#### **ASSIGNMENT 3**

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#### **Question1:**

The Shape of the L\*a\*b\* Color Space

Unlike the RGB or HSV spaces, the L\*a\*b\* space does not have a regular shape

. In this assignment, explore the shape of the L\*a\*b\* color space.

Divide the L\*a\*b\* space into 500 bins, as follows:

5 bins in the L\* dimension

10 bins the a\* dimension

10 bins the b\* dimension

Map the colors from a standard RGB cube to the bins Find out how many bins in the L\*a\*b\* space are occupied and how many are always empty

Optionally, you can find a

creative way to display or illustrate the L\*a\*b\* (as a 3d volume or as slices). Write a complete report of your work, including your documented source code and results. Submit your report and your source code as attachments.

#### **Solution:**

#### **Source code:**

```
#include <opencv2/core/core.hpp>
#include <opencv2/imgproc_imgproc_c.h>
#include <opencv2/highgui/highgui.hpp>
#include <iostream>
#include <string>
using namespace std;
int main()
{
// loading an image
IplImage* image = cvLoadImage("images/test.jpg", 1);
//condition if the image is not found
```

```
if (!image)
{
cout << "file not found" << endl;</pre>
exit(0);
}
// Creating the image1 equivalent to the size of original image
IplImage* image1 = cvCreateImage(cvSize(image->width, image->height),IPL DEPTH 8U, 3);
//converting the color image to l*a*b* color space
cvCvtColor(image, image1, CV BGR2Lab);
// creating a 3D histogram for an image
int histogram[5][10][10];
// Initializing the count for no. of pixels occupied in each bin
int count = 0;
// processing the entire image by referring each row & column in a image
for (int row = 0; row < image1->height; row++)
{
for (int column = 0; column < image1->width; column++) {
int 1, a, b;
// initializing the channels
int step,channels=3;
//defining the pointer for stepping into each row
step=image1->widthStep;
// indexing the bins in each channel
1 = image1->imageData[step * row + channels * column + 0] / 51.0;
a = image1->imageData[step * row + channels * column + 1] / 25.5;
b = image1->imageData[step * row + channels * column + 2] / 25.5;
```

```
// checking whether any bin in the histogram is occupied with l*,a* and b* color spaces or not
if (histogram[1][a][b] != 1)
{
// defining the occupied bins in histogram to '1'
histogram[1][a][b] = 1;
// incrementing the count
count += 1;
}
// calculating the unoccupied bins by just subtracting the occupied bins from total no. of available
int unoccupied = 500 - count;
// printing the no. of unoccupied and occupied(count) bins in a histogram
cout << Number of unoccupied bins: << unoccupied << endl;
cout << Number of unoccupied bins: <<count << endl;
}
```

#### **Description:**

In this, I first loaded the color image by using cvLoadImage(). I used cvCvtColor()to convert BGR color image to l\*a\*b\* color space.

By using 3D array, I formulated a histogram for this 1\*a\*b\* color space. In

histogram, I indexed the bin by just dividing each channel with corresponding

channel's bin size. Since, in the problem it is given that we need to formulate 500 bins in such a way that we have 5 bins for 1\* channel and 10 bins for a\*, 10 bins for b\* so, to get the individual bin size in each channel, I divided the channel size of 255 by corresponding partitions as follows:

```
For l* channel, bin size = 255/5=51.0
For a* channel, bin size = 255/10=25.5
For b* channel, bin size = 255/10=25.5
```

Indexing the bins tells how many pixels are there in each bin. Finally, I printed the count of occupied and unoccupied bins in a histogram.

### **Tools used:**

- 1) OpenCv 2.4.6.0
- 2) Microsoft visual studio 2010

## **Input:**

I took original raw .jpg,.gif,.png images one at a time as an input to my program. I placed all the image files int the following folder: images/test.jpg

# **Outputs:**

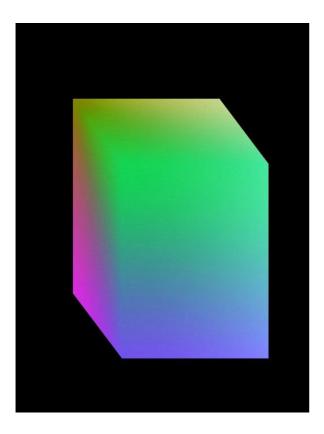
1)Image1:test1.jpg



## output:

Number of unoccupied bins: 336

# 2)Image2:lab.jpg



# output:

Number of unoccupied bins: 425 Number of occupied bins: 75