

Lecture 1: Basics of Graph Theory

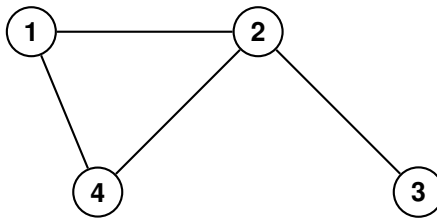
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In this lecture, we will be dealing with some basic terminology required to learn Graph Theory.

A graph G is a pair $G = (V, E)$, where V is a finite set and E is a set of 2-element subsets of V . The elements of V are called vertices of the graph G and the elements of E are called edges of G .

For a graph $G = (V, E)$, let $V(G)$ & $E(G)$ denote the vertex and edge set of G respectively.

Example:-



$$V = \{1, 2, 3, 4\}$$
$$E = \{\{1, 2\}, \{1, 4\}, \{2, 3\}, \{2, 4\}\}$$

The number of vertices of a graph G is its order(or size), denoted as $|G|$ or $|V|$.

Note:-

- From this lecture onwards n denotes the number of vertices in a graph.
- Also m denotes the number of edges in a graph.
- The graphs we consider in this course are finite unless otherwise stated.

An edge x, y is usually written as xy (or yx). Two vertices x, y of G are adjacent or neighbours if xy is an edge of G . Two edges e, f are adjacent if they have an end in common.

Definition 1.1 (Degree(or Valency)). *The degree(or valency) of a vertex v in a graph G is the number of edges incident with v , with loops counted twice. It is denoted by $\deg_G(v)$ or $d(v)$.*

Lemma 1.2 (Handshaking Lemma). *The sum of the degrees of the vertices of a graph equals twice the number of edges.*

Proof. Each edge contributes two to the sum of the degrees, one for each of its endpoints.

$$2|E| = \sum_{v \in V} d(v)$$

□

Corollary 1.3. *In any graph G , the number of vertices of odd degree is even.*

Proof. We know that

$$2|E| = \sum_{v \in V} d(v)$$

$$\underbrace{2|E|}_{\text{EVEN}} = \underbrace{\sum_{\substack{v \in V \\ d(v) \text{ is odd}}} d(v)}_{\mathbf{x}} + \underbrace{\sum_{\substack{v \in V \\ d(v) \text{ is even}}} d(v)}_{\text{EVEN}}$$

For the above equation to satisfy the value of \mathbf{x} should be even (i.e. for the LHS to be even sum of terms of RHS should be even, which is only possible when value of \mathbf{x} is even since the other term is even.) □

Definition 1.4 (Isolated vertex). *A vertex of degree zero is called isolated vertex.*

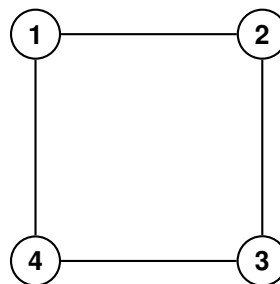
Definition 1.5 (Minimum degree). *The degree of the vertex with the least number of edges incident to it (i.e. $\min\{d(v) : v \in V\}$) is the minimum degree of G . It is represented by $\delta(G)$*

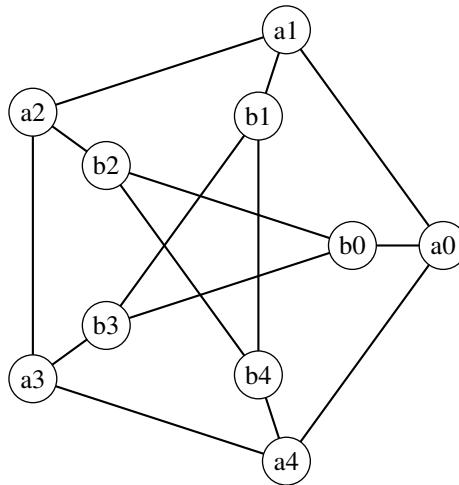
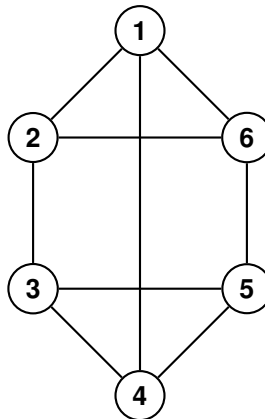
Definition 1.6 (Maximum degree). *The degree of the vertex with the most number of edges incident to it (i.e. $\max\{d(v) : v \in V\}$) is the maximum degree of G . It is represented by $\Delta(G)$*

Definition 1.7 (Regular Graph). *If all the vertices of G have the same degree k then the graph G is called k -regular.*

Example:-

(a) 2-Regular Graph

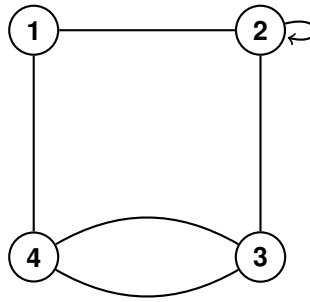


(b) Petersen's Graph(3-Regular Graph)**(c) 3-Regular Graph**

Definition 1.8 (Multiple edges). *Multiple edges are two or more edges that are incident to the same two vertices. Multiple edges are also known as parallel edges*

Definition 1.9 (Self loop). *A self-loop is an edge that connects a vertex to itself.*

Example:-



Definition 1.10 (Simple Graph). A graph with no self loops and no multiple edges is called a simple graph.

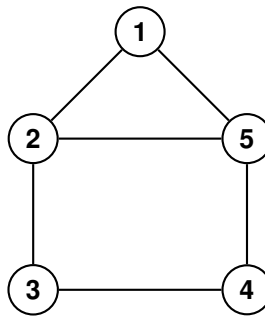
Note:- In this course unless specified all graphs are simple graphs.

Definition 1.11 (Subgraphs). A graph H is called a subgraph of a graph G , if $V(H) \subseteq V(G)$ and $E(H) \subseteq E(G)$.

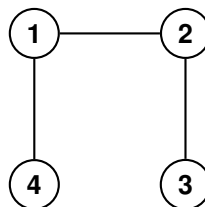
Definition 1.12 (Induced Subgraph). A subgraph H of G is called induced subgraph of G , if for any two vertices $u, v \in H$, if $uv \in E(G)$ then $uv \in E(H)$

Example:-

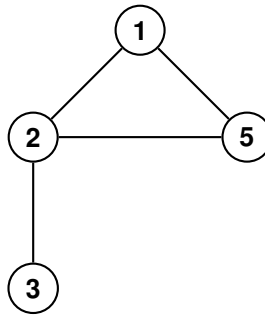
(a) Let graph G be



Let the below graph be H_1



Let the below graph be H_2



Note:-

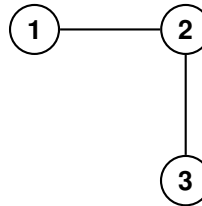
- H_1 is a subgraph of G , but not induced because $3, 4 \in V$ and edge $34 \in E(G)$ but $34 \notin E(H_1)$.
- H_2 is an induced subgraph of G because $\forall u, v \in V$ and edge $uv \in E(G)$ we have $uv \in E(H_2)$.

Representation of graphs:

1. **Adjacency matrix:** Adjacency matrix of a graph G is $n \times n$ matrix, where

$$a_{ij} = \begin{cases} 1 & \text{if } ij \in E(G); \\ 0 & \text{otherwise;} \end{cases}$$

Example:- Let graph G be,



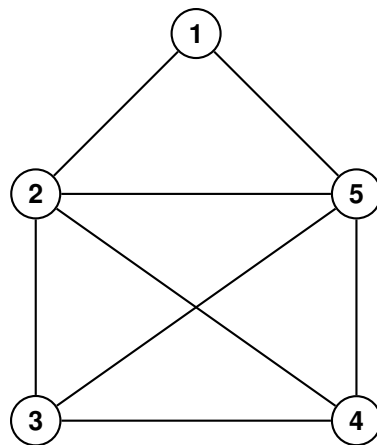
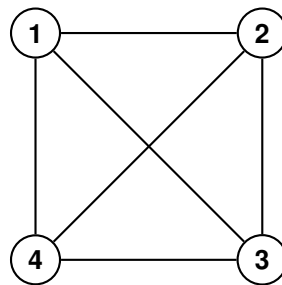
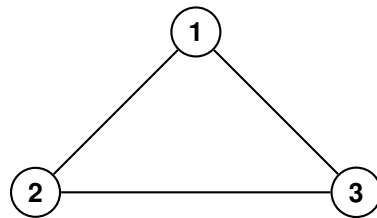
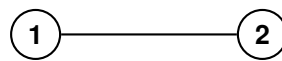
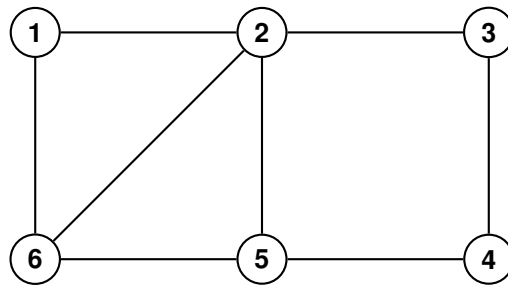
For the given graph the adjacency matrix would look like,

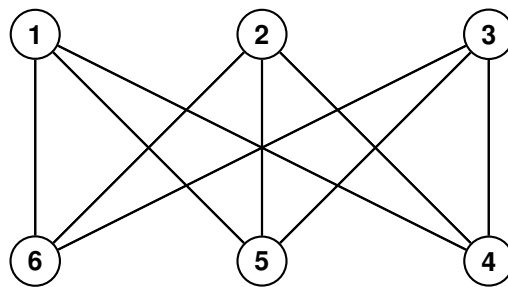
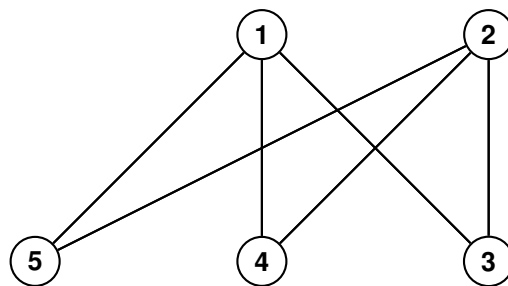
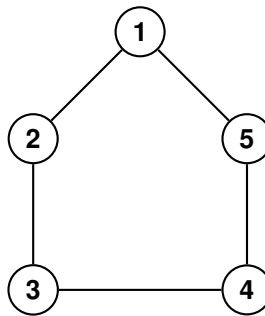
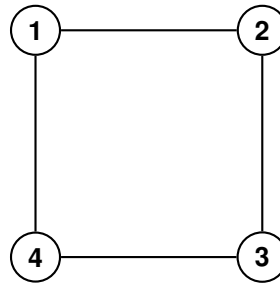
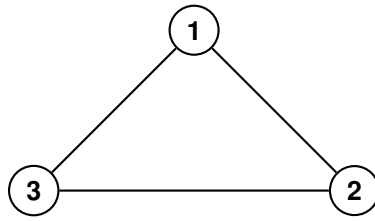
$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

2. **Adjacency list:** Adjacency list is a collection of unordered lists used to represent a finite graph. Each list describes the set of neighbors of a vertex in the graph.

The adjacency list of the given graph G is,

$$\begin{aligned} & \boxed{1} \rightarrow \boxed{2} \\ & \boxed{2} \rightarrow \boxed{1} \rightarrow \boxed{3} \\ & \boxed{3} \rightarrow \boxed{2} \end{aligned}$$





1.1 Some theorems and stuff

We now delve right into the proof.

Lemma 1.13. *This is the first lemma of the lecture.*

Proof. The proof is by induction on \dots . We also throw in a figure (which you might want to make larger).

This is the end of the proof, which is marked with a little box. □

1.1.1 A few items of note

Here is an itemized list:

- this is the first item;
- this is the second item.

Here is an enumerated list:

1. this is the first item;
2. this is the second item.

Here is an exercise:

Exercise: Find an efficient algorithm for triangulation.

Here is how to define things in the proper mathematical style. Let f_k be the *AND – OR* function, defined by

$$f_k(x_1, x_2, \dots, x_{2^k}) = \begin{cases} x_1 & \text{if } k = 0; \\ \text{AND}(f_{k-1}(x_1, \dots, x_{2^{k-1}}), f_{k-1}(x_{2^{k-1}+1}, \dots, x_{2^k})) & \text{if } k \text{ is even;} \\ \text{OR}(f_{k-1}(x_1, \dots, x_{2^{k-1}}), f_{k-1}(x_{2^{k-1}+1}, \dots, x_{2^k})) & \text{otherwise.} \end{cases}$$

Here is another equation that uses one of the AMS commands, align

$$\begin{aligned} p(x_{1:5}) &= \sum_{x_{2:5}} p(x_1) p(x_2|x_1) p(x_3|x_1) p(x_4|x_2) p(x_5|x_1) p(x_6|x_2, x_5) \\ &= p(x_1) \sum_{x_2} p(x_2|x_1) \sum_{x_3} p(x_3|x_1) \sum_{x_4} p(x_4|x_2) \sum_{x_5} p(x_5|x_1) p(x_6|x_2, x_5) \\ &= p(x_1) \sum_{x_2} p(x_2|x_1) \sum_{x_3} p(x_3|x_1) \sum_{x_4} p(x_4|x_2) \sum_{x_5} p(x_5|x_1) \phi_{X_6}(x_2, x_5) \end{aligned}$$

which assumes that $X_4 \perp\!\!\!\perp \{X_1, X_3\} | X_2$.

Theorem 1.14. *This is the first theorem.*

Proof. This is the proof of the first theorem. We show how to write pseudo-code now.

Consider a comparison between x and y :


```

if  $x$  or  $y$  or both are in  $S$  then
    answer accordingly
else
    Make the element with the larger score (say  $x$ ) win the comparison
    if  $F(x) + F(y) < \frac{n}{t-1}$  then
         $F(x) \leftarrow F(x) + F(y)$ 
         $F(y) \leftarrow 0$ 
    else
         $S \leftarrow S \cup \{x\}$ 
         $r \leftarrow r + 1$ 
    endif
endif

```

This concludes the proof. □

1.2 Next topic

Here is some citations [JB00] and [L2000]

References

- [JB00] M.I. JORDAN and C. BISHOP, “An Introduction to Graphical Models,” *To be published*, 2000
- [L2000] S.L. LAURITZEN “Graphical Models,” *Oxford Science Publications*, 1996