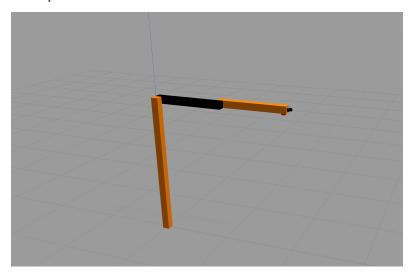
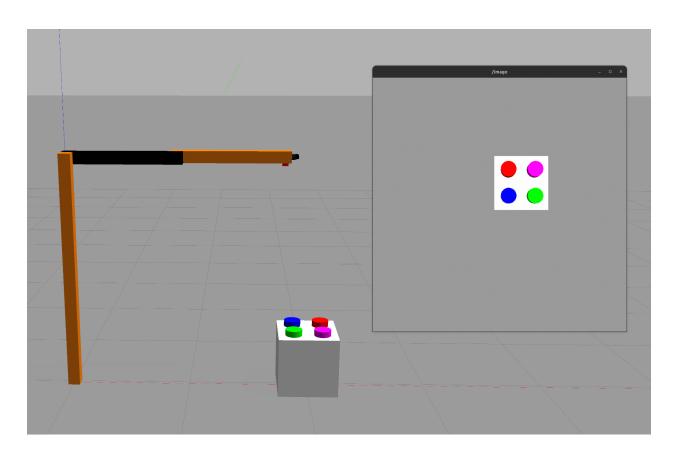
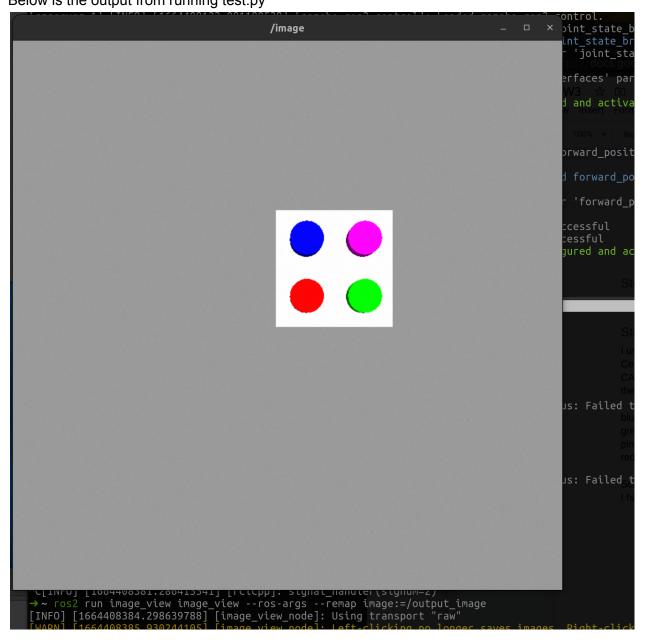
Step 1



Step 2



Step3
Below is the output from running test.py



Step 4

I used HSV space to segment color.

Centers I got from thresholding

CAUTION : the centers I got are from opency convention. To access the array we need to invert the x and y

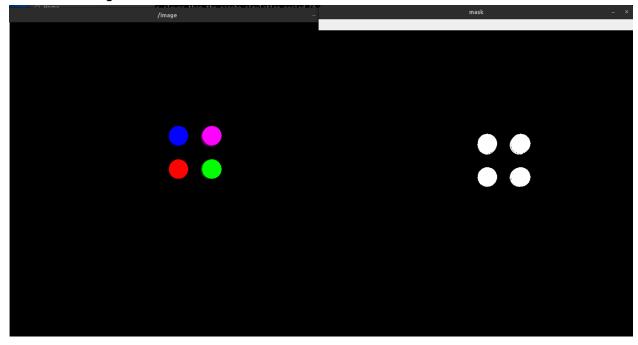
blue:(427.4, 287.9) green:(511.1, 371.6) pink:(511.0, 288.0) red:(427.7, 371.3)

Screenshot of the code is next page

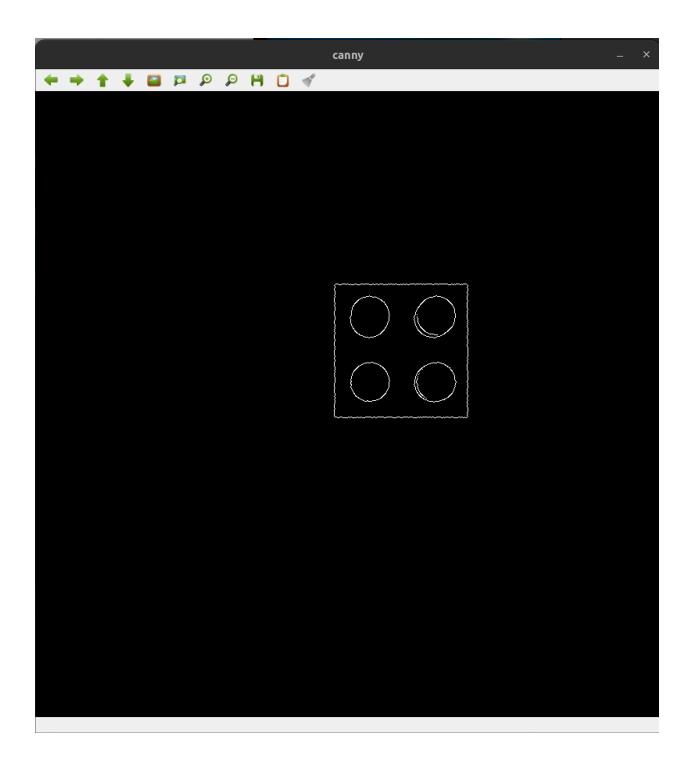
I have included line numbers in the screenshot so that code can be referred from test1.py

```
14 import numpy as np
15
16 def get_center_of_mask( mask):
        x_i = 0;
18
        y i = 0;
19
        count = 0;
20
        coords = np.argwhere(mask)
21
22
        count = coords.shape[0]
        coords = np.sum(coords,axis=0)
23
24
25
26
        if count > 0:
            coords = coords/count
            return coords
27
        return (0,0)
28
test1.py
        # PLACE YOUR CODE HERE. PROCESS THE CURRENT FRAME AND PUBLISH I
72
        #cv2.imshow("output image", current frame)
73
        #cv2.waitKey(1)
74
75
        #cv2.imwrite("output image.png",current frame)
76
        #exit()
77
        blue_low = (100,100,100)
78
        blue high = (120, 255, 255)
79
80
        green_low = (50, 100, 100)
81
        green high = (100, 255, 255)
82
83
        red_{low} = (0,100,100)
84
        red high = (50,255,255)
85
86
        pink_low = (145, 100, 100)
87
        pink_high = (150, 255, 255)
88
89
90
        hsv = cv2.cvtColor(current_frame,cv2.COLOR_BGR2HSV)
91
        blue mask = cv2.inRange(hsv,blue low,blue high)
92
        red_mask = cv2.inRange(hsv,red_low,red_high)
93
94
        green_mask = cv2.inRange(hsv,green_low,green_high)
        pink_mask = cv2.inRange(hsv,pink_low,pink_high)
95
96
        final mask = blue mask + red mask + green mask + pink mask
97
        cv2.imshow("output image", final mask)
98
99
        x_blue,y_blue = get_center_of_mask(blue_mask)
100
        x_green,y_green = get_center_of_mask(green_mask)
101
        x pink,y_pink = get_center_of_mask(pink_mask)
102
        x_red,y_red = get_center_of_mask(red_mask)
        print(f"blue:{x_blue,y_blue}")
103
        print(f"green:{x_green,y_green}")
print(f"pink:{x_pink,y_pink}")
print(f"red:{x_red,y_red}")
104
105
test1.py
```

Below is the segmented color and mask



Step 5
Below is the output canny edge detection



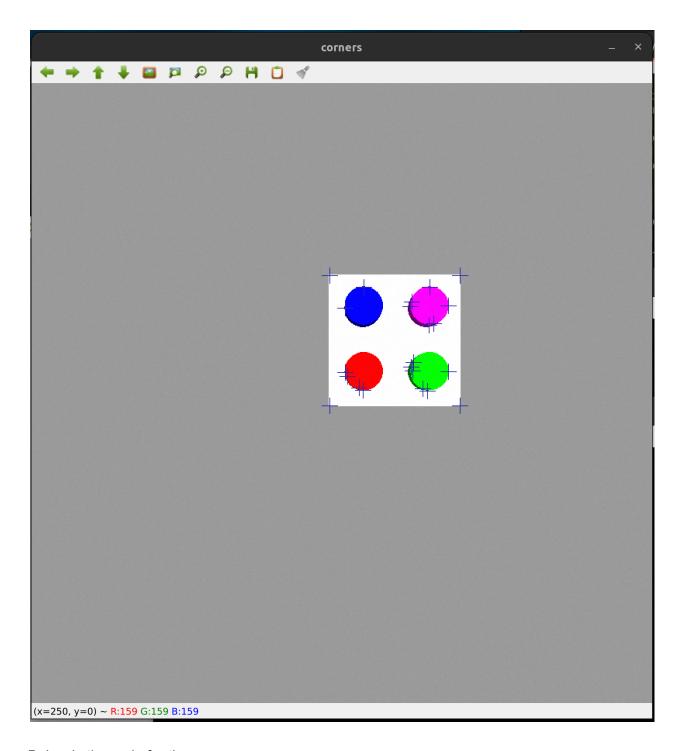
Code:

```
111
112
        # get gray scale image
        gray = cv2.cvtColor(current_fram, cv2.COLOR_BGR2GRAY)
113
114
115
        ## Canny Edge detection
        canny = cv2.Canny(gray,200,300)
116
        cv2.imshow("canny", canny)
117
118
        cv2.waitKey(1)
119
120
```

Step 6

Below is the output from corner harris.

Dark Blue cross marks are the local maxima corners obtained after thresholding corner harris scores



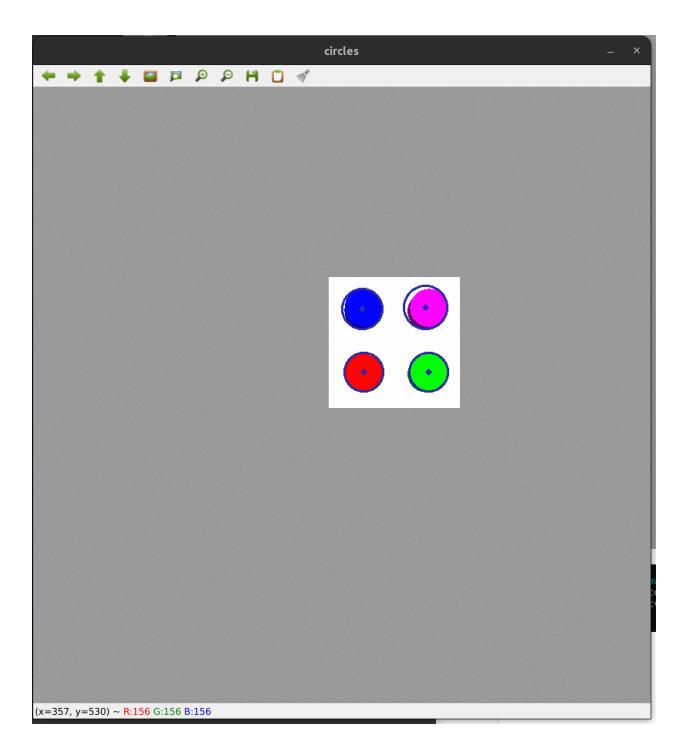
Below is the code for the same

Step 7

Centers from hough circles algo. As before CAUTION that below numbers are in opency coordinate convention blue center:(426, 288) green center:(512, 370) pink center:(508, 286) red center:(428, 370)

They are very close to the centers calculated from Step 4

below is the output from hough circles algorithm
As before, Dark Blue cross marks and Dark Blue circles indicate the output



Below is the code for the same

```
131
132
133
         # hough circles
134
         circles = cv2.HoughCircles(gray,
135
                                      cv2.HOUGH_GRADIENT,1,20,
136
                                      param1=100,
137
                                      param2=30,
138
                                      minRadius=0,
139
                                      maxRadius=0)
140
141
         circles = np.uint16(np.around(circles))
142
         img_circles = current_frame.copy()
143
         for i in circles[0,:]:
              cv2.circle(img_circles,(i[0],i[1]),i[2],(165,42,42),2)
cv2.circle(img_circles,(i[0],i[1]),2,(165,42,42),3)
144
145
146
         #blue center: (426, 288)
#red center: (428, 370)
147
148
         #pink center:(508, 286)
149
         #green center:(512, 370)
150
151
152
         cv2.imshow("circles",img_circles)
153
```