This arduino sketch is for the "Onkruidvrij in the Rij" conveyor weeder demonstrator. This demonstrator has a conveyor belt with fake crops and weeds. The position of these plants needs to be tracked.

Inputs:

- -AMT212b RS485 encoder on the driveshaft to track shaft revolutions
- -Infrared sensor module that detects a reflective tape on the black belt to track belt revolutions.

Output:

Arduino is connected via USB to a computer. Open terminal 115200

baud and type "Help" to get the commandlist:

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"Type READ to read the sensor once",
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[&]quot;Type RUN to start continues measument",

[&]quot;Type STOP to stop continues measument",

[&]quot;Type RESET to reset settings and encoder",

[&]quot;Type VELOCITY to receive velocity data [m/s], only updates if systems runs -> type RUN to run.",

[&]quot;Type DISTANCE to recieve the traveld distance [m]], only updates if systems runs -> type RUN to run.",

[&]quot;Print an checksum example with correct data",

[&]quot;Print an checksum example with incorrect data"