## VIT-AP AMARAVATI

## Assignment, Winter 2020

MAT2005 - Linear Algebra

Due:06.06.2020

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Points: 20

## Answer all the questions

1. Convert the following differential equation into a system, solve the system and use this solution to get the solution to the original differential equation.

$$2y'' + 5y' - 3y = 0$$
,  $y(0) = -4$   $y'(0) = 9$ 

2. A car rental agency has three rental locations, denoted by 1, 2, and 3. A customer may rent a car from any of the three locations and return the car to any of the three locations after, say, t days. The manager finds that customers return the cars to the various locations according to the probabilities given in the transition matrix:

$$P = \begin{bmatrix} 0.8 & 0.3 & 0.2 \\ 0.1 & 0.2 & 0.6 \\ 0.1 & 0.5 & 0.2 \end{bmatrix}$$

- (a) If the car was at rental location 1 initially, what is the probability that it will be at rental location 3 after 3 days? What is the probability that it will be at rental location 2 after 3 days?
- (b) What is the state vector for the system after 4 years?
- (c) Discuss the behaviour of  $\mathbf{x}(n) = P^n \mathbf{x}(0)$  as  $n \to \infty$ .
- 3. Find the canonical form of the quadratic form  $3x_1^2 + 2x_2^2 + x_3^2 + 4x_1x_2 + 4x_2x_3$  and discuss its definiteness.

4.

(a) Find an orthogonal basis for the column space of the matrix

$$A = \begin{bmatrix} 2 & 2 & 3 \\ 1 & 3 & 3 \\ -1 & -2 & -2 \end{bmatrix}$$

- (b) Find QR-decomposition of A such that A = QR.
- (c) For u = (0, 2, 1, 0), find  $u = w_1 + w_2$  such that  $w_1 \in W = C(A)$  and  $w_2 \in W^{\perp}$ .
- (d) Find the Jordan form of A.
- 5. Given  $A = \begin{bmatrix} 2 & -1 & 3 \\ 3 & 1 & 0 \end{bmatrix}$ 
  - (a) Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be the linear transformation whose representation is A with respect to the ordered bases  $B = \{(1,0,-1),(0,2,0),(1,2,3)\}$  and  $B' = \{(1-1),(2,0)\}$ . Find the representation of T with respect to the natural bases for  $\mathbb{R}^3$  and  $\mathbb{R}^2$ . Also, find bases for kernel and Range of T.
  - (b) Find the Psuedoinverse of the A through SVD.