

## Tensors

The four momentum we have been working with is part of a family of objects called Tensors, which can have more than one index.

Consider angular momentum (non-relativistic):

$$\underline{L} = \underline{r} \times \underline{p}$$

$$\text{so } L^1 = y p_z - z p_y$$

$$L^2 = z p_x - x p_z$$

$$L^3 = x p_y - y p_x$$

Relativistically, we express this as a tensor:

$$L^{\mu\nu} = x^\mu p^\nu - p^\mu x^\nu$$

where  $x^1, x^2, x^3 = x, y, z$  respectively

$p^1, p^2, p^3 = p_x, p_y, p_z$  respectively

$$\text{so eg. } L^{12} = x^1 p^2 - p^1 x^2 = x p_y - y p_x = L^3$$

Tensors have many properties, some of which are:

- Under Lorentz transformations  $L'^{\mu\nu} = \Lambda^\mu_\alpha \Lambda^\nu_\beta L^{\alpha\beta}$

- Lorentz invariant:  $L^{\mu\nu} L_{\mu\nu} = (L^{00})^2 - (L^{01})^2 + (L^{11})^2 + \dots = \text{constant}$

There will be 16 terms in the final matrix here, but the diagonal terms will be 0. So there are really only 6 independent terms.

like the metric  $g_{\mu\nu} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$  is a tensor