

#### **CHAPTER 18**

#### **Strategies for Query Processing**

#### Introduction

- DBMS techniques to process a query
  - Scanner identifies query tokens
  - Parser checks the query syntax
  - Validation checks all attribute and relation names
  - Query tree (or query graph) created
  - Execution strategy or query plan devised
- Query optimization
  - Planning a good execution strategy

#### **Query Processing**

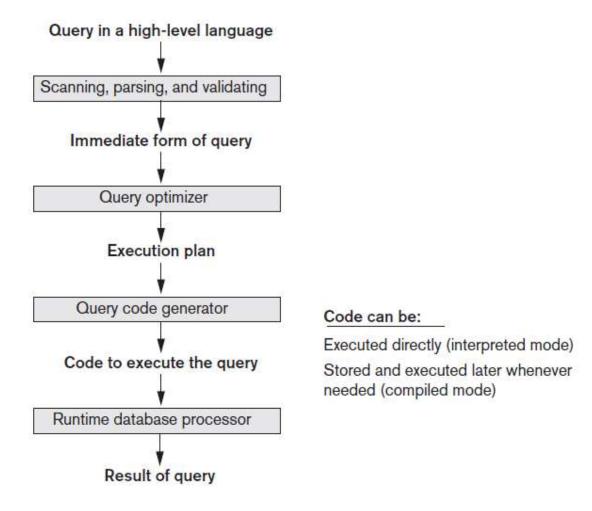


Figure 18.1 Typical steps when processing a high-level query

#### 18.1 Translating SQL Queries into Relational Algebra and Other Operators

- SQL
  - Query language used in most RDBMSs
- Query decomposed into query blocks
  - Basic units that can be translated into the algebraic operators
  - Contains single SELECT-FROM-WHERE expression
    - May contain GROUP BY and HAVING clauses

#### Translating SQL Queries (cont'd.)

#### Example:

```
SELECT Lname, Fname
FROM EMPLOYEE
WHERE Salary > ( SELECT MAX (Salary)
FROM EMPLOYEE
WHERE Dno=5 );
```

Inner block

```
( SELECT MAX (Salary)
FROM EMPLOYEE
WHERE Dno=5 )
```

Outer block

SELECT Lname, Fname FROM EMPLOYEE WHERE Salary > c

#### Translating SQL Queries (cont'd.)

- Example (cont'd.)
  - Inner block translated into:

$$\Im_{MAX \ Salary}(\sigma_{Dno=5}(EMPLOYEE))$$

Outer block translated into:

$$\pi_{Lname,Fname}(\sigma_{Salary>c}(EMPLOYEE))$$

 Query optimizer chooses execution plan for each query block

#### Additional Operators Semi-Join and Anti-Join

- Semi-join
  - Generally used for unnesting EXISTS, IN, and ANY subqueries
  - Syntax: T1.X S = T2.Y
    - T1 is the left table and T2 is the right table of the semi-join
  - A row of T1 is returned as soon as T1.X finds a match with any value of T2.Y without searching for further matches

# Additional Operators Semi-Join and Anti-Join (cont'd.)

- Anti-join
  - Used for unnesting NOT EXISTS, NOT IN, and ALL subqueries
  - Syntax: T1.x A = T2.y
    - T1 is the left table and T2 is the right table of the anti-join
  - A row of T1 is rejected as soon as T1.x finds a match with any value of T2.y
  - A row of T1 is returned only if T1.x does not match with any value of T2.y

#### 18.2 Algorithms for External Sorting

- Sorting is an often-used algorithm in query processing
- External sorting
  - Algorithms suitable for large files that do not fit entirely in main memory
  - Sort-merge strategy based on sorting smaller subfiles (runs) and merging the sorted runs
  - Requires buffer space in main memory
    - DBMS cache

```
i \leftarrow 1;
       j \leftarrow b;
                             (size of the file in blocks)
        k \leftarrow n_B;
                             {size of buffer in blocks}
        m \leftarrow \lceil (j/k) \rceil;
                              (number of subfiles- each fits in buffer)
(Sorting Phase)
while (i \le m)
do {
        read next k blocks of the file into the buffer or if there are less than k blocks
            remaining, then read in the remaining blocks;
        sort the records in the buffer and write as a temporary subfile;
        i \leftarrow i + 1:
{Merging Phase: merge subfiles until only 1 remains}
      i \leftarrow 1:
set
        p \leftarrow \log_{k-1} m {p is the number of passes for the merging phase}
       i \leftarrow m;
while (i \le p)
do {
        n \leftarrow 1:
        q \leftarrow (j/(k-1)); {number of subfiles to write in this pass}
        while (n \le q)
        do {
            read next k-1 subfiles or remaining subfiles (from previous pass)
               one block at a time;
           merge and write as new subfile one block at a time;
           n \leftarrow n + 1;
        i \leftarrow i + 1;
```

Figure 18.2 Outline of the sort-merge algorithm for external sorting

#### Algorithms for External Sorting (cont'd.)

- Degree of merging
  - Number of sorted subfiles that can be merged in each merge step
- Performance of the sort-merge algorithm
  - Number of disk block reads and writes before sorting is completed

#### 18.3 Algorithms for SELECT Operation

#### SELECT operation

- Search operation to locate records in a disk file that satisfy a certain condition
- File scan or index scan (if search involves an index)
- Search methods for simple selection
  - S1: Linear search (brute force algorithm)
  - S2: Binary search
  - S3a: Using a primary index
  - S3b: Using a hash key

# Algorithms for SELECT Operation (cont'd.)

- Search methods for simple selection (cont'd.)
  - S4: Using a primary index to retrieve multiple records
  - S5: Using a clustering index to retrieve multiple records
  - S6: Using a secondary (B+ -tree) index on an equality comparison
  - S7a: Using a bitmap index
  - S7b: Using a functional index

# Algorithms for SELECT Operation (cont'd.)

- Search methods for conjunctive (logical AND) selection
  - Using an individual index
  - Using a composite index
  - Intersection of record pointers
- Disjunctive (logical OR) selection
  - Harder to process and optimize

# Algorithms for SELECT Operation (cont'd.)

#### Selectivity

- Ratio of the number of records (tuples) that satisfy the condition to the total number of records (tuples) in the file
- Number between zero (no records satisfy condition) and one (all records satisfy condition)
- Query optimizer receives input from system catalog to estimate selectivity

#### 18.4 Implementing the JOIN Operation

- JOIN operation
  - One of the most time consuming in query processing
  - EQUIJOIN (NATURAL JOIN)
  - Two-way or multiway joins
- Methods for implementing joins
  - J1: Nested-loop join (nested-block join)
  - J2: Index-based nested-loop join
  - J3: Sort-merge join
  - J4: Partition-hash join

Figure 18.3 Implementing JOIN, PROJECT, UNION, INTERSECTION, and SET DIFFERENCE by using sort-merge, where R has n tuples and S has m tuples. (a) Implementing the operation  $T \leftarrow R \bowtie_{A=B} S$ .

```
(*assume R has n tuples (records)*)
(a) sort the tuples in R on attribute A;
     sort the tuples in S on attribute B;
                                                                     (*assume S has m tuples (records)*)
     set i \leftarrow 1, j \leftarrow 1;
     while (i \le n) and (j \le m)
     do { if R(i)[A] > S(i)[B]
              then set i \leftarrow i + 1
          elseif R(i)[A] < S(i)[B]
                then set i \leftarrow i + 1
          else { (*R(i)[A] = S(i)[B], so we output a matched tuple *)
                  output the combined tuple \langle R(i), S(i) \rangle to T;
                  (* output other tuples that match R(i), if any *)
                  set l \leftarrow i + 1;
                  while (I \le m) and (R(i)[A] = S(I)[B])
                  do { output the combined tuple \langle R(i), S(l) \rangle to T;
                           set / \leftarrow / + 1
           (* output other tuples that match S(i), if any *)
            set k \leftarrow i + 1:
            while (k \le n) and (R(k)[A] = S(i)[B])
            do { output the combined tuple \langle R(k), S(j) \rangle to T;
                    set k \leftarrow k+1
           set i \leftarrow k, j \leftarrow l
```

```
(b) create a tuple t[<attribute list>] in T' for each tuple t in R;
          (* T' contains the projection results before duplicate elimination *)
     if <attribute list> includes a key of R
          then T \leftarrow T'
     else { sort the tuples in T';
           set i \leftarrow 1, i \leftarrow 2;
           while i \leq n
           do { output the tuple T'[i] to T;
                   while T'[i] = T'[j] and j \le n do j \leftarrow j + 1;
                                                                                (* eliminate duplicates *)
                   i \leftarrow j; j \leftarrow i+1
     (*T contains the projection result after duplicate elimination*)
```

Figure 18.3 (cont'd.) Implementing JOIN, PROJECT, UNION, INTERSECTION, and SET DIFFERENCE by using sort-merge, where R has n tuples and S has m tuples. (b) Implementing the operation  $T \leftarrow \pi_{\text{cattribute list}}(R)$ .

```
(c) sort the tuples in R and S using the same unique sort attributes;
     set i \leftarrow 1, j \leftarrow 1;
     while (i \le n) and (i \le m)
     do { if R(i) > S(j)
                 then { output S(i) to T;
                            set i \leftarrow i + 1
             elseif R(i) < S(j)
                 then { output R(i) to T;
                            set i \leftarrow i + 1
             else set i \leftarrow i + 1
                                                        (* R(i)=S(j), so we skip one of the duplicate tuples *)
     if (i \le n) then add tuples R(i) to R(n) to T;
     if (i \le m) then add tuples S(i) to S(m) to T;
```

Figure 18.3 (cont'd.) Implementing JOIN, PROJECT, UNION, INTERSECTION, and SET DIFFERENCE by using sort-merge, where R has n tuples and S has m tuples. (c) Implementing the operation  $T \leftarrow R \cup S$ .

```
(d) sort the tuples in R and S using the same unique sort attributes; set i \leftarrow 1, j \leftarrow 1; while (i \le n) and (j \le m) do \{if R(i) > S(j) \\ then set <math>j \leftarrow j + 1 elseif R(i) < S(j) then set i \leftarrow i + 1 else \{if C(j) \in S(j) \in
```

Figure 18.3 (cont'd.) Implementing JOIN, PROJECT, UNION, INTERSECTION, and SET DIFFERENCE by using sort-merge, where R has n tuples and S has m tuples. (d) Implementing the operation  $T \leftarrow R \cap S$ .

```
(e) sort the tuples in R and S using the same unique sort attributes; set i \leftarrow 1, j \leftarrow 1; while (i \le n) and (j \le m) do \{ if R(i) > S(j) then set j \leftarrow j + 1 elseif R(i) < S(j) then \{ output R(i) to T; (*R(i) has no matching S(j), so output R(i) *) set i \leftarrow i + 1 \} else set i \leftarrow i + 1, j \leftarrow j + 1 \} if (i \le n) then add tuples R(i) to R(n) to T;
```

Figure 18.3 (cont'd.) Implementing JOIN, PROJECT, UNION, INTERSECTION, and SET DIFFERENCE by using sort-merge, where R has n tuples and S has m tuples. (e) Implementing the operation  $T \leftarrow R - S$ .

- Available buffer space has important effect on some JOIN algorithms
- Nested-loop approach
  - Read as many blocks as possible at a time into memory from the file whose records are used for the outer loop
  - Advantageous to use the file with fewer blocks as the outer-loop file

- Join selection factor
  - Fraction of records in one file that will be joined with records in another file
  - Depends on the particular equijoin condition with another file
  - Affects join performance
- Partition-hash join
  - Each file is partitioned into M partitions using the same partitioning hash function on the join attributes
  - Each pair of corresponding partitions is joined

- Hybrid hash-join
  - Variation of partition hash-join
  - Joining phase for one of the partitions is included in the partition
  - Goal: join as many records during the partitioning phase to save cost of storing records on disk and then rereading during the joining phase

## 18.5 Algorithms for PROJECT and Set Operations

- PROJECT operation
  - After projecting R on only the columns in the list of attributes, any duplicates are removed by treating the result strictly as a set of tuples
- Default for SQL queries
  - No elimination of duplicates from the query result
    - Duplicates eliminated only if the keyword DISTINCT is included

# Algorithms for PROJECT and Set Operations (cont'd.)

- Set operations
  - UNION
  - INTERSECTION
  - SET DIFFERENCE
  - CARTESIAN PRODUCT
- Set operations sometimes expensive to implement
  - Sort-merge technique
  - Hashing

# Algorithms for PROJECT and Set Operations (cont'd.)

- Use of anti-join for SET DIFFERENCE
  - EXCEPT or MINUS in SQL
  - Example: Find which departments have no employees

Select Dnumber from DEPARTMENT MINUS Select Dno from EMPLOYEE;

#### becomes

SELECT DISTINCT DEPARTMENT.Dnumber
FROM DEPARTMENT, EMPLOYEE
WHERE DEPARTMENT.Dnumber A = EMPLOYEE.Dno

#### 18.6 Implementing Aggregate Operations and Different Types of JOINs

- Aggregate operators
  - MIN, MAX, COUNT, AVERAGE, SUM
  - Can be computed by a table scan or using an appropriate index
- Example: SELECT MAX(Salary) FROM EMPLOYEE;
  - If an (ascending) B+-tree index on Salary exists:
    - Optimizer can use the Salary index to search for the largest Salary value
    - Follow the rightmost pointer in each index node from the root to the rightmost leaf

# Implementing Aggregate Operations and Different Types of JOINs (cont'd.)

#### AVERAGE or SUM

- Index can be used if it is a dense index
- Computation applied to the values in the index
- Nondense index can be used if actual number of records associated with each index value is stored in each index entry

#### COUNT

Number of values can be computed from the index

# Implementing Aggregate Operations and Different Types of JOINs (cont'd.)

- Standard JOIN (called INNER JOIN in SQL)
- Variations of joins
  - Outer join
    - Left, right, and full
    - Example:

```
SELECT E.Lname, E.Fname, D.Dname

FROM (EMPLOYEE E LEFT OUTER JOIN DEPARTMENT D ON E.Dno = D.Dnumber);
```

- Semi-Join
- Anti-Join
- Non-Equi-Join

# 18.7 Combining Operations Using Pipelining

- SQL query translated into relational algebra expression
  - Sequence of relational operations
- Materialized evaluation
  - Creating, storing, and passing temporary results
- General query goal: minimize the number of temporary files
- Pipelining or stream-based processing
  - Combines several operations into one
  - Avoids writing temporary files

# Combining Operations Using Pipelining (cont'd.)

#### Pipelined evaluation benefits

- Avoiding cost and time delay associated with writing intermediate results to disk
- Being able to start generating results as quickly as possible

#### Iterator

- Operation implemented in such a way that it outputs one tuple at a time
- Many iterators may be active at one time

# Combining Operations Using Pipelining (cont'd.)

- Iterator interface methods
  - Open()
  - Get\_Next()
  - Close()
- Some physical operators may not lend themselves to the iterator interface concept
  - Pipelining not supported
- Iterator concept can also be applied to access methods

# 18.8 Parallel Algorithms for Query Processing

- Parallel database architecture approaches
  - Shared-memory architecture
    - Multiple processors can access common main memory region
  - Shared-disk architecture
    - Every processor has its own memory
    - Machines have access to all disks
  - Shared-nothing architecture
    - Each processor has own memory and disk storage
    - Most commonly used in parallel database systems

- Linear speed-up
  - Linear reduction in time taken for operations
- Linear scale-up
  - Constant sustained performance by increasing the number of processors and disks

- Operator-level parallelism
  - Horizontal partitioning
    - Round-robin partitioning
    - Range partitioning
    - Hash partitioning
- Sorting
  - If data has been range-partitioned on an attribute:
    - Each partition can be sorted separately in parallel
    - Results concatenated
  - Reduces sorting time

- Selection
  - If condition is an equality condition on an attribute used for range partitioning:
    - Perform selection only on partition to which the value belongs
- Projection without duplicate elimination
  - Perform operation in parallel as data is read
- Duplicate elimination
  - Sort tuples and discard duplicates

- Parallel joins divide the join into n smaller joins
  - Perform smaller joins in parallel on n processors
  - Take a union of the result
- Parallel join techniques
  - Equality-based partitioned join
  - Inequality join with partitioning and replication
  - Parallel partitioned hash join

#### Aggregation

 Achieved by partitioning on the grouping attribute and then computing the aggregate function locally at each processor

#### Set operations

 If argument relations are partitioned using the same hash function, they can be done in parallel on each processor

- Intraquery parallelism
  - Approaches
    - Use parallel algorithm for each operation, with appropriate partitioning of the data input to that operation
    - Execute independent operations in parallel
- Interquery parallelism
  - Execution of multiple queries in parallel
  - Goal: scale up
  - Difficult to achieve on shared-disk or sharednothing architectures

#### 18.9 Summary

- SQL queries translated into relational algebra
- External sorting
- Selection algorithms
- Join operations
- Combining operations to create pipelined execution
- Parallel database system architectures