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import cv2
import numpy as np

def transform(img, angle): # backward transformation
    height, width = img.shape
    result = np.zeros((height, width), np.uint8) # result image

    affine = np.array([[np.cos(np.radians(angle)), np.sin(np.radians(angle)), 0],
                       [-np.sin(np.radians(angle)), np.cos(np.radians(angle)), 0],
                       [0, 0, 1]]) # Affine transformation matrix

    for x in range(width):
        for y in range(height):
            p = affine.dot(np.array([x, y, 1]))

            xp = int(p[0])
            yp = int(p[1])

            if 0 <= yp < height and 0 <= xp < width:
                result[y, x] = img[yp, xp]
    return result

in_image = cv2.imread('lena.jpg', 0) # img2numpy

out_image = transform(in_image, 20)

cv2.imshow('Input Image', in_image)
cv2.imshow('Result Image', out_image)

cv2.imwrite('Lenna.png', out_image) # save result img
cv2.waitKey()

```

