

IoT and ML for Ecosystem Restoration & Multihazard Resilience

05th to 09th of June 2021









Introduction to Git & GitHub

Sai Shibu

Note: Contents are from publicly available data

About Me

Social Profiles













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Research TAG: Intelligent Infrastructure & Pervasive Mobile Computing

Area of Interest: Future Mobility, Blockchain Technology, IoT & ML



Git & Github

Git is an example of version control

Version control is a system that records changes to a file or set of files and helps us recall specific versions later if needed. E.g. Subversion (SVN), CVS etc It allows you to:

- Revert files or the whole project to an earlier state
- Compare changes over time
- See who modified what?
- Control modifications by collaborators with the permission of admin/owners

Github is a repository hosting service for Git

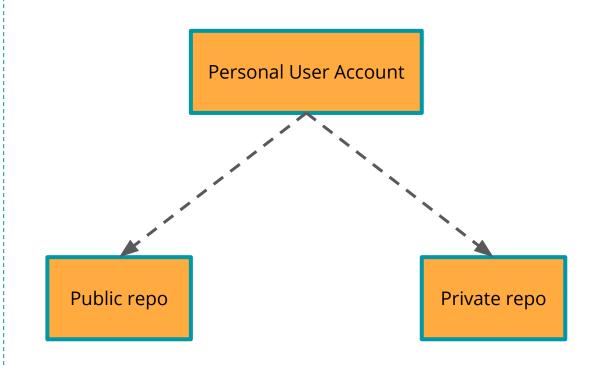


Workshop materials will be available on our GitHub repo



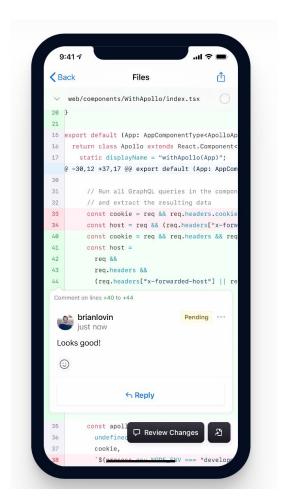
Github

- Unlimited public repositories and collaborators on all plans
- Limited Private repositories
- Ability to add unlimited repository collaborators
- Public repositories are open to view and copy but not commit changes.

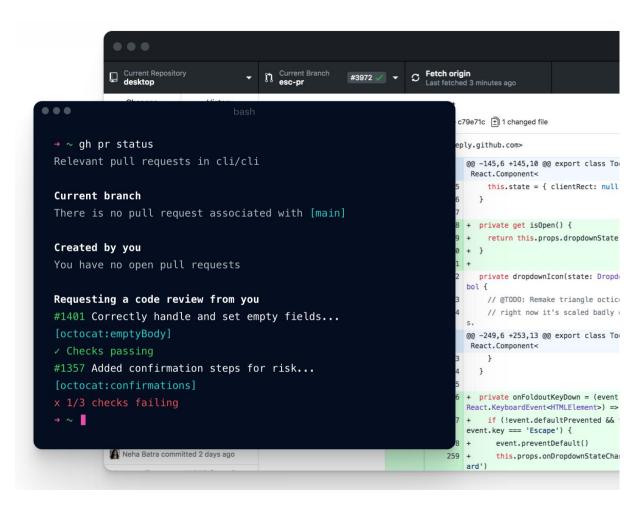




GitHub Clients



Mobile App



CLI & GUI Desktop App



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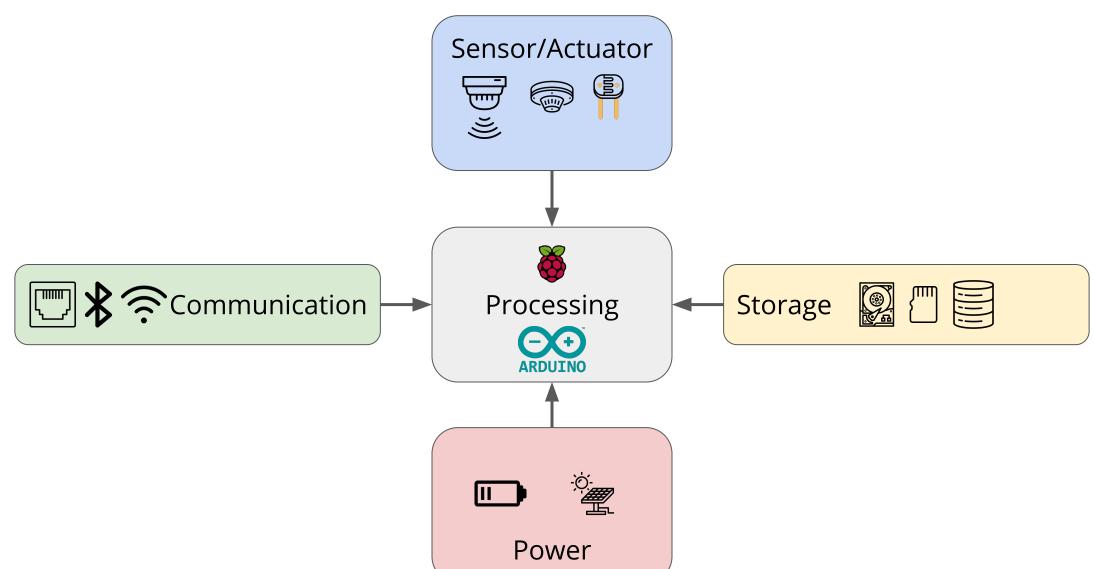
Introduction to Single Board Computers

Sai Shibu

Note: Contents are from publicly available data



General IoT Architecture - Simplified form





Raspberry Pi

The **Raspberry Pi** is a credit-card-sized single-board computer developed in the UK by the Raspberry Pi Foundation for promoting the teaching of basic computer science in schools.

Makers, tinkerers and hackers adapted the R-Pi to act as a tiny computer that they can easily embed into their projects.







RPi ZERO W



RPI COMPUTE MODULE







- OS Support
- Onboard WiFi & Bluetooth
- Parallel Processing
- Storage
- Multiple language support
- Sensitive to current
- No ADC
- 3.3V GPIOs

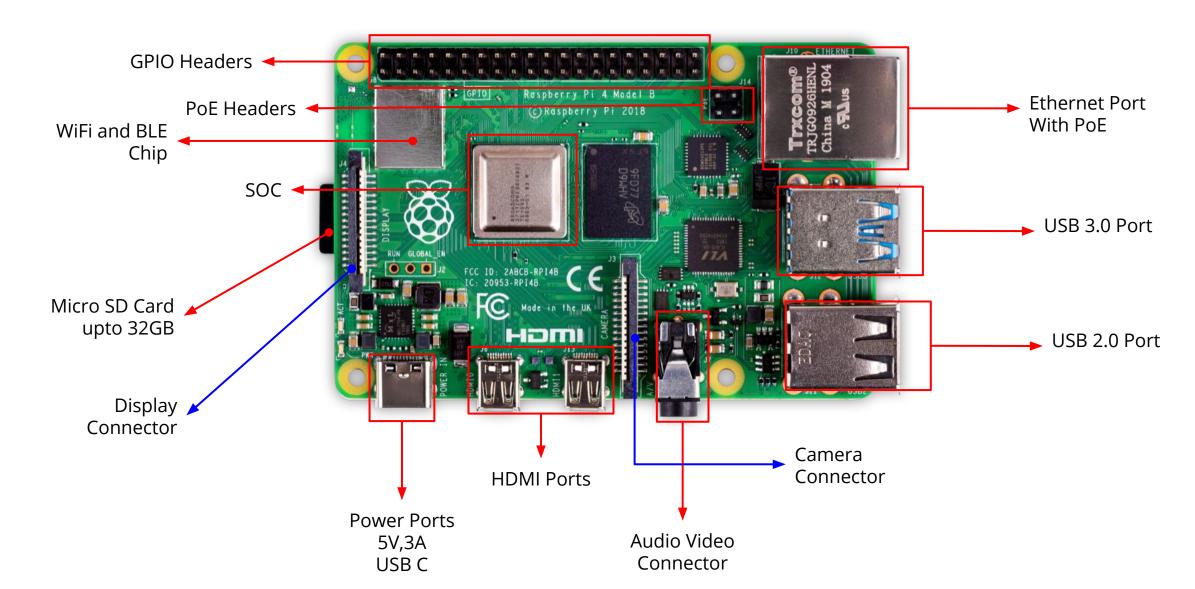




- Onboard ADC
- Low cost
- Less sensitive to current
- 5V I/O Ports
- Single programming Language
- low memory & Storage
- less number of I/Os

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Raspberry Pi - Board Layout

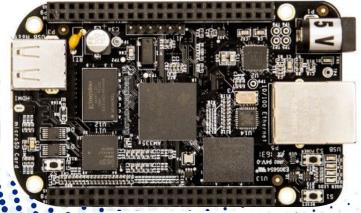




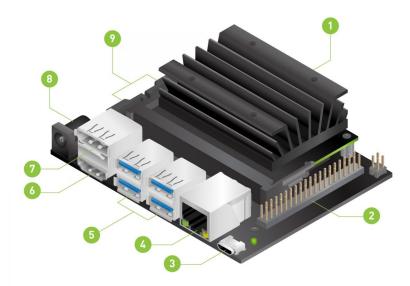
Do we have any other SBCs other than RPi?







Beagle Bone:



Nvidia Jetson Nano











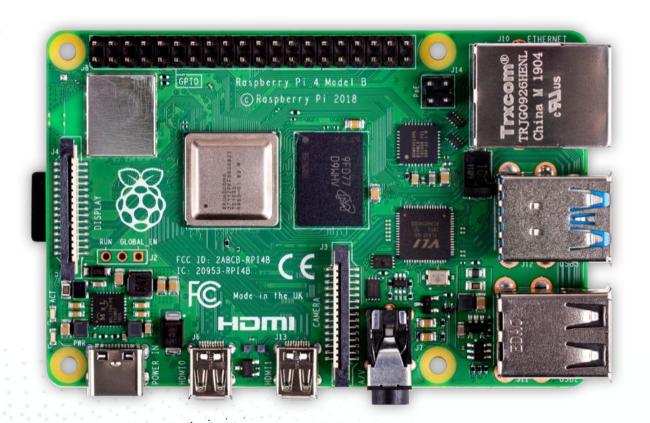






Let's get started

- 1. Input devices Keyboard & Mouse
- 2. Display
- 3. SD with OS on it





What is OS? Why do we need this?

- Intermediate between user application and hardware
- Provides, file system, I/O Operation, program control, memory management









OS for Raspberry Pi

Raspberry Pi OS - 32 bit operating system

Light version and Full version

- Stripped down Linux with required packages for Raspberry Pi
- Python and other programming languages included
- Support to access GPIOs

Any other OS available for RPI?



Ubuntu MATE



Ubuntu Core



Ubuntu Server



OSMC



LibreELEC



Mozilla WebThings



PiNet



RISC OS



Weather Station





GPIO

- Connect Sensors and Actuators
- Digital Input and output similar to arduino. But 3.3v range & 10mA
- lack of ADC
- Possible to connect external ADCs through SPI or I2C
- PWM for motor/LED Control
- UART for communication

Pin	# NAME		NAME	Pin#
01	Green State Commission (1980)		DC Power 5v	02
03	GPIO02 (SDA1, I2C)	00	DC Power 5v	04
05	GPIO03 (SCL1, I2C)	00	Ground	06
07	GPIO04 (GPIO_GCLI		(TXD0) GPIO14	08
09	Ground	00	(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN	0)	(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN:		Ground	14
15	GPIO22 (GPIO_GEN	3)	(GPIO_GEN4) GPIO23	16
17	3.3v DC Power	00	(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)	00	Ground	20
21	GPIO09 (SPI_MISO)	00	(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)	00	(SPI_CE0_N) GPIO08	24
25	Ground	00	(SPI_CE1_N) GPIO07	26
27	ID_SD (I ² C ID EEPRO	OM) (O) (O)	(I ² C ID EEPROM) ID_SC	28
29	GPIO05	00	Ground	30
31	GPIO06	00	GPIO12	32
33	GPIO13	00	Ground	34
35	GPIO19	00	GPIO16	36
37	GPIO26	00	GPIO20	38
39	Ground	00	GPIO21	40



Using the GPIOs (Python based)

GPIO Library

Very similar to Arduino Digital Input & Output

Set GPIO to Input / Output

If input - read the specific pin to get the value

if output - set high/low to control

More reading: https://www.raspberrypi.org/documentation/usage/gpio/

UART, SPI & I2C have to enabled through raspi-config

specific libraries allow data read/write operations through these protocols.

Modbus protocol is used for industry M2M communications, eg: reading data from a smart meter. No native support available, but RS232 to Modbus converter is possible

Other SBC - Beaglebone supports CANBUS



Using GPIO

```
import RPi.GPIO as GPIO
                                             Import the GPIO Library
import time
                                              Choose GPIO Pinmode
GPIO.setmode(GPIO.BOARD)-
GPIO.setup(7,GPIO.OUT) -
                                              Config GPIO as output
for i in range (50):
     GPIO.output (7, True)
                                               Set GPIO to high
     time.sleep(1)
     GPIO.output(7, False)
                                               Set GPIO to low
     time.sleep(1)
                                               Clean GPIO configs
GPIO.cleanup()
```

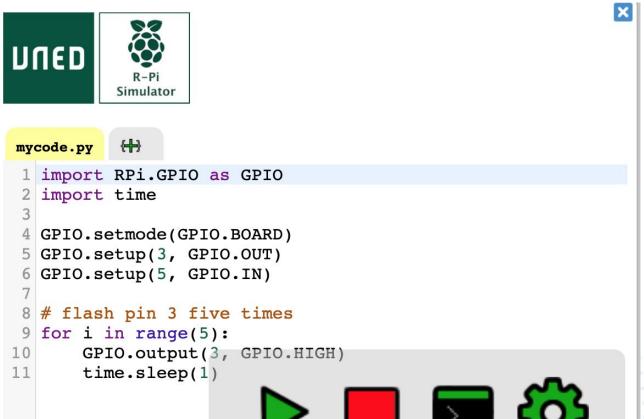


Using GPIO - Input

```
#buttonInput.py
import RPi.GPIO as GPIO
from time import sleep
GPI0.setmode(GPI0.BCM)
                                                                          Import the GPIO Library
sleepTime = .1
                                                                           Choose GPIO Pinmode
#GPIO Pin of the component
lightPin = 4
buttonPin = 17
GPIO.setup(lightPin, GPIO.OUT)
GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP) -
                                                                         Config GPIO as Input
GPIO.output(lightPin, False)
   while True:
       GPIO.output(lightPin, GPIO.input(buttonPin))
       sleep(.1)
finally:
                                                                            Read GPIO Input
   GPIO.output(lightPin, False)
   GPIO.cleanup()
                                                                             Clean GPIO configs
```

Simulators (1)

https://www.iot4smes.eu/en/demonstrator.a spx?id=4.full





```
Connectors:

2
4
6
Ground
BCM
15
BCM
15
BCM
17
BCM
10
BCM
```

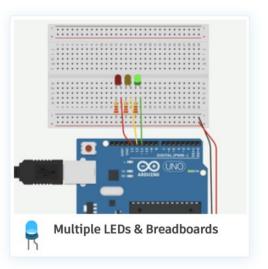


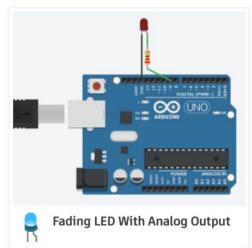
Simulators (2)

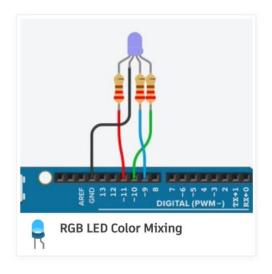
https://www.tinkercad.com

Learn Arduino

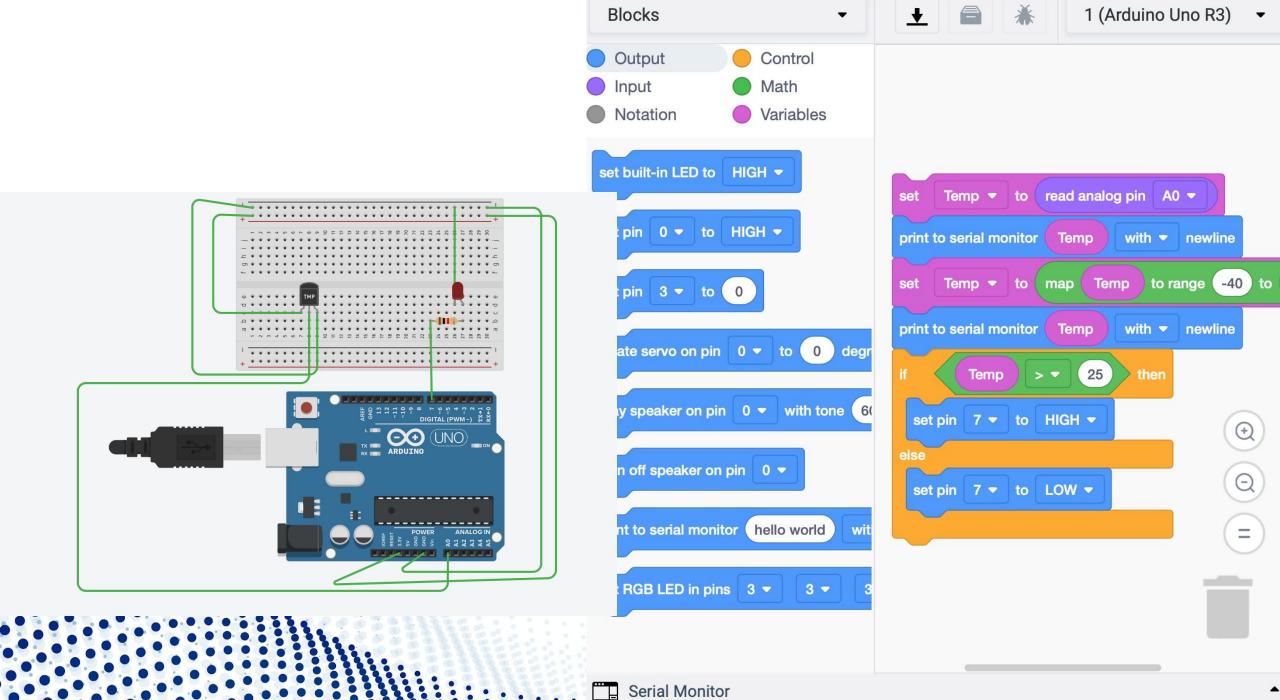












ACKNOWLEDGMENTS / REFERENCES

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 hore-communications-networks
- https://www.amrita.edu/research/project/amrita-wireless-smart-grid