

# Resilience in Transportation Networks

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## Problem Definition

Given a graph  $G(V, E)$  and a set of paths  $P = \{(s_1, t_1), (s_2, t_2), \dots, (s_k, t_k)\}$ , where each  $p_i \equiv (s_i, t_i) \in P$  represents the source and destination node for a path  $p_i$ , find a set  $E' \subseteq E$  consisting of all edges which when removed from the graph, maximum number of paths are affected. Let a path be represented by an ordered list of edges  $p_i = (e_1, e_2, \dots, e_j)$ . It is assumed that a path connecting the nodes  $(s_i, t_i)$  is affected if atleast one of the edge  $e \in p_i$  is attacked. Also  $p_i$  is the only path connecting the nodes  $(s_i, t_i)$ , and there is no other path connecting  $(s_i, t_i)$ . Further,  $\sum_{e_i \in E'} b(e_i) \leq B$ , where  $B$  is the budget of the adversary and  $b(e_i)$  is the cost of removing edge  $e_i$ .

## Proposed Solution

Let us assume the graph has  $n$  nodes and  $m$  edges.

We construct a  $m \times 1$  matrix  $\mathbf{C}$  such that  $i$ th element in  $\mathbf{C}$  represents the number of paths in set  $P$  passing through the  $i^{th}$  edge. This can be found by iterating over all the paths in  $P$ .

Let  $\mathbf{b}$  be a  $m \times 1$  matrix where  $b_i$  represents the cost of removing the  $i^{th}$  edge.

Let  $\mathbf{X}$  be a  $m \times 1$  matrix such that  $x_i = 1$  if  $i^{th}$  edge belongs to  $E'$ , otherwise it is 0.

The solution to the above problem is equivalent to solving a linear program

$$\arg \max_{\mathbf{X}} \mathbf{C}^T \cdot \mathbf{X} \quad (1)$$

$$\text{such that } \mathbf{b}^T \cdot \mathbf{X} \leq B \text{ and } x_i \in \{0, 1\}$$

which is equivalent to

$$\arg \min_{\mathbf{X}} -\mathbf{C}^T \cdot \mathbf{X} \quad (2)$$

$$\text{such that } \mathbf{b}^T \cdot \mathbf{X} \leq B \text{ and } x_i \in \{0, 1\}$$

## Proposed solution 2

Let us assume the graph has  $n$  nodes,  $m$  edges and  $k$  paths. Let each path  $p_i \in P$  have a weight  $w_i \in W$ , where the weight represents the importance of the path. Thus if  $w_i < w_j; w_i, w_j \in W$  implies that it is beneficial to destroy path  $p_j$  over  $p_i$ .

We create a  $k \times m$  matrix  $\mathbf{A}$  whose entry  $a_{ij} = 1$  if  $e_j \in p_i$ , else it is zero.

Let  $\mathbf{X}'$  represent the  $m \times 1$  unit vector  $\vec{1}$ .

Let  $\mathbf{X}$  be a  $m \times 1$  matrix such that  $x_i = 1$  if  $e_i \in \mathbf{E}'$ , otherwise it is 0.

Let  $\mathbf{W}$  be a vector such that each element  $w_i \in \mathbf{W}$  represents weight of path  $p_i$ .

Then the above problem is equivalent to solving a linear program

$$\arg \max_{\mathbf{X}} f(\mathbf{A} \cdot (\mathbf{X}' - \mathbf{X}))^T \cdot \mathbf{W} \quad (3)$$

$$\text{such that } \mathbf{b}^T \cdot \mathbf{X} \leq B \text{ and } x_i \in \{0, 1\}$$

where we define function  $f$  for every element  $z_i \in \mathbf{Z}$  in any vector  $\mathbf{Z}$  as  $f(z_i) = \begin{cases} 0, & \text{if } z_i = 0 \\ 1, & \text{otherwise} \end{cases}$

Basically,  $f(\mathbf{A} \cdot (\mathbf{X}' - \mathbf{X}))$  is  $k$  dimensional vector whose  $i^{th}$  entry is 1 if the path  $p_i \in P$  is affected.