xv6 (OS Assignment) Report

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Original xv6 Scheduler

- Original xv6 scheduler is a round robin scheduler
- On testing the original scheduler with 3 "myprog" (test programs) programs, it was observed that the process which started earlier finished earlier.
- Also, there is no way to set priority or make a runnable program running unless a program exits (because of overshooting out of time quantum given to it).

Priority Based xv6 Scheduler

- We've implemented a priority based scheduler
- Priority number can be between 1 to 100. Lower the number higher will be the priority. All the processes are initially given priority 60.
- On testing the priority based scheduler with 3 "myprog" (test programs) programs, it was observed that the process which higher priority finished earlier.
- We can adjust priority of the processes with set_priority command.

For Round Robin Based xv6 Scheduler

Two processes with same priority have been created with command myprog &

----first process created
\$ myprog &
\$ ps
NAME PID STATE PRIORITY
init 1 SLEEPING 60
sh 2 SLEEPING 60
ps 5 RUNNING 60
myprog 4 RUNNABLE 60

----second process created \$ myprog & \$ ps NAME PID STATE PRIORITY init 1 SLEEPING 60 sh 2 SLEEPING 60
ps 8 RUNNING 60
myprog 4 RUNNING 60
myprog 7 RUNNABLE 60

----now note that each of the following ps were done in gap of 1 second.

\$ ps

NAME PID STATE PRIORITY

init 1 SLEEPING 60

sh 2 SLEEPING 60

ps 9 RUNNING 60

myprog 4 **RUNNING** 60 myprog 7 RUNNABLE 60

\$ ps

NAME PID STATE PRIORITY

init 1 SLEEPING 60

sh 2 SLEEPING 60

ps 10 RUNNING 60

myprog 4 **RUNNING** 60 myprog 7 RUNNABLE 60

\$ ps

NAME PID STATE PRIORITY

init 1 SLEEPING 60

sh 2 SLEEPING 60

ps 11 RUNNING 60

myprog 4 RUNNABLE 60 RUNNING 60

Here we can clearly see (in **BOLD** font) that once the time quantum for pid=5 elapses, its state changes from Running to Runnable. The processes swap irrespective of their priorities: Round-robin Scheduling.

For Priority Based xv6 Scheduler

- Here we simply ran the code with modified scheduling algorithm. Now, set priority of the last process to 10, so that it is executed before all others.
- Create two processes similar to previous experiment

---create first program
\$ myprog &
\$ ps
NAME PID STATE PRIORITY
init 1 SLEEPING 60

```
sh 2
      SLEEPING 60
ps 5
      RUNNING 60
           RUNNABLE 60
myprog 4
---create second program
$ myprog &
$ ps
NAME PID STATE PRIORITY
init 1 SLEEPING 60
sh 2
      SLEEPING 60
ps 8
      RUNNING 60
           RUNNING 60
myprog 4
           RUNNABLE 60
myprog 7
---change the priority of one process higher than the others
$ set priority 7 10
pid=7, new-priority=10
----following ps were run at time gap of 2 seconds.
$ ps
NAME PID STATE PRIORITY
init 1 SLEEPING 60
sh 2
      SLEEPING 60
ps 10 RUNNING 60
           RUNNABLE 60
myprog 4
myprog 7
           RUNNING 10
$ ps
NAME PID STATE PRIORITY
init 1 SLEEPING 60
sh 2
      SLEEPING 60
ps 11 RUNNING 60
myprog 4
           RUNNABLE 60
myprog 7
           RUNNING 10
$ ps
NAME PID STATE PRIORITY
     SLEEPING 60
init 1
sh 2
      SLEEPING 60
ps 12 RUNNING 60
           RUNNABLE 60
myprog 4
myprog 7
           RUNNING 10
$ ps
NAME PID STATE PRIORITY
init 1 SLEEPING 60
sh 2
      SLEEPING 60
ps 13 RUNNING 60
```

RUNNABLE 60

myprog 4

myprog 7 RUNNING 10

--- so here we can clearly see once the process with highest priority comes, it's executed first (state=RUNNING for pid=7) and then others are executed (see pid=4 after set priority).