CMPE 200 Computer Architecture & Design

Lecture 1. Computer Architecture & Design Overview (1)

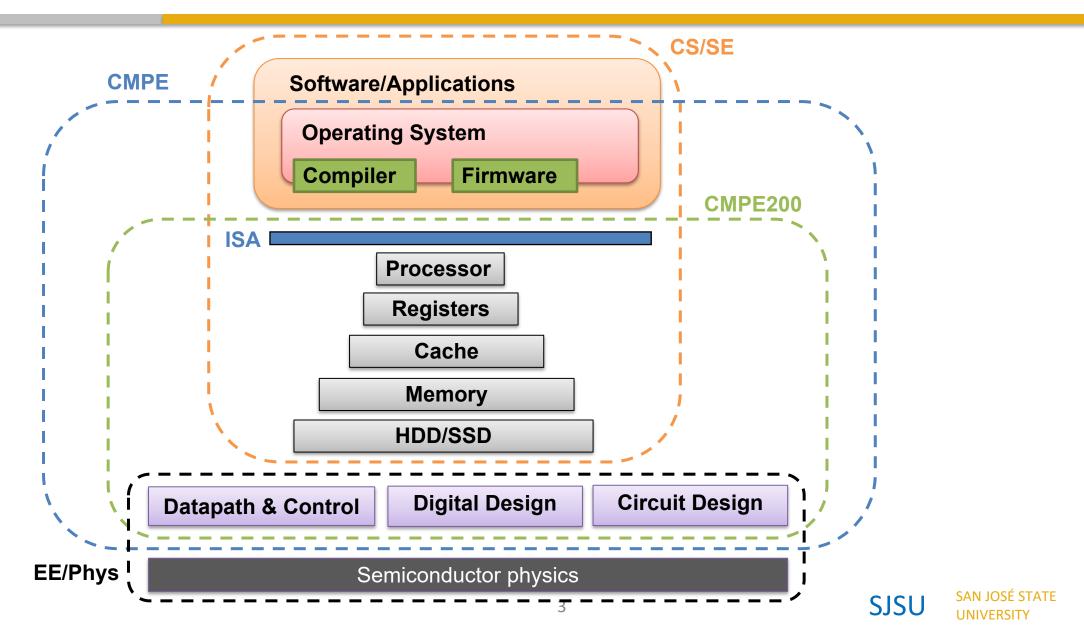
Haonan Wang



About Prerequisite – What to Submit?

- If you have 180D in your admission letter
 - You then need to submit your transcript with 180D highlighted
 - You cannot take this course before finishing 180D
- If you do not have 180D in your admission letter
 - You then need to submit your admission letter

Abstraction of Computers



The Software's Point of View

Application software

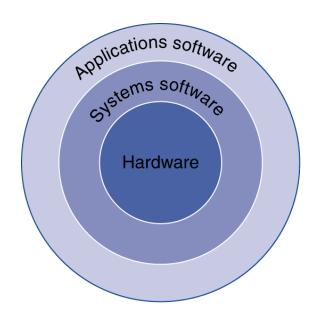
Written in high-level language

System software

- Compiler: translates HLL code to machine code
- Operating System: service code
 - Handling input/output
 - Managing memory and storage
 - Scheduling tasks & sharing resources

Hardware

Processor, memory, I/O controllers, ...





The Codes' Point of View

High-level language

- Abstraction Level closer to problem domain
- Provides for productivity and portability

Assembly language

Textual representation of instructions

Hardware representation

- Binary digits (bits)
- Encoded instructions and data

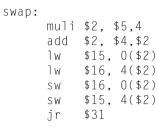
High-level language program (in C)

swap(int v[], int k)
age

{int temp;
temp = v[k];
v[k] = v[k+1];
v[k+1] = temp;



Assembly language program (for MIPS)



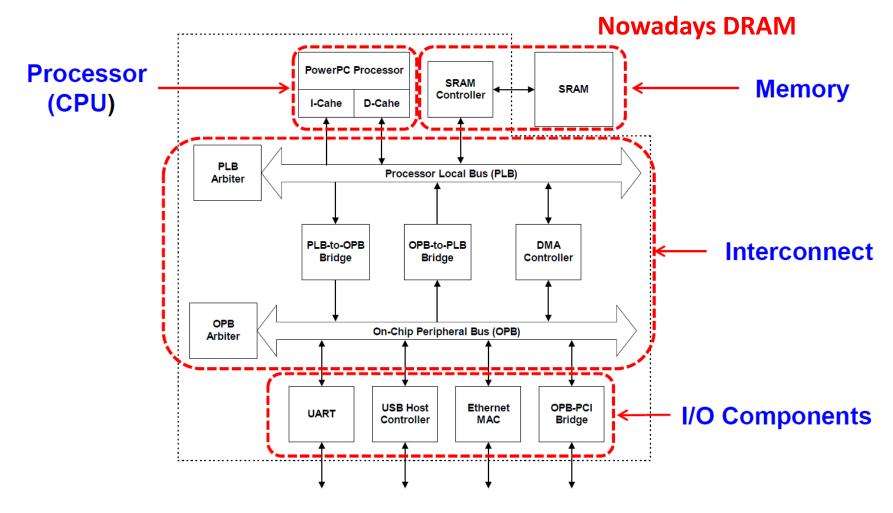


Binary machine language program (for MIPS) 

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Hardware's Point of View

Computer Organization:



Your Thoughts

Try to conclude with as few words as possible:

Computer Organization vs. Computer Architecture

– What is the key difference?

Connection vs. interface

Hardware Examples





- * Skyworks SKY77356-8 Power Amplifier Module
- * Avago ACPM-8020 Power Amplifier Module
- RF Micro Devices RF5159 Antenna Switch
- * Avago ACPM-8010 Power Amplifier Module
- Skyworks SKY77802-23 Power Amplifier Module
- # TriQuint TQF6410 Power Amplifier Module (possibly includes switch)
- Qualcomm QFE1100 Envelope Power Tracker
- Qualcomm MDM9625M Baseband Processor
- Bosch Sensortec BMA280 3-Axis Accelerometer MEMS
- # InvenSense MPU-6700? 6-Axis Gyro and Accelerometer MEMS
- Apple A8 / APL1011 Applications Processor
- Micron EDF8164A3PM-GD-F 1 GB LPDDR3 SDRAM Memory
- RF Micro Devices RF1331 RF Antenna Tuner





Package on Package





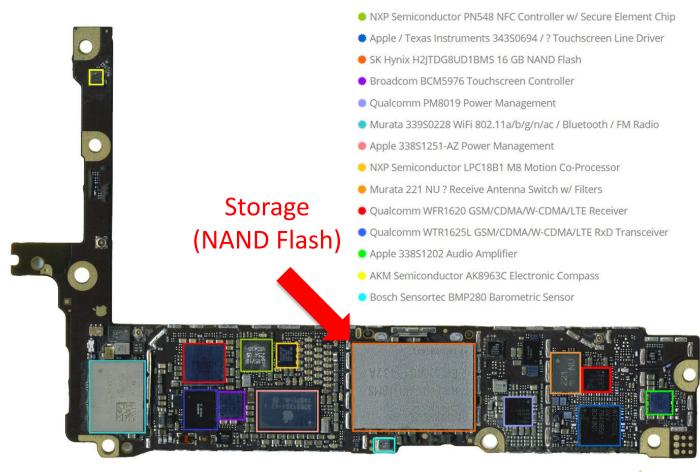




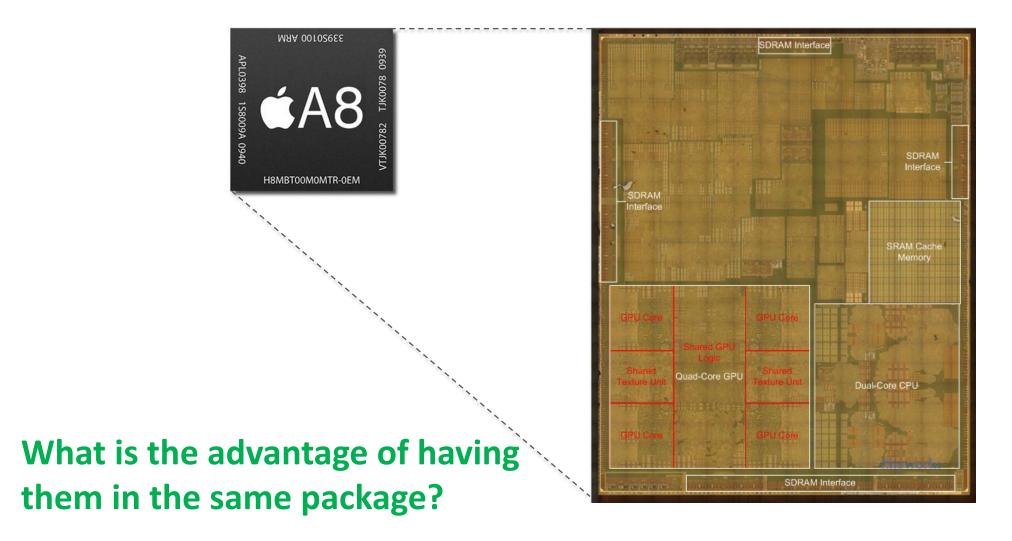
Hardware Examples



Input/output device (touch screen)



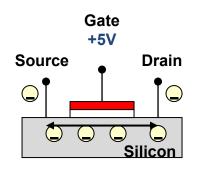
Hardware Examples

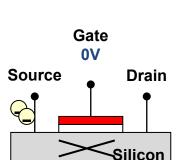


Electronic Components' Point of view

Transistors

- 3-terminal device
- Gate input: the control input; its voltage determines whether current can flow
- Source & Drain: terminals that current flows from/to
- Many transistors can be fabricated on one piece of silicon (i.e. an integrated chip, IC)





Transistor is 'on'

High voltage at gate allows current to flow between source and drain

Transistor is 'off'

Low voltage at gate prevents current from flowing between drain and source

Integrated Circuit



Actual silicon wafer is quite small but can contain several billion transistors



Silicon wafer is then packaged to form the chips we are familiar with

More transistors = faster core?

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Moore's Law (1965)



In 1975, he recalibrated it to every two years.
Later, it is recalibrated again to 18 months, as is widely known as Moore's Law.

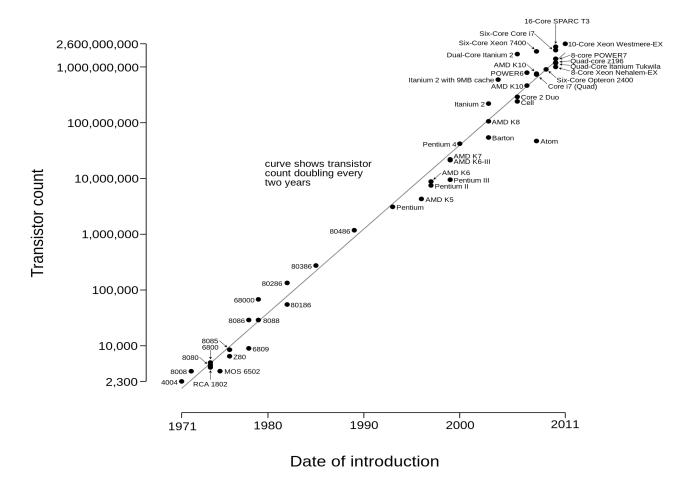
"The number of transistors per square inch on integrated circuits had doubled every year since the integrated circuit was invented and this trend would continue for the foreseeable future."

-- Gordon E. Moore, "Cramming More Components onto Integrated Circuits," Electronics, pp. 114–117, April 19, 1965.

Moore's Law (1965)

The law has been preserved over four decades..

Microprocessor Transistor Counts 1971-2011 & Moore's Law



What Does It Enable?

Applications that were impossible to run on the computers before

- 3D games, Augmented reality, Virtual reality, Deep learning...

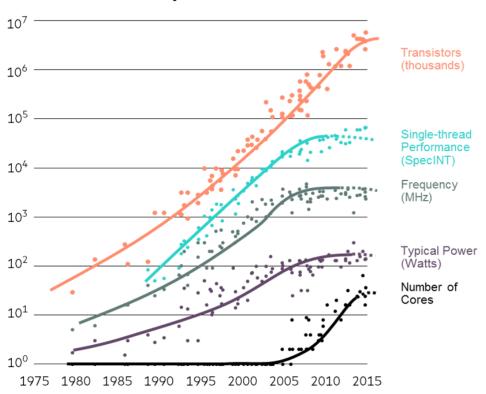




Moore's Law (1965)

Will it last forever?

Microprocessors

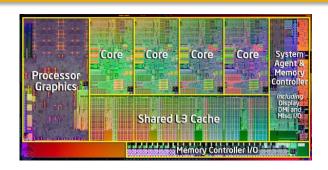


Dead?

Current Trend of Computer Systems

Multi- or Many-core Processors

- Embedding multiple cores in one CPU



Complex microarchitecture

- Out-of-order execution, branch predictor, memory prefetcher, etc...

Accelerators

- GPUs, FPGAs, etc..
- Application specific designs



Novel architectures

- Dark silicon, 3D-stacking, neuromorphic computing, quantum, etc...

Metrics: How Do We Evaluate a System?

- Performance (speed)
 - Response time (Latency):
 - How long it takes to do a task
 - Throughput :
 - Total work done per unit time
- Power efficiency
 - How much power it consumes to do a task
- Cost



What Determines Performance?

Algorithm

- Determines number of operations executed
- Programming language, compiler, architecture
 - Determine number of machine instructions executed per operation
- Processor and memory system
 - Determine how fast instructions are executed
- I/O system (including OS)
 - Determines how fast I/O operations are executed

Relative Performance

- Define Performance = 1/Execution Time
- "X is n times faster than Y"

Performance_x/Performance_y

= Execution time $_{Y}$ /Execution time $_{X} = n$

Example: time taken to run a program -- 10s on a computer A, 15s on computer B

Execution Time_B / Execution Time_A = 15s / 10s = 1.5

A is 1.5 times faster than B.

Measuring Execution Time

Elapsed time

- Total response time, including all aspects
 - Processing, I/O, OS overhead, idle time
- Determines system performance

CPU time

- Time spent processing a given job on CPU
 - Discounts I/O time, other jobs' shares
- Estimating CPU time is relatively easy based on the number of lines of code and processing speed of the CPU

Conclusion Time

Why do we need multi-core processors to keep the Moore's Law alive?

Adding transistors no longer works

How do we evaluate a system?

- Performance
- Power efficiency
- Cost



Conclusion Time

Why do we use CPU time to measure the performance?

Avoid influences

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