Financial Time Series

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Outline

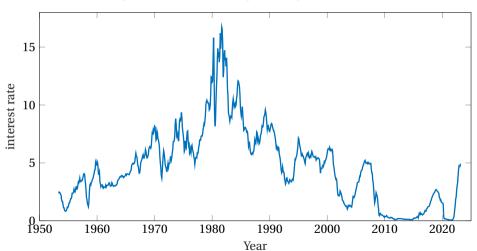
Linear Time Series Models

Estimating Time Series Models

Seasonality

Example: Modeling Interest Rates

1-year constant maturity treasury rates: 1953-2023



Stationarity and Autocorrelation Function

Weak Stationarity

A time series $\{x_t\}$ is weakly stationary if

- $E(x_t \mu)^2 = \gamma_0 < \infty;$
- **3** Cov $(x_t, x_{t-j}) = \gamma_j$ for any integer j.
- Weak stationarity is the foundation of statistical inference and forecasting for time series data.

Autocorrelation

For a weakly stationary time series $\{x_t\}$, the correlation between x_t and x_{t-k} is the lag-k autocorrelation of x_t ,

$$\rho_k = \frac{\text{Cov}(x_t, x_{t-k})}{\sqrt{Var(x_t)Var(x_{t-k})}} = \frac{\gamma_k}{\gamma_0}$$

Autoregressive Models

■ AR model: Regression with lagged variables

$$AR(1): \quad x_{t+1} = \phi_0 + \phi_1 x_t + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim \mathcal{N}(0, \sigma^2)$$

- \hookrightarrow ε_t : Gaussian white noise
- Model of 1-year treasury rates (using data from 1953-2020):

$$r_{t+1} = 0.033 + 0.993 \, r_t + \varepsilon_{t+1}$$

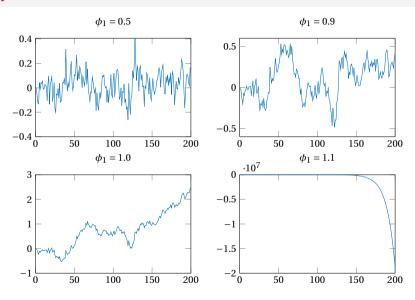
Properties of AR(1)

\blacksquare Some basic properties of AR(1):

- \hookrightarrow Stationarity: $|\phi_1| < 1$
- \hookrightarrow Mean: $E(r_t) = \frac{\phi_0}{1 \phi_1} = \mu$
- \rightarrow Variance: $Var(r_t) = \frac{\sigma^2}{1 \phi_1^2}$
- \rightarrow Autocorrelations: $\rho_1 = \phi_1, \rho_2 = \phi_1^2, \dots, \rho_k = \phi_1^k$
- De-meaned representation:

$$r_{t+1} - \mu = \phi_1(r_t - \mu) + \varepsilon_{t+1}$$

Stationarity of AR(1)



Forecasting with AR(1)

■ 1-step ahead forecast:

$$E_t[r_{t+1}] = \phi_0 + \phi_1 r_t = \mu + \phi_1 (r_t - \mu)$$

- \rightarrow Mean reversion: $|\phi_1| < 1$
- 1-step ahead forecast error:

$$r_{t+1} - \mathbf{E}_t[r_{t+1}] = \varepsilon_{t+1}$$

- → Q: Distribution of 1-step ahead forecast error?
- \blacksquare ℓ -step ahead forecast:

$$E_t[r_{t+\ell}] - \mu = \phi_1^{\ell}(r_t - \mu) \implies E_t[r_{t+\ell}] = \mu + \phi_1^{\ell}(r_t - \mu)$$

 \hookrightarrow Q: Distribution of ℓ -step ahead forecast error?

Half-life

Time τ needed for the average distance from the mean to shrink by half, $|E_t[r_{t+\tau}] - \mu| = \frac{1}{2}|r_t - \mu|$.

$$\tau = -\frac{\ln(2)}{\ln(|\phi_1|)}, \quad |\phi_1| < 1$$

AR and VAR Models

■ AR(p):

$$x_{t+1} = \phi_0 + \phi_1 x_t + \dots + \phi_p x_{t+1-p} + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim \mathcal{N}(0, \sigma^2)$$

■ VAR(p) (Vector AutoRegressive model):

$$\mathbf{x}_{t+1} = a_0 + A_1 \mathbf{x}_t + \dots + A_p \mathbf{x}_{t+1-p} + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim \mathcal{N}(0, \Omega)$$

where \mathbf{x}_t and a_0 are N-dim vectors, A_n are $N \times N$ matrices, and ε_t is N-dim vector of shocks.

Example: VAR(1)

- Modeling multiple series jointly to study the relationship between the series, and to improve the accuracy of forecasts.
- **Example:** real GDP growth (g_t) and inflation (π_t)

$$\begin{bmatrix} g_{t+1} \\ \pi_{t+1} \end{bmatrix} = \begin{bmatrix} a_g \\ a_{\pi} \end{bmatrix} + \begin{bmatrix} \phi_{11} & \phi_{12} \\ \phi_{21} & \phi_{22} \end{bmatrix} \begin{bmatrix} g_t \\ \pi_t \end{bmatrix} + \begin{bmatrix} \varepsilon_{g,t+1} \\ \varepsilon_{\pi,t+1} \end{bmatrix}$$

Example: forecasting excess returns (r_t) using dividend-price ratio (x_t)

$$\left[\begin{array}{c} r_{t+1} \\ x_{t+1} \end{array}\right] = \left[\begin{array}{c} a_r \\ a_x \end{array}\right] + \left[\begin{array}{cc} 0 & b \\ 0 & \rho \end{array}\right] \left[\begin{array}{c} r_t \\ x_t \end{array}\right] + \left[\begin{array}{c} \varepsilon_{r,t+1} \\ \varepsilon_{x,t+1} \end{array}\right]$$

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Moving-average Models

■ MA model: Shocks with finite life

$$MA(1): x_t = \mu + \varepsilon_t - \theta_1 \varepsilon_{t-1}$$

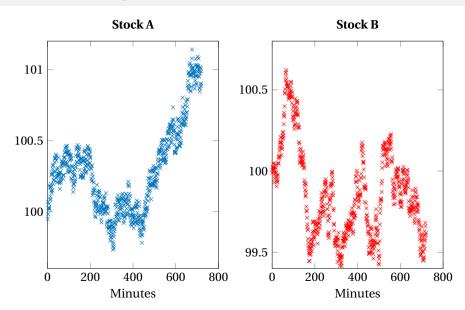
- → Always stationary
- → Autocorrelated shocks
- \hookrightarrow Finite memory: $\rho_{\ell} = 0$ for $\ell > 1$
- MA(q):

$$x_t = \mu + \varepsilon_t - \theta_1 \varepsilon_{t-1} - \dots - \theta_q \varepsilon_{t-q}$$

■ Combing AR and MA: ARMA

$$ARMA(1,1): \quad x_{t+1} = \phi_0 + \phi_1 x_t + \varepsilon_{t+1} - \theta \varepsilon_t$$

Which stock is more liquid?



Example of MA(1): Bid-Ask Bounce

- Assume market makers buy at the bid price P_b and sell at the ask price P_a .
- Observed market price P_t is assumed to be

$$P_t = P^* + I_t \frac{S}{2}$$

- \rightarrow P^* : fundamental value in a frictionless market (assumed to be constant)
- \hookrightarrow $S = P_a P_b$: bid-ask spread
- \hookrightarrow I_t : iid Bernoulli (taking value of 1 and -1 with probability 0.5)
- \hookrightarrow Interpretation: buyer-initiated ($I_t = 1$) vs. seller-initiated transaction ($I_t = -1$)
- Observed price change:

$$\Delta P_t = (I_t - I_{t-1}) \frac{S}{2}$$

Autocovariance:

$$Cov(\Delta P_t, \Delta P_{t-j}) = \begin{cases} S^2/2 & \text{if } j = 0\\ -S^2/4 & \text{if } j = 1\\ 0 & \text{if } j > 1 \end{cases}$$
 Why negative?

Autocovariance of returns as an indicator of illiquidity!

Nonstationary Time Series

■ Random walk (with drift):

$$x_{t+1} = a + x_t + \varepsilon_{t+1}$$

- → A popular model for log stock prices.
- \rightarrow Nonstationary (unit root) \Rightarrow First difference becomes white noise.
- → Permanent shocks.
- → Time trend:

$$x_t = at + x_0 + \varepsilon_t + \dots + \varepsilon_1$$

■ Trend-stationary time series:

$$x_t = \beta_0 + \beta_1 t + y_t$$

where y_t is a stationary time series, e.g., an AR(1).

■ Unit-root test (Dickey-Fuller test):

$$x_{t+1} = \phi_0 + \phi_1 x_t + \varepsilon_{t+1}$$

$$\hookrightarrow H_0: \phi_1 = 1 \text{ vs. } H_a: \phi_1 < 1$$

$$DF = \frac{\widehat{\phi}_1 - 1}{SE(\widehat{\phi}_1)}$$

Outline

Linear Time Series Models

Estimating Time Series Models

Seasonality

MLE for Dependent Observations

- MLE approach works even if observations are dependent.
- Need dependence to die out quickly enough.
- Consider a time series $x_t, x_{t+1}, ...$ and assume that the distribution of x_{t+1} depends only on L lags: $x_t, ..., x_{t+1-L}$.
- Likelihood function

$$p(\mathbf{x}|\theta) = p(x_1|\theta)p(x_2|x_1;\theta)p(x_3|x_2, x_1;\theta)...p(x_L|x_{L-1}, ..., x_1;\theta)$$

$$\prod_{t=L+1}^{T} p(x_t|x_{t-1}, ..., x_{t-L};\theta)$$

 \blacksquare θ maximizes the (conditional) likelihood

$$L(x_{L+1},...,x_T|x_L,...,x_1;\theta) \equiv \prod_{t=L+1}^T p(x_t|x_{t-1},...,x_{t-L};\theta)$$

if T is large and x_t is stationary.

Short-hand notation:

$$L(\theta)$$
 and $\mathcal{L}(\theta) \equiv \ln L(\theta)$

MLE for AR(p) Time Series

■ AR(p) with IID Gaussian errors:

$$x_{t+1} = a_0 + a_1 x_t + \dots + a_p x_{t+1-p} + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim \mathcal{N}(0, \sigma^2)$$

- Conditional on $(x_t, ..., x_{t+1-p})$, x_{t+1} is Gaussian with mean $a_0 + a_1x_t + \cdots + a_px_{t+1-p}$ and variance σ^2 .
- Construct likelihood:

$$\mathcal{L}(\theta) = \sum_{t=p}^{T-1} -\ln \sqrt{2\pi\sigma^2} - \frac{(x_{t+1} - a_0 - a_1x_t - \dots - a_px_{t+1-p})^2}{2\sigma^2}$$

■ MLE estimates of $(a_0, a_1, ..., a_p)$ are the same as OLS:

$$\underset{(a_0, a_1, \dots, a_p)}{\operatorname{arg\,max}} \, \mathcal{L}(\theta) = \underset{(a_0, a_1, \dots, a_p)}{\operatorname{arg\,min}} \sum_{t=p}^{T-1} \left(x_{t+1} - a_0 - a_1 x_t - \dots - a_p x_{t+1-p} \right)^2$$

MLE for VAR(p) Time Series

■ VAR(p) with IID Gaussian errors:

$$x_{t+1} = a_0 + A_1 x_t + \dots + A_p x_{t+1-p} + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim \mathcal{N}(0, \Omega)$$

where x_t and a_0 are N-dim vectors, A_n are $N \times N$ matrices, and ε_t are N-dim vectors of shocks.

- Conditional on $(x_t, ..., x_{t+1-p})$, x_{t+1} is Gaussian with mean $a_0 + A_1x_t + \cdots + A_px_{t+1-p}$ and cov matrix Ω .
- Construct conditional log-likelihood:

$$\mathcal{L}(\theta) = \sum_{t=p}^{T-1} -\ln \sqrt{(2\pi)^N |\Omega|} - \frac{1}{2} \varepsilon_{t+1}' \Omega^{-1} \varepsilon_{t+1}$$

MLE for VAR(p) Time Series

Parameter estimation:

$$\max_{a_0,A_1,\dots,A_p,\Omega} \mathcal{L}(\theta) \Leftrightarrow \min_{a_0,A_1,\dots,A_p,\Omega} \sum_{t=p}^{T-1} \ln \sqrt{(2\pi)^N |\Omega|} + \frac{1}{2} \varepsilon_{t+1}' \Omega^{-1} \varepsilon_{t+1}$$

■ Optimality conditions for $a_0, A_1, ..., A_p$:

$$\sum_{t} \left[x_{t-i} \varepsilon'_{t+1} \right] = 0, \ i = 0, 1, \dots, p-1, \quad \sum_{t} \varepsilon_{t+1} = 0$$

where

$$\varepsilon_{t+1} = x_{t+1} - (a_0 + A_1 x_t + \dots + A_p x_{t+1-p})$$

■ VAR coefficients can be estimated by OLS, equation by equation.

MLE and Model Selection

- In practice, we often do not know the exact model.
- In some situations, MLE can be adapted to perform model selection.
- Suppose we are considering several alternative models, one of which is the correct model.
- If the sample is large enough, we can identify the correct model by comparing maximized likelihoods and penalizing them for the number of parameters they use.
- Various forms of penalties have been proposed, defining various *information criteria*.

VAR(p) Model Selection

- \blacksquare To build a VAR(p) model, we must decide on the order p.
- Without theoretical guidance, use an information criterion.
- Consider two most popular information criteria:

Akaike (AIC) and Bayesian (BIC)

- Each criterion chooses *p* to maximize the log likelihood subject to a penalty for model flexibility (free parameters). Various criteria differ in the form of penalty.
- In Python, *auto.arima()* can automatically select the parameters using one of the two criteria:

Code

```
from pmdarima.arima import auto_arima
auto_arima(y, max_p = 5, information_criterion = "aic", trace = TRUE)
```

AIC and BIC

- Start by specifying the maximum possible order \overline{p} .
- Make sure that \overline{p} grows with the sample size, but not too fast:

$$\lim_{T \to \infty} \overline{p} = \infty, \quad \lim_{T \to \infty} \frac{\overline{p}}{T} = 0$$

For example, can choose $\overline{p} = \frac{1}{4}(\ln T)^2$. Q: Does this satisfy the above conditions?

■ Find the optimal VAR order p^* as

$$p^* = \underset{0 \le p \le \overline{p}}{\operatorname{arg\,max}} \frac{2}{T} \mathcal{L}(\theta; p) - \underset{0 \le p \le \overline{p}}{\operatorname{penalty}(p)}$$

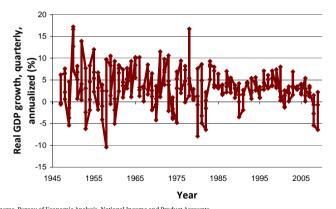
where

penalty(
$$p$$
) =
$$\begin{cases} AIC: & \frac{2}{T}pN^2 \\ BIC: & \frac{\ln T}{T}pN^2 \end{cases}$$

■ In larger samples, BIC selects lower-order models than AIC.

Example: AR(p) Model of Real GDP Growth

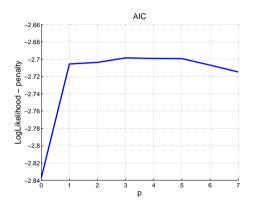
- Model quarterly seasonally adjusted GDP growth (annualized rates).
- Want to select and estimate an AR(p) model.



 $Source: U.S.\ Department\ of\ Commerce,\ Bureau\ of\ Economic\ Analysis.\ National\ Income\ and\ Product\ Accounts.$

Example: AR(p) Model of GDP Growth

 $\blacksquare \text{ Set } \overline{p} = 7.$

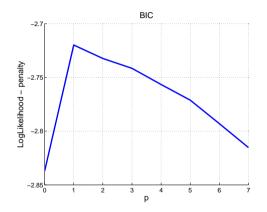


- AIC dictates p = 3.
- AR coefficients $a_1, ..., a_3$:

0.3363, 0.1371, -0.1165

Example: AR(p) Model of GDP Growth

 $\blacksquare \text{ Set } \overline{p} = 7.$



- BIC dictates p = 1.
- AR coefficient $a_1 = 0.3611$.

Outline

Linear Time Series Models

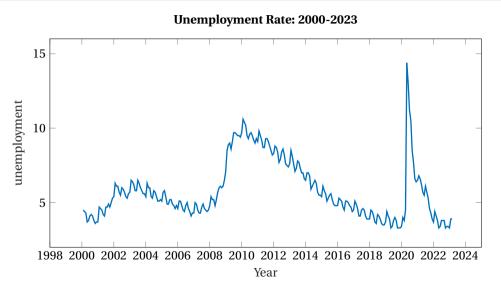
2 Estimating Time Series Models

Seasonality

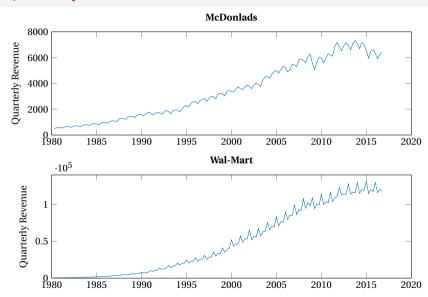
Seasonal Time Series

- Some financial time series exhibit seasonal (periodic) patterns.
 - → Examples: unemployment rate, corporate earnings, sales ...
- Cycle length could range from seconds to months and quarters to years.
- Introduces serial correlation/predictability in a particular manner.

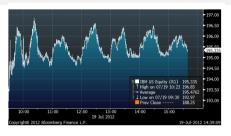
Example: Unemployment

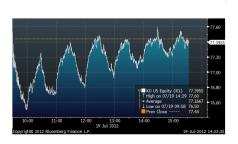


Example: Quarterly revenue



Example: IBM and Coke prices on Jul 19, 2012





Differencing for Seasonal Time Series

- Work with log revenue: $x_t = \log(\text{quarterly revenue})$
- Focus on growth rates, not levels. (Why?)

regular differencing:
$$\Delta x_t = x_t - x_{t-1}$$
 seasonal differencing: $\Delta_4 x_t = x_t - x_{t-4}$

■ Compare growth rates year over year, not quarter over quarter.

$$\Delta_4(\Delta x_t) = (x_t - x_{t-1}) - (x_{t-4} - x_{t-5})$$

■ More generally, for seasonal time series with periodicity s, use Δ_s .

"Airline Model" for Corporate Revenue

Airline model

$$(x_t - x_{t-1}) - (x_{t-s} - x_{t-s-1}) = (\varepsilon_t - \theta_1 \varepsilon_{t-1}) - \theta_s(\varepsilon_{t-s} - \theta_1 \varepsilon_{t-s-1})$$

- \blacksquare *s* is the periodicity of the series;
- \blacksquare ε_t is white noise.

Q: What are the meanings of θ_1 and θ_s ?

Q: What is the ℓ -step ahead forecast $E_t[x_{t+\ell}]$?

• Multiplicative model: Regular (quarterly) dependence and seasonal (year-to-year) dependence are assumed to be orthogonal.

Modeling McDonalds quarterly revenue

- The goal of this example: Estimate two different time-series models and compare their forecasting performances.
- Airline model:

$$(x_t - x_{t-1}) - (x_{t-4} - x_{t-5}) = (\varepsilon_t - 0.165\varepsilon_{t-1}) - 0.491(\varepsilon_{t-4} - 0.165\varepsilon_{t-5})$$

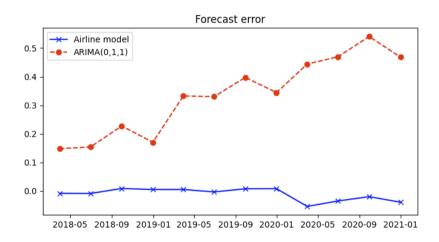
② A "naive" ARIMA(0,1,1):

$$x_t - x_{t-1} = 0.046 + \varepsilon_t - 0.468\varepsilon_{t-1}$$

Code

```
from statsmodels.tsa.statespace.sarimax import SARIMAX
m1 = SARIMAX(rev, order = (0,1,1), seasonal_order = (0,1,1,4))
m2 = SARIMAX(rev, order = (0,1,1), trend="c")
```

Comparing forecasting performances



Summary

- Weak stationarity
- Basic properties of AR, MA, random walk ...
- Estimating time series models and model selection
- Forecasting time series with seasonality