

```
In [1]: 1 import pandas as pd
2 from keras.models import Sequential
3 from keras.layers import Dense, LayerNormalization, Dropout, LSTM, Embedding
4 from keras.layers.advanced_activations import PReLU, ReLU
5 from sklearn.model_selection import train_test_split
6 from tensorflow import keras
7 import matplotlib.pyplot as plt
8 #from sklearn.model_selection import train_test_split
9 from sklearn.metrics import mean_squared_error
10 import tensorflow as tf
11 import numpy as np
```

```
In [2]: 1 df = pd.read_csv("row_size25_vector_size8000.csv")
```

```
In [3]: 1 X = df.iloc[:,7:157]
2 #X = df[['accelerometer_reading_x_0', 'accelerometer_reading_y_0', 'accelerometer_reading_z_0', 'linear_position_x', 'linear_position_y', 'linear_position_z', 'angular_velocity_x', 'angular_velocity_y', 'angular_velocity_z', 'phi_change', 'theta_change', 'psi_change']]
3 #t = df[['phi_change', 'theta_change', 'psi_change']]
4 t = df[['phi_change']]
5
```

```
In [4]: 1 t.shape
```

Out[4]: (8000, 1)

```
In [5]: 1 in_dim = X.shape[1]
2 out_dim = t.shape[1]
```

```
In [6]: 1 in_dim
```

Out[6]: 150

```
In [7]: 1 out_dim
```

Out[7]: 1

```
In [8]: 1 X_train, X_test, t_train, t_test = train_test_split(X, t, test_size=0.2)
```

```
In [9]: 1 t_train.shape
```

Out[9]: (6400, 1)

```
In [10]: 1 model = Sequential()
2 model.add(Dense(256, input_dim=in_dim, activation="elu"))
3 model.add(ReLU())
4 model.add(Dropout(.32))
5 model.add(Dense(128, activation="elu"))
6 model.add(ReLU())
7 model.add(LayerNormalization())
8 model.add(Dropout(.25))
9 model.add(Dense(64, activation="elu"))
10 model.add(ReLU())
11 model.add(LayerNormalization())
12 model.add(Dropout(.1))
13 model.add(Dense(32, activation="elu"))
14 model.add(ReLU())
15 model.add(LayerNormalization())
16 model.add(Dense(out_dim, activation="elu"))
17 model.compile(loss="mse", optimizer="sgd")
```

```
In [11]: 1 model.fit(x_train, t_train, epochs=75, batch_size=12, verbose=2)
```

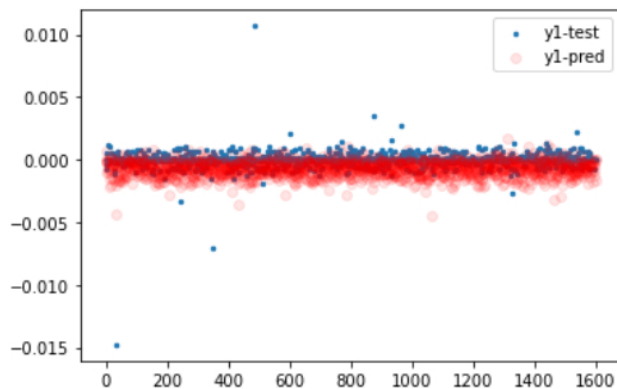
```
Epoch 67/75  
534/534 - 1s - loss: 3.5954e-05  
Epoch 68/75  
534/534 - 1s - loss: 3.3395e-05  
Epoch 69/75  
534/534 - 1s - loss: 2.7003e-05  
Epoch 70/75  
534/534 - 1s - loss: 3.2815e-05  
Epoch 71/75  
534/534 - 2s - loss: 2.8905e-05  
Epoch 72/75  
534/534 - 2s - loss: 3.0152e-05  
Epoch 73/75  
534/534 - 2s - loss: 2.9395e-05  
Epoch 74/75  
534/534 - 1s - loss: 2.5979e-05  
Epoch 75/75  
534/534 - 1s - loss: 2.0701e-05
```

```
Out[11]: <tensorflow.python.keras.callbacks.History at 0x21d9ffdc580>
```

```
In [12]: 1 ypred = model.predict(X_test)  
2 print("y1 MSE: ", mean_squared_error(t_test.iloc[:, 0], ypred[:,0]))  
3 #print("y2 MSE: ", mean_squared_error(t_test.iloc[:, 1], ypred[:,1]))  
4 #print("y3 MSE: ", mean_squared_error(t_test.iloc[:, 2], ypred[:,2]))  
5
```

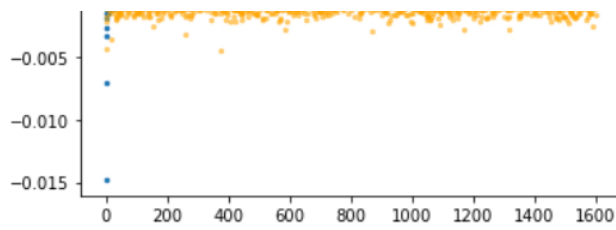
```
y1 MSE: 1.1785877934678795e-06
```

```
In [13]: 1 x_ax = range(len(X_test))  
2  
3 plt.scatter(x_ax, t_test.iloc[:, 0], s=6, label="y1-test")  
4 plt.scatter(x_ax, ypred[:,0], label="y1-pred",c="red",alpha = 0.1)  
5  
6 plt.legend()  
7 plt.show()
```



```
In [14]: 1 x_ax = range(len(X_test))  
2  
3 y_test_index = np.argsort(t_test.iloc[:, 0], axis=0).to_numpy()  
4  
5 f = plt.figure()  
6 plt.scatter(x_ax, t_test.iloc[y_test_index], s=6, label="y_test")  
7 plt.scatter(x_ax, ypred[y_test_index], s=6, label="pred",c="orange", alpha=0.1)  
8 #plt.ylim(t_test.iloc[y_test_index[0]].to_numpy()[0])  
9 plt.legend()  
10 plt.show()  
11  
12 f.savefig("foo.pdf", bbox_inches='tight')
```





In []:

1

In []:

1