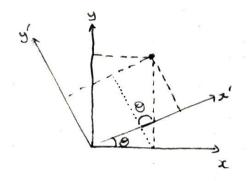
An Analogy to Rotations

It is helpful to think of loverte transformations as a generalisation of the idea of rotations.



consider two coordinate systems, with one system rotated on angle a about the origin relative to the other system.

The transformation is: $x' = x\cos\theta + y\sin\theta$ $y' = y\cos\theta - x\sin\theta$

we can express this transformation in vector form:

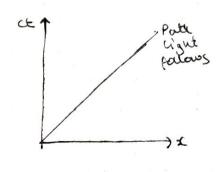
$$\begin{pmatrix} \partial_{1} \\ x_{1} \end{pmatrix} = \begin{pmatrix} -\epsilon_{1} \sqrt{6} & \cos \theta \\ \cos \theta & \epsilon_{1} \sqrt{6} \end{pmatrix} \begin{pmatrix} \partial_{1} \\ \chi \end{pmatrix}$$

There is an invariant quantity, a property that is the same in both reference frames: the distance of a particle from the origin:

$$L^2 = x^2 + y^2 = x^2 + y^2$$

Now consider a Lorentz transformation in the same way. We can do something similar with Lorentz transformations.

Consider the x-ct plane:



The transformation to a frame moving relative to this is:

ct' =
$$yct - \frac{y}{c}yx$$

who ct' = 0 => ct = $\frac{y}{c}x$
 $x' = yx - \frac{y}{c}yct$

who $x' = 0 \Rightarrow ct = Gx$

The invariant is this case will be $ct^2 - |x|^2$ when we construct "4-vectors" is the next section, this will be the "length" of the 4-vector.

The constructed matrix will be:

$$\begin{pmatrix} x' \end{pmatrix} = \begin{pmatrix} -\frac{\zeta}{\lambda} & \chi \\ \frac{\zeta}{\lambda} & -\frac{\zeta}{\lambda} \end{pmatrix} \begin{pmatrix} x \\ \zeta \end{pmatrix}$$