dog_app

April 11, 2020

1 Convolutional Neural Networks

1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you DO NOT need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human_files and dog_files.

Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [2]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [3]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face_detector function.

- What percentage of the first 100 images in human_files have a detected human face?
- What percentage of the first 100 images in dog_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer:

Human Faces detected in humans dataset: 98% Human Faces detected in dogs dataset: 17%

```
In [4]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        human_detect=0
        dog_detect=0
        for i in range(100):
            if (face_detector(human_files_short[i])):
                human_detect+=1
            if (face_detector(dog_files_short[i])):
                dog_detect+=1
        print("Human Faces detected in humans dataset: {}".format(human_detect))
        print("Human Faces detected in dogs dataset: {}".format(dog_detect))
Human Faces detected in humans dataset: 98
Human Faces detected in dogs dataset: 17
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

```
In [5]: ### (Optional)
     ### TODO: Test performance of anotherface detection algorithm.
     ### Feel free to use as many code cells as needed.
```

Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [5]: import torch
        import torchvision.models as models
        from torch import nn
        # define VGG16 model
        VGG16 = models.vgg16(pretrained=True)
        # check if CUDA is available
        use_cuda = torch.cuda.is_available()
        # move model to GPU if CUDA is available
        if use_cuda:
            VGG16 = VGG16.cuda()
In [6]: print(VGG16)
VGG (
  (features): Sequential(
    (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace)
    (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (3): ReLU(inplace)
    (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (6): ReLU(inplace)
    (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU(inplace)
```

```
(9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (11): ReLU(inplace)
    (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (13): ReLU(inplace)
    (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (15): ReLU(inplace)
    (16): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (18): ReLU(inplace)
    (19): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (20): ReLU(inplace)
    (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (22): ReLU(inplace)
    (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (24): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (25): ReLU(inplace)
    (26): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (27): ReLU(inplace)
    (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (29): ReLU(inplace)
    (30): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (classifier): Sequential(
    (0): Linear(in_features=25088, out_features=4096, bias=True)
    (1): ReLU(inplace)
    (2): Dropout(p=0.5)
    (3): Linear(in_features=4096, out_features=4096, bias=True)
    (4): ReLU(inplace)
    (5): Dropout(p=0.5)
    (6): Linear(in_features=4096, out_features=1000, bias=True)
 )
)
```

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
import torchvision.transforms as transforms
def VGG16_predict(img_path):
    Use pre-trained VGG-16 model to obtain index corresponding to
    predicted ImageNet class for image at specified path
    Args:
        img_path: path to an image
    Returns:
        Index corresponding to VGG-16 model's prediction
    ## TODO: Complete the function.
    ## Load and pre-process an image from the given img_path
    ## Return the *index* of the predicted class for that image
    im=Image.open(img_path)
    transform=transforms.Compose([transforms.Resize((224,224)),
                                  transforms.ToTensor(),
                                  transforms.Normalize([0.485, 0.456, 0.406],[0.229, 0.2
    im=transform(im)
    im=im.unsqueeze(0)
    if use_cuda:
        im=im.cuda()
    output=VGG16.forward(im)
    _, pred = torch.max(output, 1)
    return pred # predicted class index
```

1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog_detector function below, which returns True if a dog is detected in an image (and False if not).

1.1.6 (IMPLEMENTATION) Assess the Dog Detector

Question 2: Use the code cell below to test the performance of your dog_detector function.

- What percentage of the images in human_files_short have a detected dog?
- What percentage of the images in dog_files_short have a detected dog?

Answer:

Dogs detected in humans dataset: 0% Dogss detected in dogs dataset: 100%

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

```
Curly-Coated Retriever American Water Spaniel
```

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

```
Yellow Labrador Chocolate Labrador
```

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog_images/train, dog_images/valid, and dog_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
In [10]: import os
         from torchvision import datasets, transforms
         train_transform=transforms.Compose([transforms.Resize(256),
                                             transforms.CenterCrop(224),
                                             transforms.RandomHorizontalFlip(),
                                             transforms.RandomRotation(30),
                                             transforms.ToTensor(),
                                             transforms.Normalize([0.485, 0.456, 0.406],[0.229,
         transform=transforms.Compose([transforms.Resize(256),
                                      transforms.CenterCrop(224),
                                       transforms.ToTensor(),
                                      transforms.Normalize([0.485, 0.456, 0.406],[0.229, 0.224,
         train_data=datasets.ImageFolder('/data/dog_images/train',transform=train_transform)
         valid_data=datasets.ImageFolder('/data/dog_images/valid',transform=transform)
         test_data=datasets.ImageFolder('/data/dog_images/test',transform=transform)
         loaders={}
```

```
loaders['train']=torch.utils.data.DataLoader(train_data,batch_size=32,shuffle=True)
loaders['valid']=torch.utils.data.DataLoader(valid_data,batch_size=32,shuffle=True)
loaders['test']=torch.utils.data.DataLoader(test_data,batch_size=32)
### TODO: Write data loaders for training, validation, and test sets
## Specify appropriate transforms, and batch_sizes

In [11]: def display_img(image):
    image=image.cpu()
    image=image.squeeze().numpy()
    image=image.transpose((1,2,0))
    image=image* np.array((0.229, 0.224, 0.225)) + np.array((0.485, 0.456, 0.406))
    image=np.clip(image,0,1)
    plt.imshow(image)
    plt.show()
    return
```

Question 3: Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

Answer:

I have resized each image into 2562563 first. And then I have applied CenterCrop transform which makes the image dimensions 2242243 The size of the input tensor is 3224224.

I have augumented the training dataset with the following transforms

1)RandomHorizontalFlip 2)RandomRotation

Because of these augumentations the model works better on the untrained images.

Test and Validation sets are not augumented we want to know the best performance of the model on untrained images

1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
nn.MaxPool2d(2,2),
                                nn.BatchNorm2d(32),
                                nn.Conv2d(32,64,3,padding=1),
                                nn.ReLU(),
                                nn.MaxPool2d(2,2),
                                nn.BatchNorm2d(64),
                                nn.Conv2d(64,128,3,padding=1),
                                nn.ReLU(),
                                nn.MaxPool2d(2,2),
                                nn.BatchNorm2d(128),
                                nn.Conv2d(128,128,3,padding=1),
                                nn.ReLU(),
                                nn.MaxPool2d(2,2),
                                nn.BatchNorm2d(128),
        self.classifier = nn.Sequential(nn.Linear(128*14*14,1024),
                                         nn.ReLU(),
                                         nn.Linear(1024,512),
                                         nn.ReLU(),
                                         nn.Linear(512,256),
                                         nn.ReLU(),
                                         nn.Linear(256,133),
                                        nn.LogSoftmax(dim=1))
    def forward(self, x):
        ## Define forward behavior
        x=self.conv(x)
        x=x.view(x.shape[0],-1)
        x=self.classifier(x)
        return x
#-#-# You so NOT have to modify the code below this line. #-#-#
# instantiate the CNN
model_scratch = Net()
# move tensors to GPU if CUDA is available
if use_cuda:
    model_scratch.cuda()
```

Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

Answer:

I have done research on the internet regarding Dog Breed Classifiers And I have found that we need a complex covolution network to get a better accuracy. I have tried many architectures but no where the acuracy is more than 10%. I have used Adam Optimizer till then Then I have decided to change my optimizer to RMSProp the result was much better than Adam Optimizer.

I have used four convolution layers each followed by RELU acivation, Max pooling, Batch Nor-

malization. Then finally I have flattened the output from the convolutional layers and passed it to fully connected layer with three Dense Layers.I have used Relu activation for all the layers except the final one where i have used LogSoftMax. I have used Negative Log likelyhood Loss. The last LogSoftmax and NLL loss forms the CrossEntropy loss.

1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_scratch, and the optimizer as optimizer_scratch below.

1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_scratch.pt'.

```
In [14]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             """returns trained model"""
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train_loss = 0.0
                 valid_loss = 0.0
                 ##################
                 # train the model #
                 ##################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## find the loss and update the model parameters accordingly
                     ## record the average training loss, using something like
                     \#\# train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
                     optimizer.zero_grad()
                     output=model(data)
                     loss=criterion(output, target)
```

loss.backward()

```
train_loss+=loss.item()
        train_loss=train_loss/len(loaders['train'])
        #######################
        # validate the model #
        ######################
        model.eval()
        correct=0
        total=0
        for batch_idx, (data, target) in enumerate(loaders['valid']):
            # move to GPU
            if use_cuda:
                data, target = data.cuda(), target.cuda()
            ## update the average validation loss
            output=model(data)
            loss=criterion(output, target)
            valid_loss+=loss.item()
            pred = output.data.max(1, keepdim=True)[1]
            # compare predictions to true label
            correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().nump
            total+=data.size(0)
        valid_loss=valid_loss/len(loaders['valid'])
        # print training/validation statistics
        print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}\t Accuracy:{
            epoch,
            train_loss,
            valid loss,
            correct/total
            ))
        ## TODO: save the model if validation loss has decreased
        if (valid_loss_min>valid_loss):
            print("Validation loss decreased {}---->{}".format(valid_loss_min,valid_lo
            valid_loss_min=valid_loss
            torch.save(model.state_dict(),save_path)
            print("Model Saved")
    # return trained model
    return model
# train the model
model_scratch = train(10, loaders, model_scratch, optimizer_scratch,criterion_scratch,
# load the model that got the best validation accuracy
model_scratch.load_state_dict(torch.load('model_scratch.pt'))
```

optimizer.step()

```
Training Loss: 4.506344
                                                                                    Accuracy:0.04
Epoch: 1
                                                 Validation Loss: 4.239167
Validation loss decreased inf---->4.239166975021362
Model Saved
Epoch: 2
                                                                                    Accuracy:0.09
                 Training Loss: 3.972035
                                                 Validation Loss: 3.994789
Validation loss decreased 4.239166975021362---->3.9947888674559415
Model Saved
Epoch: 3
                 Training Loss: 3.682225
                                                 Validation Loss: 3.944543
                                                                                    Accuracy: 0.10
Validation loss decreased 3.9947888674559415---->3.944543052602697
Model Saved
Epoch: 4
                 Training Loss: 3.436903
                                                 Validation Loss: 3.727430
                                                                                    Accuracy:0.12
Validation loss decreased 3.944543052602697---->3.727429813808865
Model Saved
Epoch: 5
                 Training Loss: 3.241523
                                                                                    Accuracy:0.12
                                                 Validation Loss: 3.692886
Validation loss decreased 3.727429813808865---->3.6928858668715865
Model Saved
                 Training Loss: 3.024549
                                                                                    Accuracy:0.12
Epoch: 6
                                                 Validation Loss: 3.625952
Validation loss decreased 3.6928858668715865---->3.625951678664596
Model Saved
Epoch: 7
                 Training Loss: 2.824701
                                                 Validation Loss: 3.586521
                                                                                    Accuracy:0.14
Validation loss decreased 3.625951678664596---->3.586520795468931
Model Saved
Epoch: 8
                 Training Loss: 2.638097
                                                 Validation Loss: 3.681996
                                                                                    Accuracy:0.15
Epoch: 9
                 Training Loss: 2.451582
                                                 Validation Loss: 3.527066
                                                                                    Accuracy:0.16
Validation loss decreased 3.586520795468931---->3.5270661071494773
Model Saved
Epoch: 10
                  Training Loss: 2.286135
                                                  Validation Loss: 3.569978
                                                                                     Accuracy:0.1
```

```
In [15]: model_scratch.load_state_dict(torch.load('model_scratch.pt'))
```

1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [16]: def test(loaders, model, criterion, use_cuda):
    # monitor test loss and accuracy
    test_loss = 0.
    correct = 0.
    total = 0.

model.eval()
    for batch_idx, (data, target) in enumerate(loaders['test']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
        # forward pass: compute predicted outputs by passing inputs to the model
```

```
output = model(data)
                 # calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                 # convert output probabilities to predicted class
                 pred = output.data.max(1, keepdim=True)[1]
                 # compare predictions to true label
                 correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                 total += data.size(0)
             print('Test Loss: {:.6f}\n'.format(test_loss))
             print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                 100. * correct / total, correct, total))
         # call test function
         test(loaders, model_scratch, criterion_scratch, use_cuda)
Test Loss: 3.609517
Test Accuracy: 18% (151/836)
```

Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

```
transforms.Normalize([0.485, 0.456, 0.406],[0.229,
                                   1)
transform=transforms.Compose([transforms.Resize(256),
                             transforms CenterCrop(224),
                              transforms.ToTensor(),
                             transforms.Normalize([0.485, 0.456, 0.406],[0.229, 0.224,
train_data=datasets.ImageFolder('/data/dog_images/train',transform=train_transform)
valid_data=datasets.ImageFolder('/data/dog_images/valid',transform=transform)
test_data=datasets.ImageFolder('/data/dog_images/test',transform=transform)
data_transfer={'train':train_data,'test':test_data,'valid':valid_data}
loaders={}
loaders['train'] = torch.utils.data.DataLoader(train_data,batch_size=32,shuffle=True)
loaders['valid']=torch.utils.data.DataLoader(valid_data,batch_size=32,shuffle=True)
loaders['test'] = torch.utils.data.DataLoader(test_data,batch_size=32)
### TODO: Write data loaders for training, validation, and test sets
## Specify appropriate transforms, and batch_sizes
```

1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model_transfer.

```
In [18]: import torchvision.models as models
         import torch.nn as nn
         import torch.optim as optim
         import torch
         use_cuda = torch.cuda.is_available()
         ## TODO: Specify model architecture
         model_transfer=models.vgg16(pretrained=True)
         for params in model_transfer.parameters():
             params.requires_grad=False
         classifier=nn.Sequential(nn.Linear(25088,4096),
                                 nn.ReLU(),
                                 nn.Dropout(p=0.5),
                                  nn.Linear(4096,1024),
                                   nn.ReLU(),
                                   nn.Dropout(0.5),
                                   nn.Linear(1024,133),
                                   nn.LogSoftmax(dim=1))
         model_transfer.classifier=classifier
         print(model_transfer)
         if use_cuda:
             model_transfer = model_transfer.cuda()
```

```
VGG(
  (features): Sequential(
    (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (1): ReLU(inplace)
    (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (3): ReLU(inplace)
    (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (6): ReLU(inplace)
    (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU(inplace)
    (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (11): ReLU(inplace)
    (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (13): ReLU(inplace)
    (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (15): ReLU(inplace)
    (16): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (18): ReLU(inplace)
    (19): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (20): ReLU(inplace)
    (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (22): ReLU(inplace)
    (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (24): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (25): ReLU(inplace)
    (26): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (27): ReLU(inplace)
    (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (29): ReLU(inplace)
    (30): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  )
  (classifier): Sequential(
    (0): Linear(in_features=25088, out_features=4096, bias=True)
    (1): ReLU()
    (2): Dropout(p=0.5)
    (3): Linear(in_features=4096, out_features=1024, bias=True)
    (4): ReLU()
    (5): Dropout(p=0.5)
    (6): Linear(in_features=1024, out_features=133, bias=True)
    (7): LogSoftmax()
 )
)
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reason-

ing at each step. Describe why you think the architecture is suitable for the current problem.

Answer:

In [20]: # train the model

I have changed the classifier of VGG16 Network to fit our problem. As the number of inputs to the classifier is quite high I have used three Dense layers each followed by Relu activation except the last one where i have used logsoftmax.

1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_transfer, and the optimizer as optimizer_transfer below.

1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_transfer.pt'.

```
n_{epochs=5}
         train(n_epochs, loaders, model_transfer, optimizer_transfer, criterion_transfer, use_cu
         # load the model that got the best validation accuracy (uncomment the line below)
         model_transfer.load_state_dict(torch.load('model_transfer.pt'))
Epoch: 1
                 Training Loss: 3.788508
                                                 Validation Loss: 1.627100
                                                                                    Accuracy:0.58
Validation loss decreased inf---->1.6271001531018152
Model Saved
Epoch: 2
                 Training Loss: 2.008366
                                                                                    Accuracy:0.70
                                                 Validation Loss: 1.040175
Validation loss decreased 1.6271001531018152---->1.0401754754560966
Model Saved
Epoch: 3
                 Training Loss: 1.424652
                                                                                    Accuracy:0.75
                                                 Validation Loss: 0.805102
Validation loss decreased 1.0401754754560966---->0.80510155249525
Model Saved
Epoch: 4
                 Training Loss: 1.152808
                                                 Validation Loss: 0.668165
                                                                                    Accuracy:0.78
Validation loss decreased 0.80510155249525---->0.6681654442239691
Model Saved
Epoch: 5
                 Training Loss: 0.947728
                                                 Validation Loss: 0.696090
                                                                                    Accuracy:0.76
```

1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [21]: test(loaders, model_transfer, criterion_transfer, use_cuda)
```

Test Loss: 0.723975

Test Accuracy: 78% (657/836)

1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [22]: ### TODO: Write a function that takes a path to an image as input
         ### and returns the dog breed that is predicted by the model.
         # list of class names by index, i.e. a name can be accessed like class_names[0]
         class_names = [item[4:].replace("_", " ") for item in data_transfer['train'].classes]
         def predict_breed_transfer(img_path):
             # load the image and return the predicted breed
             im=Image.open(img_path)
             transform=transforms.Compose([transforms.Resize((224,224)),
                                           transforms.ToTensor(),
                                           transforms.Normalize([0.485, 0.456, 0.406],[0.229, 0.
             im=transform(im)
             im=im.unsqueeze(0)
             if use_cuda:
                 im=im.cuda()
             output=model_transfer.forward(im)
             _, pred = torch.max(output, 1)
             return class_names[pred]
```

Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face_detector and human_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

1.1.18 (IMPLEMENTATION) Write your Algorithm



Sample Human Output

```
def run_app(img_path):
    ## handle cases for a human face, dog, and neither
    im=Image.open(img_path)
    transform=transforms.Compose([transforms.Resize((224,224)),
                                  transforms.ToTensor(),
                                  transforms.Normalize([0.485, 0.456, 0.406],[0.229, 0.
   im=transform(im)
    im=im.unsqueeze(0)
    if use_cuda:
        im=im.cuda()
    if dog_detector(img_path):
        print("Hello dog")
        display_img(im)
        print("Your breed is {}".format(predict_breed_transfer(img_path)))
    elif face_detector(img_path):
        print("Hello Human")
        display_img(im)
        print("You look like a {}".format(predict_breed_transfer(img_path)))
        print("You are neither a Human nor a Dog")
        print("Who are you!!!!")
        display_img(im)
    print('')
    print('')
```

Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

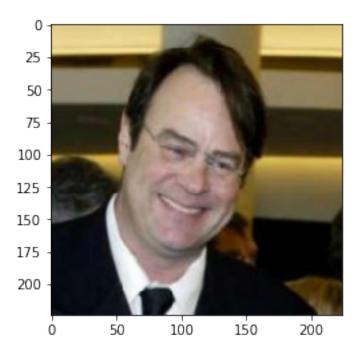
Answer:

- 1) The part of detecting whether the image contains a human or not is quite accurate. We can use a Neural Network to find whether the images contains a human or not. It's a classification Task
- 2) I could have trained the final Breed Detection by transfer learning a bit more. The accuracy could have increased.But I have stopped at 5 epochs as it's a very large network.
- 3) After making the network from scratch the accuracy was pretty bad and the loss wasn't converging. I would be happy if i have made a network which gives more accuracy

```
In [24]: ## TODO: Execute your algorithm from Step 6 on
    ## at least 6 images on your computer.
    ## Feel free to use as many code cells as needed.

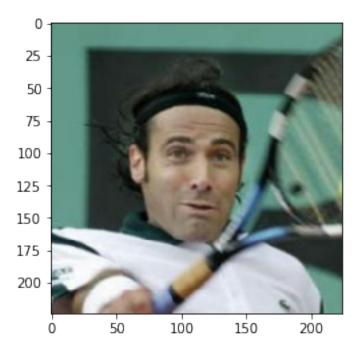
## suggested code, below
for file in np.hstack((human_files[:3], dog_files[:3])):
    run_app(file)
```

Hello Human



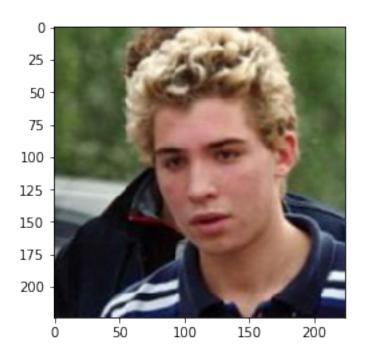
You look like a American staffordshire terrier

Hello Human



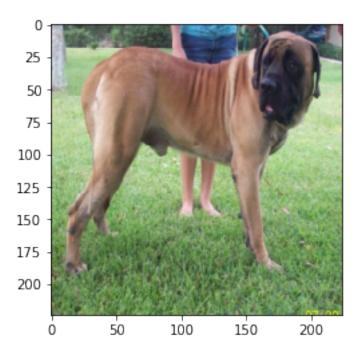
You look like a Chinese crested

Hello Human



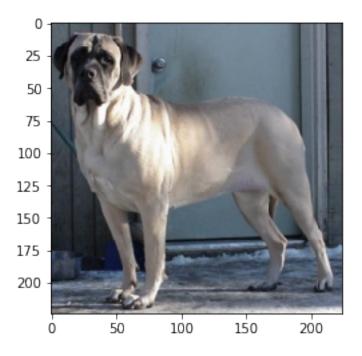
You look like a Chesapeake bay retriever

Hello dog



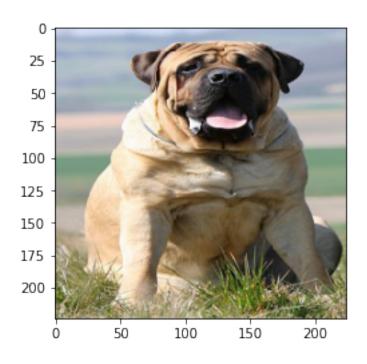
Your breed is Mastiff

Hello dog



Your breed is Bullmastiff

Hello dog



Your breed is Mastiff

In []: