(Reference [1], [2])
- Made slides corresponding to sections 3, 4, 5 and 7

## 2. Bhargav:

- Worked on the comments given in mid-term review and explained Universal approximation property, Pearson correlation metric and change of variables
- Verified the code replication for both experiments
- Learnt about GNNs and GRNNs using Reference [4],[6]
- Read the entire Deep Statistical Solver paper(Reference [1], [2])
- Made slides corresponding to sections 1, 2, 4 and 6

# References

- [1] Deep Statistical Solvers, 2020 by *Balthazar Donon, Wenzhuo Liu, Antoine Marot, Zhengying Liu, Isabelle Guyon, Marc Schoenaue* [[Link](#)]
- [2] Author's presentation video. [[Link](#)]
- [3] GitHub repository of Deep Statistical solvers [[Link](#)]
- [4] YouTube Playlist on GNNs [[Link](#)]
- [5] Penn Engineering, Graph Neural Networks [[Link](#)]
- [6] Residual or Gate? Towards Deeper Graph Neural Networks for Inductive Graph Representation Learning, 2019, *Binxuan Huang, Kathleen M. Carley* [[Link](#)]