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1. Contest

1.1. rng.h

```
mt19937_64
rng(chrono::steady_clock::now().time_since_epoch().count());

int random(int a, int b) {
    if (a > b)
        return 0;
    return a + rng() % (b - a + 1);
}
double random_double(double a, double b) {
    return a + (b - a) * (rng() / (double)rng.max());
}
```

1.2. template.h

```
#include <bits/stdc++.h>

#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace std;
using namespace __gnu_pbds;
```

```
typedef tree<int, null_type, less_equal<int>, rb_tree_tag,
            tree_order_statistics_node_update>
            ordered_multiset;
typedef tree<int, null_type, less<int>, rb_tree_tag,
            tree_order_statistics_node_update>
            ordered_set;
// find_by_order returns iterator to kth largest (0-indexed)
// order_of_key returns number of elements strictly less than
// given value -->
// basically index (0-indexed) for multiset, to erase use
// upper_bound.
// Upper_bound lower_bound exchange their roles
#define ONLINE_JUDGE
#ifndef ONLINE_JUDGE
#define db(x) cerr << #x << " == " << x << endl
#define dbs(x) cerr << x << endl
#else
#define db(x) ((void)0)
#define dbs(x) ((void)0)
#endif

#define int long long
#define fast()
\ ios_base::sync_with_stdio(0);
\ cin.tie(NULL);
\ cout.tie(NULL);
#define fr(i, a, b) for (int i = (a); i < (int)(b); ++i)
#define pb push_back
#define prDouble(x) cout << fixed << setprecision(10) << x
int M = 1e9 + 7;
#define all(x) x.begin(), x.end()
#define allr(x) x.rbegin(), x.rend()
#define sz(x) (int)x.size()
```

```

void solve() {}
signed main() {
    fast();
    int t = 1;
    cin >> t;
    while (t--) {
        solve();
    }
    return 0;
}

```

2. Data Structures

2.1. LazySegTree.h

```

template <typename T, typename U> struct seg_tree_lazy {
    int S, H;
    T zero;
    vector<T> value;
    U noop;
    vector<bool> dirty;
    vector<U> prop;
    seg_tree_lazy(int _S, T _zero = T(), U _noop = U()) {
        zero = _zero, noop = _noop;
        for (S = 1, H = 1; S < _S;)
            S *= 2, H++;
        value.resize(2 * S, zero);
        dirty.resize(2 * S, false);
        prop.resize(2 * S, noop);
    }
    void set_leaves(vector<T> &leaves) {
        copy(leaves.begin(), leaves.end(), value.begin() + S);
        for (int i = S - 1; i > 0; i--)
            value[i] = value[2 * i] + value[2 * i + 1];
    }
    void apply(int i, U &update) {
        value[i] = update(value[i]);
    }
}

```

```

    if (i < S) {
        prop[i] = prop[i] + update;
        dirty[i] = true;
    }
}
void rebuild(int i) {
    for (int l = i / 2; l; l /= 2) {
        T combined = value[2 * l] + value[2 * l + 1];
        value[l] = prop[l](combined);
    }
}
void propagate(int i) {
    for (int h = H; h > 0; h--) {
        int l = i >> h;
        if (dirty[l]) {
            apply(2 * l, prop[l]);
            apply(2 * l + 1, prop[l]);
            prop[l] = noop;
            dirty[l] = false;
        }
    }
}
void upd(int i, int j, U update) {
    i += S, j += S;
    propagate(i), propagate(j);
    for (int l = i, r = j; l <= r; l /= 2, r /= 2) {
        if ((l & 1) == 1)
            apply(l++, update);
        if ((r & 1) == 0)
            apply(r--, update);
    }
    rebuild(i), rebuild(j);
}
T query(int i, int j) {
    i += S, j += S;
    propagate(i), propagate(j);
}
```

```

T res_left = zero, res_right = zero;
for (; i <= j; i /= 2, j /= 2) {
    if ((i & 1) == 1)
        res_left = res_left + value[i++];
    if ((j & 1) == 0)
        res_right = value[j--] + res_right;
}
return res_left + res_right;
};

struct node {
    int sum, width;
    node operator+(const node &n) {
        // change 1
        return {sum + n.sum, width + n.width};
    }
};

struct update {
    bool type; // 0 for add, 1 for reset
    int value;
    node operator()(const node &n) {
        // change 2
        if (type)
            return {n.width * value, n.width};
        else
            return {n.sum + n.width * value, n.width};
    }
    update operator+(const update &u) {
        // change 3
        if (u.type)
            return u;
        return {type, value + u.value};
    }
};

// Example Initialization
// seg_tree_lazy<node, update> lst(size, {0, 1}, {0, 0});

```

```

// lst.set_leaves(leaves);
// lst.upd(l, r, {0, value});
// auto result = lst.query(l, r);

```

2.2. Merge_sort_tree_pbds.h

```

// Merge Sort Tree with point updates - paste into a .cpp file
#include <bits/stdc++.h>
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace std;
using namespace __gnu_pbds;

template <typename T>
using ordered_set = tree<pair<T, int>, null_type, less<pair<T, int>>,
                                         rb_tree_tag,
                                         tree_order_statistics_node_update>;

class MergeSortTree {
    int n;
    vector<ordered_set<int>> st;
    vector<int> arr;

    void insert_at(int node, int l, int r, int pos, int val) {
        st[node].insert({val, pos});
        if (l == r)
            return;
        int mid = (l + r) >> 1;
        if (pos <= mid)
            insert_at(node << 1, l, mid, pos, val);
        else
            insert_at(node << 1 | 1, mid + 1, r, pos, val);
    }

    void erase_at(int node, int l, int r, int pos, int val) {
        st[node].erase({val, pos});
    }
}
```

```

if (l == r)
    return;
int mid = (l + r) >> 1;
if (pos <= mid)
    erase_at(node << 1, l, mid, pos, val);
else
    erase_at(node << 1 | 1, mid + 1, r, pos, val);
}

int query_le_rec(int node, int l, int r, int ql, int qr, int
k) {
    if (qr < l || r < ql)
        return 0;
    if (ql <= l && r <= qr) {
        return (int)st[node].order_of_key({k + 1,
numeric_limits<int>::min()});
    }
    int mid = (l + r) >> 1;
    return query_le_rec(node << 1, l, mid, ql, qr, k) +
        query_le_rec(node << 1 | 1, mid + 1, r, ql, qr, k);
}

public:
    MergeSortTree() : n(0) {}

    MergeSortTree(const vector<int> &a) { build(a); }

    void build(const vector<int> &a) {
        arr = a;
        n = (int)arr.size();
        if (n == 0)
            return;
        st.assign(4 * n, ordered_set<int>());
        for (int i = 0; i < n; ++i)
            insert_at(1, 0, n - 1, i, arr[i]);
    }
}

void point_update(int pos, int newVal) {
    if (pos < 0 || pos >= n)
        return;
    int old = arr[pos];
    if (old == newVal)
        return;
    erase_at(1, 0, n - 1, pos, old);
    insert_at(1, 0, n - 1, pos, newVal);
    arr[pos] = newVal;
}

int count_le(int l, int r, int k) {
    if (l < 0)
        l = 0;
    if (r >= n)
        r = n - 1;
    if (l > r || n == 0)
        return 0;
    return query_le_rec(1, 0, n - 1, l, r, k);
}

int count_lt(int l, int r, int k) { return count_le(l, r, k - 1); }

int count_gt(int l, int r, int k) { return (r - l + 1) -
    count_le(l, r, k); }

const vector<int> &data() const { return arr; }

// Example usage:
// int main() {
//     vector<int> a = {5,1,7,3,4};
//     MergeSortTree mst(a);
//     cout << mst.count_le(1,4,3) << "\n";
}

```

```
//     mst.point_update(2,2);
//     cout << mst.count_le(1,4,3) << "\n";
// }
```

2.3. Mos.h

```
int BLOCK = DO_NOT_FORGET_TO_CHANGE_THIS;
struct Query {
    int l, r, id;
    Query(int _l, int _r, int _id) : l(_l), r(_r), id(_id) {}
    bool operator<(Query &o) {
        int mblock = l / BLOCK, oblock = o.l / BLOCK;
        return (mblock < oblock) or
               (mblock == oblock and mblock % 2 == 0 and r < o.r)
or
               (mblock == oblock and mblock % 2 == 1 and r > o.r);
    };
};

void solve() {
    vector<Query> queries;
    queries.reserve(q);
    for (int i = 0; i < q; i++) {
        int l, r;
        cin >> l >> r;
        l--, r--;
        queries.emplace_back(l, r, i);
    }
    sort(all(queries));
    int ans = 0;
    auto add = [&](int v) {};
    auto rem = [&](int v) {};
    vector<int> out(q); // Change out type if necessary
    int cur_l = 0, cur_r = -1;
    for (auto &[l, r, id] : queries) {
        while (cur_l > l)
            add(--cur_l);
        while (cur_l < l)
```

```
            rem(cur_l++);
        while (cur_r < r)
            add(++cur_r);
        while (cur_r > r)
            rem(cur_r--);
        out[id] = ans;
    }
}
```

2.4. SegTree.h

```
struct segtree {
    typedef int T;
    // for max segtree, set unit = INT_MIN and f(a,b) = max(a,b)
    static constexpr T unit = 0; // identity for sum
    T f(T a, T b) { return a + b; } // (any associative fn)
    vector<T> s;
    int n;
    segtree(int n = 0, T def = unit) : s(2 * n, def), n(n) {}
    void update(int pos, T val) {
        for (s[pos += n] = val; pos /= 2;)
            s[pos] = f(s[pos * 2], s[pos * 2 + 1]);
    }
    T query(int b, int e) { // query [b, e)
        T ra = unit, rb = unit;
        for (b += n, e += n; b < e; b /= 2, e /= 2) {
            if (b % 2)
                ra = f(ra, s[b++]);
            if (e % 2)
                rb = f(s[--e], rb);
        }
        return f(ra, rb);
    }
};
```

2.5. fenwick.h

```
#include <bits/stdc++.h>
using namespace std;

/*
FenwickRange<T>
- 0-based public indexing for callers
- Internally uses 1-based Fenwick arrays
- Methods:
    FenwickRange(int n) : create size n
(elements indexed 0..n-1)
    void range_add(int l, int r, T v): add v to every element
in [l, r]
    (0-based inclusive) T prefix_sum(int idx) : sum of
elements
    [0..idx] (0-based). idx < 0 -> 0 T range_sum(int l, int
r) : sum of
elements [l..r] (0-based) T point_query(int idx) : value at index
    idx (0-based)
*/
template <typename T = long long> class FenwickRange {
public:
    explicit FenwickRange(int n = 0)
        : n_(n), B1(n_ + 1, T(0)), B2(n_ + 1, T(0)) {}

    int size() const noexcept { return n_; }

    // add val to every element in [l, r] (0-based indices)
    void range_add(int l, int r, T val) {
        if (n_ == 0)
            return;
        if (l < 0)
            l = 0;
        if (r >= n_)
            r = n_ - 1;
    }
}
```

```
if (l > r)
    return;
int L = l + 1; // convert to 1-based
int R = r + 1;
add(B1, L, val);
add(B1, R + 1, -val);
add(B2, L, val * T(L - 1));
add(B2, R + 1, -val * T(R));
}

// sum of [0..idx] (0-based). if idx<0 -> 0
T prefix_sum(int idx) const {
    if (idx < 0)
        return T(0);
    if (idx >= n_)
        idx = n_ - 1;
    int i = idx + 1; // 1-based
    return sum(B1, i) * T(i) - sum(B2, i);
}

// sum of [l..r] (0-based)
T range_sum(int l, int r) const {
    if (l > r)
        return T(0);
    return prefix_sum(r) - prefix_sum(l - 1);
}

// value at single index (0-based)
T point_query(int idx) const { return range_sum(idx, idx); }

void reset() {
    std::fill(B1.begin(), B1.end(), T(0));
    std::fill(B2.begin(), B2.end(), T(0));
}

private:
```

```

int n_;
vector<T> B1, B2; // 1..n

static void add(vector<T> &bit, int idx1, T val) {
    int n = (int)bit.size() - 1;
    for (int i = idx1; i <= n; i += (i & -i))
        bit[i] += val;
}

static T sum(const vector<T> &bit, int idx1) {
    if (idx1 <= 0)
        return T(0);
    int i = idx1;
    T res = T(0);
    for (; i > 0; i -= (i & -i))
        res += bit[i];
    return res;
}
};

```

2.6. node_segtree.h

```

struct node {};

node merge_node(const node &a, const node &b) {
    // TODO: implement merging logic for your problem
    return node();
}

struct SegTree {
    int n;
    int off;
    vector<node> st;
    SegTree(const vector<node> &init) {
        n = (int)init.size();
        off = 1;
        while (off < n)

```

```

            off <= 1;
            st.assign(2 * off, node());
            for (int i = 0; i < n; ++i)
                st[off + i] = init[i];
            for (int i = n; i < off; ++i)
                st[off + i] = node(); // empty
            for (int i = off - 1; i >= 1; --i)
                st[i] = merge_node(st[2 * i], st[2 * i + 1]);
        }
        void point_set(int pos, const node &val) {
            int p = off + pos;
            st[p] = val;
            for (p >= 1; p >= 1; p >= 1)
                st[p] = merge_node(st[2 * p], st[2 * p + 1]);
        }
        node range_query(int left, int r) {
            if (left > r)
                return node();
            node left_id, right_id;
            int L = left + off, R = r + off;
            while (L <= R) {
                if (L & 1)
                    left_id = merge_node(left_id, st[L++]);
                if (!(R & 1))
                    right_id = merge_node(st[R--], right_id);
                L >= 1;
                R >= 1;
            }
            return merge_node(left_id, right_id);
        }
    };
    // USAGE NOTES:
    // - Implement `node` fields and `merge_node` according to your
    // operation (sum,
    // // min, max, gcd, custom struct, etc.).

```

```
// - If you need identity elements, ensure default `node()`
acts as identity or
// replace left_id/right_id initializers.
// - Add #include <bits/stdc++.h> and `using namespace std;` in
file if needed.
```

2.7. range_update_tree.h

```
template <typename T, typename F> struct RangeUpdateTree {
    int n;
    vector<T> tree;
    T identity;
    F merge;
    RangeUpdateTree(const vector<T> &arr, T id, F _m)
        : n((int)arr.size()), tree(2 * n), identity(id),
    merge(_m) {
        for (int i = 0; i < n; i++)
            tree[n + i] = arr[i];
        for (int i = n - 1; i >= 1; i--)
            tree[i] = merge(tree[2 * i], tree[2 * i + 1]);
    }
    void update(int l, int r, T value) {
        assert(l >= 0 && r < n && l <= r);
        for (l += n, r += n; l <= r; l >= 1, r >= 1) {
            if (l & 1)
                tree[l] = merge(value, tree[l]), l++;
            if (!(r & 1))
                tree[r] = merge(value, tree[r]), r--;
        }
        if (l == r)
            tree[l] = merge(value, tree[l]);
    }
    T query(int v) {
        T res = tree[v += n];
        for (; v > 1; v >= 1)
            res = merge(res, tree[v > 1]);
        return res;
    }
}
```

```
    }
};

// ex: RangeUpdateTree<int, decltype(join)> v(vi (n, 1e9), 1e9,
join); use auto
// func for join
```

2.8. sparse_table.h

```
class gcd_sparse_table {
public:
    vector<long long> a;
    int n;
    vector<vector<long long>> sparse_table;

    gcd_sparse_table(vector<long long> &arr) {
        a = arr;
        n = a.size();
        sparse_table.assign(n + 1, vector<long long>(log2(n) + 2));
        build();
    }

    void build() {
        for (int i = 0; i < n; i++)
            sparse_table[i][0] = a[i];
        for (int j = 1; (1 << j) <= n; j++) {
            for (int i = 0; i + (1 << j) - 1 < n; i++) {
                sparse_table[i][j] = __gcd(sparse_table[i][j - 1],
                                            sparse_table[i + (1 << (j -
1))][j - 1]);
            }
        }
    }

    long long query(int l, int r) {
        if (l > r)
            return 0;
```

```

        int len = r - l + 1;
        int p = log2(len);
        return __gcd(sparse_table[l][p], sparse_table[r - (1 << p)
+ 1][p]);
    }
};

class GcdSparseTable2D {
public:
    int n, m, K;
    std::vector<std::vector<long long>> a;
    std::vector<std::vector<std::vector<long long>>> st;

    GcdSparseTable2D(const std::vector<std::vector<long long>>&matrix) {
        a = matrix;
        n = a.size();
        m = n ? a[0].size() : 0;
        K = std::log2(std::min(n, m)) + 1;
        st.assign(
            n, std::vector<std::vector<long long>>(m,
            std::vector<long long>(K)));
        build();
    }

    void build() {
        for (int i = 0; i < n; ++i)
            for (int j = 0; j < m; ++j)
                st[i][j][0] = a[i][j];

        for (int k = 1; k < K; ++k) {
            int len = 1 << k, hl = len >> 1;
            for (int i = 0; i + len <= n; ++i) {
                for (int j = 0; j + len <= m; ++j) {
                    long long g1 = std::gcd(st[i][j][k - 1], st[i + hl]
[j][k - 1]);
                    long long g2 =
                        std::gcd(st[i][j + hl][k - 1], st[i + hl][j + hl]
[k - 1]);
                    st[i][j][k] = std::gcd(g1, g2);
                }
            }
        }
    }

    long long query(int x1, int y1, int x2, int y2) {
        if (x1 > x2)
            std::swap(x1, x2);
        if (y1 > y2)
            std::swap(y1, y2);
        int k = std::log2(std::min(x2 - x1 + 1, y2 - y1 + 1));
        int dx = x2 - (1 << k) + 1, dy = y2 - (1 << k) + 1;
        long long t1 = std::gcd(st[x1][y1][k], st[dx][y1][k]);
        long long t2 = std::gcd(st[x1][dy][k], st[dx][dy][k]);
        return std::gcd(t1, t2);
    }
};

class max_sparse_table {
public:
    vector<long long> a;
    int n;
    vector<vector<long long>> sparse_table;

    max_sparse_table(vector<long long> &arr) {
        a = arr;
        n = a.size();
        sparse_table.assign(n + 1, vector<long long>(log2(n) + 2));
        build();
    }

    void build() {

```

```

for (int i = 0; i < n; i++)
    sparse_table[i][0] = a[i];
for (int j = 1; (1 << j) <= n; j++) {
    for (int i = 0; i + (1 << j) - 1 < n; i++) {
        sparse_table[i][j] = max(sparse_table[i][j - 1],
                                  sparse_table[i + (1 << (j -
1))][j - 1]);
    }
}
}

long long query(int l, int r) {
    if (l > r)
        return LLONG_MIN;
    int len = r - l + 1;
    int p = log2(len);
    return max(sparse_table[l][p], sparse_table[r - (1 << p) +
1][p]);
}
};

class MaxSparseTable2D {
public:
    int n, m, K;
    std::vector<std::vector<long long>> a;
    std::vector<std::vector<std::vector<long long>>> st;

    MaxSparseTable2D(const std::vector<std::vector<long long>>
&matrix) {
        a = matrix;
        n = a.size();
        m = n ? a[0].size() : 0;
        K = std::log2(std::min(n, m)) + 1;
        st.assign(
            n, std::vector<std::vector<long long>>(m,
std::vector<long long>(K)));
    }

    void build();
}

void build() {
    for (int i = 0; i < n; ++i)
        for (int j = 0; j < m; ++j)
            st[i][j][0] = a[i][j];

    for (int k = 1; k < K; ++k) {
        int len = 1 << k, hl = len >> 1;
        for (int i = 0; i + len <= n; ++i) {
            for (int j = 0; j + len <= m; ++j) {
                st[i][j][k] =
                    std::max({st[i][j][k - 1], st[i + hl][j][k - 1],
                              st[i][j + hl][k - 1], st[i + hl][j +
hl][k - 1]});
            }
        }
    }
}

long long query(int x1, int y1, int x2, int y2) {
    if (x1 > x2)
        std::swap(x1, x2);
    if (y1 > y2)
        std::swap(y1, y2);
    int k = std::log2(std::min(x2 - x1 + 1, y2 - y1 + 1));
    int dx = x2 - (1 << k) + 1, dy = y2 - (1 << k) + 1;
    return std::max(
        {st[x1][y1][k], st[dx][y1][k], st[x1][dy][k], st[dx]
[dy][k]} );
}

class min_sparse_table {
public:

```

```

vector<long long> a;
int n;
vector<vector<long long>> sparse_table;

min_sparse_table(vector<long long> &arr) {
    a = arr;
    n = a.size();
    sparse_table.assign(n + 1, vector<long long>(log2(n) + 2));
    build();
}

void build() {
    for (int i = 0; i < n; i++)
        sparse_table[i][0] = a[i];
    for (int j = 1; (1 << j) <= n; j++) {
        for (int i = 0; i + (1 << j) - 1 < n; i++) {
            sparse_table[i][j] = min(sparse_table[i][j - 1],
                                      sparse_table[i + (1 << (j - 1))][j - 1]);
        }
    }
    long long query(int l, int r) {
        if (l > r)
            return LLONG_MAX;
        int len = r - l + 1;
        int p = log2(len);
        return min(sparse_table[l][p], sparse_table[r - (1 << p) + 1][p]);
    }
};

class MinSparseTable2D {
public:
    int n, m, K;
    std::vector<std::vector<long long>> a;
    std::vector<std::vector<std::vector<long long>>> st;

    MinSparseTable2D(const std::vector<std::vector<long long>> &matrix) {
        a = matrix;
        n = a.size();
        m = n ? a[0].size() : 0;
        K = std::log2(std::min(n, m)) + 1;
        st.assign(
            n, std::vector<std::vector<long long>>(m,
std::vector<long long>(K)));
        build();
    }

    void build() {
        for (int i = 0; i < n; ++i)
            for (int j = 0; j < m; ++j)
                st[i][j][0] = a[i][j];

        for (int k = 1; k < K; ++k) {
            int len = 1 << k, hl = len >> 1;
            for (int i = 0; i + len <= n; ++i) {
                for (int j = 0; j + len <= m; ++j) {
                    st[i][j][k] =
                        std::min({st[i][j][k - 1], st[i + hl][j][k - 1],
                                  st[i][j + hl][k - 1], st[i + hl][j + hl][k - 1]});
                }
            }
        }
    }

    long long query(int x1, int y1, int x2, int y2) {
        if (x1 > x2)
            std::swap(x1, x2);
    }
};

```

```

    if (y1 > y2)
        std::swap(y1, y2);
    int k = std::log2(std::min(x2 - x1 + 1, y2 - y1 + 1));
    int dx = x2 - (1 << k) + 1, dy = y2 - (1 << k) + 1;
    return std::min(
        {st[x1][y1][k], st[dx][y1][k], st[x1][dy][k], st[dx]
        [dy][k]});
}
};

```

3. Graph

3.1. DSU.h

```

class DSU {
public:
    vector<int> parent;
    vector<int> size;
    void make_set(int v) {
        parent[v] = v;
        size[v] = 1;
    }
    DSU(int n) {
        parent.resize(n);
        size.resize(n);
        for (int i = 0; i < n; i++) {
            make_set(i);
        }
    }
    int find_set(int v) {
        if (v == parent[v])
            return v;
        return parent[v] = find_set(parent[v]);
    }
    void union_sets(int a, int b) {
        a = find_set(a);
        b = find_set(b);
    }
};

```

```

    if (a != b) {
        if (size[a] < size[b])
            swap(a, b);
        parent[b] = a;
        size[a] += size[b];
    }
};

```

3.2. HLD.h

```

struct HLD {
    int n, timer = 0;
    vi top, tin, p, sub;
    HLD(vvi &adj) : n(sz(adj)), top(n), tin(n), p(n, -1), sub(n,
    1) {
        vi ord(n + 1);
        for (int i = 0, t = 0, v = ord[i]; i < n; v = ord[++i])
            for (auto &to : adj[v])
                if (to != p[v])
                    p[to] = v, ord[++t] = to;
        for (int i = n - 1, v = ord[i]; i > 0; v = ord[--i])
            sub[p[v]] += sub[v];
        for (int v = 0; v < n; v++)
            if (sz(adj[v]))
                iter_swap(begin(adj[v]), max_element(all(adj[v]), [&
                (int a, int b) {
                    return make_pair(a != p[v], sub[a]) <
                        make_pair(b != p[v], sub[b]);
                })));
        function<void(int)> dfs = [&](int v) {
            tin[v] = timer++;
            for (auto &to : adj[v])
                if (to != p[v]) {
                    top[to] = (to == adj[v][0] ? top[v] : to);
                    dfs(to);
                }
        }
    }
};

```

```

    };
    dfs(0);
}
int lca(int u, int v) {
    return process(u, v, [](){}(int, int) {});
}
template <class B> int process(int a, int b, B op, bool
ignore_lca = false) {
    for (int v;; op(tin[v], tin[b]), b = p[v]) {
        if (tin[a] > tin[b])
            swap(a, b);
        if ((v = top[b]) == top[a])
            break;
    }
    if (int l = tin[a] + ignore_lca, r = tin[b]; l <= r)
        op(l, r);
    return a;
}
template <class B> void subtree(int v, B op, bool ignore_lca
= false) {
    if (sub[v] > 1 or !ignore_lca)
        op(tin[v] + ignore_lca, tin[v] + sub[v] - 1);
}

```

3.3. KthAnc.h

```

// O(log n) LCA with Kth anc
struct LCA {
    int n;
    vvi &adjLists;
    int lg;
    vvi up;
    vi depth;
    LCA(vvi &_adjLists, int root = 0) : n(sz(_adjLists)),
adjLists(_adjLists) {
        lg = 1;

```

```

        int pw = 1;
        while (pw <= n)
            pw <<= 1, lg++;
        // lg = 20
        up = vvi(n, vi(lg));
        depth.assign(n, -1);
        function<void(int, int)> parentDFS = [&](int from, int
parent) {
            depth[from] = depth[parent] + 1;
            up[from][0] = parent;
            for (auto to : adjLists[from]) {
                if (to == parent)
                    continue;
                parentDFS(to, from);
            }
        };
        parentDFS(root, root);
        for (int j = 1; j < lg; j++) {
            for (int i = 0; i < n; i++) {
                up[i][j] = up[up[i][j - 1]][j - 1];
            }
        }
    }
    int kthAnc(int v, int k) {
        int ret = v;
        int pw = 0;
        while (k) {
            if (k & 1)
                ret = up[ret][pw];
            k >>= 1;
            pw++;
        }
        return ret;
    }
    int lca(int u, int v) {
        if (depth[u] > depth[v])

```

```

    swap(u, v);
    v = kthAnc(v, depth[v] - depth[u]);
    if (u == v)
        return v;
    while (up[u][0] != up[v][0]) {
        int i = 0;
        for (; i < lg - 1; i++) {
            if (up[u][i + 1] == up[v][i + 1])
                break;
        }
        u = up[u][i], v = up[v][i];
    }
    return up[u][0];
};

int dist(int u, int v) { return depth[u] + depth[v] - 2 *
depth[lca(u, v)]; }
};

```

3.4. LCA.h

```

// O(1) LCA
struct LCA {
    int T = 0;
    vi st, path, ret;
    vi en, d;
    RMQ<int> rmq;
    LCA(vector<vi> &C)
        : st(sz(C)), en(sz(C)), d(sz(C)), rmq((dfs(C, 0, -1),
ret)) {}
    void dfs(vvi &adj, int v, int par) {
        st[v] = T++;
        for (auto to : adj[v])
            if (to != par) {
                path.pb(v), ret.pb(st[v]);
                d[to] = d[v] + 1;
                dfs(adj, to, v);
            }
    }
};

int lca(int a, int b) {
    if (a == b)
        return a;
    tie(a, b) = minmax(st[a], st[b]);
    return path[rmq.query(a, b - 1)];
}
int dist(int a, int b) { return d[a] + d[b] - 2 * d[lca(a,
b)]; }
};

```

```

    en[v] = T - 1;
}
bool anc(int p, int c) { return st[p] <= st[c] and en[p] >=
en[c]; }
int lca(int a, int b) {
    if (a == b)
        return a;
    tie(a, b) = minmax(st[a], st[b]);
    return path[rmq.query(a, b - 1)];
}
int dist(int a, int b) { return d[a] + d[b] - 2 * d[lca(a,
b)]; }
};

3.5. bellman.h
bool bellman_ford(int n, int src, vector<vector<pair<int,
int>> &adj,
vector<long long> &dist) {
    const long long INF = 1e18;
    dist.assign(n, INF);
    dist[src] = 0;
    for (int i = 0; i < n - 1; i++) {
        for (int u = 0; u < n; u++) {
            if (dist[u] == INF)
                continue;
            for (auto &p : adj[u]) {
                int v = p.first, w = p.second;
                if (dist[u] + w < dist[v])
                    dist[v] = dist[u] + w;
            }
        }
    }
    for (int u = 0; u < n; u++) {
        if (dist[u] == INF)
            continue;
        for (auto &p : adj[u]) {

```

3.5. bellman.h

```

            if (dist[u] + w < dist[v])
                dist[v] = dist[u] + w;
            }
        }
    }
}
```

```

        int v = p.first, w = p.second;
        if (dist[u] + w < dist[v])
            return false;
    }
}
return true;
}

```

3.6. blockcuttree.h

```

struct BlockCutTree {
    int n;
    vector<vector<int>> adj;
    vector<int> tin, low;
    int timer;
    stack<int> st;
    vector<vector<int>> tree_adj;
    vector<int> is_ap;
    int num_blocks;

    BlockCutTree(int n)
        : n(n), adj(n), tin(n, -1), low(n, -1), timer(0),
    is_ap(n, 0),
        num_blocks(0) {}

    void add_edge(int u, int v) {
        adj[u].push_back(v);
        adj[v].push_back(u);
    }

    void dfs(int u, int p = -1) {
        tin[u] = low[u] = timer++;
        st.push(u);
        int children = 0;
        for (int v : adj[u]) {
            if (v == p)
                continue;

```

```

                if (tin[v] != -1) {
                    low[u] = min(low[u], tin[v]);
                } else {
                    dfs(v, u);
                    low[u] = min(low[u], low[v]);
                    if (low[v] >= tin[u] && p != -1)
                        is_ap[u] = 1;
                    children++;
                }
                if (low[v] >= tin[u]) {
                    int block_node = n + num_blocks++;
                    tree_adj.emplace_back();
                    tree_adj[block_node].push_back(u);
                    tree_adj[u].push_back(block_node);
                    while (true) {
                        int node = st.top();
                        st.pop();
                        if (node != u) {
                            tree_adj[block_node].push_back(node);
                            tree_adj[node].push_back(block_node);
                        }
                        if (node == v)
                            break;
                    }
                }
            }
            if (p == -1 && children > 1)
                is_ap[u] = 1;
        }
    }

    void build() {
        timer = num_blocks = 0;
        tree_adj.assign(n, {});
        fill(tin.begin(), tin.end(), -1);
        fill(is_ap.begin(), is_ap.end(), 0);
        while (!st.empty())

```

```

        st.pop();
    for (int i = 0; i < n; ++i) {
        if (tin[i] == -1) {
            dfs(i);
            while (!st.empty())
                st.pop();
        }
    }
}

int size() const { return n + num_blocks; }
};

void find_bridges() {
    timer = 0;
    visited.assign(n, false);
    tin.assign(n, -1);
    low.assign(n, -1);
    for (int i = 0; i < n; ++i) {
        if (!visited[i])
            dfs(i);
    }
}

// ARTICULATION POINTS:
int n;
vector<vector<int>> adj; // adjacency list of graph

vector<bool> visited;
vector<int> tin, low;
int timer;

void dfs(int v, int p = -1) {
    visited[v] = true;
    tin[v] = low[v] = timer++;
    for (int to : adj[v]) {
        if (to == p)
            continue;
        if (visited[to]) {
            low[v] = min(low[v], tin[to]);
        } else {
            dfs(to, v);
            low[v] = min(low[v], low[to]);
            if (low[to] > tin[v])
                IS_BRIDGE(v, to);
        }
    }
}

```

3.7. bridges.h

```

int n; // number of nodes
vector<vector<int>> adj; // adjacency list of graph

vector<bool> visited;
vector<int> tin, low;
int timer;

void dfs(int v, int p = -1) {
    visited[v] = true;
    tin[v] = low[v] = timer++;
    for (int to : adj[v]) {
        if (to == p)
            continue;
        if (visited[to]) {
            low[v] = min(low[v], tin[to]);
        } else {
            dfs(to, v);
            low[v] = min(low[v], low[to]);
            if (low[to] > tin[v])
                IS_BRIDGE(v, to);
        }
    }
}

```

```

if (p == -1 && children > 1)
    IS_CUTPOINT(v);
}

void find_cutpoints() {
    timer = 0;
    visited.assign(n, false);
    tin.assign(n, -1);
    low.assign(n, -1);
    for (int i = 0; i < n; ++i) {
        if (!visited[i])
            dfs(i);
    }
}

// arya bridges
void findBridges_dfs(int u, int p, int &time,
vector<vector<int>> &adj,
                vector<int> &disc, vector<int> &low,
                vector<pair<int, int>> &bridges) {
    disc[u] = low[u] = time++;
    for (int v : adj[u]) {
        if (v == p)
            continue;

        if (disc[v] != -1) {
            low[u] = min(low[u], disc[v]);
        } else {
            findBridges_dfs(v, u, time, adj, disc, low, bridges);
            low[u] = min(low[u], low[v]);
            if (low[v] > disc[u]) {
                bridges.push_back({u, v});
            }
        }
    }
}
}

vector<pair<int, int>> findBridges(int n, vector<vector<int>>
&adj) {
    vector<int> disc(n, -1), low(n, -1);
    vector<pair<int, int>> bridges;
    int time = 0;

    for (int i = 0; i < n; ++i) {
        if (disc[i] == -1) {
            findBridges_dfs(i, -1, time, adj, disc, low, bridges);
        }
    }
    return bridges;
}

```

3.8. dijkstra.h

```

const int INF = 1000000000;
vector<vector<pair<int, int>>> adj;

void dijkstra(int s, vector<int> &d, vector<int> &p) {
    int n = adj.size();
    d.assign(n, INF);
    p.assign(n, -1);
    vector<bool> u(n, false);

    d[s] = 0;
    for (int i = 0; i < n; i++) {
        int v = -1;
        for (int j = 0; j < n; j++) {
            if (!u[j] && (v == -1 || d[j] < d[v]))
                v = j;
        }

        if (d[v] == INF)
            break;
    }
}

```

```

        u[v] = true;
        for (auto edge : adj[v]) {
            int to = edge.first;
            int len = edge.second;

            if (d[v] + len < d[to]) {
                d[to] = d[v] + len;
                p[to] = v;
            }
        }
    }
}

```

3.9. floyd_washall.h

```

const long long INF = (long long)1e18;
bool floyd_marshall(int n, vector<vector<long long>> &dist) {
    // initialise dist with edge weights, INF if no edge exists
    for (int k = 0; k < n; k++)
        for (int i = 0; i < n; i++)
            for (int j = 0; j < n; j++)
                if (dist[i][k] < INF && dist[k][j] < INF)
                    dist[i][j] = min(dist[i][j], dist[i][k] + dist[k]
[j]);

    for (int i = 0; i < n; i++)
        if (dist[i][i] < 0)
            return true;
    return false;
}

```

4. Number Theory

4.1. ModularArithmetic.h

```

int add(int x, int y, int m = M) {
    int ret = (x + y) % m;
    if (ret < 0)

```

```

        ret += m;
        return ret;
    }
    int mult(int x, int y, int m = M) {
        int ret = (x * y) % m;
        if (ret < 0)
            ret += m;
        return ret;
    }
    int pw(int a, int b, int m = M) {
        int ret = 1;
        int p = a;
        while (b) {
            if (b & 1)
                ret = mult(ret, p, m);
            b >= 1;
            p = mult(p, p, m);
        }
        return ret;
    }
#define LL int
const long long mod = 1e9 + 7;

int euclid(int a, int b, int &x, int &y) {
    if (!b)
        return x = 1, y = 0, a;
    int d = euclid(b, a % b, y, x);
    return y -= a / b * x, d;
}

int modulo_inverse(int a, int m) {
    int x, y;
    int g = euclid(a, m, x, y);
    if (g != 1) {
        return -1;
    }
    return x;
}

```

```

} else {
    x = (x % m + m) % m;
    return x;
}

LL mod_mul(LL a, LL b) {
    a = a % mod;
    b = b % mod;
    return (((a * b) % mod) + mod) % mod;
}

LL mod_add(LL a, LL b) {
    a = a % mod;
    b = b % mod;
    return (((a + b) % mod) + mod) % mod;
}

const int MX = 5e5 + 1;
vector<int> inv(MX + 1), fci(MX + 1), fc(MX + 1);
const int Mod = 1e9 + 7;

void Inverses() {
    inv[1] = 1;
    for (int i = 2; i <= MX; i++) {
        inv[i] = Mod - Mod / i * inv[Mod % i] % Mod;
    }
}

void Factorials() {
    fc[0] = fc[1] = 1;
    for (int i = 2; i <= MX; i++) {
        fc[i] = fc[i - 1] * i % Mod;
    }
}

void InverseFactorials() {
    Inverses();
    Factorials();
    fci[1] = fci[0] = 1;
    for (int i = 2; i <= MX; i++) {
        fci[i] = fci[i - 1] * inv[i] % Mod;
    }
}

int nck(int num, int k) {
    if (num < 0) {
        return 0;
    }
    if (k < 0) {
        return 0;
    }
    if (num < k) {
        return 0;
    } else {
        return fc[num] * fci[k] % Mod * fci[num - k] % Mod;
    }
}

int BinExpItermod(int a, int b) {
    int ans = 1;
    while (b > 0) {
        if (b & 1) {
            ans = (ans * a) % mod;
        }
        a = (a * a) % mod;
        b = b >> 1;
    }
    return ans;
}

```

4.2. bit_bns.h

```
// --- Bit Binary Search in o(log(n)) ---
const int M = 20 const int N = 1 << M

int
lower_bound(int val) {
    int ans = 0, sum = 0;
    for (int i = M - 1; i >= 0; i--) {
        int x = ans + (1 << i);
        if (sum + bit[x] < val)
            ans = x, sum += bit[x];
    }

    return ans + 1;
}
```

4.3. crt.h

```
#ifndef CRT_H
#define CRT_H

#include <numeric>
#include <utility>
#include <vector>

namespace CRT {
using ll = long long;
using ull = __int128;

inline ll mult(ll a, ll b, ll mod) { return ((ull)a * b % mod); }

ll exEuclid(ll a, ll b, ll &x, ll &y) {
    if (b == 0) {
        x = 1;
        y = 0;
        return a;
    }
}
```

```
}
ll x1, y1;
ll d = exEuclid(b, a % b, x1, y1);
x = y1;
y = x1 - y1 * (a / b);
return d;

// Solves x = a_i (mod m_i). Returns {x, LCM(m_i)}.
// If no solution, returns {-1, -1}.
// Works for non-coprime moduli.
std::pair<ll, ll> crt(const std::vector<ll> &a, const
std::vector<ll> &m) {
    ll x = 0, M = 1;
    if (a.empty())
        return {0, 1};
    x = a[0];
    M = m[0];
    for (size_t i = 1; i < a.size(); ++i) {
        ll a_i = a[i], m_i = m[i];
        ll c = (a_i - x % m_i + m_i) % m_i;
        ll x_i, y_i;
        ll g = exEuclid(M, m_i, x_i, y_i);
        if (c % g != 0)
            return {-1, -1}; // No solution
        ll k = mult(c / g, x_i, m_i / g);
        x = x + k * M;
        M = std::lcm(M, m_i);
        x = (x % M + M) % M;
    }
    return {x, M};
}
} // namespace CRT
#endif
```

4.4. discretelog.h

```
#ifndef DISCRETE_LOG_H
#define DISCRETE_LOG_H

#include <cmath>
#include <map>
#include <numeric>

namespace DiscreteLog {
using ll = long long;
using ull = __int128;

inline ll mult(ll a, ll b, ll mod) { return (ll)((ull)a * b % mod); }

ll power(ll a, ll b, ll m) {
    ll res = 1;
    a %= m;
    while (b > 0) {
        if (b & 1)
            res = mult(res, a, m);
        a = mult(a, a, m);
        b >>= 1;
    }
    return res;
}

// Solves a^x = b (mod m). Returns x, or -1 if no solution.
// Assumes gcd(a, m) = 1.
ll bsgs(ll a, ll b, ll m) {
    a %= m;
    b %= m;
    if (b == 1 || m == 1)
        return 0;
    ll n = (ll)std::sqrt(m) + 1;
    std::map<ll, ll> giant_steps;
```

```
ll an = 1;
for (ll i = 0; i < n; i++)
    an = mult(an, a, m);

for (ll q = 0, cur = b; q <= n; q++) {
    giant_steps[cur] = q;
    cur = mult(cur, a, m);
}

for (ll p = 1, cur = 1; p <= n; p++) {
    cur = mult(cur, an, m);
    if (giant_steps.count(cur)) {
        ll x = p * n - giant_steps[cur];
        if (power(a, x, m) == b)
            return x;
    }
}
return -1;
} // namespace DiscreteLog
#endif
```

4.5. discroot.h

```
#ifndef DISCRETE_ROOT_H
#define DISCRETE_ROOT_H

#include <algorithm>
#include <array>
#include <cmath>
#include <map>
#include <numeric>
#include <vector>

namespace DiscreteRoot {
using ll = long long;
using ull = __int128;
```

```

// --- Core Dependencies ---
inline ll mult(ll a, ll b, ll mod) { return (ll)((u128)a * b % mod); }

ll power(ll a, ll b, ll m) {
    ll res = 1;
    a %= m;
    while (b > 0) {
        if (b & 1)
            res = mult(res, a, m);
        a = mult(a, a, m);
        b >>= 1;
    }
    return res;
}

ll exEuclid(ll a, ll b, ll &x, ll &y) {
    if (b == 0) {
        x = 1;
        y = 0;
        return a;
    }
    ll x1, y1;
    ll d = exEuclid(b, a % b, x1, y1);
    x = y1;
    y = x1 - y1 * (a / b);
    return d;
}

// --- Primality & Factorization Dependencies ---
bool miller_rabin(ll n, int a, ll d, int s) {
    ll x = power(a, d, n);
    if (x == 1 || x == n - 1)
        return true;
    for (int r = 1; r < s; r++) {
        x = mult(x, x, n);
        if (x == n - 1)
            return true;
    }
    return false;
}

bool is_prime(ll n) {
    if (n < 2 || (n % 2 == 0 && n > 2))
        return false;
    if (n == 2 || n == 3)
        return true;
    ll d = n - 1;
    int s = 0;
    while ((d & 1) == 0) {
        d >>= 1;
        s++;
    }
    static const std::array<int, 12> bases = {2, 3, 5, 7, 11,
13, 17, 19, 23, 29, 31,
37};
    for (int a : bases) {
        if (n <= a)
            break;
        if (!miller_rabin(n, a, d, s))
            return false;
    }
    return true;
}

ll brent(ll n, ll x0 = 2, ll c = 1) {
    ll x = x0;
    ll g = 1;
    ll q = 1;
    ll xs, y;

```

```

int m = 128;
int l = 1;
while (g == 1) {
    y = x;
    for (int i = 1; i < l; i++)
        x = (mult(x, x, n) + c) % n;
    int k = 0;
    while (k < l && g == 1) {
        xs = x;
        for (int i = 0; i < m && i < l - k; i++) {
            x = (mult(x, x, n) + c) % n;
            q = mult(q, std::abs(y - x), n);
        }
        g = std::gcd(q, n);
        k += m;
    }
    l *= 2;
}
if (g == n) {
    do {
        xs = (mult(xs, xs, n) + c) % n;
        g = std::gcd(std::abs(xs - y), n);
    } while (g == 1);
}
return g;
}

void factorize_recursive(ll n, std::vector<ll> &factors) {
    if (n == 1)
        return;
    if (is_prime(n)) {
        factors.push_back(n);
        return;
    }
    ll g = n;
    for (ll c = 1; g == n; c++) {
        g = brent(n, 2, c);
    }
    factorize_recursive(g, factors);
    factorize_recursive(n / g, factors);
}

std::vector<ll> factorize(ll n) {
    std::vector<ll> factors;
    factorize_recursive(n, factors);
    std::sort(factors.begin(), factors.end());
    return factors;
}

// --- Primitive Root Dependency ---
ll primitive_root(ll p) {
    if (!is_prime(p))
        return -1;
    ll phi = p - 1;
    std::vector<ll> factors = factorize(phi);
    factors.erase(std::unique(factors.begin(), factors.end()),
    factors.end());
    for (ll g = 2; g <= p; g++) {
        bool ok = true;
        for (ll f : factors) {
            if (power(g, phi / f, p) == 1) {
                ok = false;
                break;
            }
        }
        if (ok)
            return g;
    }
    return -1;
}

// --- Discrete Log Dependency ---

```

```

ll bsgs(ll a, ll b, ll m) {
    a %= m;
    b %= m;
    if (b == 1 || m == 1)
        return 0;
    ll n = (ll)std::sqrt(m) + 1;
    std::map<ll, ll> giant_steps;
    ll an = 1;
    for (ll i = 0; i < n; i++)
        an = mult(an, a, m);
    for (ll q = 0, cur = b; q <= n; q++) {
        giant_steps[cur] = q;
        cur = mult(cur, a, m);
    }
    for (ll p = 1, cur = 1; p <= n; p++) {
        cur = mult(cur, an, m);
        if (giant_steps.count(cur)) {
            ll x = p * n - giant_steps[cur];
            if (power(a, x, m) == b)
                return x;
        }
    }
    return -1;
}

// --- Discrete Root ---
// Solves  $x^k \equiv a \pmod{p}$  for prime p.
ll discrete_root(ll k, ll a, ll p) {
    if (a == 0)
        return 0;
    ll g = primitive_root(p);
    if (g == -1)
        return -1; // Not prime
    ll b = bsgs(g, a, p);
    if (b == -1)
        return -1; // a is not in the group
}

```

```

ll x_0, y_0;
ll d = exEuclid(k, p - 1, x_0, y_0);
if (b % d != 0)
    return -1;
ll x = mult(x_0, b / d, (p - 1) / d);
x = (x % ((p - 1) / d) + ((p - 1) / d)) % ((p - 1) / d);
return power(g, x, p);
}
} // namespace DiscreteRoot
#endif

```

4.6. euler_totient_fxn.h

```

int euler_totient_function(int n) {
    int res = 1;
    for (int i = 2; i * i <= n; i++) {
        if (n % i == 0) {
            int count = 0;
            int val = 1;
            while (n % i == 0) {
                count++;
                val = val * i;
                n = n / i;
            }
            res = res * ((val / i) * (i - 1));
        }
    }
    if (n > 1) {
        res = res * (n - 1);
    }
    return res;
}

```

4.7. factorization.h

```

namespace NT {
using ll = long long;
using u128 = __int128;
}

```

```

inline ll mult(ll a, ll b, ll mod) { return (ll)((u128)a * b % mod); }

ll power(ll a, ll b, ll m) {
    ll res = 1;
    a %= m;
    while (b > 0) {
        if (b & 1)
            res = mult(res, a, m);
        a = mult(a, a, m);
        b >>= 1;
    }
    return res;
}

bool miller_rabin(ll n, int a, ll d, int s) {
    ll x = power(a, d, n);
    if (x == 1 || x == n - 1)
        return true;
    for (int r = 1; r < s; r++) {
        x = mult(x, x, n);
        if (x == n - 1)
            return true;
    }
    return false;
}

// Deterministic Miller-Rabin for 64-bit integers
bool is_prime(ll n) {
    if (n < 2)
        return false;
    if (n == 2 || n == 3)
        return true;
    if (n % 2 == 0 || n % 3 == 0)
        return false;

    ll d = n - 1;
    int s = 0;
    while ((d & 1) == 0) {
        d >>= 1;
        s++;
    }
    static const array<int, 12> bases = {2, 3, 5, 7, 11, 13,
                                             17, 19, 23, 29, 31, 37};
    for (int a : bases) {
        if (n <= a)
            break;
        if (!miller_rabin(n, a, d, s))
            return false;
    }
    return true;
}

ll brent(ll n, ll x0 = 2, ll c = 1) {
    ll x = x0;
    ll g = 1;
    ll q = 1;
    ll xs, y;
    int m = 128;
    int l = 1;
    while (g == 1) {
        y = x;
        for (int i = 1; i < l; i++)
            x = (mult(x, x, n) + c) % n;
        int k = 0;
        while (k < l && g == 1) {
            xs = x;
            for (int i = 0; i < m && i < l - k; i++)
                x = (mult(x, x, n) + c) % n;
            q = mult(q, abs(y - x), n);
        }
        g = gcd(q, n);
    }
}

```

```

        k += m;
    }
    l *= 2;
}
if (g == n) {
    do {
        xs = (mult(xs, xs, n) + c) % n;
        g = gcd(abs(xs - y), n);
    } while (g == 1);
}
return g;
}

void factorize_recursive(ll n, vector<ll> &factors) {
    if (n == 1)
        return;
    // Trial division for small primes can speed up standard
    cases
    if (n < 1000) {
        for (ll p : {2, 3, 5}) {
            while (n % p == 0) {
                factors.push_back(p);
                n /= p;
            }
        }
        if (n == 1)
            return;
    }
    if (is_prime(n)) {
        factors.push_back(n);
        return;
    }
    ll g = n;
    // Retry brent with different params if it fails
    for (ll c = 1; g == n; c++) {
        g = brent(n, 2, c);
    }
}

}
factorize_recursive(g, factors);
factorize_recursive(n / g, factors);
}

// Main function to call
vector<ll> factorize(ll n) {
    vector<ll> factors;
    factorize_recursive(n, factors);
    sort(factors.begin(), factors.end());
    return factors;
}
} // namespace NT

```

4.8. garner.h

```

#ifndef GARNER_H
#define GARNER_H

#include <numeric>
#include <vector>

namespace Garner {
using ll = long long;
using u128 = __int128;

inline ll mult(ll a, ll b, ll mod) { return (ll)((u128)a * b % mod); }

ll exEuclid(ll a, ll b, ll &x, ll &y) {
    if (b == 0) {
        x = 1;
        y = 0;
        return a;
    }
    ll x1, y1;
    ll d = exEuclid(b, a % b, x1, y1);
    x = y1;
    y = x1 - (a / b) * y1;
    return d;
}
}

```

```

x = y1;
y = x1 - y1 * (a / b);
return d;
}

ll modInverse(ll a, ll m) {
    ll x, y;
    ll g = exEuclid(a, m, x, y);
    if (g != 1)
        return -1;
    return (x % m + m) % m;
}

// Solves x = a_i (mod m_i) for *coprime* m_i.
ll garner(const std::vector<ll> &a, const std::vector<ll> &m) {
    int n = a.size();
    std::vector<ll> x(n);
    for (int i = 0; i < n; ++i) {
        x[i] = a[i];
        for (int j = 0; j < i; ++j) {
            ll inv = modInverse(m[j], m[i]);
            x[i] = mult((x[i] - x[j] + m[i]), inv, m[i]);
        }
    }
    ll res = x[n - 1];
    // Use a large prime (e.g., 10^18 + 9) or __int128 for M if
    result overflows
    // ll
    ll M = 1e18 + 9;
    for (int i = n - 2; i >= 0; --i) {
        res = (mult(res, m[i], M) + x[i]) % M;
    }
    return res;
}
} // namespace Garner
#endif

```

4.9. matrix_expo.h

```

int **matrixmul(int **matrix1, int **matrix2) {
    int **matrix3 = new int *[2];
    for (int i = 0; i < 2; i++)
        matrix3[i] = new int[2];

    matrix3[0][0] =
        (matrix1[0][0] * matrix2[0][0]) + (matrix1[0][1] *
matrix2[1][0]);
    matrix3[0][1] =
        (matrix1[0][0] * matrix2[0][1]) + (matrix1[0][1] *
matrix2[1][1]);
    matrix3[1][0] =
        (matrix1[1][0] * matrix2[0][0]) + (matrix1[1][1] *
matrix2[1][0]);
    matrix3[1][1] =
        (matrix1[1][0] * matrix2[0][1]) + (matrix1[1][1] *
matrix2[1][1]);
    matrix3[0][0] %= M;
    matrix3[1][0] %= M;
    matrix3[0][1] %= M;
    matrix3[1][1] %= M;

    return matrix3;
}

int **matrixexpo(int **matrix, int n, int **ans) {
    while (n > 0) {
        if (n % 2 == 1)
            ans = matrixmul(ans, matrix);
        matrix = matrixmul(matrix, matrix);
        n /= 2;
    }
    return ans;
}

```

4.10. montgomery.h

4.11. precompute_divisors.h

```
const int MAX = 1e5;
vector<int> divisor[MAX + 1];
void sieve() {
    for (int i = 1; i <= MAX; ++i) {
        for (int j = i; j <= MAX; j += i)
            divisor[j].push_back(i);
    }
}
```

4.12. primroot.h

```
#ifndef PRIMITIVE_ROOT_H
#define PRIMITIVE_ROOT_H

#include <algorithm>
#include <array>
#include <cmath>
#include <numeric>
#include <vector>

namespace PrimitiveRoot {
using ll = long long;
using ull = __int128;

inline ll mult(ll a, ll b, ll mod) { return ((ull)((ull)a * b % mod)); }

ll power(ll a, ll b, ll m) {
    ll res = 1;
    a %= m;
    while (b > 0) {
        if (b & 1)
```

```
            res = mult(res, a, m);
            a = mult(a, a, m);
            b >>= 1;
    }
    return res;
}

bool miller_rabin(ll n, int a, ll d, int s) {
    ll x = power(a, d, n);
    if (x == 1 || x == n - 1)
        return true;
    for (int r = 1; r < s; r++) {
        x = mult(x, x, n);
        if (x == n - 1)
            return true;
    }
    return false;
}

bool is_prime(ll n) {
    if (n < 2 || (n % 2 == 0 && n > 2))
        return false;
    if (n == 2 || n == 3)
        return true;
    ll d = n - 1;
    int s = 0;
    while ((d & 1) == 0) {
        d >>= 1;
        s++;
    }
    static const std::array<int, 12> bases = {2, 3, 5, 7, 11,
13, 17, 19, 23, 29, 31,
37};
    for (int a : bases) {
        if (n <= a)
```

```

        break;
    if (!miller_rabin(n, a, d, s))
        return false;
}
return true;
}

ll brent(ll n, ll x0 = 2, ll c = 1) {
    ll x = x0;
    ll g = 1;
    ll q = 1;
    ll xs, y;
    int m = 128;
    int l = 1;
    while (g == 1) {
        y = x;
        for (int i = 1; i < l; i++)
            x = (mult(x, x, n) + c) % n;
        int k = 0;
        while (k < l && g == 1) {
            xs = x;
            for (int i = 0; i < m && i < l - k; i++)
                x = (mult(x, x, n) + c) % n;
            q = mult(q, std::abs(y - x), n);
        }
        g = std::gcd(q, n);
        k += m;
    }
    l *= 2;
}
if (g == n) {
    do {
        xs = (mult(xs, xs, n) + c) % n;
        g = std::gcd(std::abs(xs - y), n);
    } while (g == 1);
}
}

        return g;
}

void factorize_recursive(ll n, std::vector<ll> &factors) {
    if (n == 1)
        return;
    if (is_prime(n)) {
        factors.push_back(n);
        return;
    }
    ll g = n;
    for (ll c = 1; g == n; c++) {
        g = brent(n, 2, c);
    }
    factorize_recursive(g, factors);
    factorize_recursive(n / g, factors);
}

std::vector<ll> factorize(ll n) {
    std::vector<ll> factors;
    factorize_recursive(n, factors);
    std::sort(factors.begin(), factors.end());
    return factors;
}

// Finds the smallest primitive root modulo p.
ll primitive_root(ll p) {
    if (!is_prime(p))
        return -1;
    ll phi = p - 1;
    std::vector<ll> factors = factorize(phi);
    factors.erase(std::unique(factors.begin(), factors.end()), factors.end());
    for (ll g = 2; g <= p; g++) {
        bool ok = true;
        for (ll f : factors) {

```

```

    if (power(g, phi / f, p) == 1) {
        ok = false;
        break;
    }
    if (ok)
        return g;
}
return -1;
}
} // namespace PrimitiveRoot
#endif

```

4.13. some_dp.h

```

// LIS
int lis(vector<int> const &a) {
    int n = a.size();
    const int INF = 1e9;
    vector<int> d(n + 1, INF);
    d[0] = -INF;

    for (int i = 0; i < n; i++) {
        int l = upper_bound(d.begin(), d.end(), a[i]) - d.begin();
        if (d[l - 1] < a[i] && a[i] < d[l])
            d[l] = a[i];
    }

    int ans = 0;
    for (int l = 0; l <= n; l++) {
        if (d[l] < INF)
            ans = l;
    }
    return ans;
}
// or segtree lol

```

4.14. spf.h

```

int MX = 1e7 + 1;
vi spf(MX + 1, INT32_MAX);
vector<int> is_prime(MX + 1, 1);
void sieve(int n = MX) {
    is_prime[0] = is_prime[1] = 0;
    int cnt = 1;
    for (int i = 2; i <= n; i++) {
        if (is_prime[i]) {
            for (int j = i * i; j <= n; j += i) {
                is_prime[j] = 0;
                spf[j] = min(i, spf[j]);
            }
            is_prime[i] = cnt;
            cnt++;
        }
    }
    return;
}

```

5. Strings

5.1. Trie.h

```

class TrieNode {
public:
    unordered_map<char, TrieNode *> children;
    bool isEndOfWord;

    TrieNode() : isEndOfWord(false) {}
};

class Trie {
private:
    TrieNode *root;

public:
    Trie() { root = new TrieNode(); }

```

```

void insert(const string &word) {
    TrieNode *node = root;
    for (char ch : word) {
        if (node->children.find(ch) == node->children.end()) {
            node->children[ch] = new TrieNode();
        }
        node = node->children[ch];
    }
    node->isEndOfWord = true;
}
bool search(const string &word) {
    TrieNode *node = root;
    for (char ch : word) {
        if (node->children.find(ch) == node->children.end()) {
            return false;
        }
        node = node->children[ch];
    }
    return node->isEndOfWord;
}
bool startsWith(const string &prefix) {
    TrieNode *node = root;
    for (char ch : prefix) {
        if (node->children.find(ch) == node->children.end()) {
            return false;
        }
        node = node->children[ch];
    }
    return true;
}

```

5.2. ahocorasick.h

```

class AhoCorasick {
public:
    static const int K = 26;

```

```

struct Vertex {
    int next[K];
    int p = -1;
    char pch;
    int link = -1;
    int go[K];
    vector<int> out; // pattern indices that end here

    Vertex(int p = -1, char ch = '$') : p(p), pch(ch) {
        fill(begin(next), end(next), -1);
        fill(begin(go), end(go), -1);
    }
};

vector<Vertex> t;
int pattern_count = 0; // next pattern id to assign

AhoCorasick() {
    t.emplace_back(); // root vertex (index 0)
}

// add a lowercase 'a'...'z' pattern, returns its pattern
index (0-based)
int add_string(const string &s) {
    int v = 0;
    for (char ch : s) {
        int c = ch - 'a';
        if (c < 0 || c >= K)
            throw runtime_error("patterns must be lowercase a-z");
        if (t[v].next[c] == -1) {
            t[v].next[c] = (int)t.size();
            t.emplace_back(v, ch);
        }
        v = t[v].next[c];
    }
}

```

```

        int id = pattern_count++;
        t[v].out.push_back(id);
        return id;
    }

    // returns vector of (text_index, patternIndex) pairs for
    // every match
    vector<pair<int, int>> search(const string &text) {
        vector<pair<int, int>> res;
        int v = 0;
        for (int i = 0; i < (int)text.size(); ++i) {
            char ch = text[i];
            if (ch < 'a' || ch > 'z') {
                // reset on invalid char (same behaviour as before)
                v = 0;
                continue;
            }
            v = go(v, ch);

            // follow output/link chain to collect matches
            for (int u = v; u != 0; u = get_link(u)) {
                for (int patId : t[u].out) {
                    res.emplace_back(i, patId);
                }
            }
            // optionally check root outputs (only relevant if you
            inserted empty
            // pattern)
            for (int patId : t[0].out) {
                res.emplace_back(i, patId);
            }
        }
        return res;
    }

    int get_link(int v) {

```

```

        if (t[v].link == -1) {
            if (v == 0 || t[v].p == 0)
                t[v].link = 0;
            else
                t[v].link = go(get_link(t[v].p), t[v].pch);
        }
        return t[v].link;
    }

    int go(int v, char ch) {
        int c = ch - 'a';
        if (t[v].go[c] == -1) {
            if (t[v].next[c] != -1)
                t[v].go[c] = t[v].next[c];
            else
                t[v].go[c] = v == 0 ? 0 : go(get_link(v), ch);
        }
        return t[v].go[c];
    };

```

5.3. expression_parsing.h

```

bool delim(char c) { return c == ' ' ; }

bool is_op(char c) { return c == '+' || c == '-' || c == '*' ||
c == '/'; }

bool is_unary(char c) { return c == '+' || c == '-' ; }

int priority(char op) {
    if (op < 0) // unary operator
        return 3;
    if (op == '+' || op == '-')
        return 1;
    if (op == '*' || op == '/')
        return 2;

```

```

    return -1;
}

void process_op(stack<int> &st, char op) {
    if (op < 0) {
        int l = st.top();
        st.pop();
        switch (-op) {
            case '+':
                st.push(l);
                break;
            case '-':
                st.push(-l);
                break;
        }
    } else {
        int r = st.top();
        st.pop();
        int l = st.top();
        st.pop();
        switch (op) {
            case '+':
                st.push(l + r);
                break;
            case '-':
                st.push(l - r);
                break;
            case '*':
                st.push(l * r);
                break;
            case '/':
                st.push(l / r);
                break;
        }
    }
}

int evaluate(string &s) {
    stack<int> st;
    stack<char> op;
    bool may_be_unary = true;
    for (int i = 0; i < (int)s.size(); i++) {
        if (delim(s[i]))
            continue;

        if (s[i] == '(') {
            op.push('(');
            may_be_unary = true;
        } else if (s[i] == ')') {
            while (op.top() != '(') {
                process_op(st, op.top());
                op.pop();
            }
            op.pop();
            may_be_unary = false;
        } else if (is_op(s[i])) {
            char cur_op = s[i];
            if (may_be_unary && is_unary(cur_op))
                cur_op = -cur_op;
            while (!op.empty() &&
                   ((cur_op >= 0 && priority(op.top()) >=
                     priority(cur_op)) ||
                    (cur_op < 0 && priority(op.top()) >
                     priority(cur_op)))) {
                process_op(st, op.top());
                op.pop();
            }
            op.push(cur_op);
            may_be_unary = true;
        } else {
            int number = 0;
            while (i < (int)s.size() && isalnum(s[i]))

```

```

        number = number * 10 + s[i++]- '0';
        --i;
        st.push(number);
        may_be_unary = false;
    }
}

while (!op.empty()) {
    process_op(st, op.top());
    op.pop();
}
return st.top();
}

5.4. finding_repetitions.h

vector<int> z_function(string const &s) {
    int n = s.size();
    vector<int> z(n);
    for (int i = 1, l = 0, r = 0; i < n; i++) {
        if (i <= r)
            z[i] = min(r - i + 1, z[i - l]);
        while (i + z[i] < n && s[z[i]] == s[i + z[i]])
            z[i]++;
        if (i + z[i] - 1 > r) {
            l = i;
            r = i + z[i] - 1;
        }
    }
    return z;
}

int get_z(vector<int> const &z, int i) {
    if (0 <= i && i < (int)z.size())
        return z[i];
    else
        return 0;
}

}
vector<pair<int, int>> repetitions;

void convert_to_repetitions(int shift, bool left, int cntr, int l, int k1,
                           int k2) {
    for (int l1 = max(l, l - k2); l1 <= min(l, k1); l1++) {
        if (left && l1 == l)
            break;
        int l2 = l - l1;
        int pos = shift + (left ? cntr - l1 : cntr - l - l1 + 1);
        repetitions.emplace_back(pos, pos + 2 * l - 1);
    }
}

void find_repetitions(string s, int shift = 0) {
    int n = s.size();
    if (n == 1)
        return;

    int nu = n / 2;
    int nv = n - nu;
    string u = s.substr(0, nu);
    string v = s.substr(nu);
    string ru(u.rbegin(), u.rend());
    string rv(v.rbegin(), v.rend());

    find_repetitions(u, shift);
    find_repetitions(v, shift + nu);

    vector<int> z1 = z_function(ru);
    vector<int> z2 = z_function(v + '#' + u);
    vector<int> z3 = z_function(ru + '#' + rv);
    vector<int> z4 = z_function(v);
}

```

```

for (int cntr = 0; cntr < n; cntr++) {
    int l, k1, k2;
    if (cntr < nu) {
        l = nu - cntr;
        k1 = get_z(z1, nu - cntr);
        k2 = get_z(z2, nv + 1 + cntr);
    } else {
        l = cntr - nu + 1;
        k1 = get_z(z3, nu + 1 + nv - 1 - (cntr - nu));
        k2 = get_z(z4, (cntr - nu) + 1);
    }
    if (k1 + k2 >= l)
        convert_to_repetitions(shift, cntr < nu, cntr, l, k1,
        k2);
}
}

```

5.5. hash.h

```

template <int MOD, int P> struct RH {
    // using H1 = RH<1000000007, 91138233>;
    // using H2 = RH<1000000009, 97266353>;
    vector<long long> h, p;
    RH(const string &s) {
        int n = s.size();
        h.resize(n + 1, 0);
        p.resize(n + 1, 0);
        p[0] = 1;
        for (int i = 0; i < n; i++) {
            h[i + 1] = (h[i] * P + s[i]) % MOD;
            p[i + 1] = p[i] * P % MOD;
        }
    }
    long long get(int l, int r) { // [l,r]
        long long res = (h[r + 1] - h[l] * p[r - l + 1]) % MOD;
        return res < 0 ? res + MOD : res;
    }
}

```

```

    }
};


```

5.6. kmp.h

```

vector<int> prefix_function(string s) {
    int n = (int)s.length();
    vector<int> pi(n);
    for (int i = 1; i < n; i++) {
        int j = pi[i - 1];
        while (j > 0 && s[i] != s[j])
            j = pi[j - 1];
        if (s[i] == s[j])
            j++;
        pi[i] = j;
    }
    return pi;
}

```

```

vector<int> KMP(string text, string pattern) {
    string s = pattern + "#" + text;
    vector<int> pi = prefix_function(s);
    vector<int> matches;
    int p = pattern.length();

    for (int i = 0; i < s.length(); i++) {
        if (pi[i] == p) {
            int match_pos = i - 2 * p;
            matches.push_back(match_pos); // 0-based index in text
        }
    }
    return matches;
}

```

5.7. longest_common_prefix.h

```

#include <bits/stdc++.h>
using namespace std;

```

```

// --- suffix array (sort_cyclic_shifts + suffix_array) ---
vector<int> sort_cyclic_shifts(const string &a) {
    int n = a.size();
    const int alphabet = 256;

    vector<int> p(n), c(n);
    vector<int> cnt(max(alphabet, n), 0);

    for (int i = 0; i < n; i++)
        cnt[(unsigned char)a[i]]++;
    for (int i = 1; i < alphabet; i++)
        cnt[i] = cnt[i - 1] + cnt[i];
    for (int i = n - 1; i >= 0; i--)
        p[--cnt[(unsigned char)a[i]]] = i;

    c[p[0]] = 0;
    int classes = 1;
    for (int i = 1; i < n; i++) {
        if (a[p[i]] != a[p[i - 1]])
            classes++;
        c[p[i]] = classes - 1;
    }

    for (int h = 0; (1 << h) < n; h++) {
        vector<int> pn(n), cn(n);
        for (int i = 0; i < n; i++) {
            pn[i] = p[i] - (1 << h);
            if (pn[i] < 0)
                pn[i] += n;
        }
        fill(cnt.begin(), cnt.begin() + classes, 0);
        for (int i = 0; i < n; i++)
            cnt[c[pn[i]]]++;
        for (int i = 1; i < classes; i++)
            cnt[i] += cnt[i - 1];
    }
}

```

```

for (int i = n - 1; i >= 0; i--)
    p[--cnt[c[pn[i]]]] = pn[i];

cn[p[0]] = 0;
classes = 1;
for (int i = 1; i < n; i++) {
    pair<int, int> cur = {c[p[i]], c[(p[i] + (1 << h)) % n]};
    pair<int, int> prev = {c[p[i - 1]], c[(p[i - 1] + (1 << h)) % n]};
    if (cur != prev)
        classes++;
    cn[p[i]] = classes - 1;
}
c.swap(cn);

return p;
}

vector<int> suffix_array(string s) {
    s += '$';
    vector<int> sorted_shifts = sort_cyclic_shifts(s);
    // remove sentinel position
    sorted_shifts.erase(sorted_shifts.begin());
    return sorted_shifts;
}

// --- Kasai LCP construction ---
vector<int> lcp_construction(const string &s, const vector<int> &p) {
    int n = (int)s.size();
    vector<int> rank(n, 0);
    for (int i = 0; i < n; i++)
        rank[p[i]] = i;

    int k = 0;
}
```

```

vector<int> lcp(max(0, n - 1), 0);
for (int i = 0; i < n; i++) {
    if (rank[i] == n - 1) {
        k = 0;
        continue;
    }
    int j = p[rank[i] + 1];
    while (i + k < n && j + k < n && s[i + k] == s[j + k])
        k++;
    lcp[rank[i]] = k;
    if (k)
        k--;
}
return lcp;
}

// --- helpers: rank from SA and sparse table (RMQ) over lcp[]
---

vector<int> build_rank_from_sa(const vector<int> &p) {
    int n = (int)p.size();
    vector<int> rank(n, 0);
    for (int i = 0; i < n; ++i)
        rank[p[i]] = i;
    return rank;
}

vector<vector<int>> build_rmq(const vector<int> &lcp) {
    int m = (int)lcp.size();
    if (m == 0)
        return {};
    int LOG = 1;
    while ((1 << LOG) <= m)
        ++LOG;
    vector<vector<int>> st(LOG, vector<int>(m));
    st[0] = lcp;
    for (int k = 1; k < LOG; ++k) {
        int len = 1 << k;
        for (int i = 0; i + len <= m; ++i) {
            st[k][i] = min(st[k - 1][i], st[k - 1][i + (len >> 1)]);
        }
    }
    return st;
}

int rmq_query(const vector<vector<int>> &st, int l, int r) {
    if (st.empty())
        return 0;
    int len = r - l + 1;
    int k = 31 - __builtin_clz(len);
    return min(st[k][l], st[k][r - (1 << k) + 1]);
}

// --- LCP class ---
struct LCP {
    string s;
    int n = 0;
    vector<int> sa;           // suffix array
    vector<int> lcp;          // kasai lcp array (size n-1)
    vector<int> rank;         // rank[i] = position of suffix i in
    sa
    vector<vector<int>> st; // sparse table on lcp[]

    // construct from a string (builds SA, LCP, rank and RMQ)
    LCP(const string &str = "") {
        if (!str.empty())
            build(str);
    }

    void build(const string &str) {
        s = str;
        n = (int)s.size();
        if (n == 0) {

```

```

    sa.clear();
    lcp.clear();
    rank.clear();
    st.clear();
    return;
}
sa = suffix_array(s);           // size n
lcp = lcp_construction(s, sa); // size n-1 (or 0 if n==1)
rank = build_rank_from_sa(sa);
st = build_rmq(lcp);
}

// answer LCP of suffixes starting at i and j (0-indexed
positions in original
// string)
int query(int i, int j) const {
    if (i < 0 || j < 0 || i >= n || j >= n)
        return 0; // invalid -> 0
    if (i == j)
        return n - i; // full suffix matches itself
    int ri = rank[i], rj = rank[j];
    if (ri > rj)
        swap(ri, rj);
    // LCP of suffixes at sa[ri] and sa[rj] is min over
    lcp[ri..rj-1]
    return rmq_query(st, ri, rj - 1);
}

// -----
// Number of different substrings
// -----
// Explanation:
// For a string of length n, total number of substrings
//(including duplicates)
// is:
//   total = n * (n + 1) / 2
// When suffixes are sorted (by SA), each suffix p[i]
contributes
//   (n - p[i]) - lcp[i-1]
// new distinct substrings (prefixes that weren't counted
earlier).
// Summing over i gives:
//
// distinct = sum_{i=0..n-1} (n - p[i]) - sum_{i=0..n-2}
lcp[i]
// which simplifies to:
// distinct = n*(n+1)/2 - sum_{i=0..n-2} lcp[i]
//
// We implement the compact formula below:
long long distinct_substrings() const {
    if (n == 0)
        return 0;
    long long total = 1LL * n * (n + 1) / 2;
    long long sum_lcp = 0;
    for (int v : lcp)
        sum_lcp += v;
    return total - sum_lcp;
}

// optional accessors
const vector<int> &get_sa() const { return sa; }
const vector<int> &get_lcp_array() const { return lcp; }
};

5.8. manacher.h
vector<int> manacher_odd(string s) {
    int n = s.size();
    s = "$" + s + "^";
    vector<int> p(n + 2);
    int l = 0, r = 1;
    for (int i = 1; i <= n; i++) {

```

```

    p[i] = min(r - i, p[l + (r - i)]);
    while (s[i - p[i]] == s[i + p[i]]) {
        p[i]++;
    }
    if (i + p[i] > r) {
        l = i - p[i];
        r = i + p[i];
    }
}
return vector<int>(begin(p) + 1, end(p) - 1);
}

// gives a vector of size 2*n - 1 each element of which gives
// the length of
// longest palindrome centred at ith location
// if i is even(0,2,4 .. etc.) center is an element -> odd
// palindromes
// and if i is odd(1, 3, 5 .. etc.) center is between two
// elements -> even
// palindromes
vector<int> manacher(string s) {
    string t;
    for (auto c : s) {
        t += string("#") + c;
    }
    auto res = manacher_odd(t + "#");
    for (auto &e : res) {
        e = e - 1;
    }
    return vector<int>(begin(res) + 1, end(res) - 1);
}

```

5.9. prefix_func.h

```

vector<int> prefix_function(const string &s) {
    int n = (int)s.size();
    vector<int> pi(n);

```

```

for (int i = 1; i < n; ++i) {
    int j = pi[i - 1];
    while (j > 0 && s[i] != s[j])
        j = pi[j - 1];
    if (s[i] == s[j])
        ++j;
    pi[i] = j;
}
return pi;
}

vector<int> prefix_function_int(const vector<long long> &v) {
    int n = (int)v.size();
    vector<int> pi(n);
    for (int i = 1; i < n; ++i) {
        int j = pi[i - 1];
        while (j > 0 && v[i] != v[j])
            j = pi[j - 1];
        if (v[i] == v[j])
            ++j;
        pi[i] = j;
    }
    return pi;
}

```

5.10. suffix_array.h

```

vector<int> sort_cyclic_shifts(const string &a) {
    int n = a.size();
    const int alphabet = 256;

    vector<int> p(n), c(n);
    vector<int> cnt(max(alphabet, n), 0);

    // initial sort for h = 0
    for (int i = 0; i < n; i++)
        cnt[(unsigned char)a[i]]++;

```

```

for (int i = 1; i < alphabet; i++)
    cnt[i] = cnt[i - 1] + cnt[i];
for (int i = n - 1; i >= 0; i--)
    p[~cnt[(unsigned char)a[i]]] = i;

c[p[0]] = 0;
int classes = 1;
for (int i = 1; i < n; i++) {
    if (a[p[i]] != a[p[i - 1]])
        classes++;
    c[p[i]] = classes - 1;
}

for (int h = 0; (1 << h) < n; h++) {
    vector<int> pn(n), cn(n);

    // first we are sorting on the basis of second half ...
    for (int i = 0; i < n; i++) {
        pn[i] = p[i] - (1 << h);
        if (pn[i] < 0)
            pn[i] += n;
    }

    // now we sort on the base of first half ... (stable
    // counting sort)
    fill(cnt.begin(), cnt.begin() + classes, 0);
    for (int i = 0; i < n; i++)
        cnt[c[pn[i]]]++;
    for (int i = 1; i < classes; i++)
        cnt[i] += cnt[i - 1];
    for (int i = n - 1; i >= 0; i--)
        p[~cnt[c[pn[i]]]] = pn[i];

    // now we evaluate new classes
    cn[p[0]] = 0;
    classes = 1;
}

```

```

for (int i = 1; i < n; i++) {
    pair<int, int> cur = {c[p[i]], c[(p[i] + (1 << h)) % n]};
    pair<int, int> prev = {c[p[i - 1]], c[(p[i - 1] + (1 <<
h)) % n]};
    if (cur != prev)
        classes++;
    cn[p[i]] = classes - 1;
}
cn.swap(cn);

return p;
}

vector<int> suffix_array(string s) {
    s += '$';
    vector<int> sorted_shifts = sort_cyclic_shifts(s);
    // remove sentinel position
    sorted_shifts.erase(sorted_shifts.begin());
    return sorted_shifts;
}

```

5.11. z_func.h

```

vector<int> z_function(const string &s) {
    int n = (int)s.size();
    if (n == 0)
        return {};
    vector<int> z(n, 0);
    int l = 0, r = 0;
    for (int i = 1; i < n; ++i) {
        if (i <= r)
            z[i] = min(r - i + 1, z[i - l]);
        while (i + z[i] < n && s[z[i]] == s[i + z[i]])
            ++z[i];
        if (i + z[i] - 1 > r) {
            l = i;
            r = i + z[i] - 1;
        }
    }
}

```

```

        r = i + z[i] - 1;
    }
}
return z;
}

vector<int> z_function_int(const vector<long long> &v) {
    int n = (int)v.size();
    if (n == 0)
        return {};
    vector<int> z(n, 0);
    int l = 0, r = 0;
    for (int i = 1; i < n; ++i) {
        if (i <= r)
            z[i] = min(r - i + 1, z[i - l]);
        while (i + z[i] < n && v[z[i]] == v[i + z[i]])
            ++z[i];
        if (i + z[i] - 1 > r) {
            l = i;
            r = i + z[i] - 1;
        }
    }
    return z;
}

```

6. DP

6.1. edit_distance.h

```

int edit_distance(string a, string b) {
    int n = a.size(), m = b.size();
    vector<int> dp(m + 1), ndp(m + 1);
    iota(dp.begin(), dp.end(), 0);
    for (int i = 1; i <= n; i++) {
        ndp[0] = i;
        for (int j = 1; j <= m; j++)
            ndp[j] = a[i - 1] == b[j - 1] ? dp[j - 1]
                                            : 1 + min({dp[j - 1],

```

```

                                            : 1 + min({dp[j - 1],
dp[j], ndp[j - 1]}));
            swap(dp, ndp);
        }
        return dp[m];
    }
}

```

6.2. lcs.h

```

int lcs(string a, string b) {
    int n = a.size(), m = b.size();
    vector<vector<int>> dp(n + 1, vector<int>(m + 1, 0));
    for (int i = 1; i <= n; i++)
        for (int j = 1; j <= m; j++)
            dp[i][j] = a[i - 1] == b[j - 1] ? 1 + dp[i - 1][j - 1]
                                              : max(dp[i - 1][j], dp[i]
                                              [j - 1]);
    return dp[n][m];
}

```

6.3. sos_dp.h

```

// SOS DP: f[mask] = sum of f[submask] for all submask ⊆ mask
void sos_dp(vector<long long> &f, int n) {
    for (int i = 0; i < n; i++)
        for (int mask = 0; mask < (1 << n); mask++)
            if (mask & (1 << i))
                f[mask] += f[mask ^ (1 << i)];
}

```

```

// SOSU DP: f[mask] = sum of f[supmask] for all supmask ⊇ mask
void sosu_dp(vector<long long> &f, int n) {
    for (int i = 0; i < n; i++)
        for (int mask = 0; mask < (1 << n); mask++)
            if (!(mask & (1 << i)))
                f[mask] += f[mask | (1 << i)];
}

```

6.4. subset_sum.h

```
int subset_sum(vector<int> &a, int sum) {
    vector<int> dp(sum + 1, 0);
    dp[0] = 1;
    for (int x : a)
        for (int s = sum; s >= x; s--)
            dp[s] += dp[s - x];
    return dp[sum];
}
```

7. Geometry

7.1. all.h

```
#ifndef GEOMETRY_H
#define GEOMETRY_H

#include <algorithm>
#include <cmath>
#include <iostream>
#include <vector>

using namespace std;

typedef long double ld;
const ld EPS = 1e-9;
const ld PI = acos(-1.0);

inline int sign(ld x) { return (x > EPS) - (x < -EPS); }
inline ld sq(ld x) { return x * x; }

struct P {
    ld x, y;
    P(ld x = 0, ld y = 0) : x(x), y(y) {}
    P operator+(const P &o) const { return P(x + o.x, y + o.y); }
    P operator-(const P &o) const { return P(x - o.x, y - o.y); }
    P operator*(ld s) const { return P(x * s, y * s); }
```

```
P operator/(ld s) const { return P(x / s, y / s); }
ld dot(const P &o) const { return x * o.x + y * o.y; }
ld cross(const P &o) const { return x * o.y - y * o.x; }
ld dist2() const { return x * x + y * y; }
ld dist() const { return sqrt(dist2()); }
P rotate(ld ang) const {
    return P(x * cos(ang) - y * sin(ang), x * sin(ang) + y * cos(ang));
}
P perp() const { return P(-y, x); }
P unit() const { return *this / dist(); }
bool operator<(const P &o) const {
    return sign(x - o.x) != 0 ? x < o.x : sign(y - o.y) < 0;
}
bool operator==(const P &o) const {
    return sign(x - o.x) == 0 && sign(y - o.y) == 0;
}
friend ostream &operator<<(ostream &os, const P &p) {
    return os << "(" << p.x << ", " << p.y << ")";
};

ld cross(P a, P b, P c) { return (b - a).cross(c - a); }

struct Line {
    ld a, b, c; // ax + by = c
    Line(ld a, ld b, ld c) : a(a), b(b), c(c) {}
    Line(P p1, P p2) : a(p1.y - p2.y), b(p2.x - p1.x), c(a * p1.x
+ b * p1.y) {}
    ld eval(P p) const { return a * p.x + b * p.y - c; }
    ld norm2() const { return a * a + b * b; }
    bool parallel(const Line &o) const { return sign(a * o.b -
o.a * b) == 0; }
    bool intersect(const Line &o, P &res) const {
        ld det = a * o.b - o.a * b;
        if (sign(det) == 0)
```

```

    return false;
res.x = (c * o.b - o.c * b) / det;
res.y = (a * o.c - o.a * c) / det;
return true;
}
ld dist(P p) const { return abs(eval(p)) / sqrt(norm2()); }
P proj(P p) const {
    ld d = eval(p) / norm2();
    return P(p.x - a * d, p.y - b * d);
}
P refl(P p) const { return proj(p) * 2 - p; }
};

struct Seg {
P s, e;
Seg(P s, P e) : s(s), e(e) {}
Line to_line() const { return Line(s, e); }
bool on_seg(P p) const {
    return sign(cross(s, e, p)) == 0 && sign((p - s).dot(p -
e)) <= 0;
}
ld dist(P p) const {
    if ((p - s).dot(e - s) < 0)
        return (p - s).dist();
    if ((p - e).dot(s - e) < 0)
        return (p - e).dist();
    return to_line().dist(p);
}
};

ld area(const vector<P> &p) {
    ld a = 0;
    for (int i = 0; i < p.size(); i++)
        a += p[i].cross(p[(i + 1) % p.size()]);
    return a / 2.0;
}

bool is_convex(const vector<P> &p) {
    bool has_pos = false, has_neg = false;
    for (int i = 0; i < p.size(); i++) {
        int o = sign(cross(p[i], p[(i + 1) % p.size()], p[(i + 2) %
p.size()])));
        if (o > 0)
            has_pos = true;
        if (o < 0)
            has_neg = true;
    }
    return !(has_pos && has_neg);
}

int in_poly(const vector<P> &p, P pt) { // 1: in, -1: on, 0:
out
    bool in = false;
    for (int i = 0; i < p.size(); i++) {
        P a = p[i] - pt, b = p[(i + 1) % p.size()] - pt;
        if (a.y > b.y)
            swap(a, b);
        if (sign(a.cross(b)) == 0 && sign(a.dot(b)) <= 0)
            return -1;
        if (a.y <= 0 && b.y > 0 && sign(a.cross(b)) > 0)
            in = !in;
    }
    return in;
}

vector<P> convex_hull(vector<P> pts) {
    if (pts.size() <= 2)
        return pts;
    sort(pts.begin(), pts.end());
    vector<P> h;
    for (int i = 0; i < 2; i++) {
        int start = h.size();

```

```

        for (auto &pt : pts) {
            while (h.size() >= start + 2 && cross(h[h.size() - 2],
h.back(), pt) <= 0)
                h.pop_back();
            h.push_back(pt);
        }
        h.pop_back();
        reverse(pts.begin(), pts.end());
    }
    return h;
}

struct Circle {
    P c;
    ld r;
    bool in(P p) { return sign((p - c).dist() - r) <= 0; }
    int intersect(Line l, vector<P> &res) {
        ld d = l.dist(c);
        if (sign(d - r) > 0)
            return 0;
        P p = l.proj(c);
        if (sign(d - r) == 0) {
            res.push_back(p);
            return 1;
        }
        P dir = P(l.b, -l.a).unit();
        ld h = sqrt(max((ld)0.0, r * r - d * d));
        res.push_back(p + dir * h);
        res.push_back(p - dir * h);
        return 2;
    }
};

#endif

```

8. Math

8.1. fft.h

```

#ifndef FFT_H
#define FFT_H

#include <algorithm>
#include <cmath>
#include <complex>
#include <vector>

typedef std::complex<double> cd;
const double PI = std::acos(-1);

void fft(std::vector<cd> &a, bool invert) {
    int n = a.size();
    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        for (; j & bit; bit >= 1)
            j ^= bit;
        j ^= bit;
        if (i < j)
            std::swap(a[i], a[j]);
    }
    for (int len = 2; len <= n; len <= 1) {
        double ang = 2 * PI / len * (invert ? -1 : 1);
        cd wlen(std::cos(ang), std::sin(ang));
        for (int i = 0; i < n; i += len) {
            cd w(1);
            for (int j = 0; j < len / 2; j++) {
                cd u = a[i + j], v = a[i + j + len / 2] * w;
                a[i + j] = u + v;
                a[i + j + len / 2] = u - v;
                w *= wlen;
            }
        }
    }
}

```

```

}

if (invert)
    for (cd &x : a)
        x /= n;
}

std::vector<long long> poly_multiply(const std::vector<long
                                         long> &a,
                                         const std::vector<long
                                         long> &b) {
    std::vector<cd> fa(a.begin(), a.end()), fb(b.begin(),
b.end());
    int n = 1;
    while (n < a.size() + b.size())
        n <= 1;
    fa.resize(n);
    fb.resize(n);

    fft(fa, false);
    fft(fb, false);
    for (int i = 0; i < n; i++)
        fa[i] *= fb[i];
    fft(fa, true);

    std::vector<long long> result(n);
    for (int i = 0; i < n; i++)
        result[i] = (long long)std::round(fa[i].real());
    while (result.size() > 1 && result.back() == 0)
        result.pop_back();
    return result;
}

#endif

```

8.2. gauss.h

```

#ifndef ICPC_SLAE_H
#define ICPC_SLAE_H

#include <algorithm>
#include <climits>
#include <cmath>
#include <vector>

namespace cp_algo {

using Real = double;
constexpr Real EPS = 1e-9;
constexpr int INF_SOLS = INT_MAX;

int solve_slae(std::vector<std::vector<Real>> &a,
std::vector<Real> &ans) {
    if (a.empty())
        return 0;
    int n = (int)a.size();
    int m = (int)a[0].size() - 1;

    std::vector<int> where(m, -1);
    int row = 0;
    for (int col = 0; col < m && row < n; ++col) {
        int sel = row;
        for (int i = row; i < n; ++i) {
            if (std::abs(a[i][col]) > std::abs(a[sel][col]))
                sel = i;
        }
        if (std::abs(a[sel][col]) < EPS)
            continue;

        std::swap(a[sel], a[row]);
        where[col] = row;
    }
}

```

```

Real div = a[row][col];
for (int j = col; j <= m; ++j)
    a[row][j] /= div;

for (int i = 0; i < n; ++i) {
    if (i != row) {
        Real mult = a[i][col];
        for (int j = col; j <= m; ++j)
            a[i][j] -= mult * a[row][j];
    }
}
++row;
}

ans.assign(m, 0);
for (int j = 0; j < m; ++j) {
    if (where[j] != -1)
        ans[j] = a[where[j]][m];
}

for (int i = 0; i < n; ++i) {
    Real sum = 0;
    for (int j = 0; j < m; ++j)
        sum += ans[j] * a[i][j];
    if (std::abs(sum - a[i][m]) > EPS)
        return 0;
}

for (int j = 0; j < m; ++j) {
    if (where[j] == -1)
        return INF_SOLS;
}

return 1;
}

```

```

} // namespace cp_algo
#endif

```

8.3. ntt.h

```

#ifndef NTT_H
#define NTT_H

#include <algorithm> // For std::swap
#include <iostream>
#include <vector>

namespace NTT {

using ll = long long;

const ll MOD = 998244353;
const ll ROOT = 3;

ll power(ll a, ll p) {
    ll res = 1;
    a %= MOD;
    while (p > 0) {
        if (p & 1)
            res = (res * a) % MOD;
        a = (a * a) % MOD;
        p >>= 1;
    }
    return res;
}

ll modInverse(ll a) { return power(a, MOD - 2); }

void ntt(std::vector<ll> &a, bool invert) {
    int n = a.size();
    if (n == 1)

```

```

    return;

for (int i = 1, j = 0; i < n; i++) {
    int bit = n >> 1;
    for (; j & bit; bit >= 1) {
        j ^= bit;
    }
    j ^= bit;
    if (i < j) {
        std::swap(a[i], a[j]);
    }
}

for (int len = 2; len <= n; len <= 1) {
    ll wlen = power(ROOT, (MOD - 1) / len);
    if (invert) {
        wlen = modInverse(wlen);
    }
    for (int i = 0; i < n; i += len) {
        ll w = 1;
        for (int j = 0; j < len / 2; j++) {
            ll u = a[i + j];
            ll v = (a[i + j + len / 2] * w) % MOD;
            a[i + j] = (u + v) % MOD;
            a[i + j + len / 2] = (u - v + MOD) % MOD;
            w = (w * wlen) % MOD;
        }
    }
}

if (invert) {
    ll n_inv = modInverse(n);
    for (ll &x : a) {
        x = (x * n_inv) % MOD;
    }
}
}

std::vector<ll> poly_multiply_ntt(std::vector<ll> a,
std::vector<ll> b) {
    int res_size = a.size() + b.size() - 1;
    int n = 1;
    while (n < res_size) {
        n <= 1;
    }
    a.resize(n);
    b.resize(n);

    ntt(a, false);
    ntt(b, false);

    for (int i = 0; i < n; i++) {
        a[i] = (a[i] * b[i]) % MOD;
    }

    ntt(a, true);

    a.resize(res_size); // Truncate to the correct polynomial
size
    return a;
}

} // namespace NTT

#endif // NTT_H

```

9. Misc

9.1. countinversions.h

```
ll count_inversion(vector<ll> &a) {
```

```

int n = a.size();
vector<ll> tmp(n);
function<ll(int, int)> ms = [&](int l, int r) -> ll {
    if (r - l <= 1)
        return 0;
    int m = (l + r) / 2;
    ll inv = ms(l, m) + ms(m, r);
    int i = l, j = m, k = l;
    while (i < m || j < r) {
        if (j == r || (i < m && a[i] <= a[j]))
            tmp[k++] = a[i++];
        else {
            tmp[k++] = a[j++];
            inv += m - i;
        }
    }
    for (int t = l; t < r; ++t)
        a[t] = tmp[t];
    return inv;
};
return ms(0, n);
}

```

9.2. lis.h

```

int LIS(vector<int> &a) {
    vector<int> v;
    for (int x : a) {
        auto it = lower_bound(v.begin(), v.end(), x);
        if (it == v.end())
            v.push_back(x);
        else
            *it = x;
    }
    return (int)v.size();
}

```

10. Tricks

10.1. geom.h

Basic Utilities

EPS-based floating point comparisons (sign).

Square function (sq).

2D Points / Vectors (struct P)

Vector arithmetic (+, -, *, /).

Dot and Cross products.

Distance calculations (dist, dist2).

Rotation (rotate) and Perpendicular vector (perp).

Unit vector normalization (unit).

Comparators for sorting (<, ==) and output stream support (<<).

Lines (struct Line)Defined as \$ax + by = c\$.

Parallel check.

Intersection with another line.

Distance from a point to the line.

Orthogonal projection of a point onto the line.

Reflection of a point across the line.

Segments (struct Seg)

Check if a point is strictly on the segment.

Shortest distance from a point to the segment (clamped to endpoints).

PolygonsSigned area.

Convexity check.

Point in polygon test (returns: inside, outside, or on boundary).

Convex Hull (Monotone Chain algorithm).

Circles (struct Circle)

Check if a point is inside or on the boundary.

Intersection with a line (finds 0, 1, or 2 points)

10.2. trees.h

1. Given a bridge tree,
the minimum number of edges required to be added to make
the graph 2 -
edge
connected = ceil(L / 2) where L are the number of
leaves
.2. Block cut tree builds a
bipartite
graph(original node->block node
->original node(may be
articulation point)
->...)
.Non -
articulation points have degree = 1,
and articulation points have degree >=
2(connecting two or more graphs).