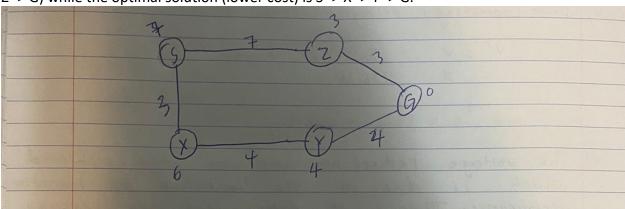
- a. Coding part
- b. It would be admissible as the sum of all the move from a given state n to the goal state would be an underestimate of the true costs.
- c. Count the number of misplaced tiles in a given state.

## Q2

- a. Given a state space where there is only one path and the goal state is at depth m, iterative depending will take O(m^2) to reach the goal state while depth first search will take O(m) to reach the goal state.
- True
  If all the step costs are equal, a path cost from a start state to goal state (n) is just a multiple of the depth n.
- c. True If h(n) = 0 i.e. heuristic cost estimate from a state(m) to a goal state is equal to 0.
- d. False
  Consider the configuration below. The number above the nodes represent the perfect heuristic and the other numbers represent the cost. Best first search yields a path (S-> Z-> G) while the optimal solution (lower cost) is S-> X-> Y-> G.



## e. True

A\* search is optimal so its guaranteed to never expand the nodes that are not in the optimal solution path.