Machine Learning

CS229

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Chapter 1

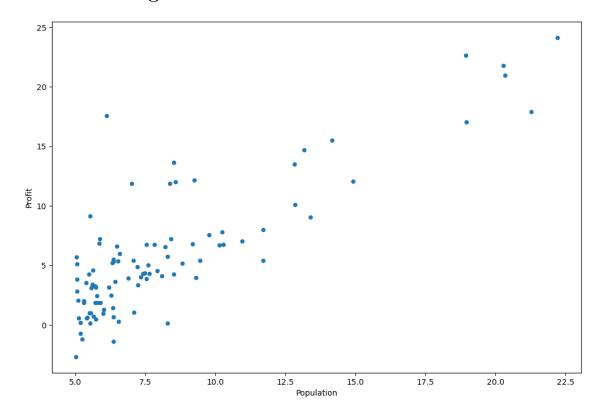
Linear Regression

1.1 Linear regression with one variable

target: predict profits

data: ex1data1.txt - population(just one feature) | profit

1.1.1 Plotting the data



1.1.2 Gradient Descent

target: fit θ to dataset (θ : to minimize cost $J(\theta)$)

variable: x - feature

Update Equations

cost function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^{2}$$

hypothesis:

$$h_{\theta}(x) = \theta^T x = \theta_0 + \theta_1 x_1 (+ \dots + \theta_n x_n)$$

```
def computeCost(X, y, theta):
  inner = np.power(((X * theta.T) - y), 2)
  return np.sum(inner) / (2 * len(X))
```

in batch gradient descent:

$$\theta_j := \theta_j = \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

```
def gradientDescent(X, y, theta, alpha, iters):
    temp = np.matrix(np.zeros(theta.shape))
    parameters = int(theta.ravel().shape[1])
    cost = np.zeros(iters)

for i in range(iters):
    error = (X * theta.T) - y

    for j in range(parameters):
        term = np.multiply(error, X[:,j])
        temp[0,j] = theta[0,j] - ((alpha / len(X)) * np.sum(term))

    theta = temp
    cost[i] = computeCost(X, y, theta)

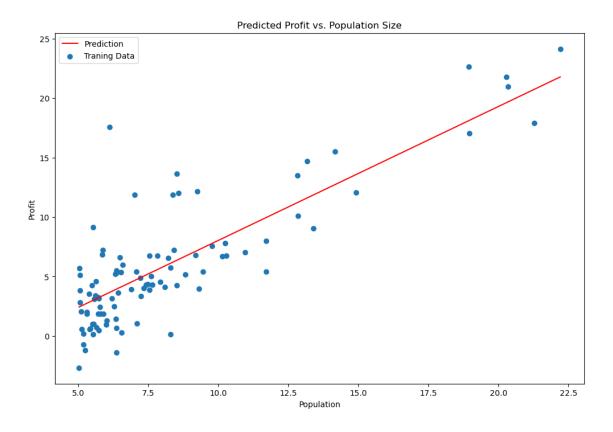
return theta, cost
```

1.1.3 Computing the cost $J(\theta)$

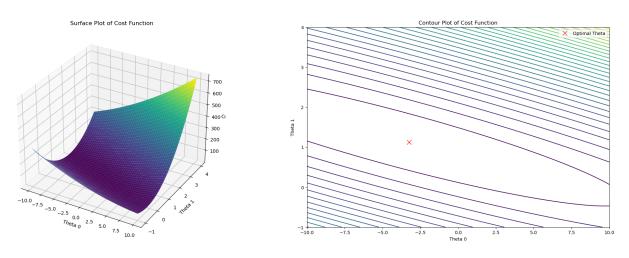
Implementation

```
alpha = 0.01
iters = 1000
Theta, cost = gradientDescent(X, y, theta, alpha, iters)
computeCost(X, y, Theta)
```

1.1.4 Visualizing regression



1.1.5 Visualizing $J(\theta)$



1.2 Linear regression with multiple variables

multiple variables:

target: predict the prices of houses

1.2.1 Feature Normalization

When features differ by orders of magnitude, first performing feature scaling can make gradient descent converge much more quickly.

formula:

$$z = \frac{x - \mu}{\sigma}$$

 $\begin{aligned} \text{mean} &= \mu \\ \text{standard deviation} &= \sigma \end{aligned}$

results:

\$	<u>123</u> Size \$	Bedrooms \$	Price \$	\$	<u>123</u> Size \$	123 Bedrooms \$	Price \$
0	2104	3	399900	0	0.130010	-0.223675	0.475747
1	1600	3	329900	1	-0.504190	-0.223675	-0.084074
2	2400	3	369000	2	0.502476	-0.223675	0.228626
3	1416	2	232000	3	-0.735723	-1.537767	-0.867025
4	3000	4	539900	4	1.257476	1.090417	1.595389

alternative: max-min

1.2.2 Gradient Descent

Update Equations

cost function:

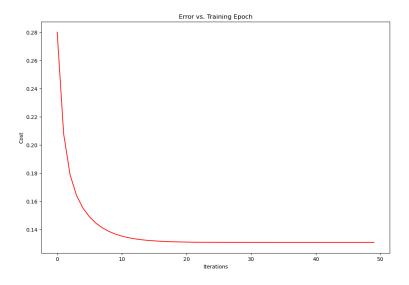
$$J(\theta) = \frac{1}{2m} (X\theta - \vec{y})^T (X\theta - \vec{y})$$

where

$$X = \begin{bmatrix} - & (x^{(1)})^T & - \\ - & (x^{(2)})^T & - \\ & \vdots & \\ - & (x^{(m)})^T & - \end{bmatrix} \qquad \vec{y} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix}$$

Selecting learning rates

try out different learning rates find a learning rate that converges quickly - less than 50 iterations



1.2.3 Normal Equations

step 1.
find θ

closed form solution to linear regression:

$$\theta = (X^T X)^{-1} X^T \vec{y}$$

- does not require any feature scaling
- will get an exact solution in one calculation
- no "loop until convergence" like in gradient descent

step2.predict

make a price prediction for a 1650-square-foot house with 3 bedrooms with θ

Chapter 2

Logistic Regression

2.1 Logistic Regression

only able to find a linear decision boundary

target: predict whether a student gets permitted into a university

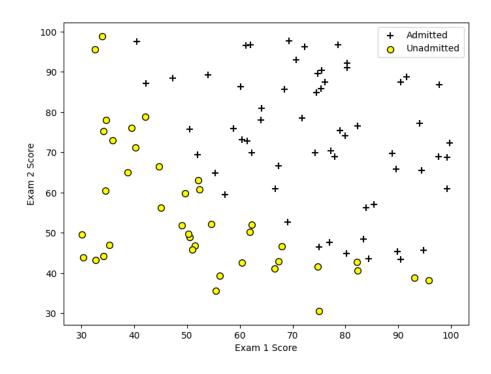
- by building a classification model

data: historical data from previous applicants

(scores on two exams and the admissions decision)

- as a training set for logistic regression

2.1.1 Visualizing the data



2.1.2 Implementation

Sigmoid Function

logistic regression hypothesis:

$$h_{\theta}(x) = g(\theta^T x)$$

where g is the **sigmoid function**:

$$g(z) = \frac{1}{1 + e^{-z}}$$

Cost function and gradient

cost function in logistic regression:

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \left[-y^{(i)} \log(h_{\theta}(x^{(i)})) - (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)})) \right]$$

gradient of the cost: (a vector of same length as θ) the j^{th} element (for j = 0, 1,...,n):

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

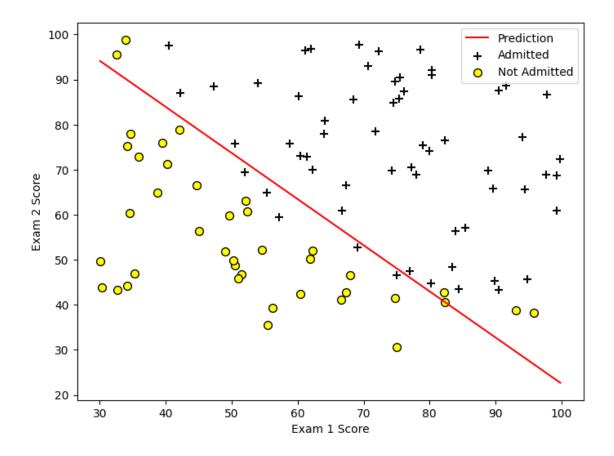
Note: while this gradient looks identical to the linear regression gradient, the formula is actually different because linear and logistic regression have different definitions of $h_{\theta}(x)$

Learning parameters using fminunc (scipy.optimize.fmin tnc in Python instead)

```
import scipy.optimize as opt
result = opt.fmin_tnc(func=cost, x0=theta, fprime=gradient, args=(X, y))
theta_min = np.matrix(result[0])
```

2.1.3 Visualing regression

```
x = np.linspace(data['Exam 1'].min(),data['Exam 1'].max(),100)
decision_boundary = -(theta_min[0,1]*x+theta_min[0,0]) / theta_min[0,2]
```



Evaluating logistic regression

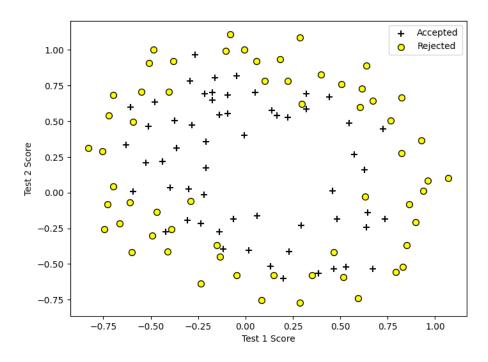
After learning the parameters, we can use the model to predic whether a particular student will be admitted. For a student with an Exam 1 score of 45 and an Exam 2 score of 85, you should expect to see an admission probability of 0.776.

```
def predict(theta, X):
   probability = sigmoid(X * theta.T)
   # return [1 if x >= 0.5 else 0 for x in probability]
   return probability

predict(theta_min, [1,45,85])[0,0]
```

2.2 Regularized logistic regression

2.2.1 Visualizing the data



2.2.2 Feature mapping

One way to fit the data better is to create more feature form each data point.â $\check{A}\check{T}$ â $\check{A}\check{T}$ map the features into all polynomial terms of x_1 and x_2 up to the sixth power.

$$mapFeature(x) = \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ x_1^2 \\ x_1x_2 \\ x_2^2 \\ x_3^3 \\ \vdots \\ x_1x_2^5 \\ x_2^6 \end{bmatrix}$$

- vector of two features \rightarrow 28-dimensional vector

While the feature mapping allows us to build a more expressive classifier, it also more susceptible to overfitting.

2.2.3 Cost function and gradient

cost function: in logistic regression

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} \left[-y^{(i)} \log(h_{\theta}(x^{(i)})) - (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)})) \right] + \frac{\lambda}{2m} \sum_{j=1}^{n} \theta_{j}^{2}$$

(**note**: do not regularize θ_0)

the j^{th} element (for j = 0, 1,...,n):

$$\frac{\partial J(\theta)}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)} \qquad for \ j = 1$$

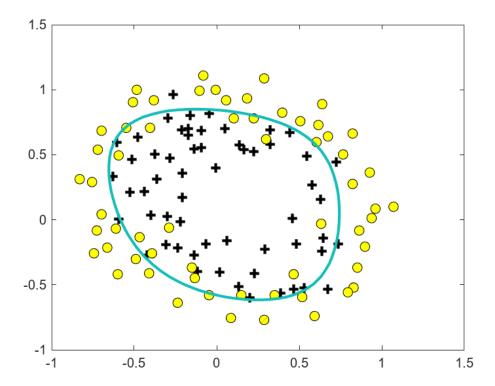
$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} \theta_j \quad for \ j \ge 1$$

Learning parameters using fminunc (scipy.optimize.fmin tnc in Python instead)

2.2.4 Plotting the decision boundary

```
options = optimset('GradObj', 'on', 'MaxIter', 400);
 [theta, J, exit_flag] = fminunc(@(t)(costFunctionReg(t, X_poly, y, lambda))
                 , initial_theta, options);
fprintf('Final_cost: \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \) \( \
plotDecisionBoundary(theta, X_poly, y);
function plotDecisionBoundary(theta, X, y)
                   plotData(X(:,2:3), y);
                   hold on
                   u = linspace(-1, 1.5, 50);
                   v = linspace(-1, 1.5, 50);
                   z = zeros(length(u), length(v));
                   for i = 1:length(u)
                                       for j = 1:length(v)
                                                            z(i,j) = mapFeature(u(i), v(j)) * theta;
                    end
                    contour(u, v, z, [0, 0], 'LineWidth', 2)
                   hold off
end
```

Code Listing 2.1: My MATLAB Code



changes in the dicision boundary as varying lambda

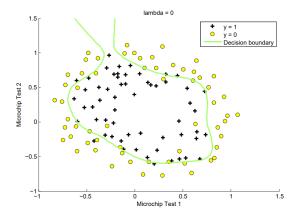


Figure 5: No regularization (Overfitting) $(\lambda=0)$

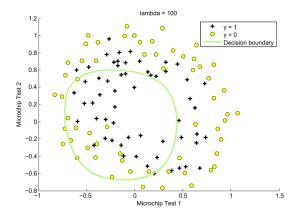


Figure 6: Too much regularization (Underfitting) $(\lambda=100)$