Sai Haneesh Allu

Personal Information Ph.D. Candidate

Intelligent Robotics and Vision Lab (IRVL)

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Education

The University of Texas at Dallas, TX, USA (2022 - Present)

Ph.D. in Computer Science Advisor: Dr. Yu Xiang

Indian Institute of Technology, Delhi, India (2018 - 2020)

M.Tech in Control Systems Advisor: Dr. Shubhendu Bhasin

National Institute of Technology, Warangal, India (2012 - 2026)

B. Tech in Electrical and Electronics Engineering

Skills

Python, ROS, PyTorch, OpenCV, Gazebo, MATLAB, Simulink, Ardupilot, Git, Java, C, C++

Experience

VECROS Technologies

Co-Founder and CTO

(Jan '20 - Nov '21)

- Beyond visual line of sight control: Developed a web interface to send commands and receive telemetry data from multiple quadrotor systems using 4g internt and aws iot module Ran anomoly detection on the edge and video streamed the detections using gstreamer and aws kinesis video stream
- Vision based gps denied navigation developed autonomous point goal navigation using interl d430 moduiles and utilized interl t261 for visual odometry replacing the gps. implemented the system on the dge using jetson nano devices

Sterlite Tech, Aurangabad, India

Operations Engineer

(May'15-Jul'15)

• electrical grounding for fiber draw mechanism Conducted comprehensive analysis of fiber spool changeover process and developed grounding mechanism to discharge the static charges affected the feedback system

Awards and Recognitions Prof. A.K.Sinha Award, IIT Delhi 1st among 140 students

(Apr '14

Best Teaching Asistant Award, IIT Delhi one among 140 students

(Apr

'14 -Mar '15)

Special Award, Sterlite Tech one among 80 employees

(Apr '14 -Mar

Spot Performance Award, Sterlite Tech one among 35 employees

(Apr

'14 -Mar '15)

Position of Responsibility Secretary, English Literary Society, IIT Kanpur

(Apr '14 -Mar '15)

- Managed Intra-College as well as Inter-College events
- Coordinated new events like Story writing & Creative writing for the society
- WonDumbC event in Galaxy(Inter-Hall Culutral Competition three times in a row

Publications

SceneReplica: Benchmarking Real-World Robot Manipulation by Creating Replicable

Ninad Khargonkar*, Sai Haneesh Allu*, Yangxiao Lu, Jishnu Jaykumar P, Balakrishnan Prabhakaran, Yu Xiang In International Conference on Robotics and Automation (ICRA), 2024.

Grasping Trajectory Optimization with Point Clouds

Yu Xiang, Sai Haneesh Allu, Rohith Peddi, Tyler Summers, Vibhav Gogate

^{*} denotes equal contribution and joint lead authorship.