Volume control using fingers.....

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import cv2
         pip install mediapipe
        Requirement already satisfied: mediapipe in c:\users\saiku\anaconda3\lib\site-packages (0.8.9)
        Requirement already satisfied: six in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (1.15.0)
        Requirement already satisfied: protobuf>=3.11.4 in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (3.19.1)
        Requirement already satisfied: attrs>=19.1.0 in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (20.3.0)
        Requirement already satisfied: matplotlib in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (3.3.4)
        Requirement already satisfied: wheel in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (0.36.2)
        Requirement already satisfied: numpy in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (1.20.1)
        Requirement already satisfied: absl-py in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (1.0.0)
        Requirement already satisfied: opency-contrib-python in c:\users\saiku\anaconda3\lib\site-packages (from mediapipe) (4.5.4.58)
        Requirement already satisfied: kiwisolver>=1.0.1 in c:\users\saiku\anaconda3\lib\site-packages (from matplotlib->mediapipe) (1.3.1)
        Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.3 in c:\users\saiku\anaconda3\lib\site-packages (from matplotlib->mediapipe) (2.4.7)
        Requirement already satisfied: cycler>=0.10 in c:\users\saiku\anaconda3\lib\site-packages (from matplotlib->mediapipe) (0.10.0)
        Requirement already satisfied: python-dateutil>=2.1 in c:\users\saiku\anaconda3\lib\site-packages (from matplotlib->mediapipe) (2.8.1)
        Requirement already satisfied: pillow>=6.2.0 in c:\users\saiku\anaconda3\lib\site-packages (from matplotlib->mediapipe) (8.2.0)
        Note: you may need to restart the kernel to use updated packages.
         import mediapipe as mp
         from math import hypot
         from ctypes import cast,POINTER
         from comtypes import CLSCTX_ALL
In [7]:
         pip install pycaw
        Requirement already satisfied: pycaw in c:\users\saiku\anaconda3\lib\site-packages (20181226)
        Requirement already satisfied: enum34 in c:\users\saiku\anaconda3\lib\site-packages (from pycaw) (1.1.10)
        Requirement already satisfied: psutil in c:\users\saiku\anaconda3\lib\site-packages (from pycaw) (5.8.0)
        Requirement already satisfied: future in c:\users\saiku\anaconda3\lib\site-packages (from pycaw) (0.18.2)
        Requirement already satisfied: comtypes in c:\users\saiku\anaconda3\lib\site-packages (from pycaw) (1.1.9)
        Note: you may need to restart the kernel to use updated packages.
         from pycaw.pycaw import AudioUtilities, IAudioEndpointVolume
         import numpy as np
         cap = cv2.VideoCapture(0)
         mpHands = mp.solutions.hands
         hands = mpHands.Hands()
         mpDraw = mp.solutions.drawing_utils
         devices =AudioUtilities.GetSpeakers()
         interface =devices.Activate(IAudioEndpointVolume._iid_,CLSCTX_ALL,None)
         volume = cast(interface, POINTER(IAudioEndpointVolume))
         volMin, volMax = volume.GetVolumeRange()[:2]
         while True:
             success,img = cap.read()
             imgRGB = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)
             results = hands.process(imgRGB)
             lmlist = []
             if results.multi_hand_landmarks:
                 for handlandmark in results.multi_hand_landmarks:
                     for id, lm in enumerate(handlandmark.landmark):
                         h, w, = img.shape
                         cx, cy = int(lm.x*w), int(lm.y*h)
                         lmlist.append([id,cx,cy])
                     mpDraw.draw_landmarks(img, handlandmark, mpHands.HAND_CONNECTIONS)
             if lmlist !=[]:
                 x1, y1 = lmlist[4][1], lmlist[4][2]
                 x2, y2 = lmlist[8][1], lmlist[8][2]
                 cv2.circle(img,(x1,y1),4,(255,0,0),cv2.FILLED)
                 cv2.circle(img,(x2,y2),4,(255,0,0),cv2.FILLED)
                 cv2.line(img,(x1,y1),(x2,y2),(255,0,0),3)
                 length = hypot(x2-x1, y2-y1)
                 vol = np.interp(length, [15, 220], [volMin, volMax])
                 print(vol,length)
                 volume.SetMasterVolumeLevel(vol, None)
         cv2.imshow('Image',img)
         if cv2.Waitkey(1) & 0xff == ord('q'):
                 break
In [ ]:
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