jupyter Keras_Baseline_sgb (unsaved changes)

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Run Code

In [1]:
```
import pandas as pd
from keras.models import Sequential
from keras.layers import Dense, BatchNormalization, Dropout
from keras.layers.advanced_activations import PReLU
from sklearn.model_selection import train_test_split
from tensorflow import keras
import matplotlib.pyplot as plt
#from sklearn.model_selection import train_test_split
from sklearn.metrics import mean_squared_error
import tensorflow as tf
import numpy as np
```

In [2]:
```
df = pd.read_csv("row_size25_vector_size8000.csv")
```

In [3]:
```
X = df.iloc[:,7:157]
#X = df[['accelerometer_reading_x_0','accelerometer_reading_y_0','accelerometer_reading_z_0','gyro
#t = df[['linear_position_x','linear_position_y','linear_position_z','angular_position_phi','angul
#t = df[['phi_change','theta_change','psi_change']]
t = df[['phi_change']]
```

In [4]:
```
t.shape
```

Out[4]: (8000, 1)

In [5]:
```
in_dim = X.shape[1]
out_dim = t.shape[1]
```

In [6]:
```
in_dim
```

Out[6]: 150

In [7]:
```
out_dim
```

Out[7]: 1

In [8]:
```
X_train, X_test, t_train, t_test = train_test_split(X, t, test_size=0.2)
```

In [9]:
```
t_train.shape
```

Out[9]: (6400, 1)

In [10]:
```
model = Sequential()
model.add(Dense(256,input_dim=in_dim, activation="sigmoid"))
model.add(PReLU())
model.add(Dropout(.4))
model.add(Dense(128, activation="sigmoid"))
model.add(PReLU())
model.add(BatchNormalization())
model.add(Dropout(.6))
model.add(Dense(64, activation="sigmoid"))
model.add(PReLU())
model.add(BatchNormalization())
model.add(Dropout(.5))
model.add(Dense(32, activation="sigmoid"))
model.add(PReLU())
model.add(BatchNormalization())
model.add(Dropout(.6))
model.add(Dense(out_dim,activation="sigmoid"))
model.compile(loss="mse", optimizer="sgd")
```

In [11]:
```
model.fit(X_train, t_train, epochs=60, batch_size=12, verbose=2)
```

```
Epoch 52/60
534/534 - 1s - loss: 6.9664e-04
Epoch 53/60
534/534 - 1s - loss: 5.7563e-04
Epoch 54/60
```

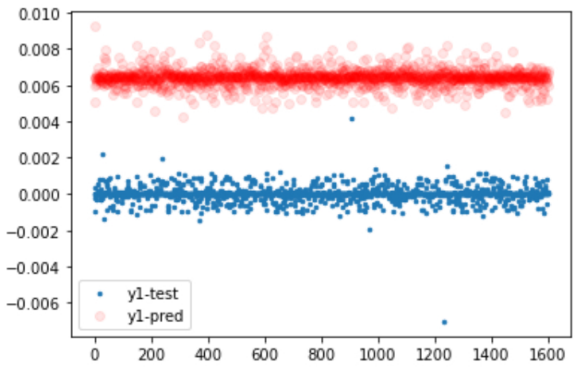
```
534/534 - 1s - loss: 6.2123e-04
Epoch 55/60
534/534 - 1s - loss: 5.5881e-04
Epoch 56/60
534/534 - 1s - loss: 6.1256e-04
Epoch 57/60
534/534 - 1s - loss: 5.8022e-04
Epoch 58/60
534/534 - 1s - loss: 5.8456e-04
Epoch 59/60
534/534 - 1s - loss: 5.6776e-04
Epoch 60/60
534/534 - 1s - loss: 5.8967e-04
```

Out[11]: <tensorflow.python.keras.callbacks.History at 0x202ee4b2400>

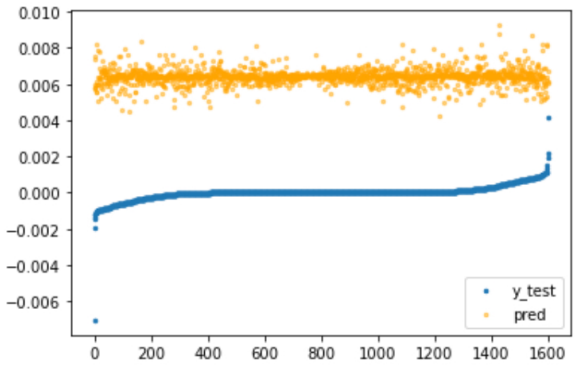
In [12]:
```
ypred = model.predict(X_test)
print("y1 MSE: ", mean_squared_error(t_test.iloc[:, 0], ypred[:,0]))
#print("y2 MSE: ", mean_squared_error(t_test.iloc[:, 1], ypred[:,1]))
#print("y3 MSE: ", mean_squared_error(t_test.iloc[:, 2], ypred[:,2]))

```

```
y1 MSE:  4.166440601532479e-05
```

In [13]:
```
x_ax = range(len(X_test))

plt.scatter(x_ax, t_test.iloc[:, 0],  s=6, label="y1-test")
plt.scatter(x_ax, ypred[:,0], label="y1-pred",c="red",alpha = 0.1)

plt.legend()
plt.show()
```



In [14]:
```
x_ax = range(len(X_test))

y_test_index = np.argsort(t_test.iloc[:, 0], axis=0).to_numpy()

f = plt.figure()
plt.scatter(x_ax, t_test.iloc[y_test_index],  s=6, label="y_test")
plt.scatter(x_ax, ypred[y_test_index], s=6, label="pred",c="orange", alpha=0.5)
#plt.ylim(t_test.iloc[y_test_index[0]].to_numpy()[0])
plt.legend()
plt.show()

f.savefig("foo.pdf", bbox_inches='tight')
```



In [ ]:
```

```