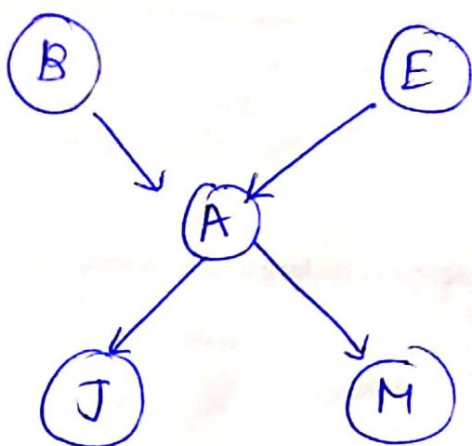


Review



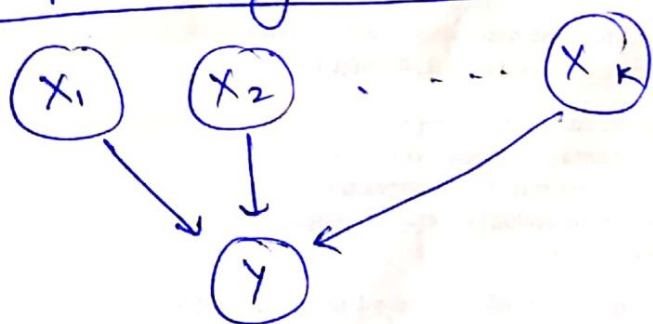
Burglary?
 Earthquake?
 Alarm?
 John calls?
 Mary calls?

* Belief Network $BN = DAG + CPTs$

* Conditional Independence on all other ancestors given parents

$$P(x_i | x_1, \dots, x_{i-1}) = P(x_i | pa(x_i))$$

Representing CPTs



For simplicity, assume binary variables $\{0, 1\}$ are the values

$$x_i \in \{0, 1\}, y \in \{0, 1\}$$

How to represent $P(y=1 | x_1, x_2, \dots)$

① Lookup table $O(2^k)$ rows store arbitrary CPT

x_1	x_2	\dots	x_k	$P(y=1 x_1, \dots, x_k)$
0	0			0.1
1	0			0.9
\vdots	\vdots			\vdots
\vdots	\vdots			0.6

2^k
 combos

too many combinations if k is large.

② Deterministic CPT

"AND" function as a CPT $P(Y=1 | x_1, \dots, x_k) = \prod_{i=1}^k x_i$

"OR" function as a CPT $P(Y=0 | x_1, \dots, x_k) = \prod_{i=1}^k (1 - x_i)$

③ Noisy-OR CPT

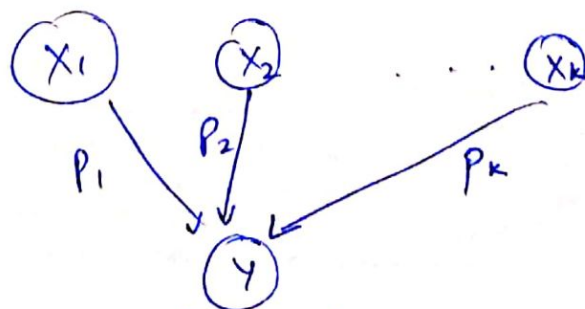
Use k numbers $p_i \in [0, 1]$ to parametrize all 2^k entries in CPT.

$$P(Y=0 | x_1, x_2, \dots, x_k) = \prod_{i=1}^k (1 - p_i)^{x_i}$$

$$P(Y=1 | x_1, x_2, \dots, x_k) = 1 - \prod_{i=1}^k (1 - p_i)^{x_i}$$

Why "Noisy-OR"? Look at prob. that $Y=1$ when exactly one parent is "on" (equal to 1):

$$\begin{aligned} P(Y=1 | x_1=0, x_2=0, \dots, x_{j-1}=0, x_j=1, x_{j+1}=0, \dots, x_k=0) \\ = 1 - (1-p_1)^0 \dots (1-p_j)^1 \dots (1-p_k)^0 \\ = 1 - (1-p_j) = p_j \end{aligned}$$



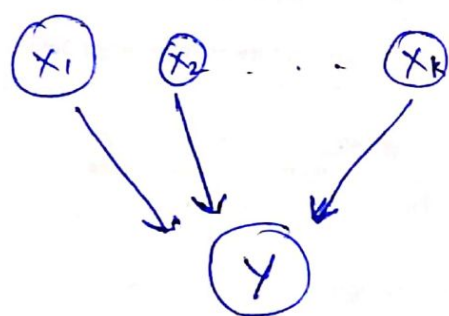
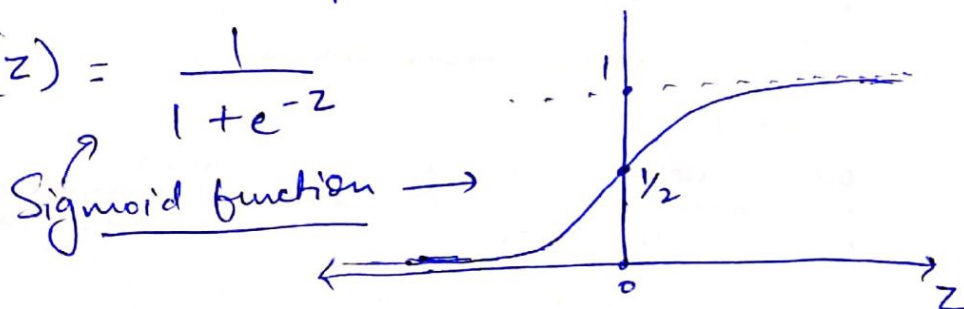
Intuitively, $p_i \in [0, 1]$ is trigger prob. that $\underbrace{x_i=1}_{\text{by itself}}$ causes $Y=1$. Setting all $p_i=1$ for $i=1, 2, \dots, k$ recovers logical OR.

Example: parents are diseases and child is symptoms.
The more diseases you have, the more probability of symptoms.

④ Sigmoid CPT

Use k real numbers θ_i to parametrize 2^k rows of CPT.

Let $\sigma(z) = \frac{1}{1 + e^{-z}}$



$$P(Y=1 | x_1, x_2, \dots, x_k) = \sigma\left(\sum_{i=1}^k \theta_i x_i\right)$$

Also known as logistic regression. ⁱⁿ Statistics or activation function in Neural Nets.

- If θ_i strongly negative, then $x_i=1$ tends to inhibit / suppress $Y=1$
- If θ_i strongly positive, then $x_i=1$ tends to activate / excite $Y=1$
- Unlike a Noisy-OR CPT, Sigmoid CPT can mix inhibition / excitation.

Conditional Independence

- A node X_i is conditionally independent of its non-parent ancestors given its parent.

$$P(X_i | X_1, X_2, \dots, X_{i-1}) = P(X_i | \text{pa}(X_i))$$

- More generally:

Let X, Y , and E refer to disjoint sets of nodes in B_N

When is X conditionally independent of Y given E ?

When is $P(X | E, Y) = P(X | E)$?

When is $P(X, Y | E) = P(X | E) P(Y | E)$?

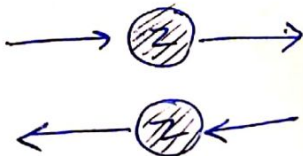
d-separation

Direction-dependent (in DAGs)

Relates conditional independence to graph theoretic properties.

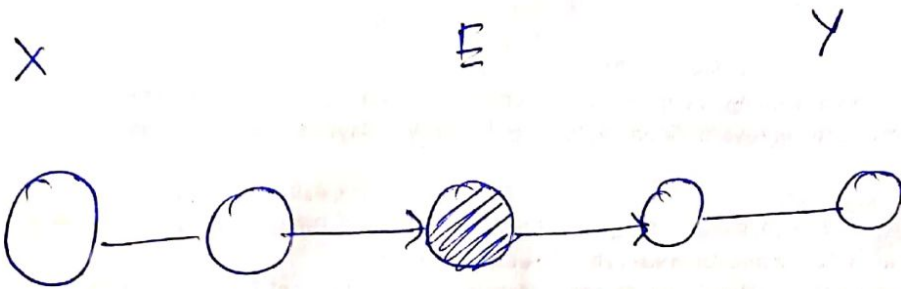
Thm: $P(X, Y | E) = P(X | E) P(Y | E)$ if and only if every (undirected) path from a node in X to a node in Y is "d-separated" by E .

Def: a path π is d-separated if there exists a node $z \in \pi$ for which one of these conditions hold:

- 1) $z \in E$ with.  edges flow through the node z

2) $Z \in E$ with $\leftarrow \textcircled{Z} \rightarrow$ edges diverge from Z

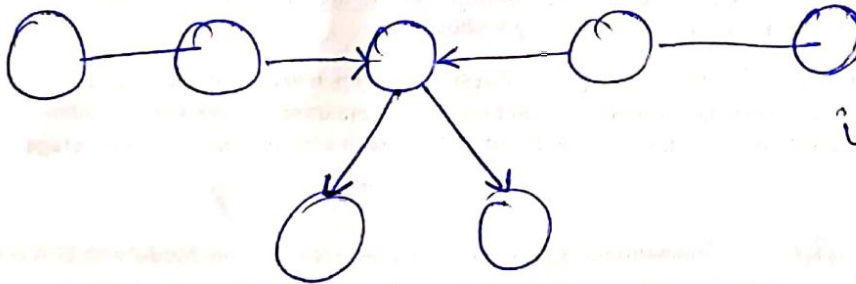
3) $Z \notin E$ ~~with~~ with \textcircled{Z} edges converge on Z
 descendants(Z) $\notin E$



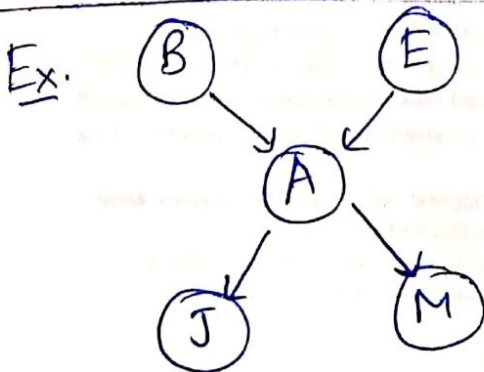
$Z \in E$ is an intervening event in a causal chain



$Z \in E$ is a common explanation or cause of X and Y .



$Z \notin E$, $\text{desc}(Z) \notin E$
 ↓
 is a common effect (unobserved).



True or false?

1) $P(B|A, M) \stackrel{?}{=} P(B|A)$



checks out $\rightarrow A \rightarrow (1) \checkmark$ True

2) $P(J, M | A) \stackrel{?}{=} P(J | A) P(M | A)$ TRUE.



3) $P(B) \stackrel{?}{=} P(B | E)$ TRUE



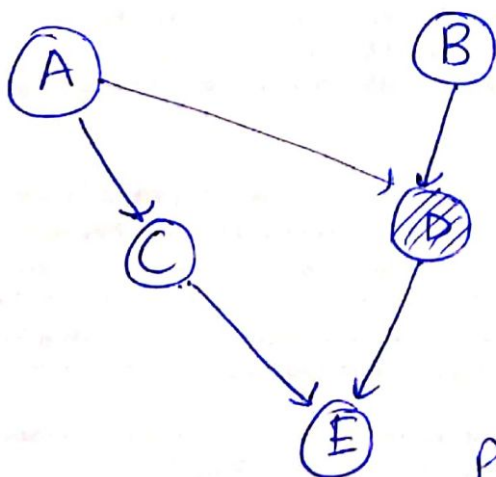
4) $P(B | M) \stackrel{?}{=} P(B | M, E)$ ~~TRUE~~ FALSE



A violates (i), (ii), (iii) \rightarrow desc(A) \cap E

explaining away.

Ex.



True or false

$\star P(B | D, E) \stackrel{?}{=} P(B | D)$ FALSE.

Path $(B \rightarrow D \rightarrow E)$

Condition (i) d-separation

Path $(B \rightarrow D \leftarrow A \rightarrow C \rightarrow E)$

\downarrow
violates
cond (iii).

all 3 conds. violated.

* Proof that d-sep \iff conditional independence is not trivial.

* Algorithms exist for efficient tests of d-separation.

Inference

* Problem.

E — set of evidence nodes

Q — set of query nodes.

How to compute posterior distribution $P(Q|E)$?

* Types of inference

— diagnostic reasoning from effects to causes.

$$P(B=1 | M=1)$$

— causal reasoning from causes to effects

$$P(M=1 | B=1)$$

— explaining away (about multiple causes)

$$P(B=1 | A=1, E=1)$$

— mixed reasoning $P(B=1, M=1 | J=1, A=1)$

When can inference be done efficiently?

i.e. (polynomial time in size of DAG and CPTs)