

+	0	Start - iRC V902-13-023, igus Arm (roboLink-legacy\RL-D-DCi-4S-M), without gripper	↑	↓	✕
+	• 1	Joint (constant: A1=0.0°, A2=0.0°, A3=0.0°, A4=90.0°, vel=40%, acc=40%, smooth=0%)	↑	↓	✕
+	2	Gripper (open gripper 0%)	↑	↓	✕
+	3	Loop (repeat until 'DIn27')	↑	↓	✕
+	4	If (if 'DIn21')	↑	↓	✕
+	5	Sub (run 'bartender1.xml')	↑	↓	✕
+	6	Else	↑	↓	✕
+	7	If (if 'DIn22')	↑	↓	✕
+	8	Sub (run 'bartender2.xml')	↑	↓	✕
+	9	Else	↑	↓	✕
+	10	If (if 'DIn23')	↑	↓	✕
+	11	Sub (run 'bartender3.xml')	↑	↓	✕
+	12	Else	↑	↓	✕
+	13	If (if 'DIn24')	↑	↓	✕
+	14	Sub (run 'bartender4.xml')	↑	↓	✕
+	15	Else	↑	↓	✕
+	16	If (if 'DIn25')	↑	↓	✕
+	17	Sub (run 'bartender5.xml')	↑	↓	✕
+	18	Else	↑	↓	✕
+	19	EndIf	↑	↓	✕
+	20	EndIf	↑	↓	✕
+	21	EndIf	↑	↓	✕
+	22	EndIf	↑	↓	✕
+	23	EndIf	↑	↓	✕
+	24	EndLoop	↑	↓	✕