

NORTH SOUTH UNIVERSITY

Department of Electrical & Computer Engineering

Project Report

Course Code: CSE331

Course Title: Microprocessor Interfacing & Embedded System

Submitted by_

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Section : 03 (Group - 5)

Title : PIN Code Based Door Lock System.

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Submitted to

Instructor : Syed Mahmud Husain (SMH2)

Project Title: PIN Code Based Door Lock System.

Objective:

The objective behind designing the "PIN Code Based Door Lock System" is to provide many modern security features than mechanical lock (Motor as a Lock) and utilize our understanding in Microcontroller and Embedded C Programming. The system can install in any doors. The electric combination lock system uses a 5-digit PIN code. We will try to build this project in order to obtain these goals:

- To develop a unique safety system.
- Unlock door by entering pre-defined pin-code.
- Provide clear indications to users about ready to enter pin, successful entries and incorrect passwords.
- Balance the security features with affordability to make the system accessible.

Block Diagram:

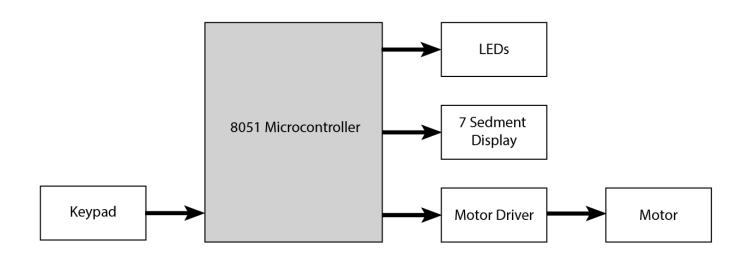


Fig: PIN Code Based Door Locked System Block Diagram

Component List & Estimated Price:

	Components	Quantity	Price
1.	8051 Kit	1	2,190 TK
2.	USB ASP AVR Programming Cable	1	410 TK
3.	DC 5V Stepper Motor with ULN2003 Driver	1	199 TK
4.	3x4 Flexible Keypad	1	95 TK
5.	1 Digit 7-Segment Display	1	12 TK
6.	5 MM LEDs	3	15 TK
7.	220 Ohm Resistors	1x5	5 TK
8.	Breadboard	1	150 TK
9.	Jumper Wires M-M	1x40	100 TK
10.	Power Source		
			Total: 3,176 TK

Circuit Diagram:

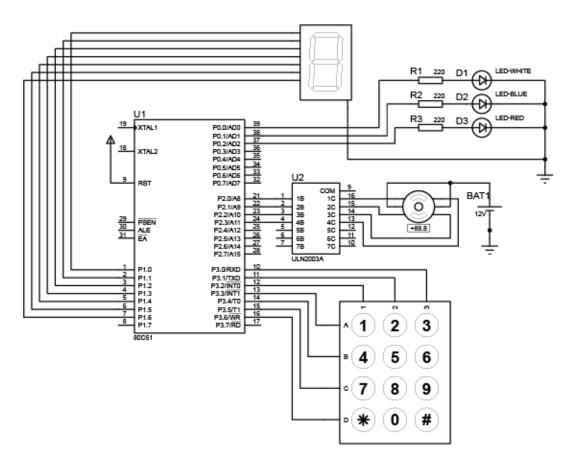
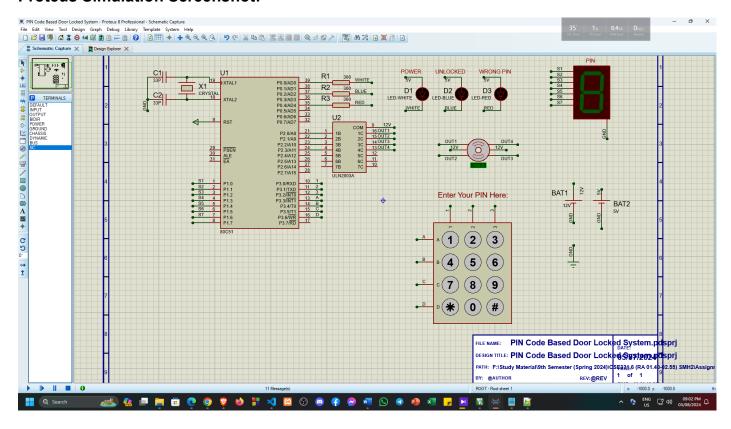


Fig: PIN Code Based Door Locked System Circuit Diagram

Proteus Simulation Screenshot:



Embedded C Programming Code:

```
1 #include <reg51.h>
 2 #include <string.h>
 3 // Pin configuration for LEDs
 4 sbit lw = P0^{\circ};
 5 sbit lb = P0^2;
 6 sbit lr = P0^4;
 8 // Pin configuration for 7-segment display
 9 sbit da = P1^0;
10 sbit db = P1^1;
11 sbit dc = P1^2;
12 sbit dd = P1^3;
13 sbit de = P1^4;
14 sbit df = P1^5;
15 sbit dg = P1^6;
17 // Pin configuration for stepper motor
18 sbit m1 = P2^{\circ};
19 sbit m2 = P2^1;
20 sbit m3 = P2^2;
21 sbit m4 = P2^3;
23 // Pin configuration for keypad column
24 sbit c1 = P3^{0};
25 \text{ sbit } c2 = P3^1;
26 \text{ sbit } c3 = P3^2;
```

```
27
28 // Pin configuration for keypad row
29 sbit r1 = P3^3;
30 sbit r2 = P3^4;
31 sbit r3 = P3^{5};
32 sbit r4 = P3^{6};
33
34 int n; // counter
35 char key; // pressed digit
36 char codes[] = "54321";
                              // PIN Code
37 char id[5];
39 // Function Declaration
                             // Initialize LEDs
40 void init led();
                            // Initialize 7-segment display
41 void init display();
                             // Delay function
42 void delay(int);
43 char scan_key();
                                                           // get digit
44 char read keypad();
                                                   // access the keypad
45 void display digit(char); // display the digit
46 void door_open();
                                                           // open door
47 void door close();
                                                   // close door
48
49 void main() {
50
          for(;;) {
                  P1 = 0 \times 00; //Using port 1 as output port
51
52
                  P2 = 0x00;
                                 //Using port 1 as output port
                                 //Using port 1 as input port
53
                  P3 = 0xff;
54
                  P0 = 0x00;
                                 //Using port 1 as output port
55
                  lw = 1;
56
                  lb = 1;
57
                  lr = 1;
58
                  init led();
59
                  init display();
60
                  n = 0;
61
                  while (n<5) {
                          key = scan key();
62
                          id[n] = key;
63
64
                          delay(100);
65
                          n++;
66
67
                  if(strcmp(codes, id) == 0) {
68
                          door_open();
69
70
71
                  else{
72
                          lw = 0;
73
                          lr = 0;
                          delay(4000);
74
                          lr = 1;
75
76
                          delay(2);
77
                  }
78
          }
79 }
80
81 void door open() {
          lw = 0;
82
          lb = 0;
83
84
          delay(200);
85
          m4 = 1;
86
          m2 = m3 = m1 = 0;
87
          delay(200);
88
          m3 = 1;
```

```
89
           m1 = m2 = m4 = 0;
           delay(5000);
 90
 91
           door close();
 92
           delay(200);
 93
 94 }
 95 void door close() {
 96
           lw = 0;
           lb = 1;
 97
 98
           delay(200);
 99
           m4 = 1;
100
           m1 = m2 = m3 = 0;
101
           delay(200);
102
           m1 = 1;
103
           m2 = m3 = m4 = 0;
104
           delay(200);
105
106 }
107
108
109 void init led() {
110
                   delay(2);
111
       lw = 0; // lw LED always on
112
                    delay(2);
113 }
114
115 void init display() {
116
                   da=db=dc=dd=de=df=dg=0;
117
                   delay(2);
118 }
119
120 char scan key()
121 {
122
           char b='a';
123
           while (b=='a') {
124
                   b=read keypad();
125
126
           return b;
127 }
128 //Function to take input from Lcd Keyboard 4*3
129 char read keypad() {
130
           c1=c2=c3=1; // all columns are initially low
131
           r1=r2=r3=r4=0; // all rows are initially low (active-high)
132
133
           //when first row is active and others are incactive
134
           r1=0;
135
           r2=r3=r4=1;
           //if row=0 column=0 then 1 is returned or if we enter 1 in keypad 2
136
137
           if(c1==0){
138
                    display digit('1');
139
                    delay(2);
140
                   return '1';
141
142
           //if row=0 column=1 then 2 is returned or if we enter in keypad 2
143
           if(c2==0){
144
                    display_digit('2');
145
                    delay(2);
146
                    return '2';
147
148
           //if row=0 column=2 then 3 is returned or if we enter in keypad 3
149
           if(c3==0){
150
                    display_digit('3');
```

```
151
                    delay(2);
                   return '3';
152
153
           }
154
155
           //when second row is active and others are incactive
156
           r2=0;
157
           r1=r3=r4=1;
158
           //if row=1 column=0 then 4 is returned or if we enter in keypad 4
159
           if(c1==0){
160
                    display digit('4');
161
                    delay(2);
162
                   return '4';
163
164
           //if row=1 column=1 then 5 is returned or if we enter in keypad 5
165
           if(c2==0){
166
                    display_digit('5');
167
                   delay(2);
168
                   return '5';
169
170
           //if row=1 column=2 then 6 is returned or if we enter in keypad 6
171
           if(c3==0){
172
                   display digit('6');
173
                   delay(2);
174
                   return '6';
175
           }
176
177
           //when third row is active and others are incactive
178
           r3=0;
179
           r1=r2=r4=1;
180
           //if row=2 column=0 then 7 is returned or if we enter in keypad 7
181
           if(c1==0){
                   display digit('7');
182
183
                   delay(2);
184
                   return '7';
185
186
           //if row=2 column=1 then 8 is returned or if we enter in keypad 8
187
           if(c2==0){
188
                   display digit('8');
189
                   delav(2);
190
                   return '8';
191
192
           //if row=2 column=2 then 9 is returned or if we enter in keypad 9
193
           if(c3==0){
194
                   display digit('9');
195
                   delay(2);
196
                   return '9';
197
           }
198
199
           //when fourth row is active and others are incactive
200
           r4=0;
201
           r1=r2=r3=1;
           //if row=3 column=0 then * is returned or if we enter in keypad *
202
203
           //if(c1==0){
204
                   lcddata('*');
205
                   delay(2);
206
                   return 0;
207
208
           //if row=3 column=1 then 0 is returned or if we enter in keypad 0
209
210
                    display_digit('0');
211
                   delay(2);
212
                   return '0';
```

```
213
            }
214
215
           return 'a';
216 }
217
218 void display digit(char digit) {
219
        switch (digit) {
            case '0':
220
                da = db = dc = dd = de = df = 1;
221
222
                dg = 0;
223
                break;
            case '1':
224
225
                db = dc = 1;
226
                da = dd = de = df = dg = 0;
227
                break;
228
            case '2':
229
                da = db = dd = de = dg = 1;
                dc = df = 0;
230
231
                break;
232
            case '3':
233
                da = db = dc = dd = dg = 1;
234
                de = df = 0;
235
                break;
236
            case '4':
                db = dc = df = dq = 1;
237
238
                da = dd = de = 0;
239
                break;
            case '5':
240
241
                da = df = dd = dc = dg = 1;
242
                db = de = 0;
243
                break;
            case '6':
244
245
                da = dc = dd = de = df = dg = 1;
246
                db = 0;
247
                break;
248
            case '7':
249
                da = db = dc = 1;
250
                dd = de = df = dq = 0;
251
                break;
252
            case '8':
253
                da = db = dc = dd = de = df = dg = 1;
254
                break;
            case '9':
255
                da = db = dc = dd = de = df = dg = 1;
256
257
258
                break;
259
            default:
260
                break;
261
262
        delay(300); // Delay for 200ms to display the digit
263
        init display(); // Turn off the display after showing the digit
264 }
265
266 void delay(int ms) {
267
        int i, j;
268
        for (i = 0; i < ms; i++)</pre>
269
            for (j = 0; j < 120; j++);
270 }
```

Discussion:

Here we'll build a PIN Code Based Digital Lock System using 8051 Microcontroller. We'll use a stepper motor as a door lock. It'll unlock the door by rotating the motor 0 degree to 180 degree. We'll use three different color of LED light as indicator. If the system is getting power, then it'll turned on the White LED whole time. If the given PIN code is correct, it will rotate the motor and unlock the door and indicate it by blinking the Blue LED, and if the given PIN code is wrong then the Red LED will blink. We'll define a 5-digit PIN code via programming manually. For getting the PIN as input we'll use a 3x4 Matrix Keypad. The PIN code can be any number between 00001 to 99999. We'll use a single digit 7-segment display, where the given current digit will be display for 2 or 3 seconds. For example, if our PIN code is "12345" then if we started to giving the input, when we press "1", the 7-segment will show 1 for 2 or 3 seconds. Then if we press "2" then the display will show "2" for 2 or 3 seconds. After giving input "12345" if it matches with our PIN that we set for unlocking the door then the Blue LED will blink for 4 or 5 second, which means our PIN is correct. Then the motor will rotate and unlock the door. The door will automatically lock again after 30 seconds. To unlock the door again we need to enter PIN again. We find the idea of building this system from some online source. The link of those sources are in the Reference section:

References:

- 1. https://www.electronicshub.org/password-based-door-lock-system-using-8051-microcontroller/
- 2. https://github.com/Sayed-Noman/NSU-CSE331-Password-Based-Door-Lock-Using-8051-Microcontroller?tab=readme-ov-file