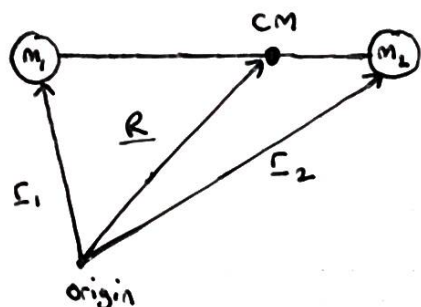


## Centre of Mass

If we have a system of particles :



CM is the centre of mass of the two particles.  $\underline{r}_1$  and  $\underline{r}_2$  are the position vectors of the particle with mass  $m_1$  and  $m_2$  relative to the origin.

From this, we can calculate  $\underline{R}$ , the position vector of CM relative to the origin:

$$\underline{R} = \frac{m_1 \underline{r}_1 + m_2 \underline{r}_2}{m_1 + m_2}$$

We can also set the origin at one of the points to reduce some of the variables in the equation.

Differentiating this with respect to time:

$$\frac{d\underline{R}}{dt} = \frac{m_1 \underline{v}_1 + m_2 \underline{v}_2}{m_1 + m_2} = \frac{\underline{p}_1 + \underline{p}_2}{m_1 + m_2}$$

if  $\underline{p}_1 + \underline{p}_2$  (linear momentum) is conserved, then the centre of mass moves with constant velocity.

The equation for centre of mass holds true for many particles as well:

$$\underline{R} = \frac{m_1 \underline{r}_1 + m_2 \underline{r}_2 + \dots + m_i \underline{r}_i}{m_1 + m_2 + \dots + m_i}$$

## Centre of Mass moving at constant velocity -

If there are  $N$  particles, the centre of mass is given by:

$$\underline{R} = \frac{\sum_{i=1}^N m_i \underline{r}_i}{\sum_{i=1}^N m_i}$$

Considering only the  $i^{\text{th}}$  particle, we can use Newton's 2 Law to give:

$$\underline{F}_i = m_i \underline{a}_i = m_i \frac{d^2 \underline{r}_i}{dt^2} = \frac{d^2 m_i \underline{r}_i}{dt^2} \quad \text{Now for the total force:}$$

$$\begin{aligned} \underline{F}_{\text{total}} &= \sum_{i=1}^N \underline{F}_i = \sum_{i=1}^N \frac{d^2 m_i \underline{r}_i}{dt^2} = \frac{d^2}{dt^2} \left( \sum_{i=1}^N m_i \underline{r}_i \right) \\ &= \frac{d^2}{dt^2} \left( \sum_{i=1}^N m_i \underline{r}_i \right) \times \frac{\text{total mass}}{\text{total mass}} \quad \text{where total mass} \\ &\quad \quad \quad = \sum_{i=1}^N m_i \\ &= \sum_{i=1}^N m_i \frac{d^2}{dt^2} \left( \underbrace{\frac{\sum_{i=1}^N m_i \underline{r}_i}{\sum_{i=1}^N m_i}}_{\text{but this is } \underline{R}} \right) \end{aligned}$$

$$\therefore \boxed{\underline{F}_{\text{total}} = M \frac{d^2}{dt^2} \underline{R}} \quad \text{where } M \text{ is total mass}$$

So regular Newtonian mechanics still apply to multiple particles focused on the centre of mass.