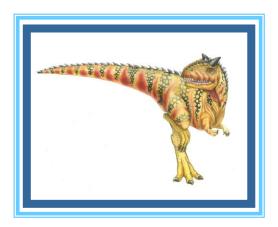
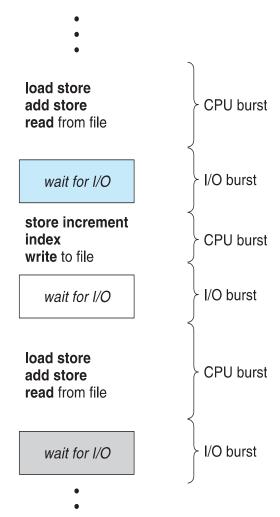
Process Scheduling





Basic Concepts

- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle Process execution consists of a cycle of CPU execution and I/O wait
- □ CPU burst followed by I/O burst
- CPU burst distribution is of main concern







CPU Scheduler

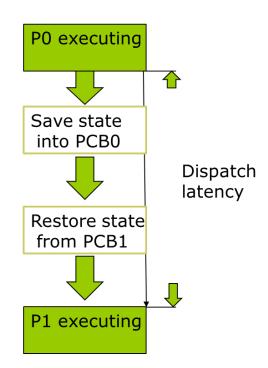
- Short-term scheduler selects from among the processes in ready queue, and allocates the CPU to one of them
 - Queue may be ordered in various ways
- CPU scheduling decisions may take place when a process:
 - Switches from running to waiting state
 - 2. Switches from running to ready state
 - 3. Switches from waiting to ready
 - Terminates
- □ Scheduling under 1 and 4 is nonpreemptive
- Otherwise it is preemptive
 - Consider access to shared data
 - Consider preemption while in kernel mode
 - Consider interrupts occurring during crucial OS activities





Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
 - switching context
 - switching to user mode
 - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running







Scheduling Criteria

- ☐ **CPU utilization** keep the CPU as busy as possible
- Throughput # of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)





Scheduling Algorithm Optimization Criteria

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time



<u>Formulas:</u>

- □ TAT = ET AT or TAT = WT + BT
- \square WT = TAT BT \circ
 - Non-preemptive:
 - WT = First CPU Receive Time AT
 - **Preemptive:**
 - WT = Final CPU Receive Time AT Cumulative Previous Burst Time
- □ RT = First CPU Receive Time AT

Where:

TAT –Turnaround time

ET – Exit or Completion Time

BT - Burst Time

WT – Waiting Time, RT – Response Time,

AT - Arrival Time



First-Come, First-Served (FCFS) Scheduling

<u>Process</u>	Burst Time	
P_1	24	
P_2	3	
P_3	3	

Suppose that the processes arrive in the order: P_1 , P_2 , P_3 The Gantt Chart for the schedule is:

	P ₁	P ₂	P ₃
0	24	2	7 30

- U Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- □ Average waiting time: (0 + 24 + 27)/3 = 17





Exercise

PID	Α	В	С	D	Е
AT	3	5	0	5	4
ВТ	4	3	2	1	3





Solution

GANTT CHART

С	Idle time	Α	E	В	D	
0	2	3	7	10	13	14

PID	AT	вт	ET	TAT	WT
Α	3	4	7	4	0
В	5	3	13	8	5
С	0	2	2	2	0
D	5	1	14	9	8
E	4	3	10	6	3
			Average:	5.8	3.2

What is the average Response Time?





FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2$$
, P_3 , P_1

The Gantt chart for the schedule is:



- □ Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- □ Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case
- Convoy effect short process behind long process
 - Consider one CPU-bound and many I/O-bound processes





Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- □ SJF is optimal gives minimum average waiting time for a given set of processes
 - The difficulty is knowing the length of the next CPU request
 - Could ask the user





Example of SJF (Non-Premptive)

<u>Process</u>	Burst Time
P_1	6
P_2	8
P_3	7
$P_{\scriptscriptstyle A}$	3

□ SJF scheduling chart (assuming same arrival time)

	P ₄	P ₁	P_3	P ₂
0	3	9) 1	6 24

 \square Average waiting time = (3 + 16 + 9 + 0) / 4 = 7



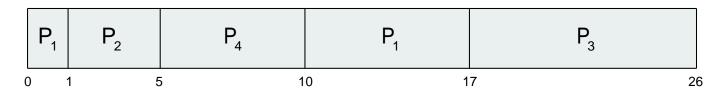


Example of Shortest-remaining-time-first (Pre-emptive SJF)

 Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>	<u> Arrival Time</u>	Burst Time
P_1	0	8
P_2	1	4
P_3	2	9
P_{4}	3	5

Preemptive SJF Gantt Chart



Average waiting time = [(10-1)+(1-1)+(17-2)+5-3)]/4 = 26/4 = 6.5 msec





Practice Exercises

Suppose that the following processes arrive for execution at the times indicated. Each process will run for the amount of time listed. In answering the questions, use nonpreemptive scheduling, and base all decisions on the information you have at the time the decision must be made.

Process	Arrival Time	Burst Time
P_1	0.0	8
P_2	0.4	4
P_3	1.0	1

- a. What is the average turnaround time for these processes with the FCFS scheduling algorithm?
- b. What is the average turnaround time for these processes with the SJF scheduling algorithm?
- c. The SJF algorithm is supposed to improve performance, but notice that we chose to run process P_1 at time 0 because we did not know that two shorter processes would arrive soon. Compute what the average turnaround time will be if the CPU is left idle for the first 1 unit and then SJF scheduling is used. Remember that processes P_1 and P_2 are waiting during this idle time, so their waiting time may increase. This algorithm could be called future-knowledge scheduling.



Priority Scheduling

- A priority number (integer) is associated with each process
- □ The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
 - Preemptive
 - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- □ Problem = Starvation low priority processes may never execute
- Solution ≡ Aging as time progresses increase the priority of the process





Example of Priority Scheduling

<u>Process</u>	Burst Time	Priority
P_1	10	3
P_2	1	1
P_3	2	4
P_4	1	5
P_5	5	2

Priority scheduling Gantt Chart



□ Average waiting time = 8.2 msec

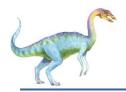




Round Robin (RR)

- □ Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- ☐ If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once. No process waits more than (*n*-1)*q* time units.
- ☐ Timer interrupts every quantum to schedule next process
- Performance
 - □ q large \Rightarrow FIFO

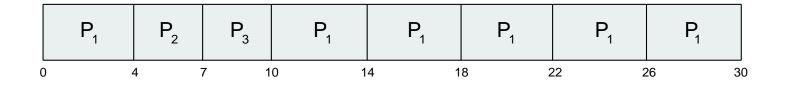




Example of RR with Time Quantum = 4

<u>Process</u>	Burst Time
P_1	24
P_2	3
P_3	3

The Gantt chart is:



- □ Typically, higher average turnaround than SJF, but better *response*
- q should be large compared to context switch time
- □ q usually 10ms to 100ms, context switch < 10 usec





Round Robin (RR): Exercise

Process Id	Arrival time	Burst time
P1	0	5
P2	1	3
P3	2	1
P4	3	2
P5	4	3

Time Quantum = 2





Round Robin (RR): Solution

(0 2	2 4	1 5	5 7	' (9 1	1 1	12 1	3 14	1
	P1	P2	P 3	P1	P4	P5	P2	P1	P 5	

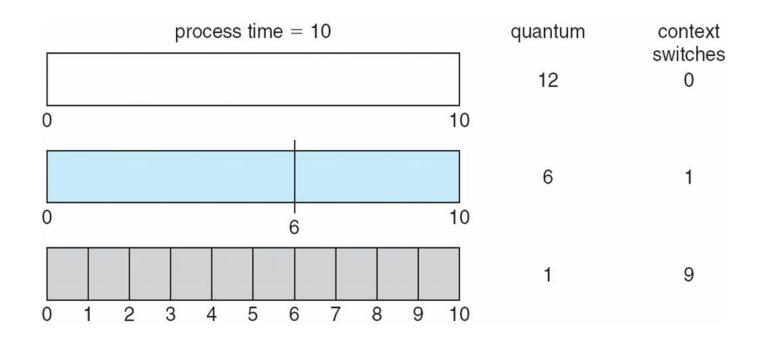
Gantt Chart

PID	AT	ВТ	ET	TAT	WT
P1	0	5	13	13	8
P2	1	3	12	11	8
P3	2	1	5	3	2
P4	3	2	9	6	4
P5	4	3	14	10	7
		8.6	5.8		





Time Quantum and Context Switch Time

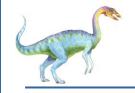


Performance

q large \Rightarrow FIFO

q small $\Rightarrow q$ must be large with respect to context switch, otherwise overhead is too high



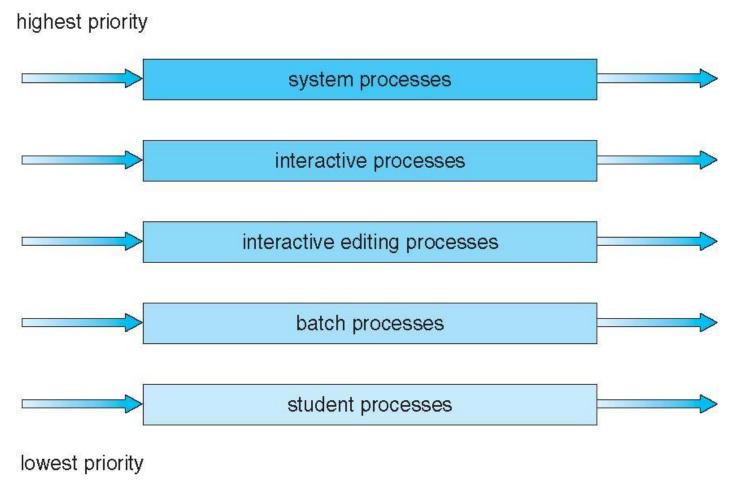


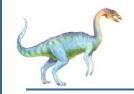
Multilevel Queue

- Ready queue is partitioned into separate queues, eg:
 - foreground (interactive)
 - background (batch)
- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
 - ☐ foreground RR
 - background FCFS
- □ Scheduling must be done between the queues:
 - Fixed priority scheduling; (i.e., serve all from foreground then from background). Possibility of starvation.
 - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR and 20% to background in FCFS



Multilevel Queue Scheduling





Exercise

Consider below data of four processes under multilevel queue scheduling, Q No. denotes the queue of the process

PID	Arrival Time	Burst Time	Q No.
P1	0	4	1
P2	0	3	1
P3	0	8	2
P4	10	5	1

Priority of queue 1 is greater than queue 2. Queue 1 uses RR (TQ=2) and queue 2 uses FCFS.

Draw the Gantt chart for above data and Calculate AWT, TAT

	P1	P2	P1	P2	P3	P4	P3
0	2	4	6	7	10	15	20





Multilevel Feedback Queue

- A process can move between the various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
 - number of queues
 - scheduling algorithms for each queue
 - method used to determine when to upgrade a process
 - method used to determine when to demote a process
 - method used to determine which queue a process will enter when that process needs service





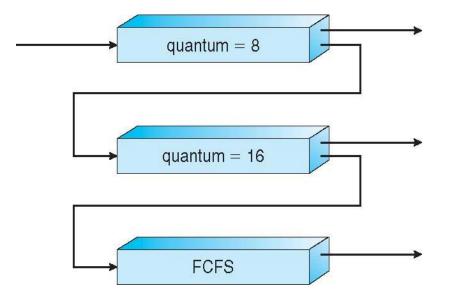
Example of Multilevel Feedback Queue

Three queues:

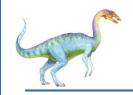
- Q₀ RR with time quantum 8 milliseconds
- Q_1 RR time quantum 16 milliseconds
- $Q_2 FCFS$

Scheduling

- A new job enters queue Q₀ which is served FCFS
 - When it gains CPU, job receives 8 milliseconds
 - If it does not finish in 8 milliseconds, job is moved to queue Q₁
- At Q₁ job is again served FCFS and receives 16 additional milliseconds
 - If it still does not complete, it is preempted and moved to queue Q₂







Exercise I

- Consider the following set of processes with the length of the CPU burst time given in millisecond
- The processes are assumed to have arrived in the order of P1,P2,P3,P4, P5, all at time 0.
- □ Draw four Gantt chart illustrating the executing of these process using FCFS, SJF, a non-preemptive priority (a smaller priority number implies a higher priority) and RR (q=1) scheduling.

PID	P1	P2	P3	P4	P5
BT	10	1	2	1	5
Priority	3	1	3	4	2

Algo.	FCFS	SJF	PRIORITY	RR
AWT				
ATT				





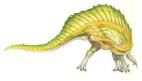
Exercise II

Consider the following set of processes, with the length of the CPU burst given in milliseconds:

Process	Burst Time	Priority
P_1	2	2
P_2	1	1
P_3	8	4
P_4	4	2
P_5	5	3

The processes are assumed to have arrived in the order P_1 , P_2 , P_3 , P_4 , P_5 , all at time 0.

- a. Draw four Gantt charts that illustrate the execution of these processes using the following scheduling algorithms: FCFS, SJF, nonpreemptive priority (a larger priority number implies a higher priority), and RR (quantum = 2).
- b. What is the turnaround time of each process for each of the scheduling algorithms in part a?
- c. What is the waiting time of each process for each of these scheduling algorithms?
- d. Which of the algorithms results in the minimum average waiting time (over all processes)?





Exercise III

The following processes are being scheduled using a preemptive, roundrobin scheduling algorithm. Each process is assigned a numerical priority, with a higher number indicating a higher relative priority. In addition to the processes listed below, the system also has an *idle task* (which consumes no CPU resources and is identified as *Pidle*). This task has priority 0 and is scheduled whenever the system has no other available processes to run. The length of a time quantum is 10 units. If a process is preempted by a higher-priority process, the preempted process is placed at the end of the queue.

Thread	Priority	Burst	Arrival
P_1	40	20	0
P_2	30	25	25
P_3	30	25	30
P_4	35	15	60
P_5	5	10	100
P_6	10	10	105

- a. Show the scheduling order of the processes using a Gantt chart.
- b. What is the turnaround time for each process?
- c. What is the waiting time for each process?
- d. What is the CPU utilization rate?



End of Chapter

