

# Readme:

Arg 1 :1,2,3,4,5,6

Arg 1 = 1

For training svm model for Task A takes arguments of positive class path and negative class path

Ex: python3 main.py 1 [+ve\_class\_path] [-ve\_class\_path]

Arg 1 = 2

For training svm model for Task B takes arguments of open\_hand path and close\_hand path

Ex: python3 main.py 2 [open\_hand\_path] [close\_hand\_path]

Arg 1=3

For volume controle using pretrained svm

Ex: python3 main.py 3 [path\_of\_pretrained\_svm]

Arg 1=4

For images classification using pretrained svm

Ex: python3 main.py 4 [test\_data\_path] [save\_csv\_to\_path]  
[path\_of\_pretrained\_svm]

Arg 1=5

For checking the accuracy and plotiong curves

Ex: python3 main.py 5 [open\_hand\_folders\_path]  
[close\_hand\_folders\_path] [path\_of\_pretrained\_svm]

Arg 1=6:

HOG visualization image saved to same path as main.py

Ex: `python3 main.py 6 [path_of_image]`

For TASK A model can be downloaded from this [link](#)