File Edit Action Flow Special

■PICKPLACE1		
	Start - iRC V902-13-023, igus Arm (robolink-legacy\RL-D-DCi-4S-M), without gripper	⊕ ₩
⊕ • 1	Joint (constant: A1=0.0°, A2=0.0°, A3=0.0°, A4=90.0°, vel=40%, acc=40%, smooth=0%)	₽₽ ₩
	Joint (constant: A1=40.0°, A2=0.0°, A3=0.0°, A4=90.0°, vel=40%, acc=40%, smooth=0%)	수 & X
⊕ 3	Linear (constant: X=183 mm, Y=156 mm, Z=346 mm, A=-139.5°, B=0.0°, C=180.0°, vel=100 mm/s, acc=40%, smooth=0%)	♦ ♦ %
4	Linear (constant: X=183 mm, Y=156 mm, Z=150 mm, A=-139.5°, B=0.0°, C=180.0°, vel=100 mm/s, acc=40%, smooth=0%)	Ŷ ♡ 🎇
⊕ 5	Wait (wait for 1 s)	♦ ♦ ♦
⊕ 6	Gripper (open gripper 100%)	◊◊ ፡፡
□ 7	Relative (base: X=0 mm, Y=0 mm, Z=-50 mm, vel=100 mm/s, acc=40%, smooth=0%)	
8	Wait (wait for 1 s)	♦ ♦ ♦
⊕ 9	Gripper (open gripper 30%)	☆ ॐ
⊕ 10	Wait (wait for 1 s)	♦ ♦ ♦
₽ 11	Relative (base: X=0 mm, Y=0 mm, Z=50 mm, vel=100 mm/s, acc=40%, smooth=0%)	↑↓ 💥
♣ 12	Linear (constant: X=183 mm, Y=156 mm, Z=346 mm, A=-139.5°, B=0.0°, C=180.0°, vel=100 mm/s, acc=40%, smooth=0%)	↑ → %
⊕ 13	Joint (constant: A1=0.0°, A2=0.0°, A3=0.0°, A4=90.0°, vel=40%, acc=40%, smooth=0%)	☆ ♥ 🕱
⊕ 14	Joint (constant: A1=-40.0°, A2=0.0°, A3=0.0°, A4=90.0°, vel=40%, acc=40%, smooth=0%)	☆ 🎸 💥
	Linear (constant: X=184 mm, Y=-154 mm, Z=347 mm, A=140.0°, B=0.0°, C=180.0°, vel=100 mm/s, acc=40%, smooth=0%)	₽₽
⊕ 16	Linear (constant: X=184 mm, Y=-154 mm, Z=150 mm, A=140.0°, B=0.0°, C=180.0°, vel=100 mm/s, acc=40%, smooth=0%)	↑ ↓ 💥
₽ 17	Wait (wait for 1 s)	☆ ♂ ※
+ 18	Relative (base: X=0 mm, Y=0 mm, Z=-50 mm, vel=100 mm/s, acc=40%, smooth=0%)	♦♦ ₩
4 19	Wait (wait for 1 s)	☆ ☆ ※
	Gripper (open gripper 100%)	☆ ☆ ¤
	Weit (wait for 1 s)	♦ ♦ ♦
⊕ 22	Linear (constant: X=184 mm, Y=-154 mm, Z=347 mm, A=140.0°, B=0.0°, C=180.0°, vel=100 mm/s, acc=40%, smooth=0%)	\$ \$ \$
+ 23	Joint (constant: A1=0.0°, A2=0.0°, A3=0.0°, A4=90.0°, vel=40%, acc=40%, smooth=0%)	♦ 🐉 🔀























