

trees & forest

agenda:

1. decision trees: introduction
2. decision trees: how does it work?
3. random forest: introduction
4. random forest: how does it work?
5. hands on

Decision Tree (DT)

metaphoric basis:

a standard tree... well... upside down

with all the bells and whistles:

- root
- branching (nodes)
- branches (edges)
- leafs, terminal nodes

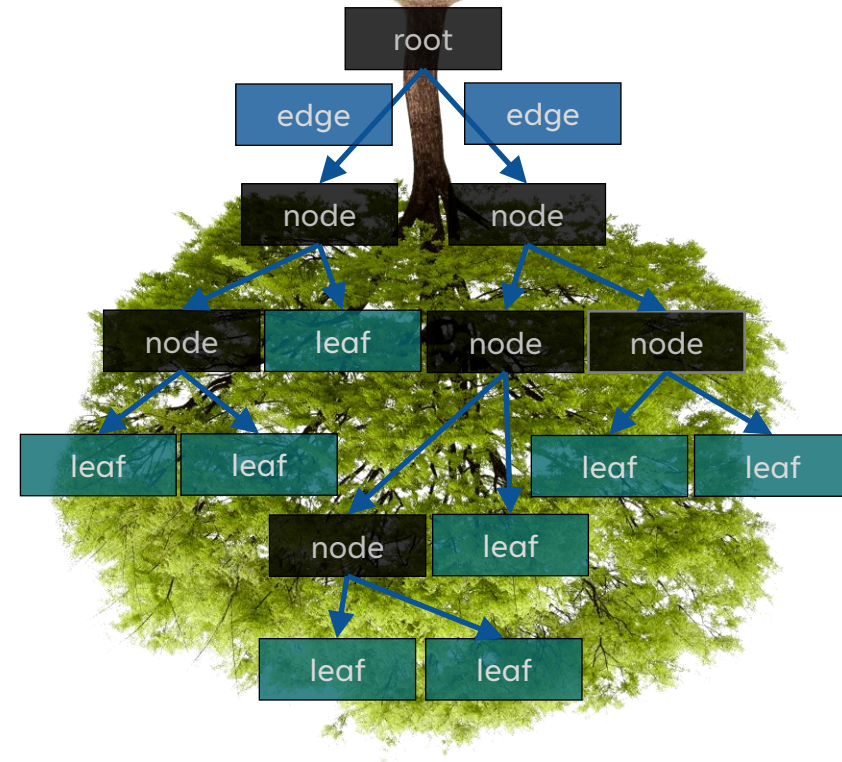
the main principle

„question-and-answer“

root/node: interrogate the data

edge: if „yes“: go left, else: go right

leaf: contains final decision / statement



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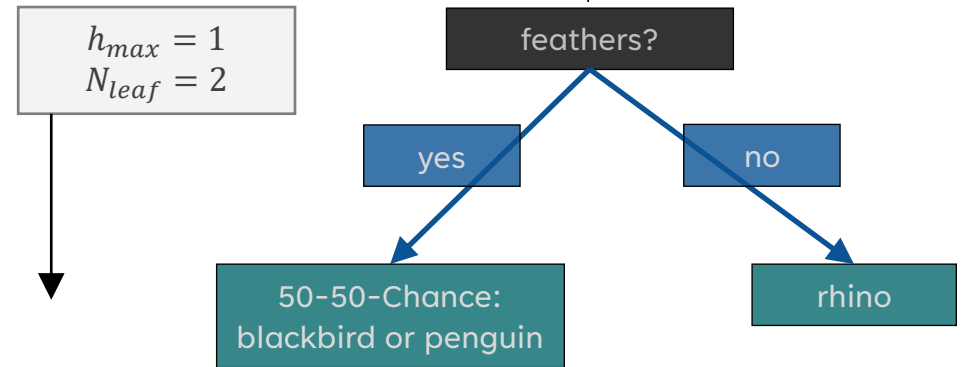
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example

classification of animals

pruned DT:
multiple statements in terminal node („impurity“)



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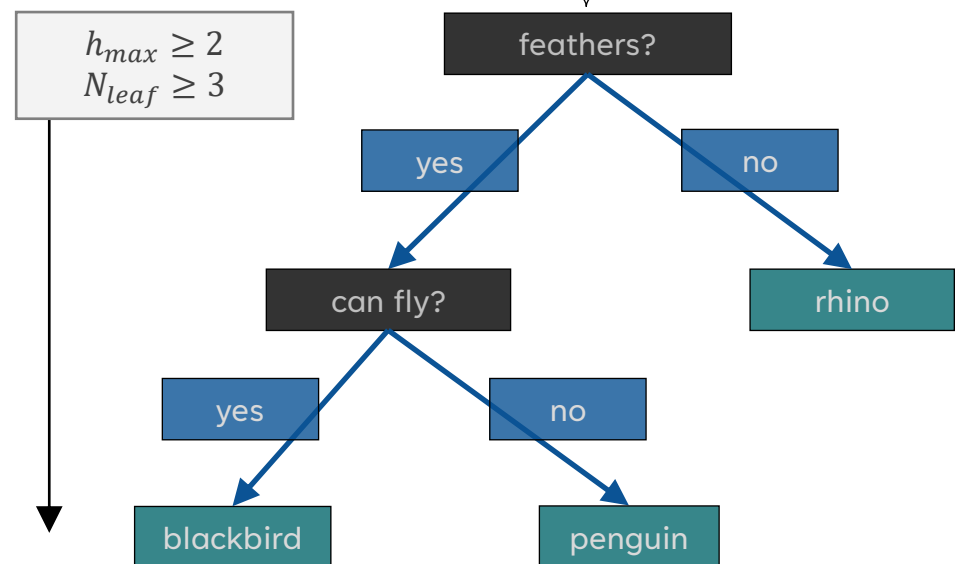
example

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unpruned DT:

single statement per leaf („purity“)

→ important **hyperparameter**: h_{max} or N_{leaf}



mathematical formulation of Q&A

regression & classification:

1. a DT splits the domain into M subdomains
2. constant value c_m in every subdomain R_m

decision to split a domain:

➔ metric: **node impurity** Q

metric for regression

N : data points, y : true value, \hat{y} : predicted value

Mean Squared Error (MSE):

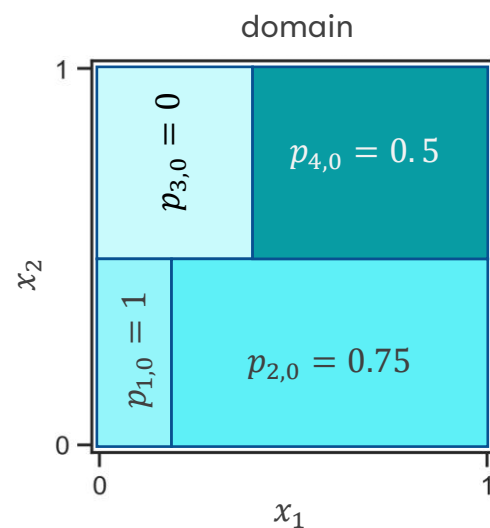
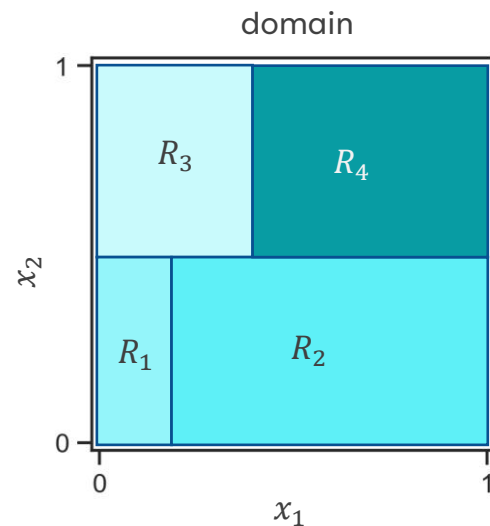
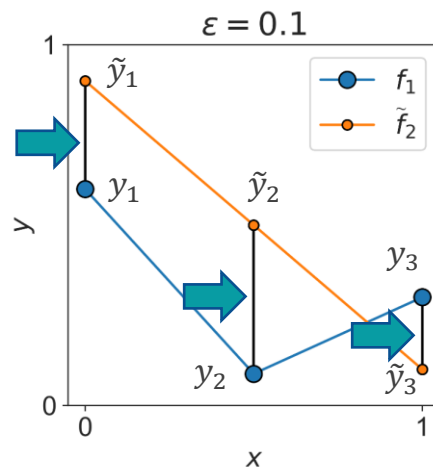
$$Q = \varepsilon_{MSE}(\mathbf{y}, \hat{\mathbf{y}}) = \frac{1}{N} \sum_{i=0}^{N-1} (y_i - \hat{y}_i)^2$$

metric for classification

$p_{m,k}$: probability of occurrence of class $k \in K$
in node $m \in M$

Gini (impurity) Index:

$$Q_m = \sum_{k=1}^K p_{m,k}(1 - p_{m,k})$$



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example

$f: \mathbb{R} \rightarrow \mathbb{R}, f(x) = x^2 = y$

mean is „best guess“ for each subdomain

$\hat{y}_i = c_m = \bar{y}_i \forall x_i \in R_m$

$$n = 11$$

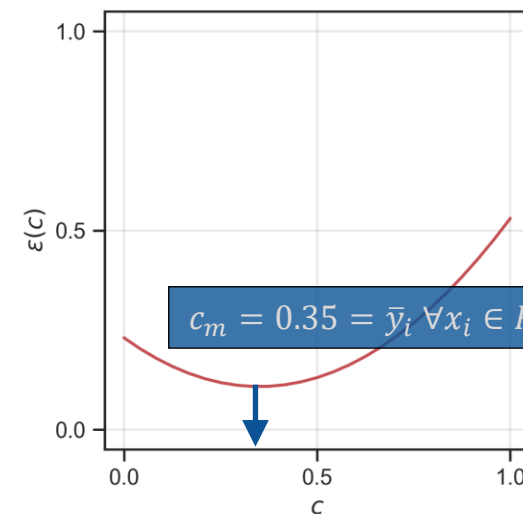
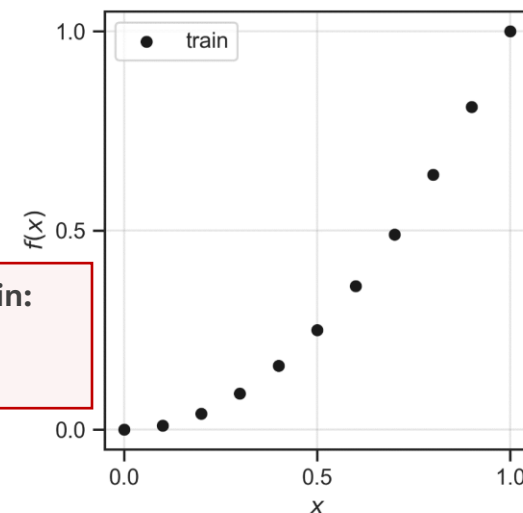
$$\hat{y} = ?$$

$$\varepsilon_{MSE} = ?$$

R_m is currently whole domain:

what is the best

$$c_m = \hat{y}_i \forall x_i \in R_m$$



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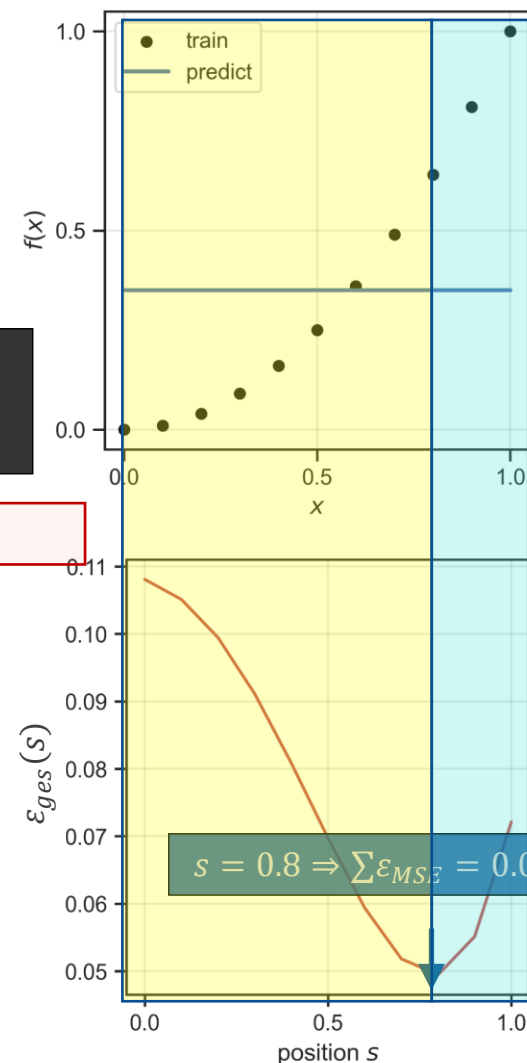
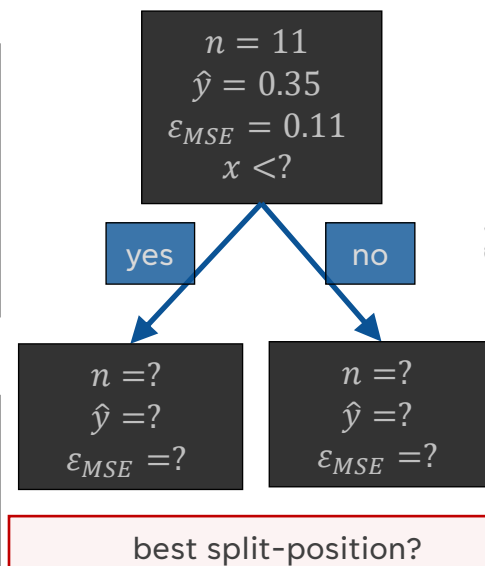
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minimize ε_{ges} by splitting domain at position s :

$$\varepsilon_{ges}(s) = \sum_{m=1}^{M=2} \varepsilon_m(s)$$



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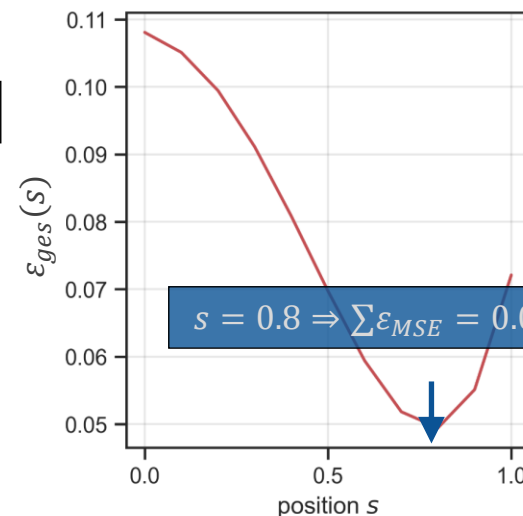
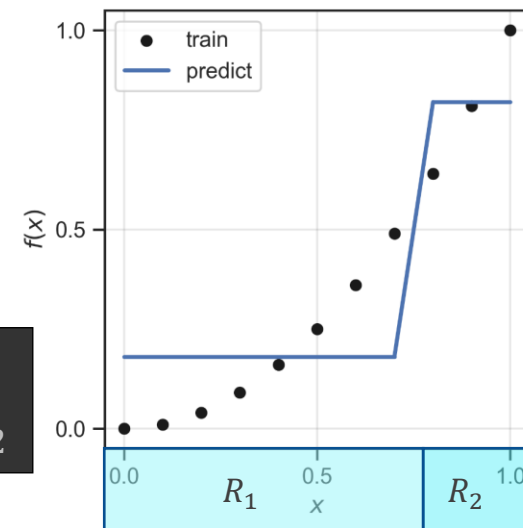
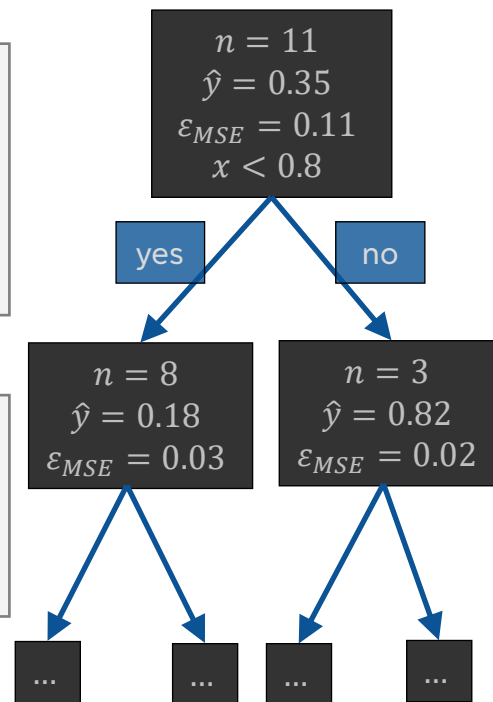
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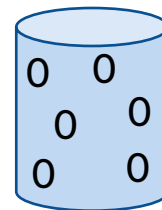
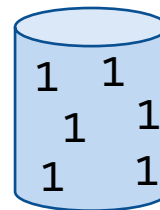
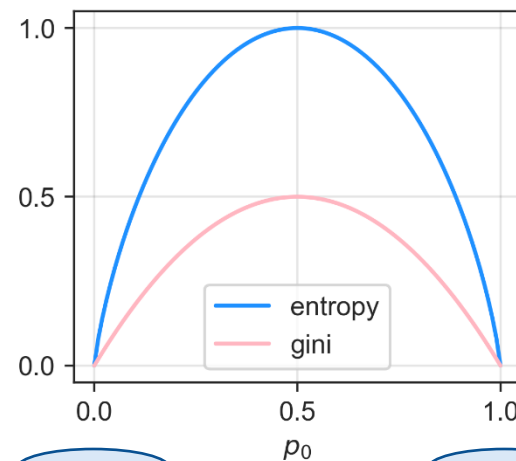
Gini (impurity) Index:

$$Q_m = \sum_{k=1}^K p_{m,k}(1 - p_{m,k})$$

Entropy H :

$$H = - \sum_{k=1}^K p_{m,k} \ln(p_{m,k})$$

Gini Index vs. Entropy ($K=2$)



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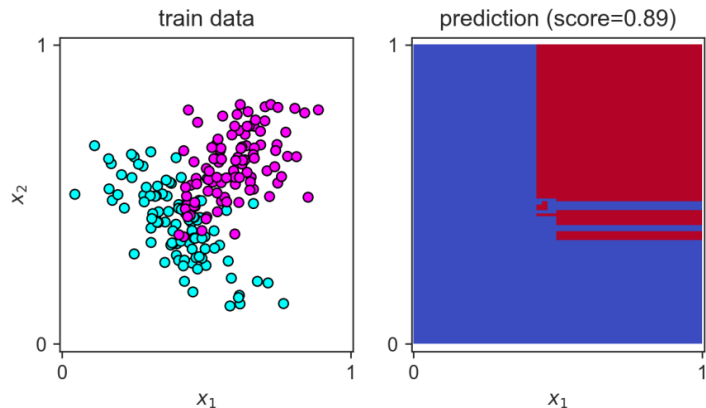
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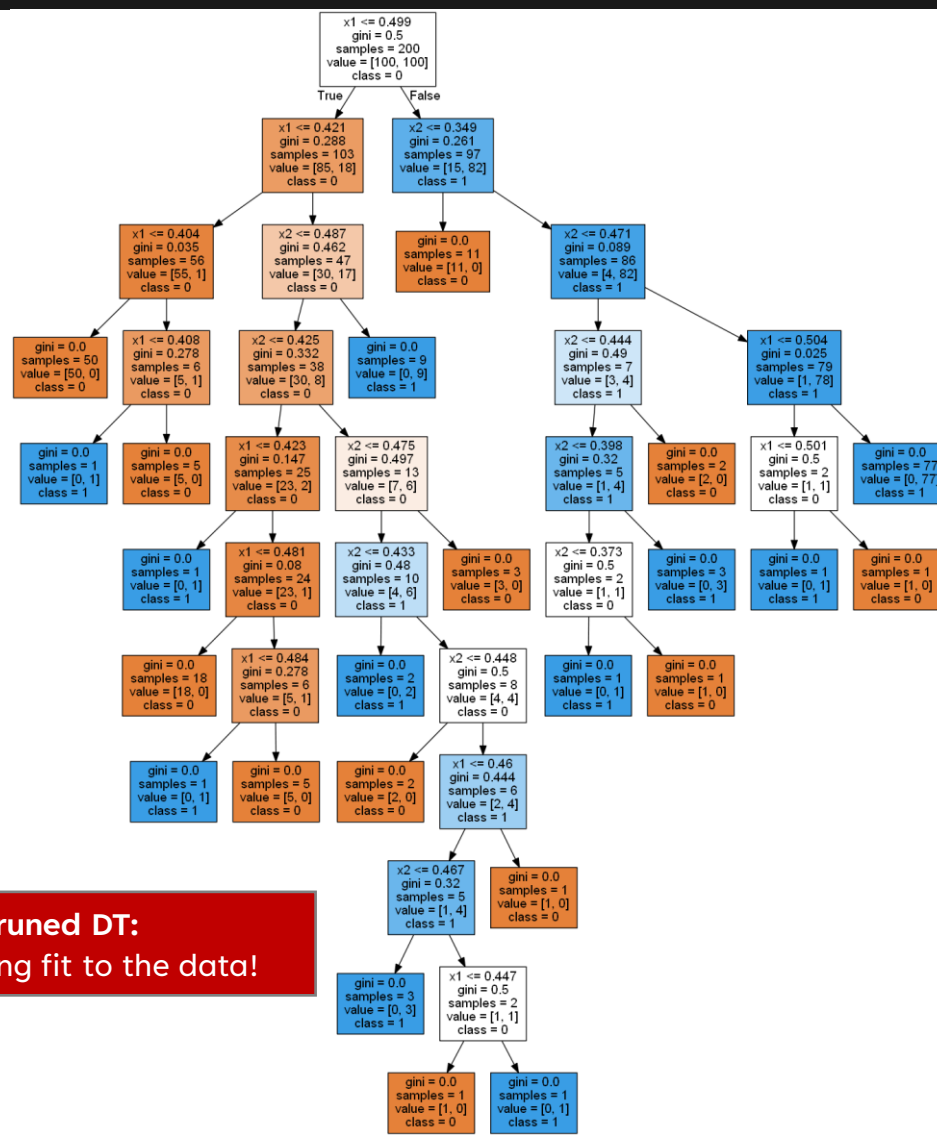
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**unpruned DT:
strong fit to the data!**



bias & variance

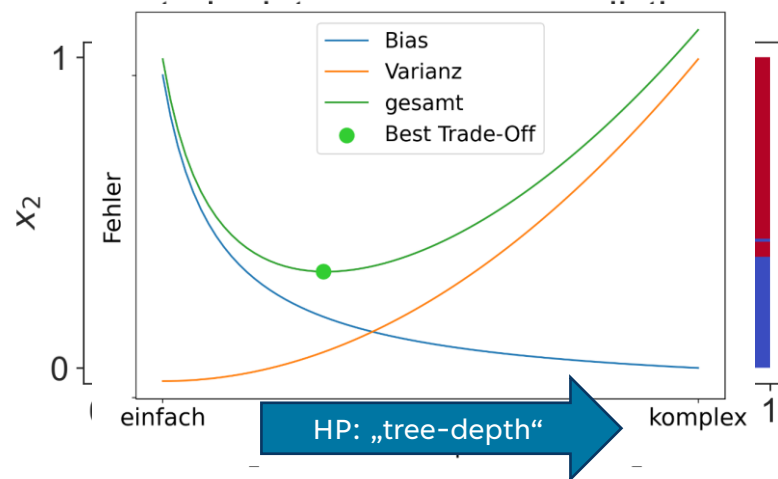
general definition of a function for approximation:

$$\hat{f}: \mathbb{R}^{n,m} \rightarrow \mathbb{R}^m, \hat{f}(X) = \hat{y} = y + \varepsilon$$

the **approximation error** ε contains of:

- unknown influences
- **model-bias**:
simplifications, high when underfitting
- **model-variance**
high complexity, high when overfitting

➔ **IMPORTANT: bias-variance trade-off**



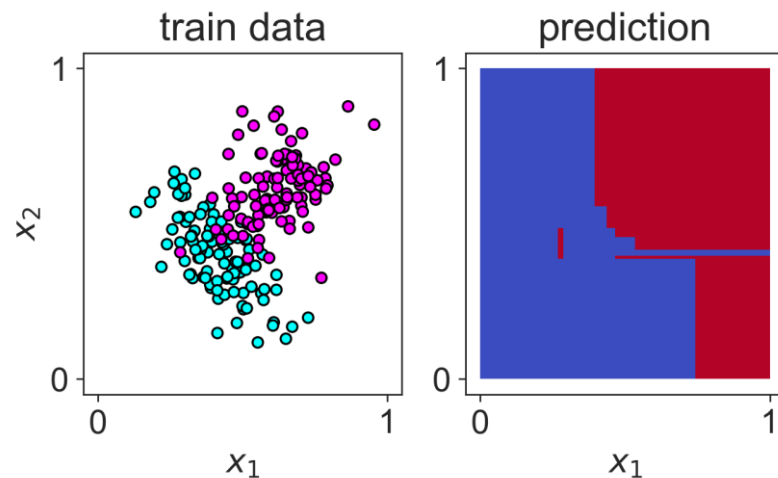
unpruned DT: pros & cons

pros:

- can handle mixed and redundant variables
- **small Bias**
- ...

cons:

- **high varianz**
- **usually prediction is not very good**
- ...



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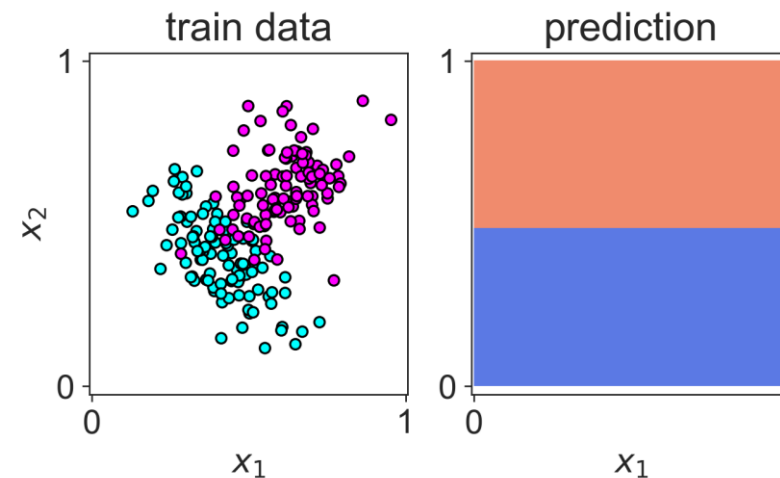
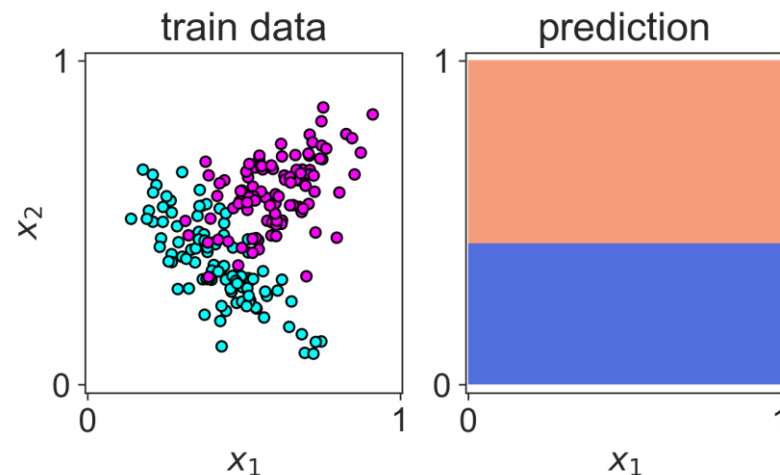
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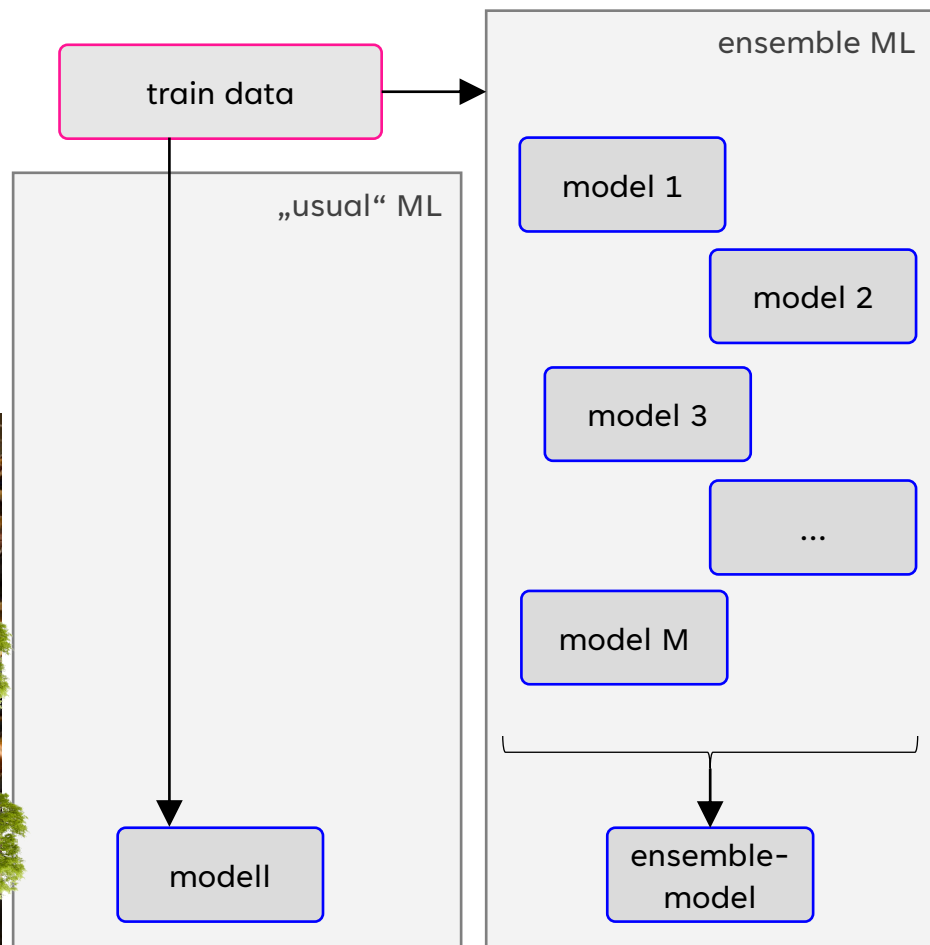
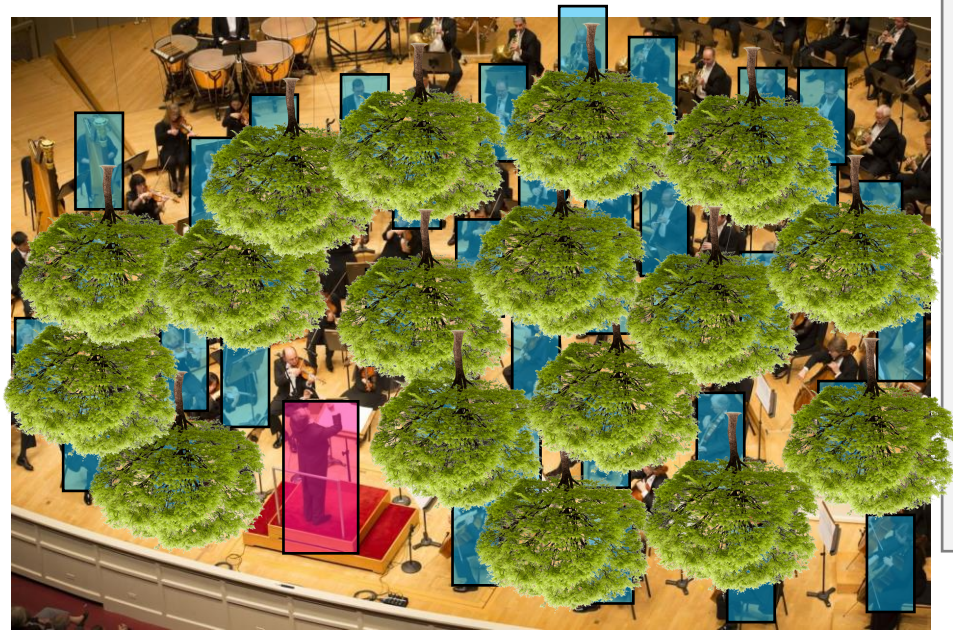
what is a random forest?

it's an ensemble

what is an ensemble?

it's an aggregation...

- of multiple models (usually DTs)
- to exploit pros
- to avoid cons



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different types of ensembles

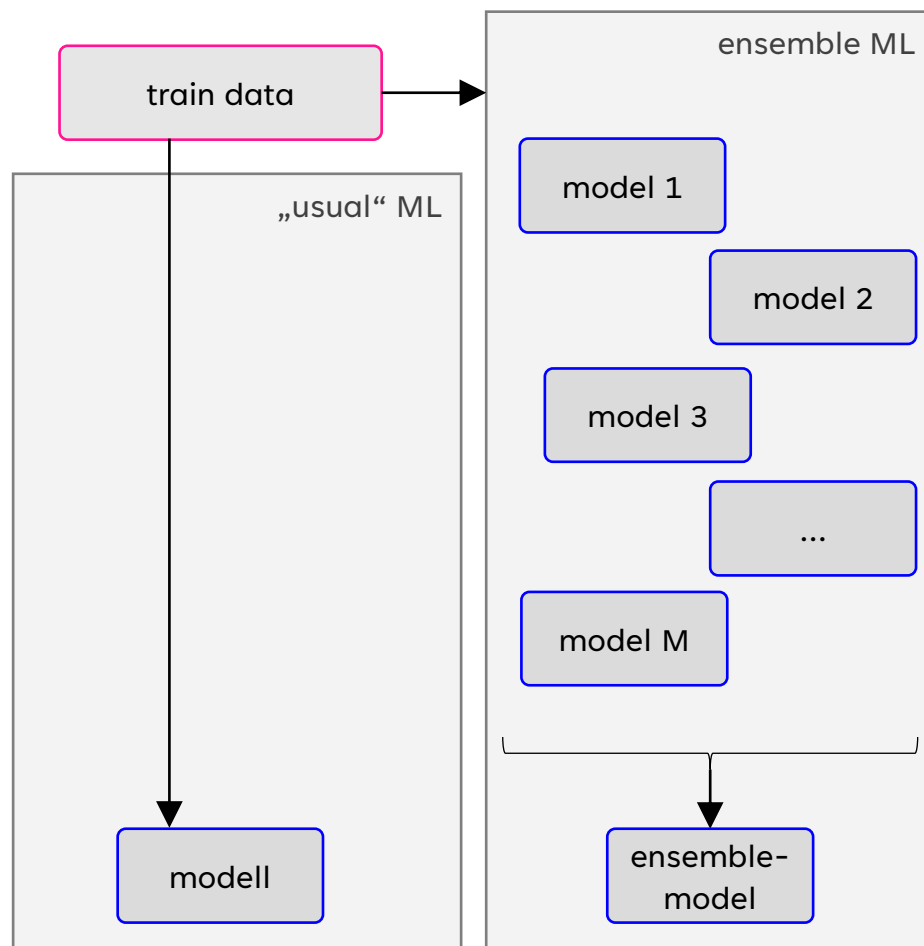
Bagging [[Breiman, 1996](#)]

- **Random Forest** [[Breiman, 2001](#)]

Boosting:

- AdaBoost [[Freund & Shapire, 1996](#)]
- Gradient Boosting [[Friedman, 1999](#)]
(*Extreme Gradient Boosting* [[Chen & Guestrin, 2016](#)])

Stacking



starting point

unpruned DT*

- pro: small bias
- con: high variance

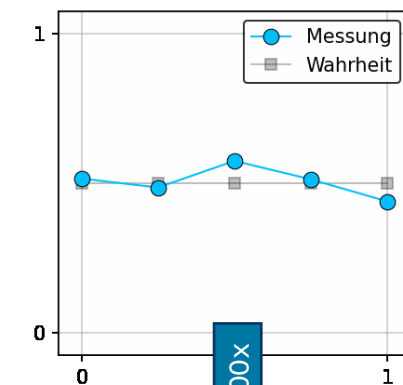
bagging

short for „bootstrap aggregation“

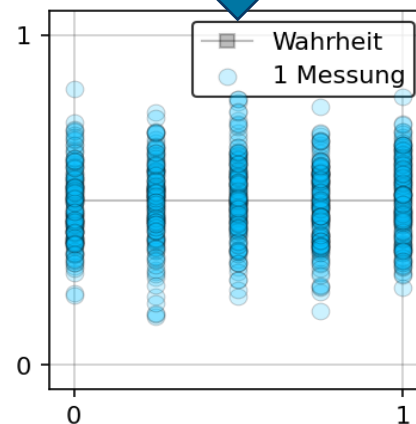
idea:

build an ensemble of unpruned DTs

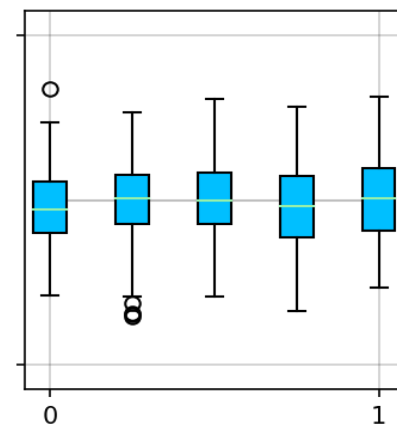
- exploit pro of **small bias** (strong adaption)
- avoid con of high variance by **bootstrapping** (averaging **random resamples**)



100x



Box-Whisker-Plot



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process

1. resample data $\mathbf{X} \in \mathbb{R}^{n,p}$

by bootstrapping $L \in \mathbb{N}$ times:

$$\mathbf{X} \rightarrow \{\mathbf{X}_{BS,1}, \dots, \mathbf{X}_{BS,L}\} \text{ with } \mathbf{X}_{BS,l} \in \mathbb{R}^{n,p}$$

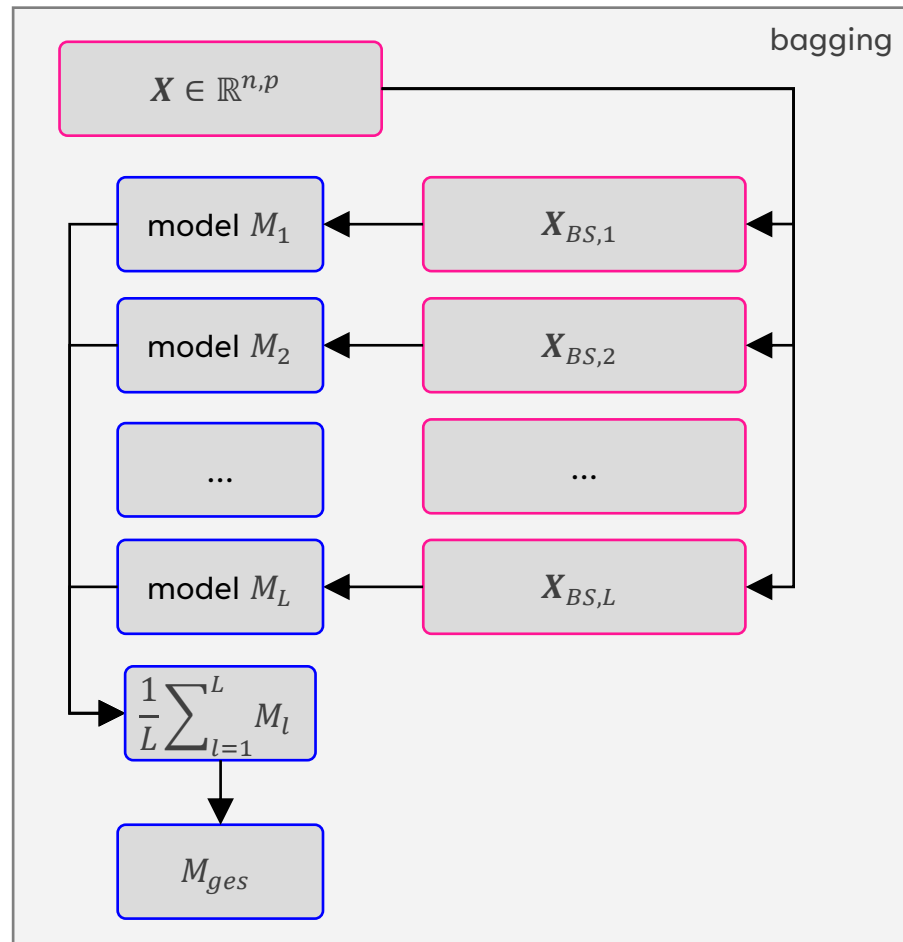
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3. answer of the whole ensemble M_{ges} :

averaging all ensemble-members

$$M_{ges} = \frac{1}{L} \sum_{l=1}^L M_l$$



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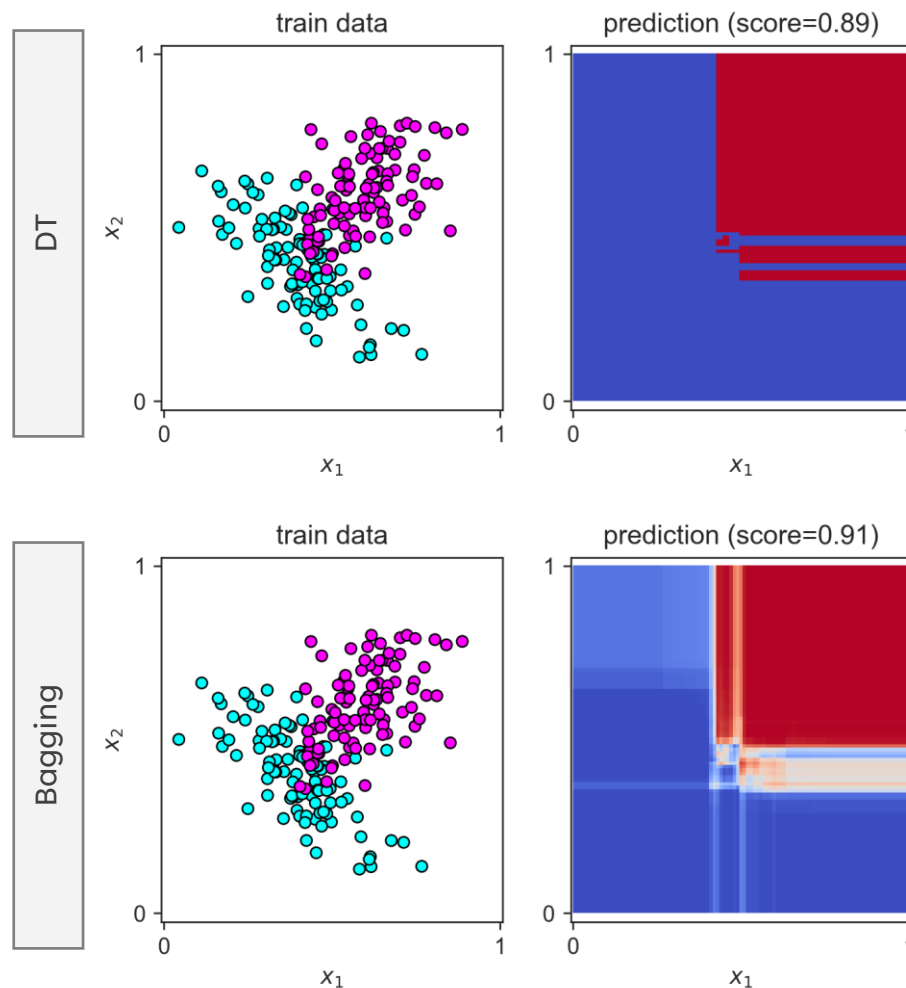
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extended bagging

decreasing variance even further by...

uncorrelated DTs

$\mathbf{X} \in \mathbb{R}^{n,p}$ training data, n samples, p features

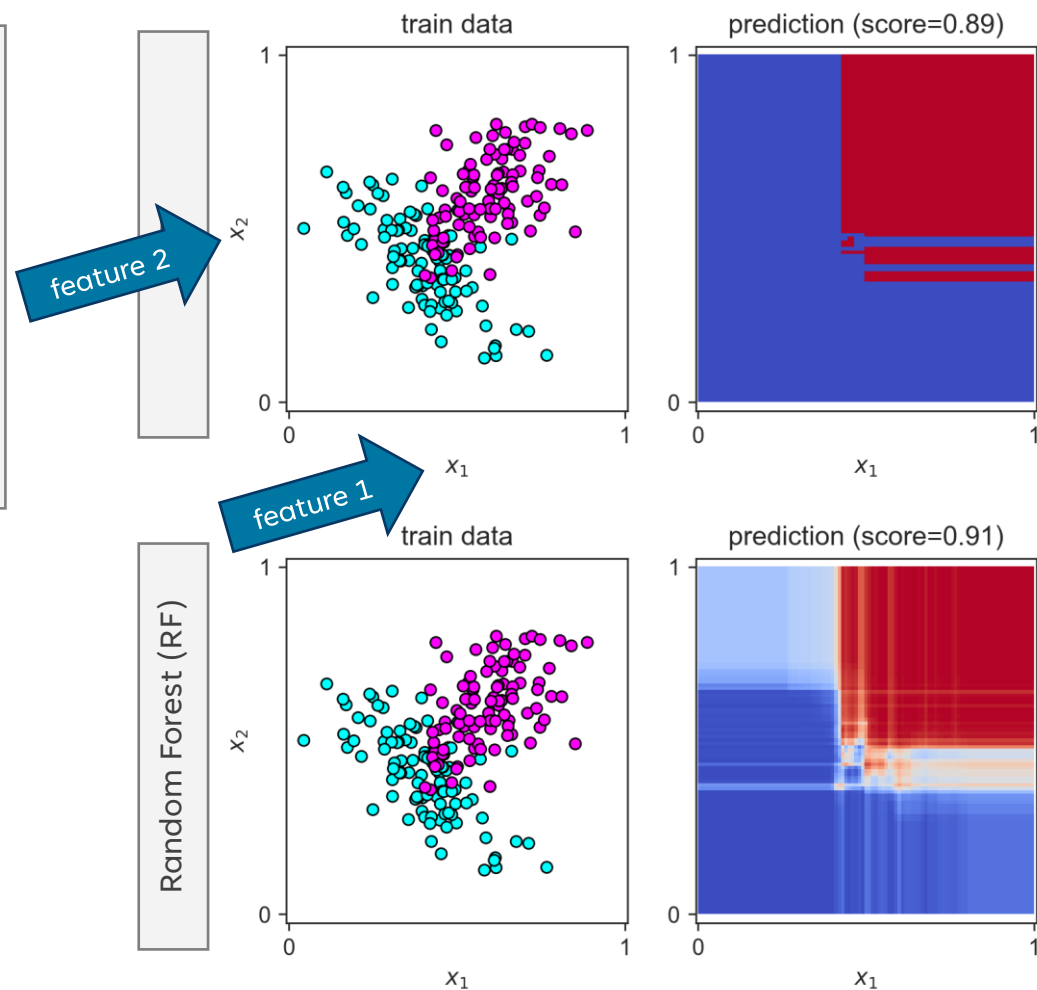
random forest:

train DTs with randomly selected $m < p$ features

$\mathbf{X} \in \mathbb{R}^{n,m}$

e.g.:

$m = \sqrt{p}$ or $\log(p)$



code available*

clone or download GitHub-Repository

https://github.com/saifedias/tree_randomForest.git

online Notebook via Binder

https://mybinder.org/v2/gh/saifedias/tree_randomForest.git/HEAD

would you like to know more? – a short outline

bagging, boosting, stacking

<https://towardsdatascience.com/ensemble-methods-bagging-boosting-and-stacking-c9214a10a205>

ensemble learning

<https://www.kaggle.com/discussions/general/263786>

An aerial photograph of a dense, lush green forest, likely a coniferous woodland, filling the entire frame. The trees are tightly packed, creating a textured canopy of various shades of green.

BTU ML-Group

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