Linear Algebra Scalars

- $\bullet x = np.array(3.0)$
- \bullet = np.array(2.0)
- $\bullet x + y, x * y, x / y, x ** y$
- •o/p
- •(array(5.), array(6.), array(1.5), array(9.))

Linear Algebra ... Matrices

- We have already discussed about length dimensionality and shape.
- A = np.arange(20).
- reshape(5, 4)
- A
- o/p

```
array([[ 0., 1., 2., 3.],
        [ 4., 5., 6., 7.],
        [ 8., 9., 10., 11.],
        [12., 13., 14., 15.],
        [16., 17., 18., 19.]])
```

Linear Algebra ... Matrices...Transpose of a Matrix

• A.T

```
array([[ 0., 4., 8., 12., 16.], [ 1., 5., 9., 13., 17.], [ 2., 6., 10., 14., 18.], [ 3., 7., 11., 15., 19.]])
```

Linear Algebra ... Transpose of a Matrix

- As a special type of the square matrix,a symmetric matrix A is equal to its transpose: A = AT.
- B = np.array([[1, 2, 3], [2, 0, 4], [3, 4, 5]])
- B

```
array([[1., 2., 3.],
[2., 0., 4.],
[3., 4., 5.]])
```

Linear Algebra ... Matrices...Transpose of a Matrix

- Now we compare B with its transpose.
- o/p

Linear Algebra Basic Properties of Tensor Arithmetic

- •Scalars, vectors, matrices, and tensors ("tensors" in this subsection refer to algebraic objects) of an arbitrary number of axes have some nice properties that often come in handy.
- For example
- Two tensors with the same shape, the result of any binary element wise operation will be a tensor of that same shape.

Linear Algebra Basic Properties of Tensor Arithmetic....

- A = np.arange(20).reshape(5, 4)
- B = A.copy() # Assign a copy of `A` to `B` by allocating new memory A, A + B

Linear Algebra Sum and Dot Product

```
• x = np.arange(4) x,
• x.sum()
• o/p
• (array([0., 1., 2., 3.]), array(6.))
• y = np.ones(4)
• x, y, np.dot(x, y)
o/p

    (array([0., 1., 2., 3.]), array([1., 1., 1., 1.]), array(6.))
```

Linear Algebra Matrix-Vector Products

- $\bullet A = [1,2,3,4]$
- •np.dot(A,2)
- o/p
- •array([2, 4, 6])

Matrix-Matrix Multiplication

- A=[1 2 3]
- B=[2,3,4]
- Np.dot(A,B)
- o/p
- 20

$$\mathbf{C} = \mathbf{A}\mathbf{B} = egin{bmatrix} \mathbf{a}_1^{\mathsf{T}} \ \mathbf{a}_2^{\mathsf{T}} \ dots \ \mathbf{a}_n^{\mathsf{T}} \end{bmatrix} egin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 & \cdots & \mathbf{b}_m \end{bmatrix}$$

Matrix-Matrix Multiplication...

- •B = np.ones(shape=(4, 3))
- np.dot(A, B)