

## Exercises-

1. Implement common logic gates in Ladder diagram.
2. S1 ON L1 and L2 ON, S2 ON-L3 and L4 ON, S3 ON L5 and L6 ON.
3. S1 ON –L1 ON, S2 OFF- L2 ON.
4. S1-ON L1- ON;S2-off L2-on;S3 on I3 on ;S4-off I4 on
5. S1 on L1 on, S2 on L2 on ,L1-off; S3 on I3 on ,L2 off

## Latching

### Exercises-

1. PB- on , L1 on L2 on;

PB	L1	L2
0	0	0
1	1	0
0	1	1

- 2.

PB	L1	L2	L3
0	0	0	0
1	1	0	0
0	1	1	0
1	1	1	1

## Memory

### Exercises.

- 1.

PB	L1
0	0
1	1
0	1
1	0

- 2.

PB	L1
0	0
1	0
0	0
1	1

## FPwinpro-

### More Exercises

1. S1&S2 on L1-on  
S3 or S4 on L2 on L1 off
2. S1 & S2 On - L1 ON  
S3 or S4 On – L2 On L1 Off  
S5 On – L1 ON L3 ON

3.

PB	L1
0	0
1	1
0	1
1	1
0	0

4.

PB	L1
0	0
1	1
0	1
1	1
0	1
1	0

## Timers and counters

### Exercises.

1. PB on , L1 on after 5 seconds.
2. PB- on , L1 On; 5 sec later L2 on ; 5 second later L3 on; 5 second later repeat process.

## Counters

### Exercises

1. 1 person enters the room – Light On.  
5 persons enter the room -fan ON.  
10 persons enter the room -AC ON Fan Off.
2. Job in sensor(JIS) & forward pushbutton (Fwd)ON- Forward motor motion  
Job out sensor(JOS) ON – motor Off.  
JOS and Reverse pushbutton (Rev) ON- Motor Reverse  
JIS ON - motor Off

## Exercises on PLC trainer kit

1. SW1 ON- LED1 ON  
Sw1 off – LED 1 OFF
2. SW1 ON – LED 1 ON  
Sw1 ON again – LED 1 OFF
3. Sw1 ON – Buzzer ON  
Sw 2 ON – Buzzer OFF ( mute switch)

- Sw2 Off – Buzzer ON
- 4. Sw2 Off – Buzzer ON  
Sw2 Off Again – Buzzer OFF
- 5. Switch on the Buzzer After a delay of 10 seconds of swiotching on SW1.
- 6. PB ON- Buzzer ON after 5 seconds Buzzer OFF after 10 Seconds.
- 7. Buzzer should beep 5 times after SW1 ON. Beep is 1 seconds buzzer ON and 1 second Buzzer OFF.
- 8. Sw1 ON – Beep Once  
Sw1 ON second time- Beep Twice  
Sw1 ON third time- Beep thrice  
Sw1 ON forth time- Beep once  
Sw1 ON fifth time- Beep Twice
- 9. Sw1 ON Beep thrice  
Sw1 ON second time- Beep Twice  
Sw1 ON third time- Beep once  
Sw1 ON forth time- Beep thrice
- 10. Decreasing series
- 11. Speed control of DC motor
- 12. Use relay to control motor
- 13. Use limit switch to control LED. NC- LED NO- Buzzer
- 14. Make a stepper motor rotate by angle of 270 degrees