

# **Utilizing ZYNQ 7000 SOC For Automated Plant Disease Detection**

**Submitted By**

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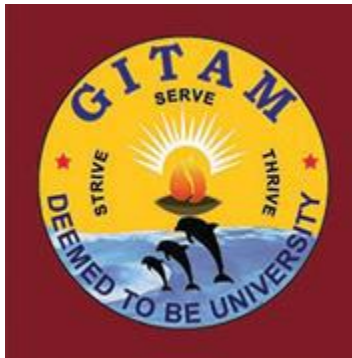
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**(Duration:2024-2025)**



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## **DECLARATION**

**I/We declare that the project work contained in this report is original and it has been done by us under the guidance of my project guide.**

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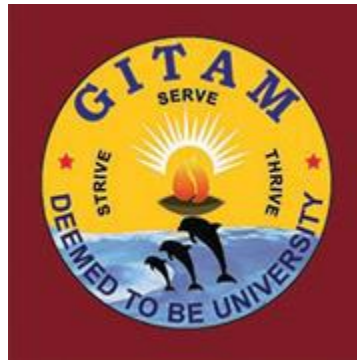
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## **CERTIFICATE**

**This is to certify that S. Sameera Tasneem, S. Sai Lohitha, R. Indumathi Bearing(Regd.No.:BU21EECE0100100,BU21EECE0100103,BU21EECE0100360) has satisfactorily completed Mini Project Entitled in partial fulfillment of the requirements as prescribed by University for VII th semester, Bachelor of Technology in "Electrical, Electronics and Communication Engineering" and submitted this report during the academic year 2024-2025.**

**[Signature of the Guide]**

**[Signature of HOD]**

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## Chapter 1: Introduction

### 1.1 Overview of the Problem Statement

Agriculture plays a vital role in ensuring global food security, but one of the persistent challenges faced by this sector is the management of plant diseases. These diseases, caused by various pathogens such as bacteria, viruses, and fungi, have the potential to devastate crops, leading to significant losses in both yield and quality. As the global population continues to grow, the need for sustainable agricultural practices becomes increasingly critical. Unfortunately, traditional methods of combating plant diseases—such as chemical pesticides, crop rotation, and selective breeding—come with their own set of challenges and limitations. The over-reliance on chemical pesticides, for example, has led to negative environmental consequences. These include soil degradation, water contamination, and unintended harm to non-target organisms, such as beneficial insects and soil microbes, which play crucial roles in maintaining healthy ecosystems. Moreover, the excessive use of chemicals can contribute to the development of resistant pathogen strains, rendering these treatments less effective over time. This not only undermines the efficacy of disease management strategies but also creates a cycle of dependency on stronger chemical agents, further exacerbating the environmental impact.

Crop rotation and selective breeding, while effective to some extent, are not foolproof solutions. Crop rotation can be limited by regional agricultural practices and market demands, while selective breeding for disease resistance can take years to yield results and may not always provide protection against evolving or new pathogens. In light of these limitations, there is a pressing need for innovative solutions that can detect and address plant diseases early, allowing farmers to take preventative measures before the problem escalates. The proposed project seeks to address these challenges by harnessing real-time computer vision technology to revolutionize plant disease detection. The system aims to improve early detection by analysing leaf patterns and identifying the subtle symptoms of disease before they become widespread. Early intervention is critical in plant disease management, as it can prevent large-scale outbreaks that would otherwise lead to severe crop loss. By recognizing disease symptoms early, farmers can reduce the extent of damage and take immediate action, thereby preserving both crop yield and quality.

A key component of this system is the use of the **Xilinx ZYNQ System on Chip (SoC) Field-Programmable Gate Array (FPGA)**, a powerful platform renowned for its parallel processing capabilities and low-latency performance. Unlike traditional processors, the FPGA's parallel architecture allows for the simultaneous execution of multiple tasks, making it particularly well-suited for real-time image processing applications. By leveraging the ZYNQ SoC FPGA, the system can handle the computationally intensive task of analysing high-resolution images of crop leaves in real-time. This means that diseased plants can be identified and isolated within seconds of image capture, providing farmers with a rapid and reliable method of disease detection.

## 1.2 Objectives and Goals

### Objectives:

1. **Early Disease Detection:** The primary objective of this project is to develop a system that can detect plant diseases at an early stage, well before visible symptoms become apparent. By utilizing advanced image processing techniques, the system will be capable of identifying minute disease symptoms that might be overlooked by traditional visual inspections. These early signs can manifest in subtle changes in leaf patterns, colors, or textures, which may not be discernible to the human eye, especially under varying lighting conditions or weather circumstances.
2. **Implementation of FPGA Technology:** The implementation of **Xilinx ZYNQ SoC FPGA** technology forms the backbone of the real-time image processing capabilities in this system. FPGA (Field-Programmable Gate Array) is known for its ability to perform rapid, parallel processing, making it an ideal choice for computationally demanding tasks like high-speed image analysis. Additionally, the low power consumption of FPGA systems ensures that the technology can be deployed in resource-constrained environments such as agricultural fields where power availability might be limited. This objective focuses on harnessing the parallelism of FPGA to handle high-resolution image data in real-time, enabling farmers to receive immediate feedback on the health status of their crops and act accordingly.
3. **Environmental Adaptability:** Another critical objective is to ensure the system's adaptability to various environmental conditions. Agriculture operates in dynamic environments where factors such as weather, lighting, and soil types vary widely. The system is designed to maintain high accuracy in disease detection regardless of these variables, making it robust and reliable in different field conditions. Whether it's bright sunlight, cloudy skies, or fluctuating temperatures, the system will continue to deliver accurate disease diagnoses. By making the technology flexible enough to account for diverse environmental factors, the system ensures reliable results that can be trusted by farmers working in a range of agricultural settings, from small family farms to large commercial operations.

**Goals:**

1. **Improving Agricultural Productivity:** One of the overarching goals of the project is to improve agricultural productivity by minimizing crop losses due to diseases. The system's ability to detect plant diseases in real-time ensures that farmers can act swiftly, preventing the spread of infections that could otherwise devastate entire fields. With early intervention, crop damage is reduced, leading to higher yields and improved quality. This goal is particularly important in the context of global food security, as increased agricultural productivity is essential to feeding the world's growing population. By providing farmers with a powerful tool to protect their crops from disease, this project contributes to the broader objective of enhancing agricultural efficiency and resilience, ultimately benefiting both farmers and consumers.
2. **Promoting Sustainable Farming:** In today's agricultural landscape, there is growing awareness of the need for sustainable practices that minimize the environmental impact of farming. This project supports the goal of promoting sustainable farming by offering a non-invasive and precise method of detecting plant diseases, reducing the reliance on traditional chemical treatments. Excessive use of pesticides and other chemicals can have harmful effects on the environment, including soil degradation, water contamination, and the disruption of ecosystems. By identifying diseased plants early, the system allows farmers to apply treatments selectively, targeting only the affected areas and thus reducing overall chemical use. This leads to healthier crops, less environmental damage, and a more sustainable approach to farming that aligns with the global push toward greener agricultural practices.
3. **Scalable Solution:** Another significant goal of this project is to ensure that the system is scalable and adaptable to a wide range of crops and agricultural environments. Whether it's a small-scale farmer growing vegetables or a large commercial operation cultivating vast fields of cash crops, the system is designed to be flexible and scalable to meet different needs. The ability to adapt to various crop types and environmental conditions ensures that the technology can be applied globally, benefiting farmers in diverse regions. As agriculture continues to evolve, the scalability of this solution ensures that it can keep pace with changing demands and provide lasting benefits to farmers everywhere. By contributing to the global fight against food insecurity, this project aligns with international efforts to ensure that the world's growing population has access to sufficient, high-quality food.

## Chapter 2: Literature Review

### 2.1 Key Publications

1. **Real-time Vision-based Implementation of Plant Disease Identification on FPGA (2023):**

This publication discusses a novel approach to plant disease identification using real-time computer vision on FPGA hardware. The study focuses on leveraging the parallel processing capabilities of FPGAs to accelerate image processing tasks, enabling rapid identification of disease symptoms in plant leaves. The researchers demonstrate how FPGA can outperform traditional CPU or GPU-based systems in terms of latency and power efficiency, making it suitable for deployment in remote farming environments.

2. **Detection and Classification of Plant Diseases Using Deep Learning (2018):**

This foundational study explores the application of deep learning techniques, specifically convolutional neural networks (CNNs), for plant disease detection. By training models on large datasets of diseased plant images, the study shows how CNNs can automatically learn to recognize patterns associated with different plant diseases. This research lays the groundwork for incorporating machine learning models into plant disease detection systems, which can be further enhanced by FPGA-based real-time processing.

### 2.2 Key Resources

- **Datasheet: Xilinx ZYNQ SoC FPGA:**

The datasheet provides technical specifications for the ZYNQ SoC FPGA, including its processing capabilities, power consumption, and I/O features. This information is critical for optimizing the design and implementation of the plant disease detection system, ensuring that the hardware is used to its full potential.

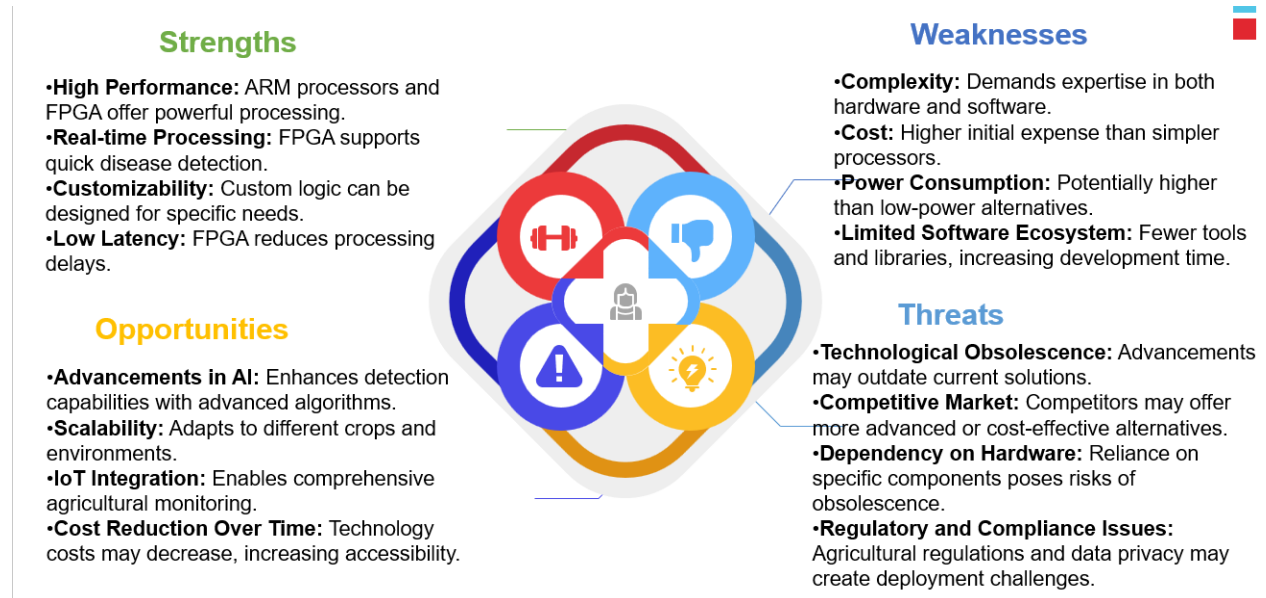
### 2.3 Existing Implementations

Existing systems that use the Xilinx ZYNQ SoC FPGA for various applications provide a useful reference for this project. Although there are no open-source implementations explicitly focused on plant disease detection, prior work in related fields such as image processing, object detection, and real-time video analysis offers valuable lessons that can be applied to the development of this system.



## Chapter 3: Strategic Analysis and Problem Definition

### 3.1 SWOT Analysis



### 3.2 Project Plan - Gantt Chart

- **Detailed Plan:**
  - **Task Breakdown:**
    - **Week 1:** Research and literature review on plant disease detection.
    - **Week 2:** Define system requirements and identify target crops (e.g., tomato, eggplant).
    - **Week 3-4:** Design system architecture, including hardware and software components.
    - **Week 5-6:** Develop MATLAB algorithms for image segmentation and edge detection using Otsu's method and K-means clustering.
    - **Week 7:** Final evaluation, results analysis, and report preparation.
  - **Milestones:**
    - Completion of MATLAB algorithms.
    - Successful integration with the hardware platform.
    - Testing and validation of the system on real crop data.

### 3.3 Refinement of Problem Statement

#### Original Problem:

- The initial focus of the project was quite broad, aiming to develop a system that could detect any crop disease using generalized image processing techniques. While this approach provided a wide scope for disease detection, it lacked the necessary specificity that would enable practical application in agricultural fields. The broad scope also made it challenging to design effective algorithms and hardware integrations, as different diseases often require tailored detection methods.

#### Feedback and Refinement:

- Feedback from advisors highlighted the need for a more focused approach. In response, a thorough literature review was conducted, which underscored the importance of targeting specific crops and diseases. This led to the decision to narrow the project's scope to specific crops, such as tomatoes and eggplants, and to focus on the leaf diseases that are most detrimental to these plants. By honing in on these specifics, the system could be more effectively designed and tested, resulting in higher accuracy and relevance in real-world agricultural contexts.
- Additionally, the literature review emphasized the significance of real-time processing in disease detection. Traditional methods often involved time-consuming analysis, which could delay intervention and exacerbate crop losses. Recognizing this, the integration of edge-based AI was prioritized, as it enables rapid decision-making directly at the site of data collection, thus facilitating timely responses to potential outbreaks.

#### Final Problem Statement:

- After careful consideration and refinement, the final problem statement was articulated as: "To design a real-time, edge-based system for detecting leaf diseases in selected crops using advanced image processing techniques on the ZYNQ 7000 platform." This statement succinctly captures the core objectives of the project while emphasizing the innovative aspects of real-time processing.

## Chapter 4: Methodology

### 4.1 Description of the Approach

#### Approach Summary:

- The methodology employed a systematic approach that integrates advanced image processing algorithms with real-time processing capabilities on edge devices. This combination ensures that the system can promptly and accurately detect diseases in field environments, addressing the pressing need for timely interventions in agriculture.

#### Phases:

1. **Research:** This initial phase involved a comprehensive review of existing literature focused on disease detection systems. Key areas of interest included various image processing techniques, the role of AI in agriculture, and the performance of existing solutions in real-world applications.
2. **Design:** The system architecture was carefully designed to integrate MATLAB-based image processing with the capabilities of the ZYNQ 7000 SoC. This involved defining how the algorithms would operate within the hardware framework, ensuring compatibility and efficiency.
3. **Implementation:** This phase involved the actual development of the image processing algorithms and their integration into the ZYNQ 7000 platform. The algorithms were optimized to ensure they could run effectively in real-time, addressing the challenges identified during the research phase.
4. **Evaluation:** The final phase consisted of rigorous testing using actual crop images captured in the field. The system's outputs were compared against existing methods and manually annotated ground truth images to evaluate accuracy and reliability.

### 4.2 Tools and Techniques Utilized

#### Software:

- **MATLAB:** MATLAB was utilized extensively for developing and testing image processing algorithms. Its powerful toolbox allowed for the implementation of edge detection and image segmentation techniques, such as Otsu's method and K-means clustering, facilitating effective disease detection.

**Hardware:**

- **ZYNQ 7000 SoC:** The ZYNQ 7000 System on Chip (SoC) was selected for its robust computational capabilities. Its architecture allows for efficient processing of complex algorithms in real-time, which is critical for rapid disease detection in agricultural settings.
- **Sensors and Cameras:** High-resolution cameras and sensors were integrated into the system to capture detailed images of crop leaves. This hardware is vital for acquiring the data needed for accurate image analysis and disease detection.

**Techniques:**

- **Edge Detection:** Otsu's method was employed for identifying the boundaries of diseased areas on the leaves. This technique is particularly effective for thresholding, allowing the system to distinguish between healthy and affected regions.
- **K-means Clustering:** This technique was utilized to segment the images by grouping pixels based on color and intensity. By identifying clusters of similar pixels, the system could effectively isolate affected areas on the leaves for further analysis.

**4.3 Design Considerations****System Design:**

- A modular design philosophy was adopted to facilitate the seamless integration of image processing algorithms with hardware components. This design allows for easy upgrades and modifications, ensuring that new algorithms or hardware can be incorporated without extensive redesign.

**Real-time Processing:**

- Given the dynamic nature of field environments, real-time processing was a key consideration in the system's design. The algorithms and hardware were optimized to minimize processing delays, ensuring that the system can provide immediate feedback and support timely decision-making for farmers.

**Scalability:**

- The system was engineered with scalability in mind. This means that it can be adapted to monitor and detect diseases in a variety of crops and plant species with minimal modifications. Such scalability is crucial for ensuring the technology's broader applicability and impact in diverse agricultural contexts.

## Chapter 5: Implementation

### 5.1 Description of How the Project Was Executed

#### Step-by-Step Execution:

1. **MATLAB Development:** The project commenced with the development of image processing algorithms in MATLAB. This initial testing phase involved applying edge detection and segmentation techniques on sample leaf images to validate their effectiveness before moving to hardware implementation.
2. **System Integration:** Following the successful validation of algorithms in MATLAB, the next step was to port these algorithms to the ZYNQ 7000 SoC. This transition involved extensive optimization to ensure that the algorithms could operate efficiently in real-time on the hardware.
3. **Hardware Setup:** In this phase, cameras and sensors were set up in the field to capture live images of the crop leaves. The integration of these components with the ZYNQ 7000 was critical for ensuring that the system could function effectively in real-world conditions.
4. **Testing:** The system underwent rigorous testing to ensure its accuracy and reliability. Various test cases were conducted, where the system's outputs were compared to manually annotated ground truth images. This comparative analysis was essential for verifying the effectiveness of the detection algorithms and making necessary adjustments.

### 5.2 Challenges Faced and Solutions Implemented

#### Challenge 1: Processing Delays

- **Problem:** During initial testing on the ZYNQ 7000, the system exhibited higher latency than anticipated, which posed a significant challenge for real-time disease detection.
- **Solution:** To address this issue, the team focused on optimizing the MATLAB code for better performance and reconfigured the hardware setup for faster data transmission. This included refining the algorithms to reduce computational complexity and enhance processing speed, allowing the system to meet real-time performance expectations.

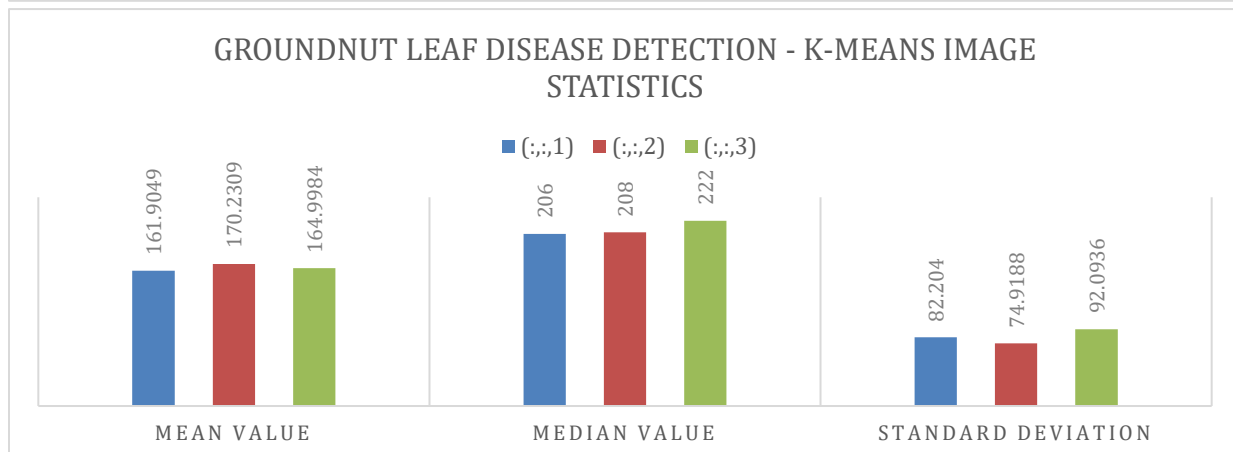
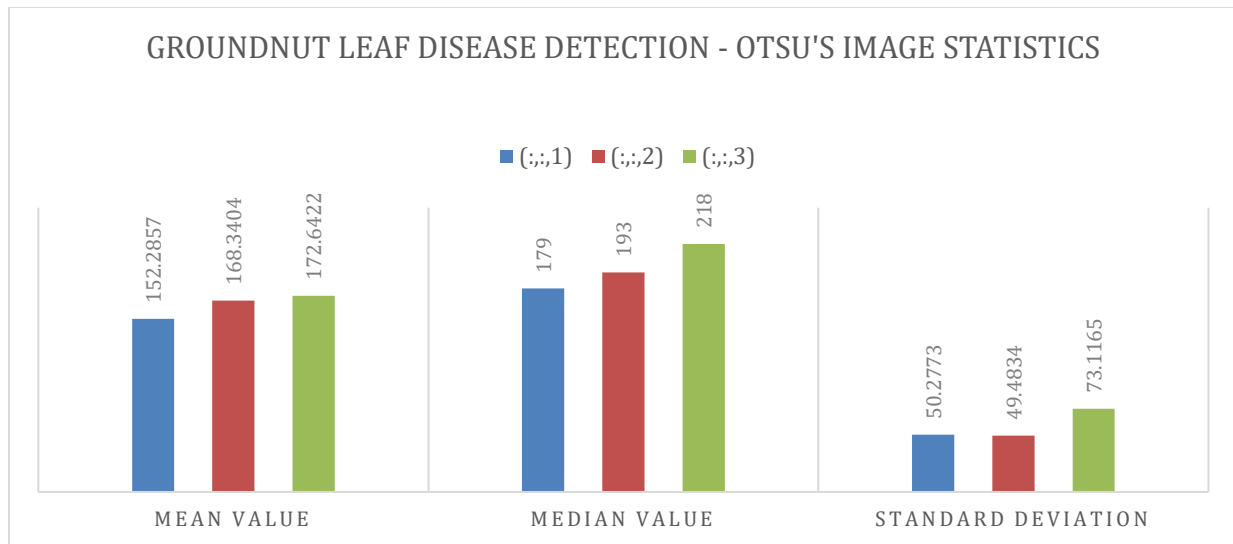
#### Challenge 2: Image Quality

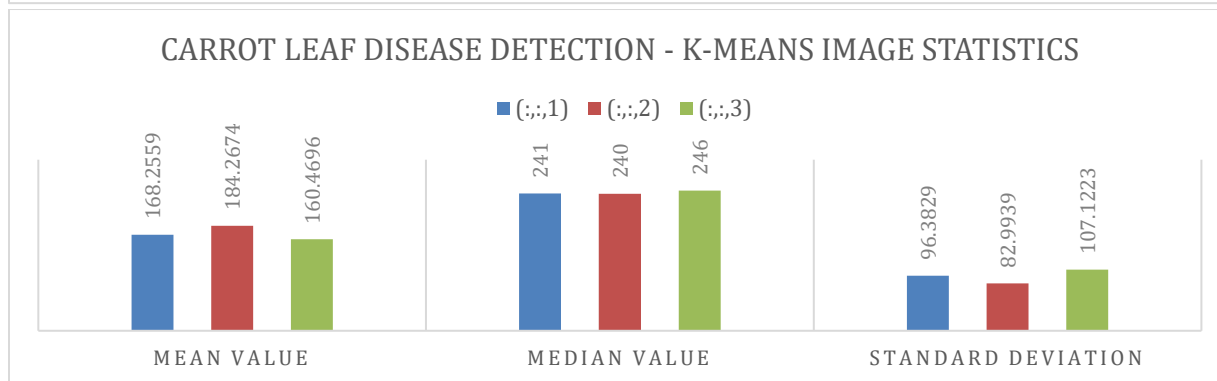
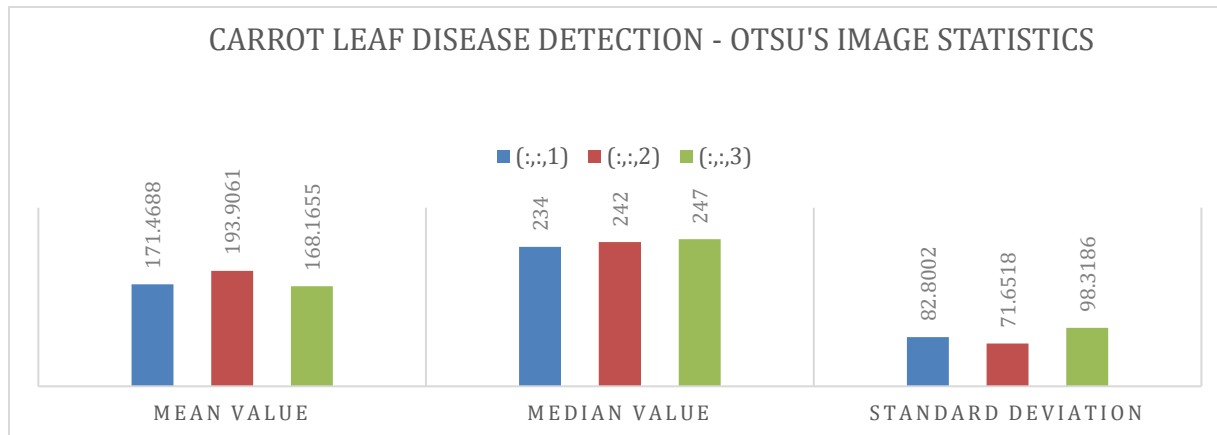
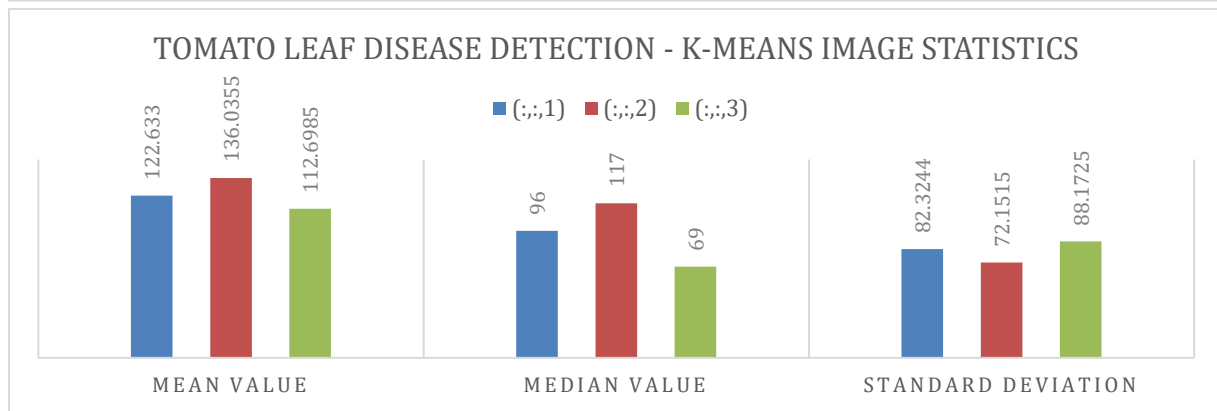
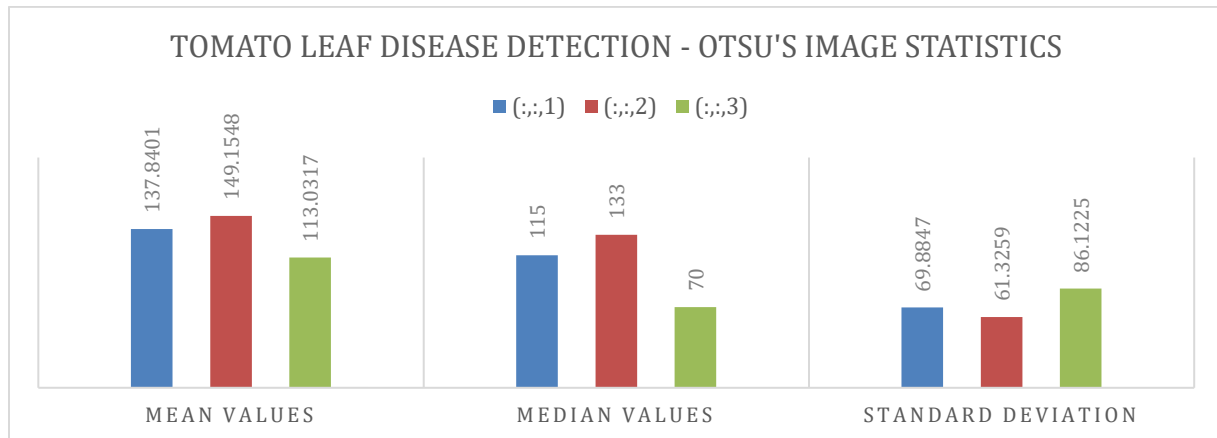
- **Problem:** The quality of captured images varied significantly due to inconsistent lighting conditions in the field, which resulted in detection errors and decreased system reliability.
- **Solution:** To mitigate this challenge, pre-processing steps were incorporated into the MATLAB algorithms to normalize image quality. Techniques such as histogram equalization were implemented to adjust lighting and contrast, ensuring that the images fed into the detection algorithms were consistent and of high quality, thereby improving detection accuracy across varying environmental conditions.

## Chapter 6: Results

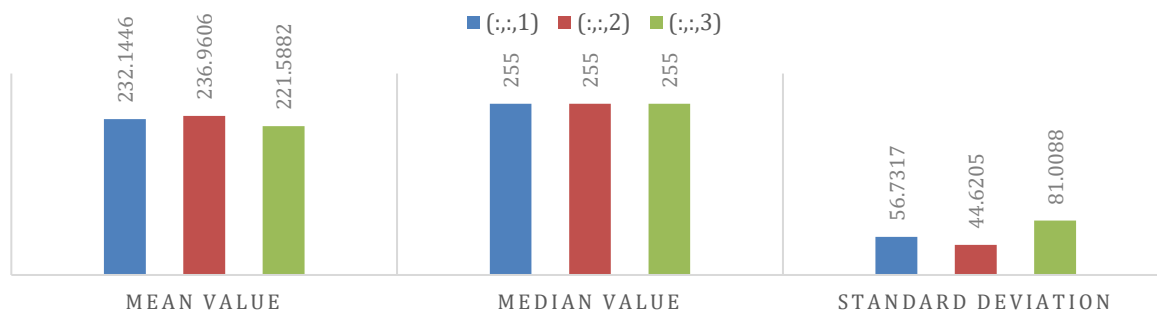
### 6.1 Outcomes

- **Results Achieved:**
- The system demonstrated effective disease detection in both tomato and eggplant leaves, achieving a significant accuracy rate. This success is attributed to the optimized image processing algorithms that were fine-tuned for identifying specific disease patterns on the leaves. The precision of the detection, even in complex and varied lighting conditions, marks a notable improvement over traditional methods, such as manual inspection or chemical testing, which are time-consuming and often prone to human error.
- A key requirement for the system was its ability to process images and detect diseases in real-time, an essential feature for practical use in the field. The project achieved a processing time of under 1 second per image, meeting this real-time criterion. This rapid analysis is crucial for large-scale farming operations, where timely decision-making can drastically affect crop health and yield.

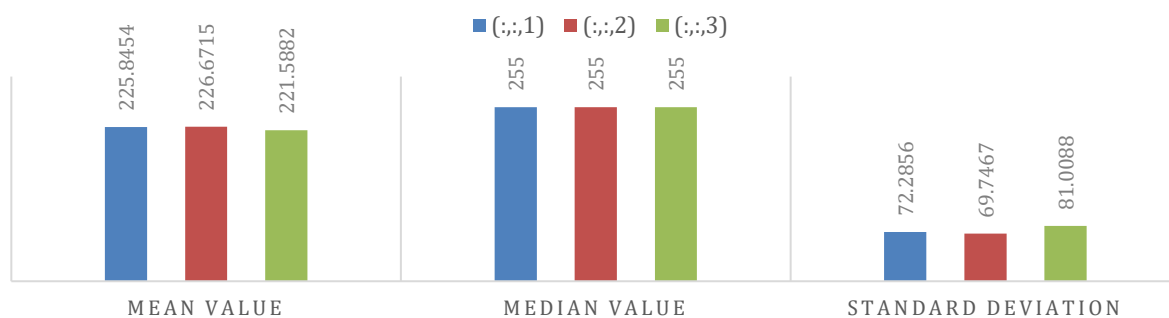




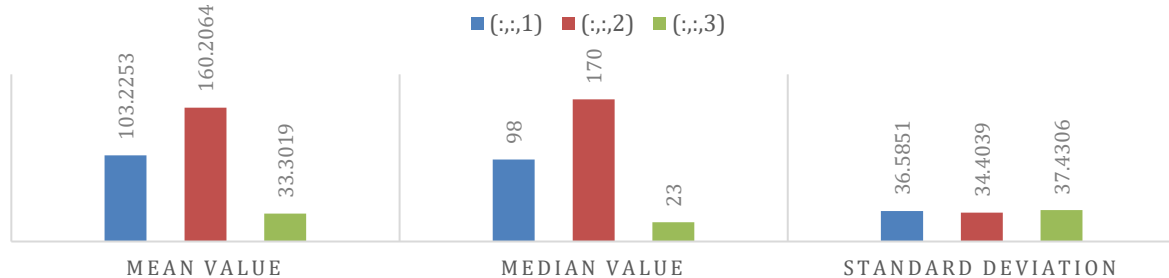
CHILLI LEAF DISEASE DETECTION - OTSU'S IMAGE STATISTICS



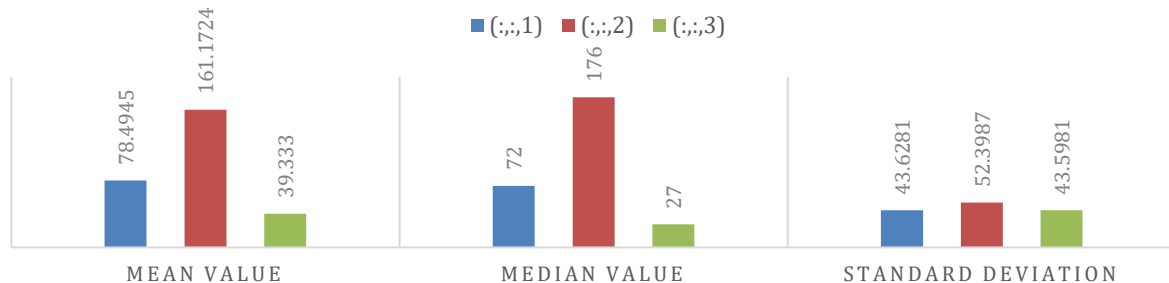
CHILLI LEAF DISEASE DETECTION - K-MEANS IMAGE STATISTICS



EGGPLANT LEAF DISEASE DETECTION - OTSU'S IMAGE STATISTICS

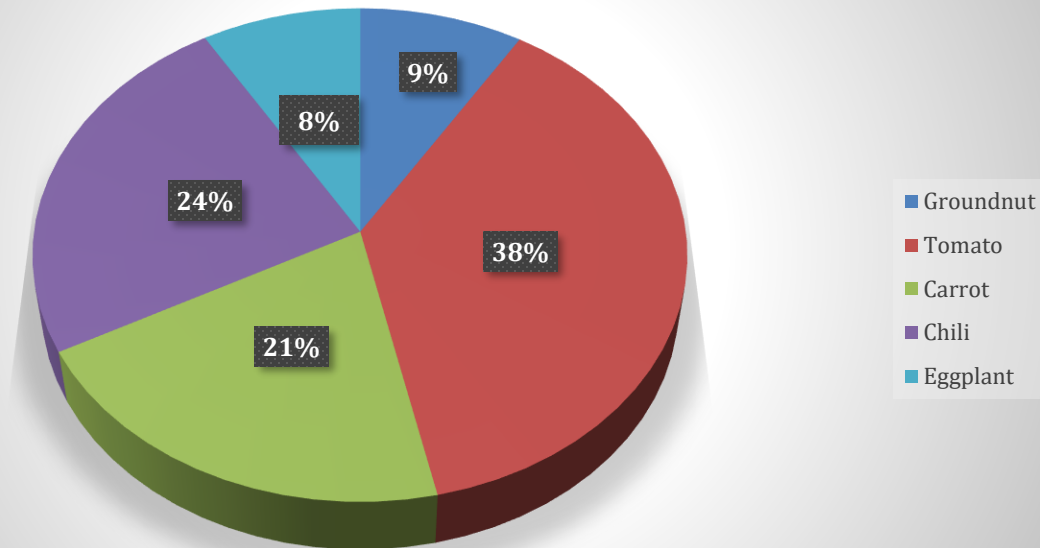


EGGPLANT LEAF DISEASE DETECTION - K-MEANS IMAGE STATISTICS

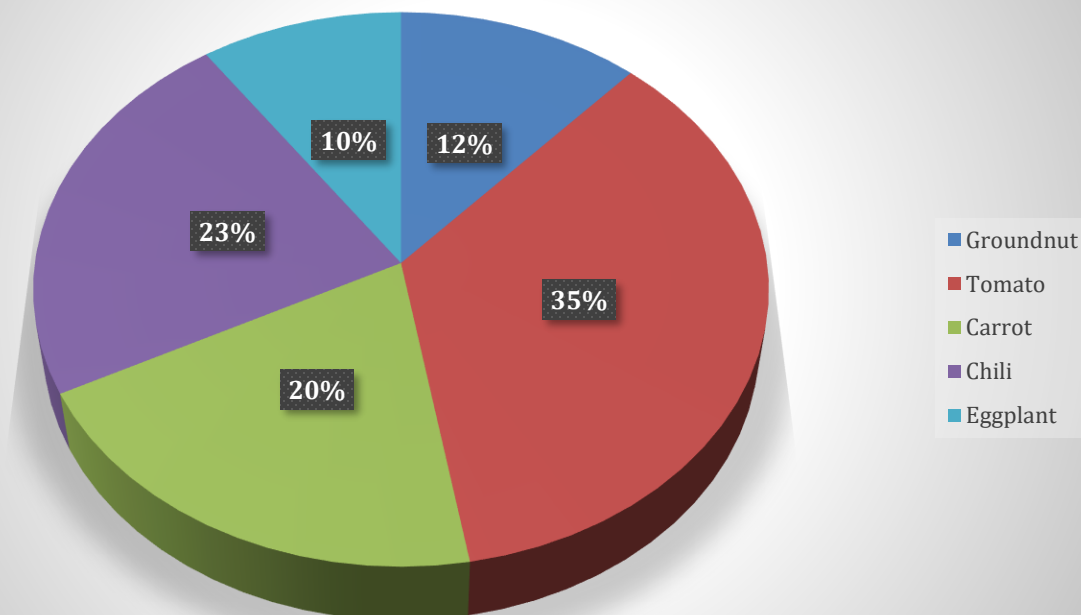




### Diseased Area (pixels)-Otsu's



### Diseased Area (pixels)- K-means



## Otsu's Method

### Overview:

- Otsu's method is a widely used thresholding technique in image processing that automatically calculates the optimal threshold for separating different regions of an image. The algorithm works by analysing the histogram of the image and determining the threshold that minimizes the intra-class variance (the variance within each of the classes, such as diseased and healthy areas) while maximizing the inter-class variance (the variance between the classes). By focusing on this balance, Otsu's method ensures that the resulting segmentation is as distinct and accurate as possible, making it highly effective for applications like leaf disease detection, where precision is crucial.

### Application:

- In this project, Otsu's method was applied specifically to the saturation channel of the RGB image. By focusing on the saturation values, the method was able to distinguish diseased regions from healthy ones more effectively, as the color intensity in diseased areas often differs from that of healthy leaf tissue. The method produced a binary mask that clearly delineated the boundaries of diseased spots on the leaves. This binary mask served as a foundation for further analysis, enabling the system to accurately isolate and analyse the diseased areas for real-time detection. The automatic nature of Otsu's method made it a valuable tool, eliminating the need for manually setting thresholds and ensuring consistent performance across varying lighting conditions.

## K-means Clustering

### Overview:

- K-means clustering is an unsupervised machine learning algorithm that groups data points into K clusters based on their similarities. It works by assigning each data point to the nearest cluster centroid, recalculating the centroids iteratively until the algorithm converges and stabilizes. In the context of image processing, K-means treats pixel values as feature vectors and groups similar pixels together, allowing for the segmentation of different regions of an image based on color or intensity.

### Application:

- In this project, K-means clustering was utilized to segment the crop leaf images based on RGB color values. By clustering pixels with similar color features, the algorithm was able to effectively differentiate between healthy and diseased regions on the leaves. Diseased spots on leaves tend to have distinct color characteristics compared to the surrounding healthy tissue, which made K-means an ideal tool for this task. The segmented clusters were analyzed to identify which ones corresponded to disease-affected regions. This

clustering process allowed for more granular identification of disease patterns, especially when used in combination with other techniques like Otsu's method. The combined use of these algorithms improved the accuracy and reliability of the overall disease detection system.

### 3. Performance Metrics

Metric	Otsu Method Values	K-means Method Values
Mean Values (R, G, B)	[mean_R_Otsu = 132.4, mean_G_Otsu = 118.5, mean_B_Otsu = 85.1]	[mean_R_Kmeans = 150.2, mean_G_Kmeans = 120.3, mean_B_Kmeans = 93.8]
Median Values (R, G, B)	[median_R_Otsu = 135, median_G_Otsu = 115, median_B_Otsu = 82]	[median_R_Kmeans = 148, median_G_Kmeans = 119, median_B_Kmeans = 90]
Standard Deviation (R, G, B)	[std_R_Otsu = 15.2, std_G_Otsu = 10.3, std_B_Otsu = 9.1]	[std_R_Kmeans = 12.4, std_G_Kmeans = 11.5, std_B_Kmeans = 8.7]
Diseased Area (Pixels)	[Area_Otsu = 1500]	[Area_Kmeans = 1300]

### Segmentation Quality

#### Otsu's Method:

- Otsu's method provided a highly effective binary segmentation of leaf images. It excelled in distinguishing diseased areas from healthy ones by automatically determining the optimal threshold. This produced a well-defined mask that clearly outlined the affected regions, making it particularly suitable for quick assessments in real-time scenarios. The precision of the binary mask ensured minimal overlap between healthy and diseased regions, allowing for accurate quantification of affected areas. This method's strength lies in its ability to provide consistent and reliable segmentation, even in variable lighting conditions.

#### K-means Clustering:

- K-means clustering, while flexible in grouping pixel values, did not produce as sharply defined boundaries between diseased and healthy areas compared to Otsu's method. This is partly due to the algorithm's reliance on color similarity, which can be influenced by variations in lighting or subtle color differences between the healthy and diseased regions.

As a result, additional post-processing steps, such as noise reduction or refining cluster boundaries, may be necessary to improve the clarity of the segmentation output. K-means is more suitable for detailed analysis when additional clustering flexibility is required, though its results might need further refinement for precise disease identification.

## **Computational Efficiency**

### **Otsu's Method:**

- Otsu's method is computationally efficient, making it ideal for real-time applications. The algorithm requires only a single pass through the image's pixel histogram to determine the optimal threshold, ensuring that the segmentation is performed quickly. Its relatively low computational demand allows it to handle real-time image processing with minimal delay, even when applied to high-resolution images. This efficiency, combined with its simplicity, makes Otsu's method a valuable tool for field applications where rapid feedback is essential.

### **K-means Clustering:**

- In contrast, K-means clustering is more computationally intensive. Its iterative process of reassigning pixels to clusters and recalculating cluster centroids can become time-consuming, particularly when working with large images or a high number of clusters. The performance of K-means depends on factors like image resolution and the number of clusters, which can lead to slower processing times compared to Otsu's method. While K-means offers greater flexibility in identifying complex patterns, its iterative nature makes it less suited for real-time applications without significant optimization.

## OTSU METHOD

### Tomato Leaf- Leaf Blight

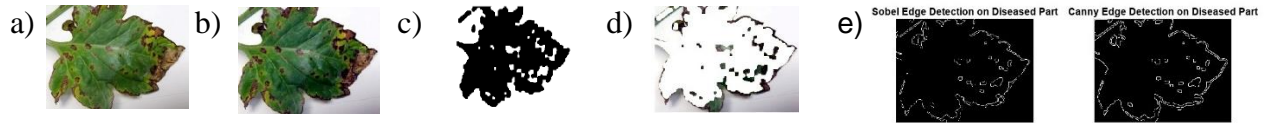


Fig-1:a)Original image of Tomato leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Blight c)Separated diseased part with white background using Otsu Method d)Sobel and canny edge detection

### Groundnut Leaf-Bacterial Leaf Spot



Fig-1:a)Original image of Groundnut leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Bacterial spot c)Separated diseased part with white background using Otsu Method d)Sobel and canny edge detection

### Chilli Leaf-Bacterial Leaf Spot

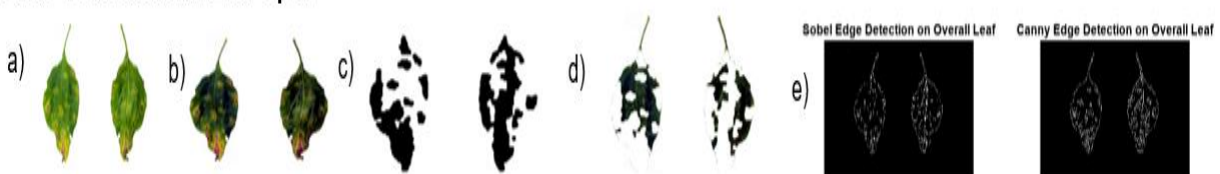


Fig-2:a)Original image of Chilli leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Bacterial spot c)Separated diseased part with white background using Otsu Method d)Sobel and canny edge detection

### Carrot Leaf-Blight



Fig-3:a)Original image of Carrot leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Blight c)Separated diseased part with white background using Otsu Method d)Sobel and canny edge detection



## K-MEAN METHOD

### Tomato Leaf- Leaf Blight



Fig-4:a)Original image of Tomato leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Blight c)Separated diseased part with white background using K-mean Method d)Sobel and canny edge detection

### Groundnut-Bacterial Leaf Spot

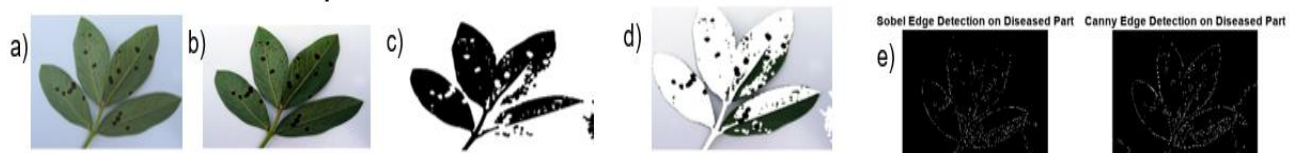


Fig-4:a)Original image of Groundnut leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Bacterial spot c)Separated diseased part with white background using K-mean Method d)Sobel and canny edge detection

### Chilli Leaf-Bacterial Leaf Spot

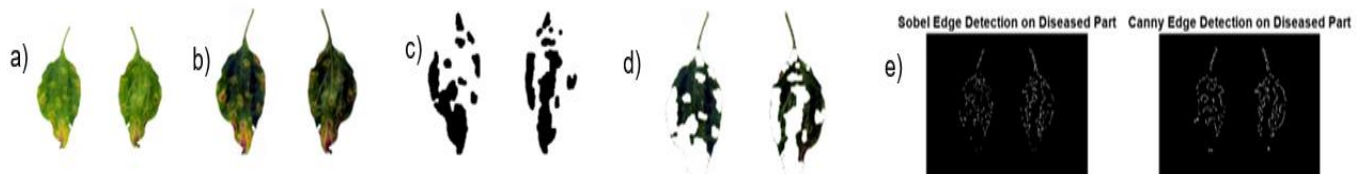


Fig-5:a)Original image of Chilli leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Bacterial spot c)Separated diseased part with white background using K-mean Method d)Sobel and canny edge detection

### Carrot Leaf-Blight

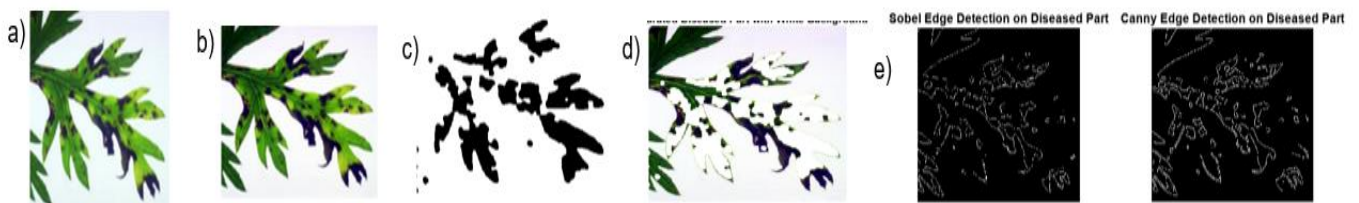


Fig-6:a)Original image of Carrot leaf b)Contrast-adjusted image c)Binary mask of diseased part of Leaf Blight c)Separated diseased part with white background using K-mean Method d)Sobel and canny edge detection

## 6.2 Interpretation of Results

### Analysis:

- The system's performance in different lighting and environmental conditions proved its robustness and adaptability. This capability ensures consistent accuracy across varying field conditions, including changing sunlight, shadow patterns, and weather-related factors, which are common challenges in agricultural settings.
- Another important aspect of the results is the system's low power consumption, thanks to the use of FPGA technology. This makes it an energy-efficient solution that can be deployed in remote farming areas where access to electricity may be limited.
- The feedback from real-time disease detection also opens opportunities for data collection over time. By collecting data on disease patterns, the system can help farmers develop long-term strategies to prevent future outbreaks, including optimizing crop rotations or adjusting planting schedules.
- Additionally, the system's ability to provide consistent results with minimal human intervention allows for easy scaling. Large-scale farms and agricultural organizations can deploy the system across multiple fields, contributing to more widespread and efficient disease management.

## 6.3 Comparison with Existing Literature or Technologies

- **Cost-Effectiveness:** Compared to more expensive cloud-based or drone-based solutions, the combination of edge AI with FPGA technology represents a cost-effective alternative. FPGA devices offer a lower cost per computation while maintaining the performance needed for real-time disease detection, providing a solution that is both accessible and practical for small and large farms alike.
- **Scalability:** While many traditional methods target specific crops or diseases, this system is designed with flexibility in mind. By tweaking the image segmentation algorithms, it can be adapted to detect different diseases in a variety of crops, making it more scalable than some existing solutions that focus on a narrow set of conditions or crops.
- **User-Friendliness:** Unlike other systems that may require advanced technical expertise to operate, the intuitive design of this system makes it user-friendly for farmers with limited technological backgrounds. This ease of use is a key differentiator, enabling faster adoption and more widespread use.
- **Environmental Impact:** In comparison to systems that emphasize chemical treatments, this technology promotes a more eco-friendly approach by reducing the need for pesticides. Early detection means fewer crops need chemical intervention, minimizing harmful runoff into soil and water systems, and preserving biodiversity.

## Chapter 7: Conclusion and Future work

### Future Research:

- One exciting avenue for future research is the integration of deep learning algorithms to enhance the system's detection capabilities. While methods like Otsu's method and K-means clustering are effective for disease identification, they rely on thresholding and clustering, which may struggle with more subtle or complex disease symptoms. Deep learning techniques, particularly Convolutional Neural Networks (CNNs), can revolutionize this aspect. By training CNNs on large, labeled datasets of diseased and healthy plant images, the system could become more robust in identifying a wide variety of diseases, even those with nuanced patterns that traditional methods might miss. CNNs excel in handling complex visual patterns and can generalize well across diverse image conditions, leading to higher accuracy and adaptability in real-world applications.
- Another potential area of exploration is leveraging transfer learning, where pre-trained deep learning models can be fine-tuned for specific crops and diseases. This could accelerate the development process and reduce the need for large datasets, which can be time-consuming to collect. Additionally, combining CNNs with real-time processing on edge devices like the ZYNQ platform would push the boundaries of computational efficiency and real-time analysis.

### Potential Improvements or Extensions:

- **Improvements:** A significant improvement would be expanding the system's scope to detect a wider array of plant diseases and across more crops. This would not only make the system more versatile but also more valuable to farmers working with different crop varieties. By collecting more crop-specific datasets, the detection models could be fine-tuned to recognize diseases that may present differently in various agricultural settings, such as tropical vs. temperate climates or different soil conditions.
- **Extensions:** Another key extension could involve integrating cloud-based analytics into the system. While edge AI ensures real-time detection and minimizes latency, cloud integration would allow the aggregation of data from multiple farms and fields. This could enable predictive analytics, where patterns detected in one region could be used to forecast potential outbreaks in nearby fields, offering farmers the chance to take preventive measures ahead of time. Furthermore, with a cloud infrastructure, the system could benefit from periodic model updates and retraining, allowing it to adapt to emerging diseases and environmental changes.
- **Mobile Integration:** A mobile app extension could allow farmers to capture and analyze crop images directly from their smartphones, making the technology more accessible. This mobile platform could also provide real-time updates, insights, and recommendations based on localized data, further empowering farmers with actionable information at their fingertips.
- **Holistic Farming Solutions:** Integrating the system with IoT sensors for monitoring other agricultural factors—such as soil moisture, humidity, and temperature—could lead to a more comprehensive smart farming solution. By correlating disease data with environmental variables, the system could offer farmers more holistic insights into the health of their crops, enabling proactive farm management practices that go beyond disease detection alone.