

P Sai Ramana Kiran

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Domain skills: Computer Vision, Deep Learning, Robot Perception, Sensor Fusion, Localization, Mapping, Motion Planning

EDUCATION

Worcester Polytechnic Institute

M.Sc. Robotics, CGPA: 4.0/4.0 | Roles: Teaching Assistant for RBE549: Computer Vision

Aug 2022 - May 2024

Courses: Computer Vision, Deep Learning

Indian Institute of Technology Madras

(B.Tech + M.Tech), Aerospace Engineering, **CGPA: 8.41/10** | Roles: Team Lead Team Abhiyaan, CFI

Jul 2013 - Jun 2018

SKILLS

Programming Languages : C++(11/14/17/20), Rust, Python, JavaScript, BASH

Softwares and Frameworks : GDB, Valgrind, Pytorch, TensorFlow, CUDA, ROS, Git, Gazebo, POSIX, Docker, Google Tests

Deep Learning Architectures : VGG16, ResNet, DenseNet, HomographNet, NeRF, RAFT, SpyNet, Transformers, LSTM

WORK EXPERIENCE

Perception and Autonomous Robotics (PeAR) | Research Assistant

Aug 2022 - Present

Deep Optical Flow Estimation on TPU | Guide Dr. Nitin Sanket

- Designing **quantization** aware **deep optical flow** architecture that can be deployed on TPU
- Investigating on **speed** and **accuracy** trade-off for **autonomous drone** navigation with the designed deep optical flow network

Quantitative Brokers LLC | Senior C++ Software Developer

Jul 2020 - Aug 2022

Profiling and Instrumentation

- Created a compile time controlled **latency profiler tool** using **shared ring buffer** to benchmark the C++ program scopes
- Developed a **Pollable-SHM** transport mechanism for freeing up busy-wait processes using **unix socket handle sharing**

Messaging Service

- Designed a light-weight **multi-threaded** message oriented **middleware** based on **publish-subscribe** model
- Built a template driven **code generator** for (de)serialization of nested messaging structures across JSON, C++ and K objects
- Developed **language neutral messaging protocols** using google protobuf for integrating statistical and visualization services

Quantitative Brokers LLC | C++ Software Developer

Jul 2018 - Jul 2020

EuroNext Market Data Handler

- Developed a **low-latency** single threaded C++ handler to fetch, parse and publish from **UDP** packets to messages
- Built a **ring buffer** to handle out of sequence packets and transport **Central Limit Order Book** using **shared memory** IPC methods
- Created **shared libraries** and **plugins** to transform messages from C++ to K structures and store in KDB

Honeywell Technology Solutions - Advanced Technology Group | Research Intern

May 2017 - Jul 2017

Green House Inspection - Sensor Fusion Localization Package

- Developed a **configurable** sensor fusion module and ROS wrapper for **proprioceptive** sources using Extended **Kalman Filter**
 - Handled **asynchronous** measurements and **heterogeneous** sensor sources using a sequential EKF model
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RELEVANT PROJECTS

Point Cloud Semantic Mapping - Built a **map** from **raw LiDAR point cloud** and transferred the predicted **semantic** labels from camera RGB images using **point painting** technique onto the LiDAR's **3D** point cloud - [GitHub](#)

Structure From Motion - Simultaneously reconstructed 3D scene (**Mapping**) and extracted camera pose (**Localization**) from given camera correspondences using (Non)Linear **triangulation**, (Non)Linear **PnP** and Bundle Adjustment (**BA**) pipeline - [GitHub](#)

Face Swap - Swapped faces in videos using traditional Delaunay **Triangulation** and Thin Plate Splines(TPS) methods and applied **Kalman motion Filtering** for smoothness - [GitHub](#)

Auto Pano - Created a **panorama** by stitching images using homography estimated from traditional (**ANMS**, **RANSAC** feature points) and Deep learning (Supervised and Unsupervised **HomographyNet**) methods - [GitHub](#)

Edge Detection - Detected edges in image using simplified probability based boundary detection using K-means clustering of Oriented DoG (**ODoG**), Leung-Malik (**LM**) and **Gabor** Filter bank responses - [GitHub](#)

Auto Calib - Implemented Zhang's camera calibration by **nonlinear optimization** of intrinsics and extrinsics - [GitHub](#)

Parallelizing RRT using CUDA - Parallelized collision checker module of RRT path planner and demonstrated 7x speedup

Multi Agent Collaborative Navigation - Master's Thesis Project | [ICC Conference Paper](#) | [GitLab Flight Stack](#) | [GitLab Ground stack](#)

- Designed software pipeline for collaborative navigation of **aerial-ground robotic system**
- Generated **terrain estimation filters** to determine navigable region for ground vehicle using elevation maps

Autonomous Ground Vehicle - Intelligent Ground Vehicle Competition 2017, Michigan - [GitLab](#)

- Engineered software for AGV capable of **lane detection**, obstacle avoidance and GPS way point navigation
 - Illustrated **pure pursuit guidance controller** with **bezier** landing curve for path following
 - Conceptualized architecture to integrate exteroceptive sensor's **point clouds** for generating **2D occupancy grid** cost maps
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