

# Deep Learning Frameworks

Tokenization, RNN, GRU, Attention

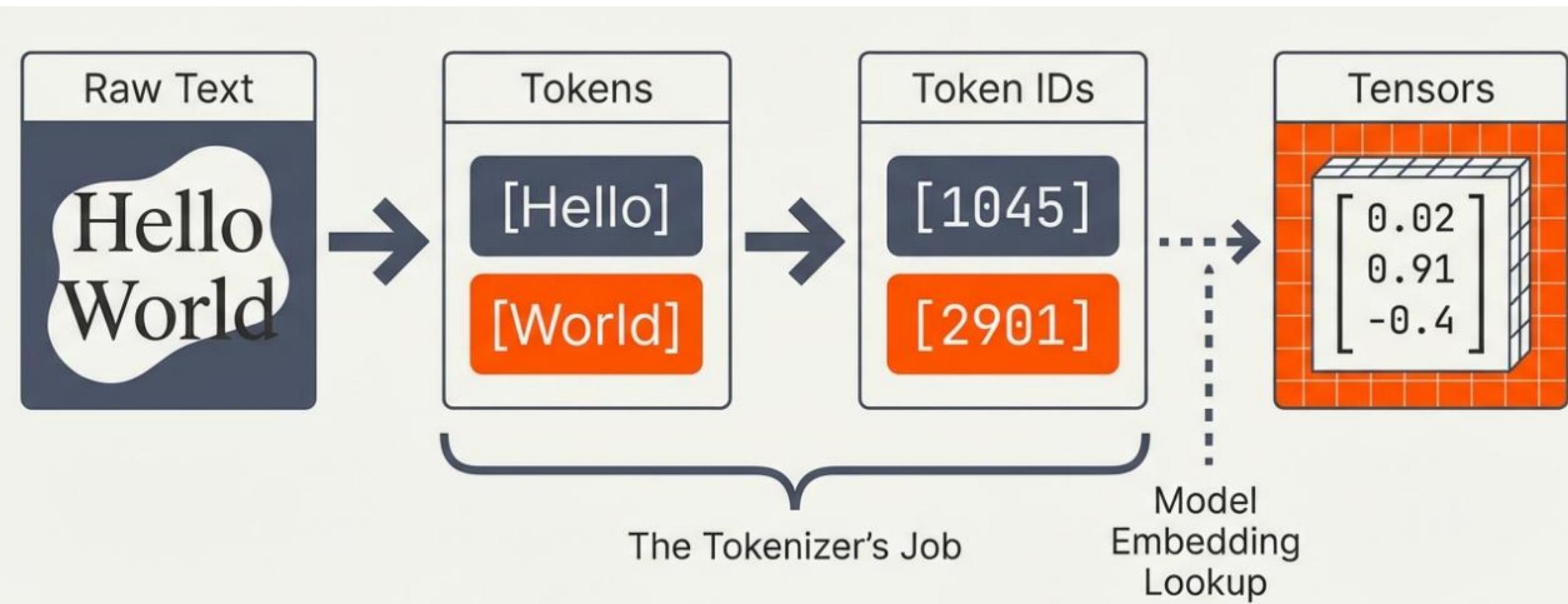
<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Challenges with Text Data

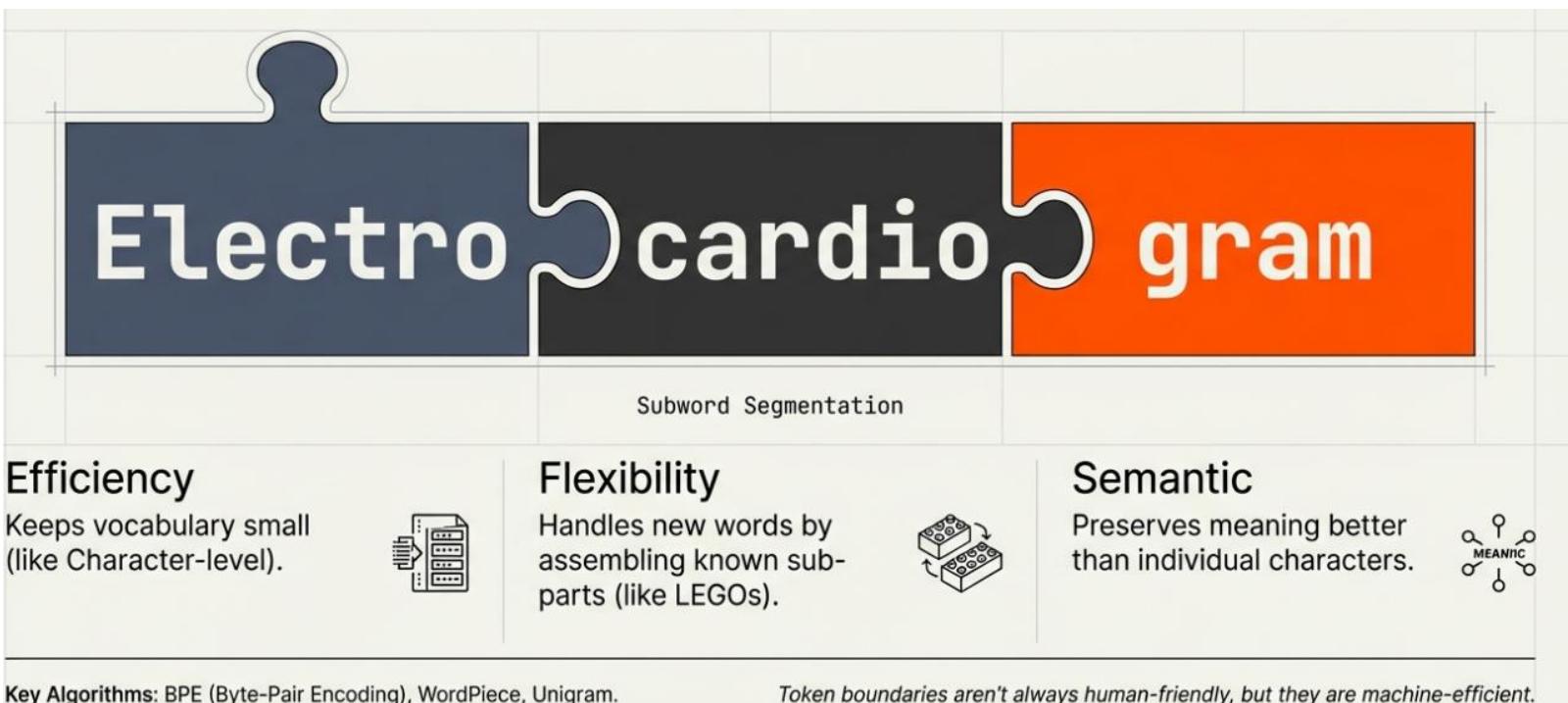
- Representing Text
- Varying Length

# Representing Text



# Tokenization: Splitting the text input

- Word level: linguistic boundaries, vocab explosion, missing words
- Character Level: Limited Vocab, No unknowns, Sequence length
- Subword Level



# Handling varying lengths

## Reality (Jagged Inputs)

"Hello" (Short)

"How are you doing today" (Long)

"Hi" (Very Short)

Standardization  
Required

## Requirement (Tensor Shape)

"Hello"

"How are you doing today"

"Hi"

# Padding and Truncation

## Technique 1: Padding

Input



Output (Target Length 9)



The [PAD] tokens are filler for uniform length.

## Technique 2: Truncation

Input



Output (Max Length 10)



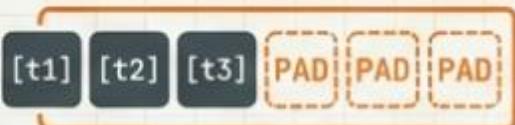
Exceeding tokens are cut to fit the limit.

# The Special Tokens Glossary

## <PAD>

### Padding

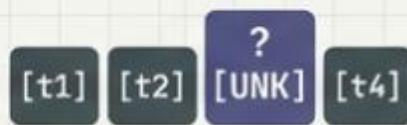
Fills empty space to maintain batch shape (rectangular constraint).



## <UNK>

### Unknown

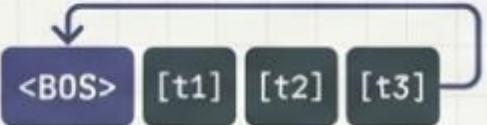
Represents out-of-vocabulary terms. Rare in modern subword models.



## <BOS> / <CLS>

### Begin-of-Sequence

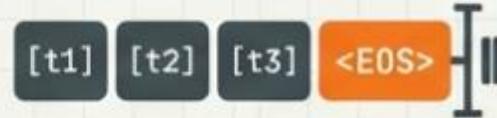
Marks the start of input.  
Often holds sentence-level context.



## <EOS> / <SEP>

### End-of-Sequence

Marks the conclusion of a segment or sentence.



# Ways to Represent

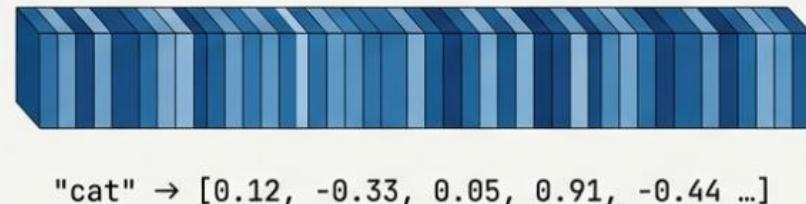
- Integers [512>8]
- One hot [1 0 0] -> orange [0 1 0]-> car

An embedding maps each discrete token ID to a dense vector of fixed dimension  $d$ . These values are learnable parameters.

Old: One-Hot  
(Sparse)



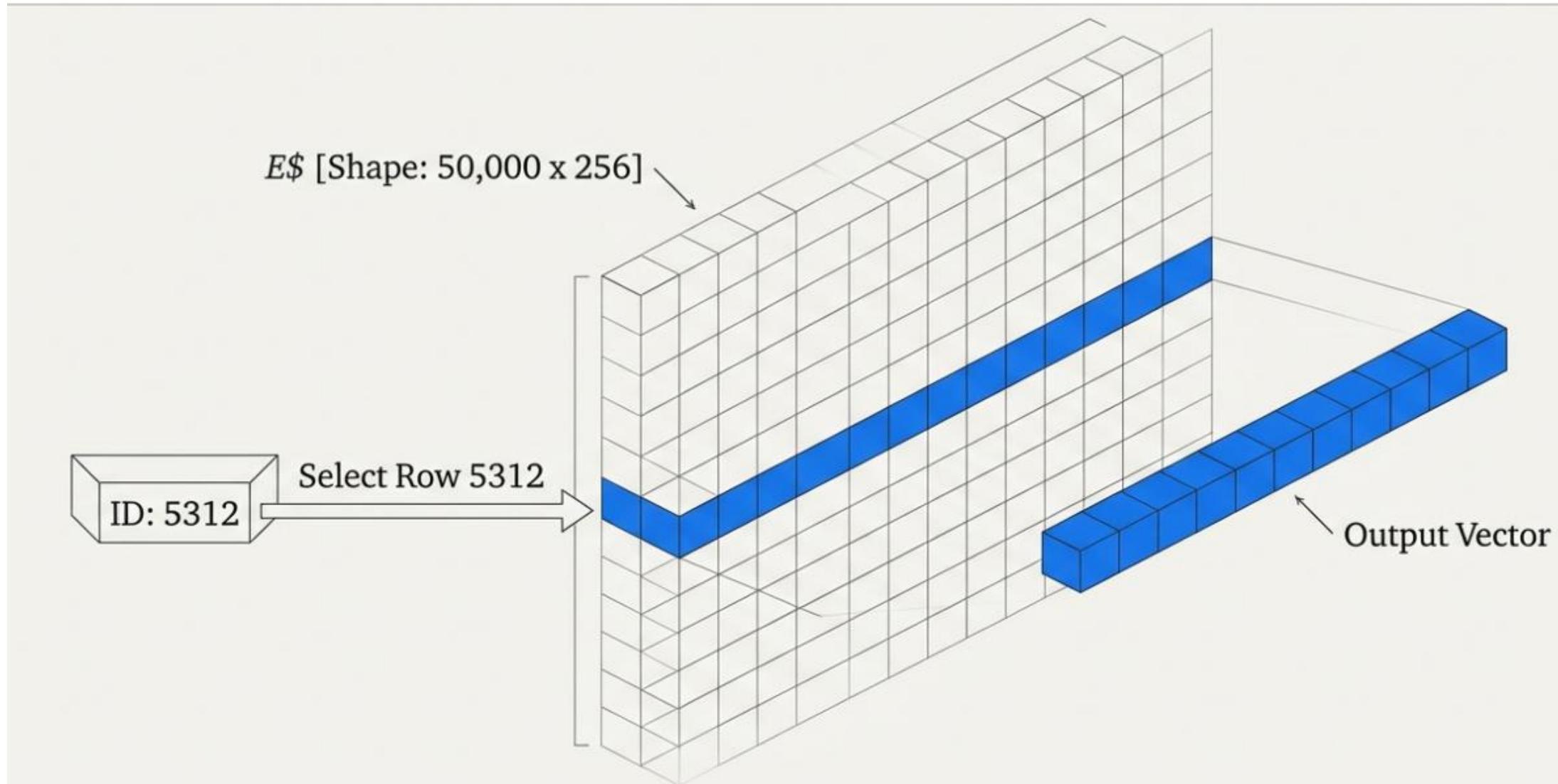
New:  
Embedding  
(Dense)



**Benefits:**

1. Compact ( $d \ll V$ )
2. Trainable Weights
3. Encodes Semantic Similarity

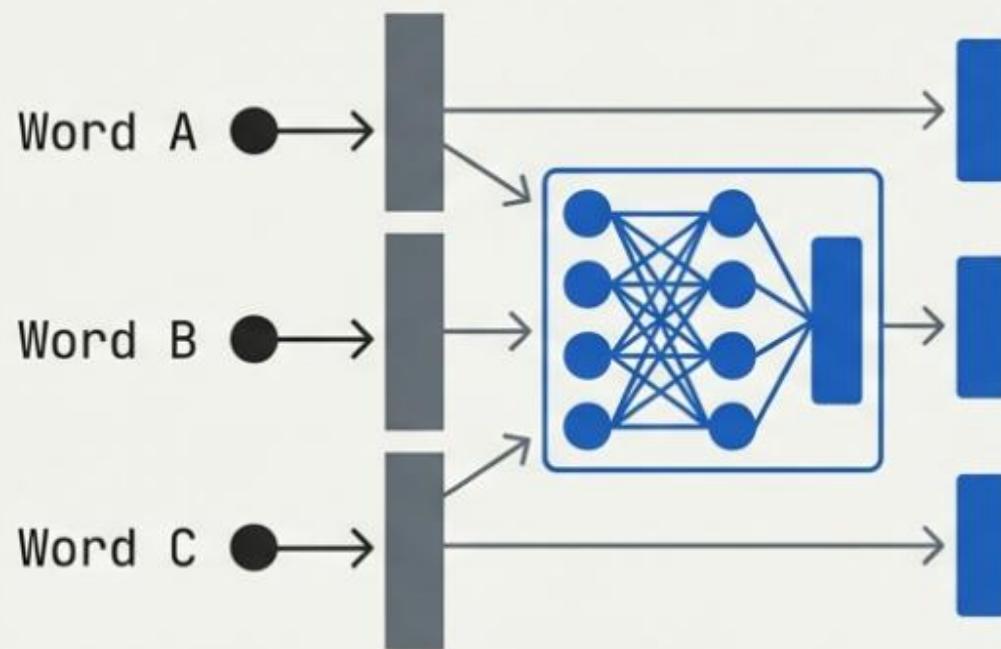
# nn.Embedding



# Sequence Matters

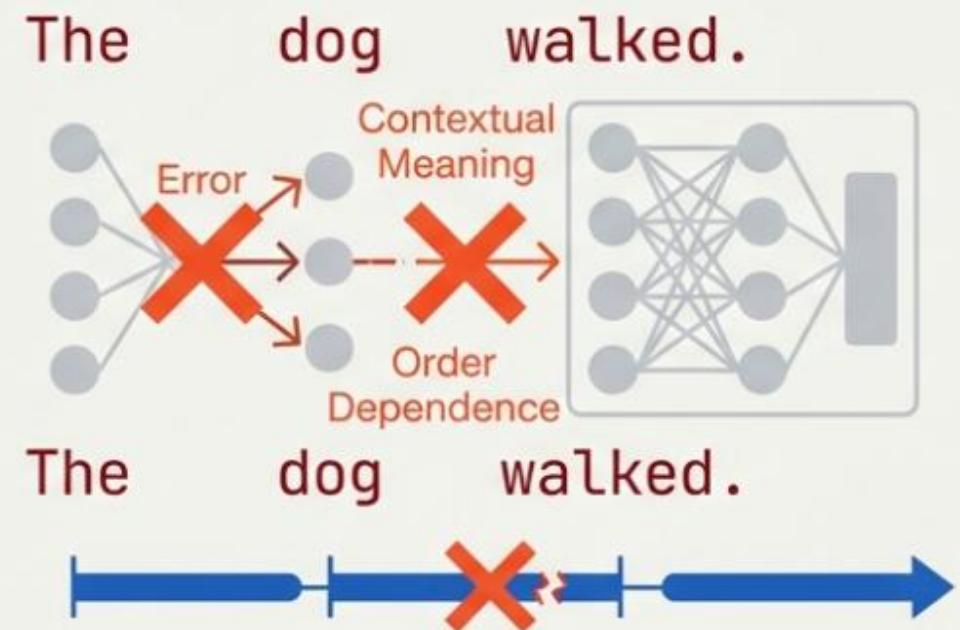
## The Gap

Standard feedforward networks treat inputs as independent events. They have no concept of “before” or “after.” A normal feedforward network cannot naturally “remember” what occurred in the previous step.



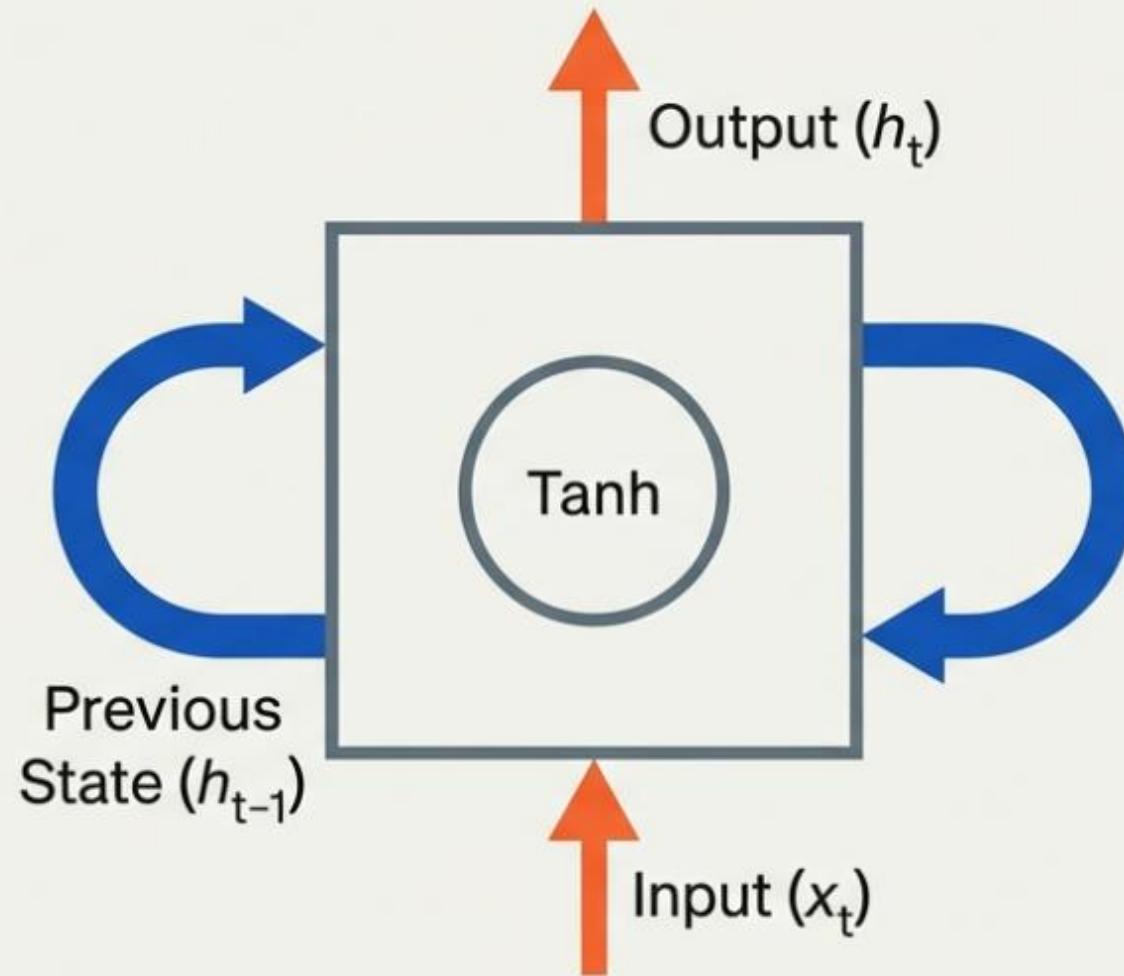
## The Reality

Real-world data, such as text and time-series, is defined by continuity. Its key attributes are: Variable length, Order dependence, and Contextual meaning.



# Recurrent Neural Network

**Concept:** The RNN processes tokens one step at a time while maintaining a ‘hidden state’ ( $h$ ) that acts as memory.



**Mechanism:** At time step  $t$ , the RNN combines two signals:

1. The Current Input ( $x_t$ );
2. The Previous Hidden State ( $h_{t-1}$ );

**Result:** A merger producing a new hidden state ( $h_t$ ) that carries the past into the present.

# State Update

**Sensory Weights:** The matrix processing the new input signal.

**Memory Weights:** The matrix processing the historical context ( $h_{t-1}$ ).

$$h_t = \tanh(W_{xh}x_t + W_{hh}h_{t-1} + b_h)$$

**Activation:** The non-linear function squashing values between -1 and 1.

**Bias:** The learnable offset.

The new state is a weighted sum of immediate sensory data and historical context, fused mathematically by the tanh activation.

# Output

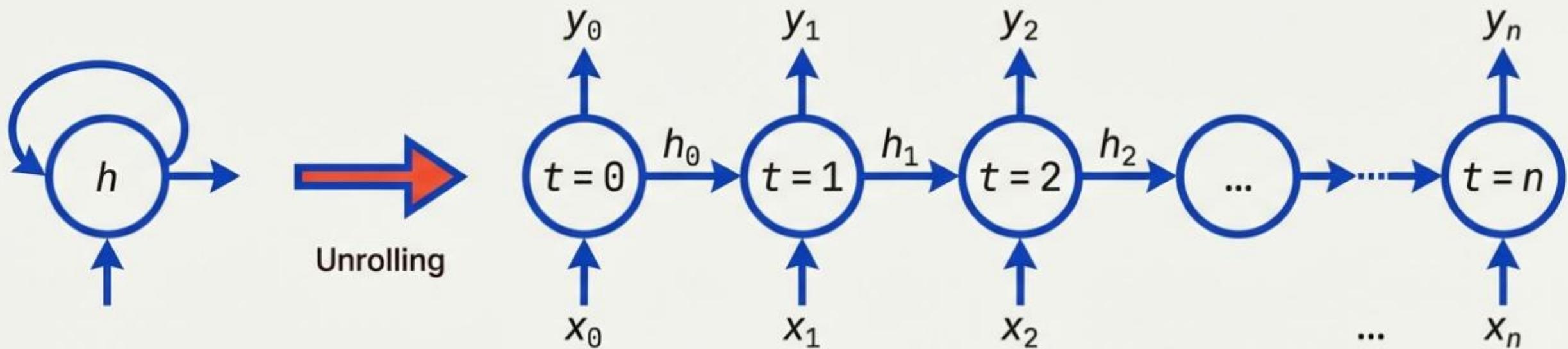
$$y_t = W_{hy}h_t + b_y$$

The hidden state  $h_t$  is internal memory. To get a prediction (like the next word), we project  $h_t$  through an output weight matrix ( $W_{hy}$ ).



Note: This output step is optional at intermediate steps, depending on the task topology.

# Unroll



The Abstraction

To train an RNN, we must visualize it not as a loop, but as a deep neural network where each layer corresponds to a time step. A sequence of 100 words is effectively a 100-layer deep network sharing the same weights.

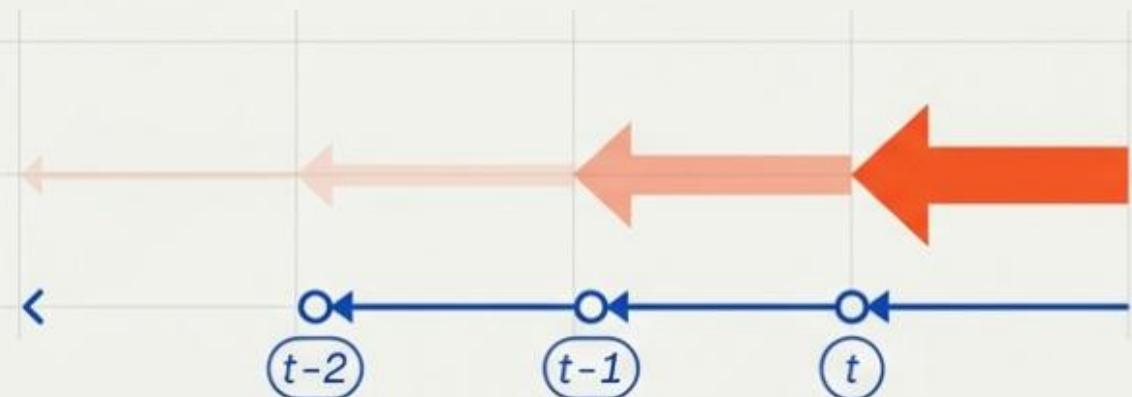
# Encoder

# Encoder - Decoder

# Instability in Long Term Dependencies

## The Vanishing and Exploding Gradient Problem

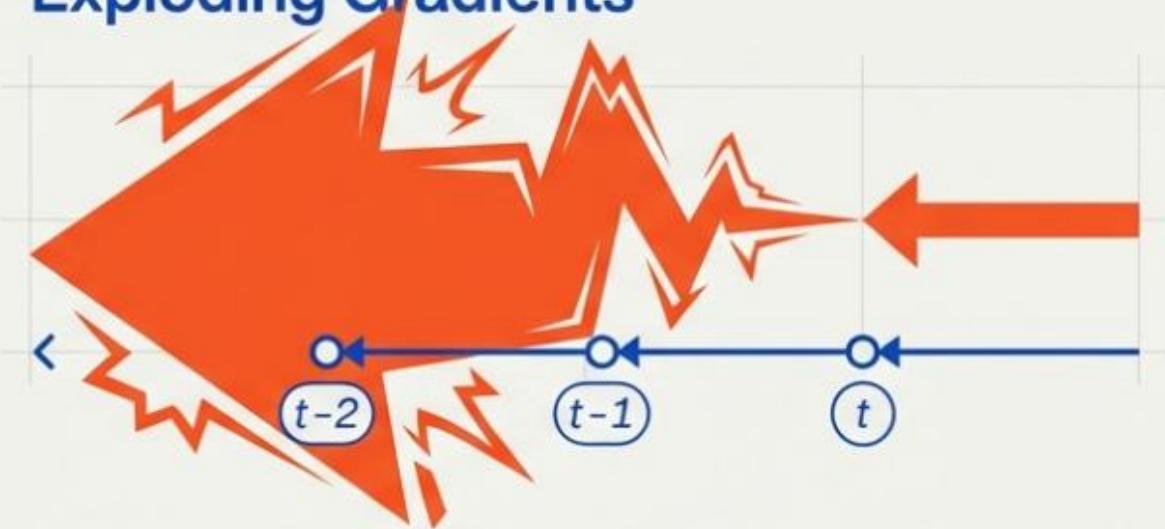
### Vanishing Gradients



Cause: Gradients  $< 1$  multiplied many times.

Effect: Signal shrinks to 0. The model “forgets” the beginning of the sequence.

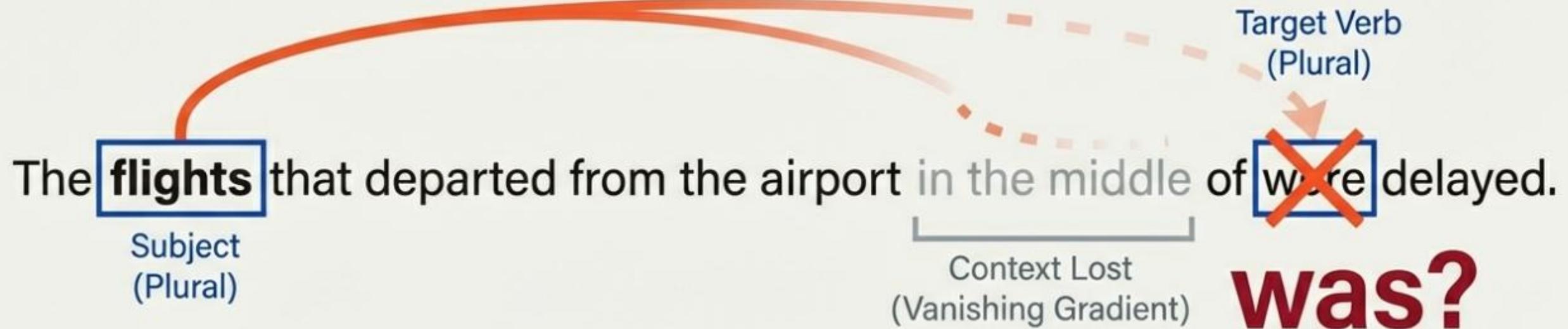
### Exploding Gradients



Cause: Gradients  $> 1$  multiplied many times.

Effect: Signal blows up. Training becomes unstable (NaN values).

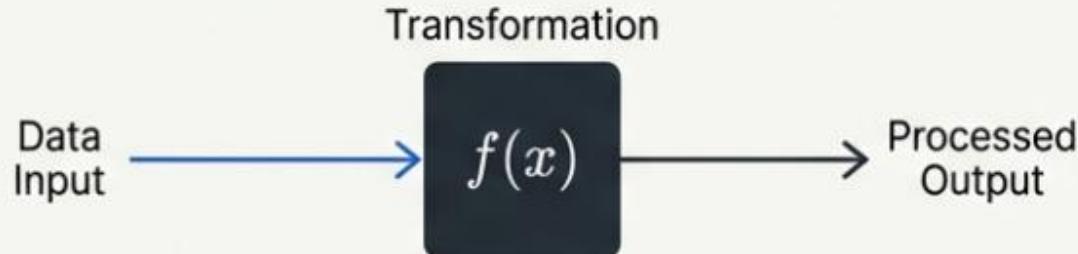
# Symptoms of Memory Loss



The Symptom: The model learns short-term dependencies well but fails at long contexts. Here, the RNN forgets the plural subject "flights" by the time it reaches the verb, potentially predicting the singular "was".

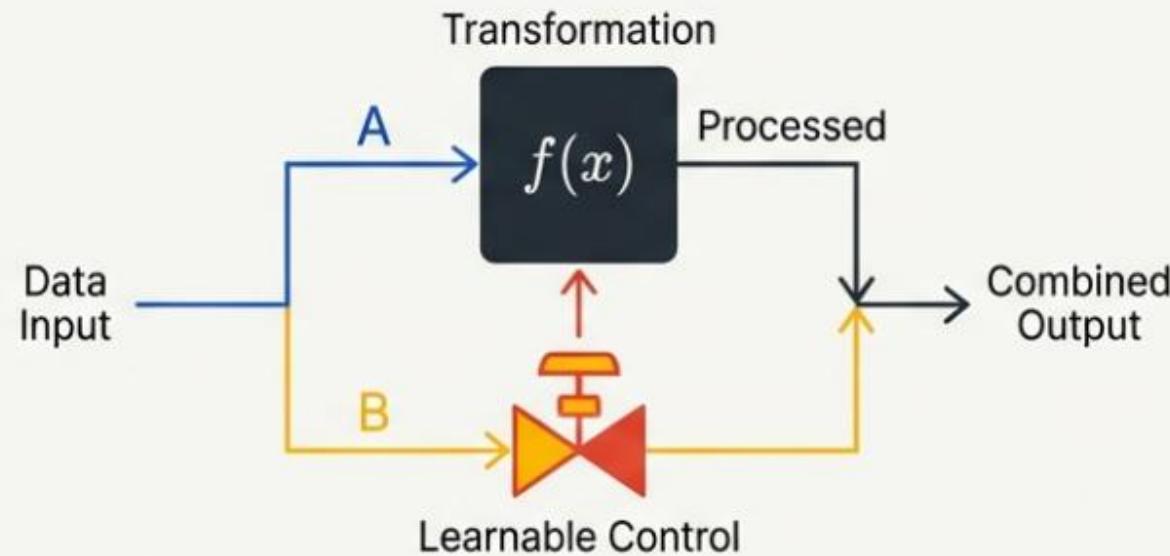
# Handling Long Term Dependencies

## Vanilla RNN Processing



Forced transformation at every step.

## Gated Recurrent Unit (GRU)

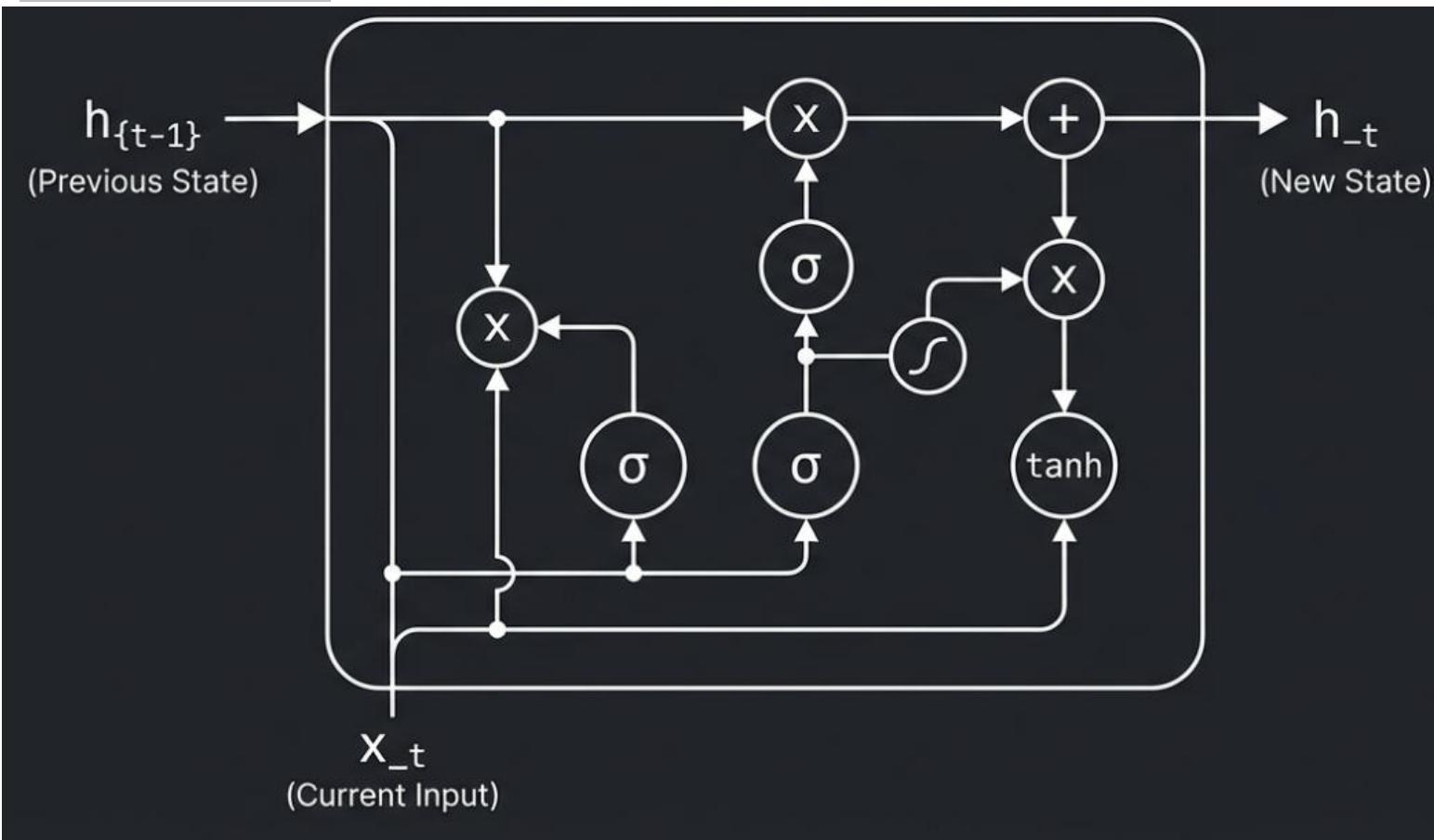


Data can bypass processing via the Highway.

**Core Concept:** Instead of forcing the model to rewrite its entire memory at every step, we add learnable **Gates** ( $z_t, r_t$ ). These differentiable knobs learn when to **Keep** existing memory, **Update** with new input, or **Ignore** irrelevant history. The GRU is a streamlined evolution of the LSTM, using only 2 gates instead of 3.

# GRU

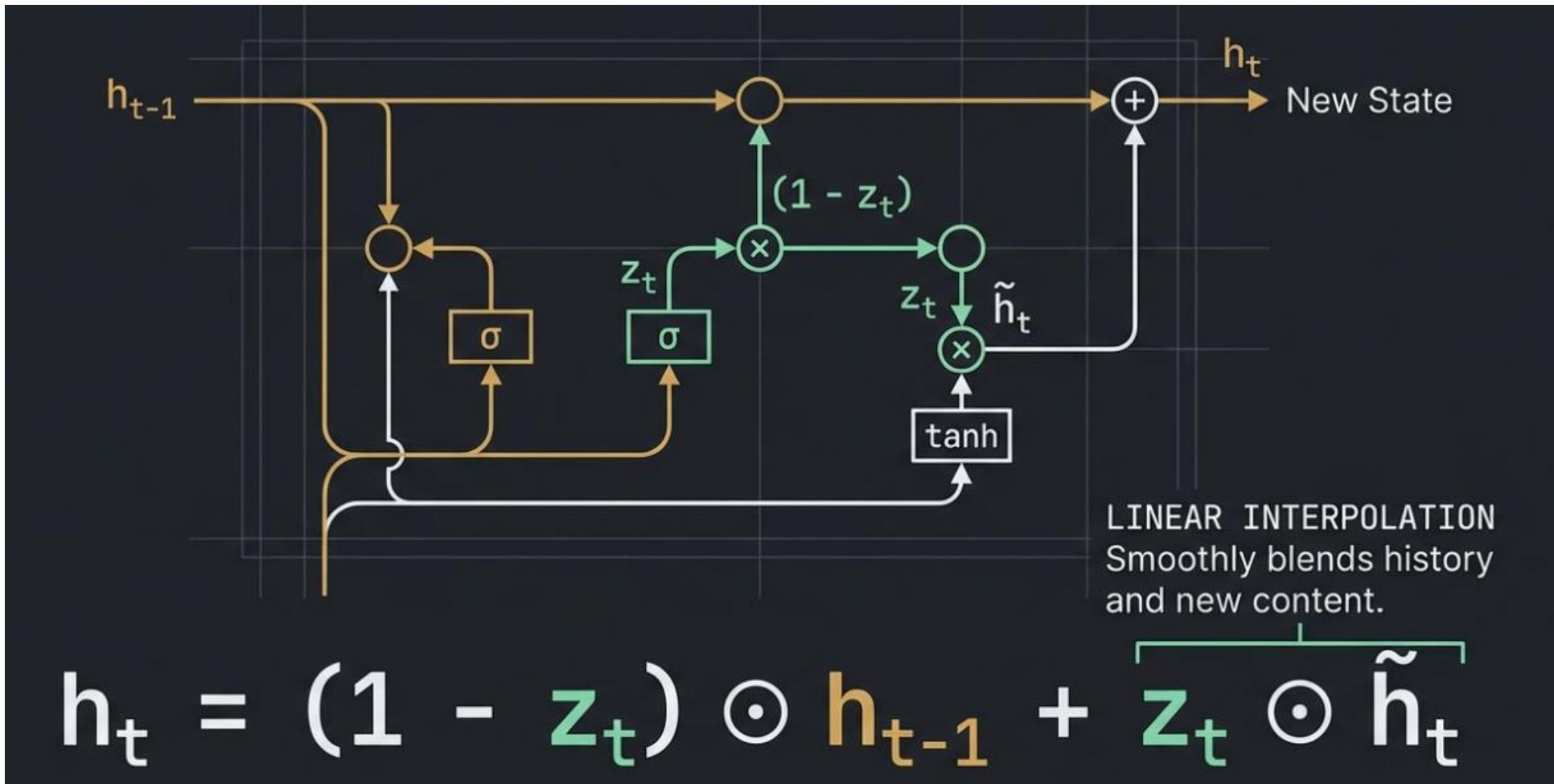
The delivery was two days late and the box was torn. Customer support was slow to respond.  
**Anyway, the Bluetooth earbuds paired instantly with my phone. The sound is clear, bass is decent, and the battery easily lasts 6–7 hours. I used them during a workout and the fit stayed secure.**



# Final State: How much should I keep vs replace?

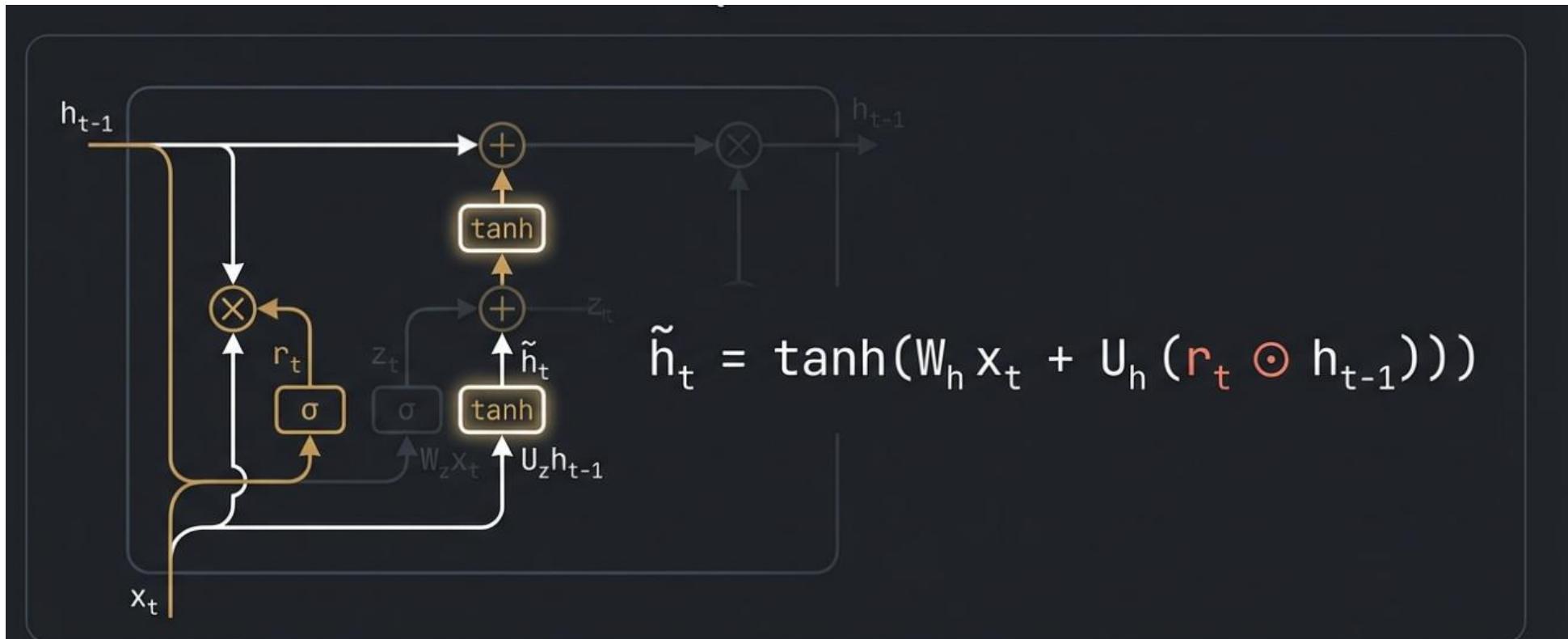
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# Candidate State

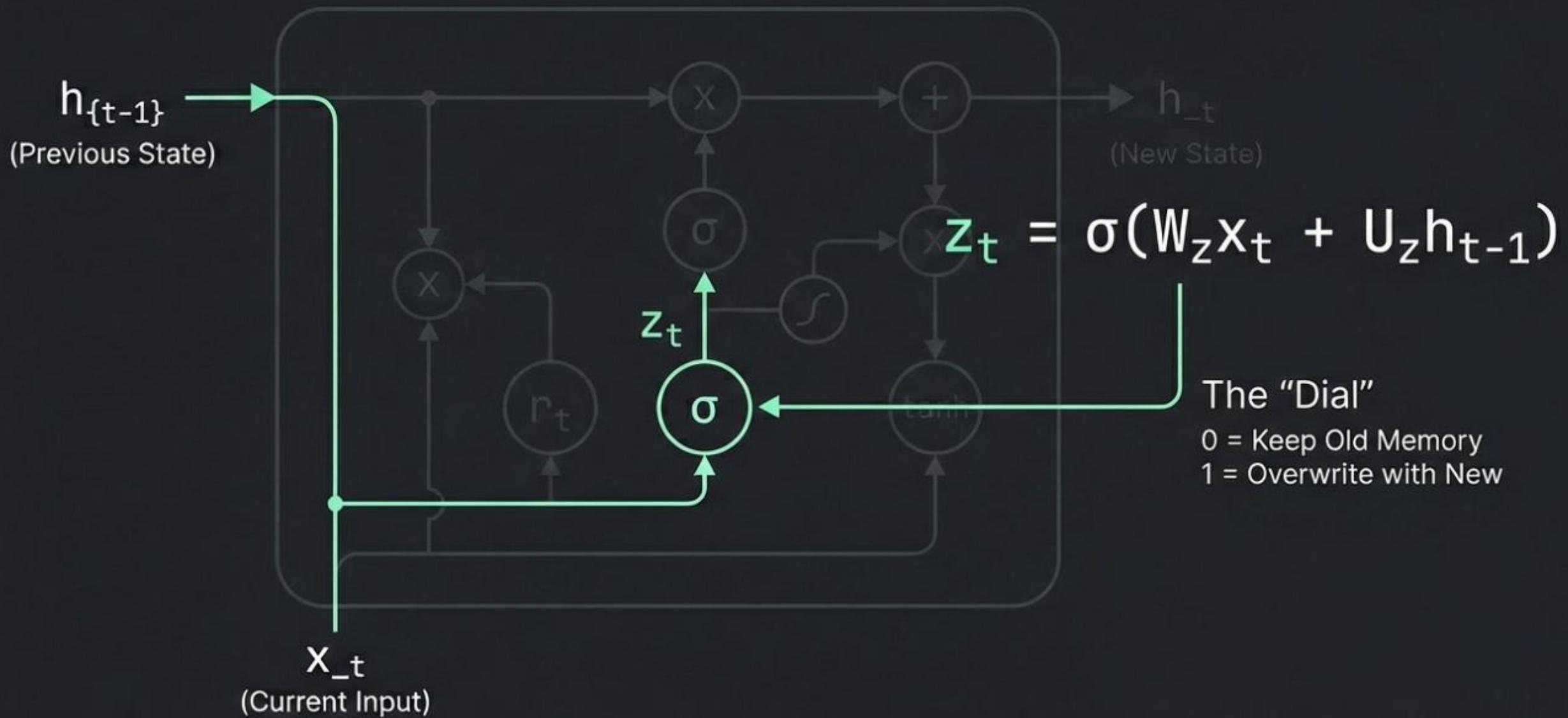
The delivery was two days late and the box was torn. Customer support was slow to respond.  
**Anyway, the Bluetooth earbuds paired instantly with my phone. The sound is clear, bass is decent, and the battery easily lasts 6–7 hours.** I used them during a workout and the fit stayed secure.



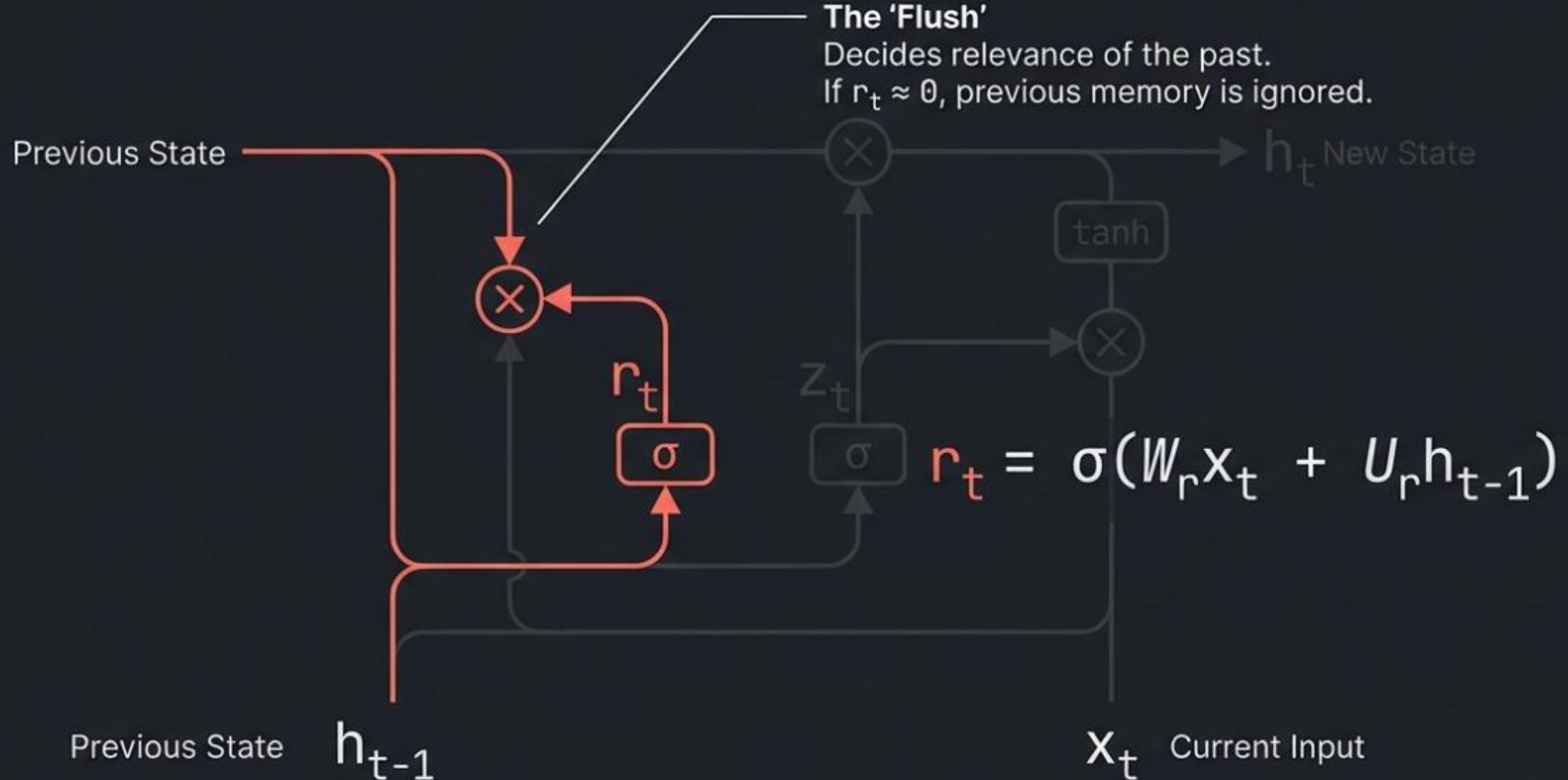
THE DRAFT

A proposal for the new state. It mixes current input with a selectively filtered history.

# Update Gate

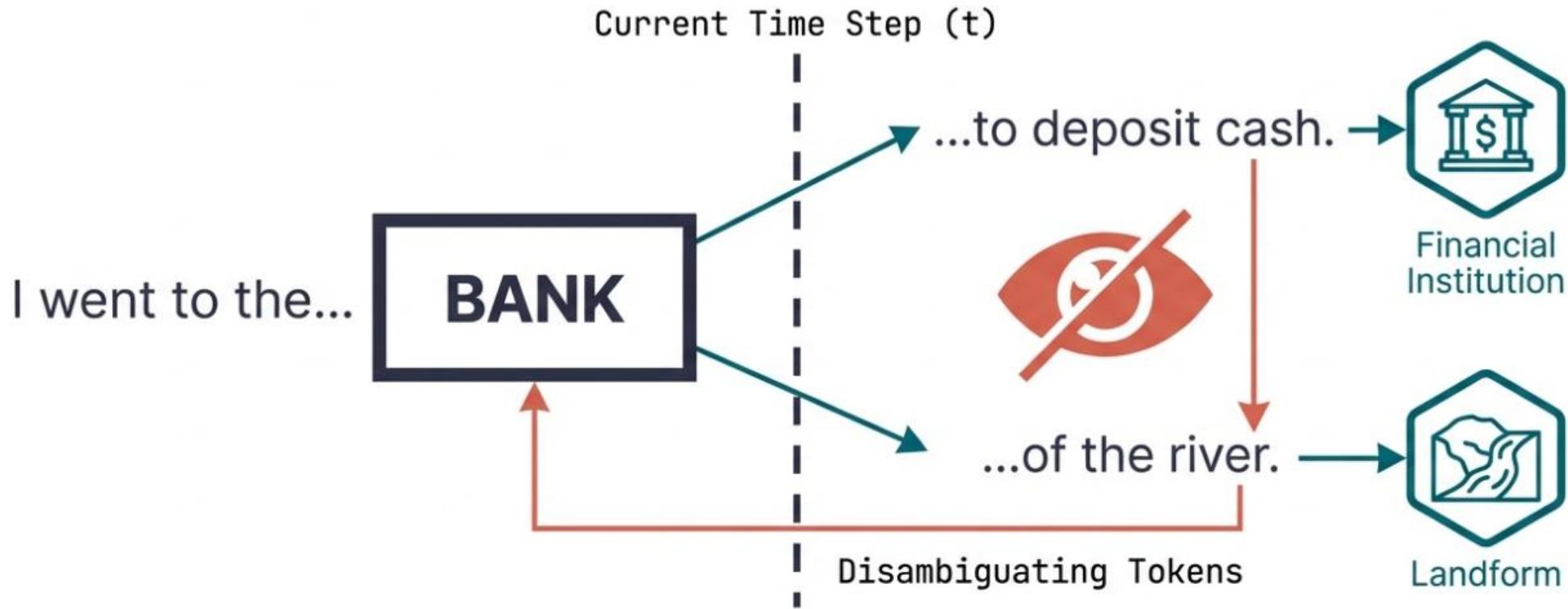


# Reset Gate

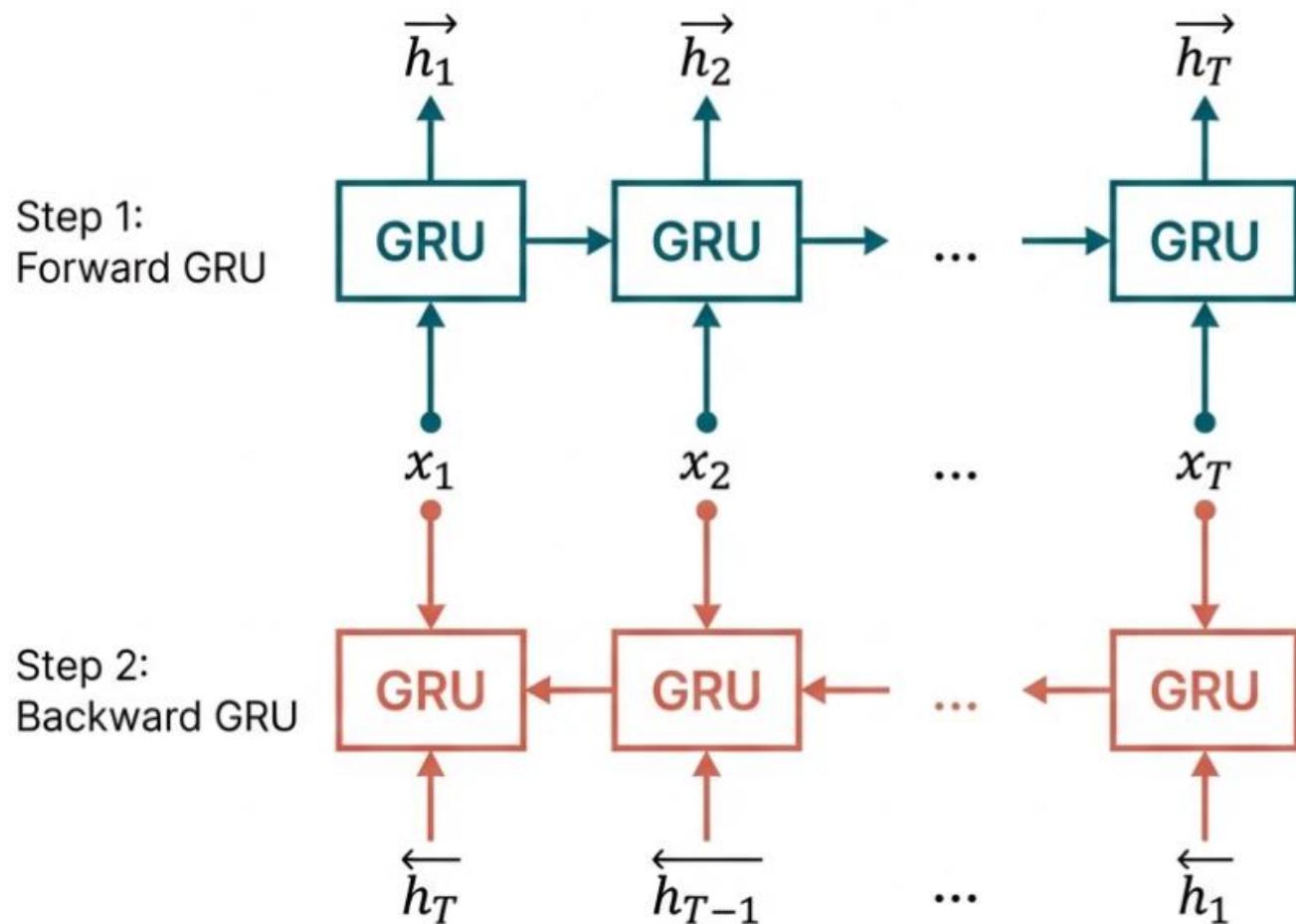


# Future gives the full picture

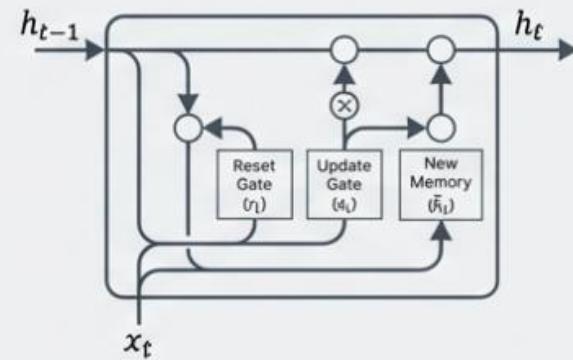
In sequence processing, the meaning of a specific token frequently depends on both its left (past) and right (future) context. Without the full picture, interpretation fails.



# Bi Directional GRU

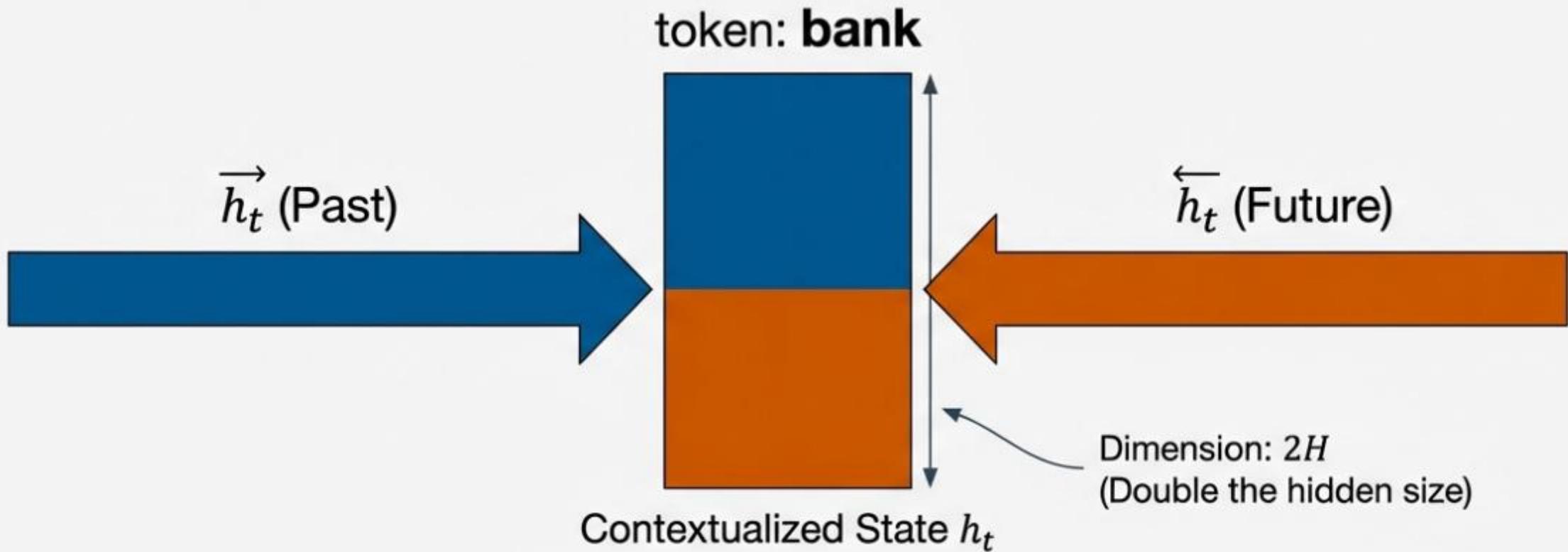


## Inside the GRU



Gates control information flow, deciding what to keep from the past and what to overwrite.

# Merging States from Both Direction



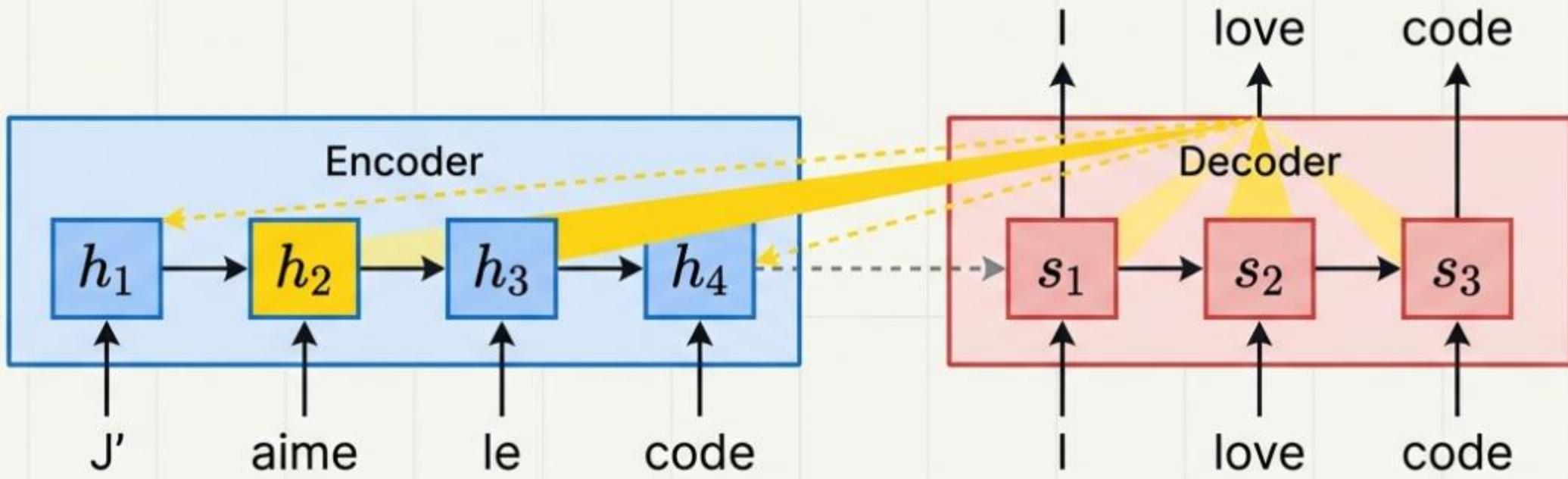
$$h_t = [\vec{h}_t ; \overleftarrow{h}_t] \text{ (Concatenation)}$$

# Lab

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Attention



**The Solution::** Instead of relying on a static summary, we allow the decoder to '**look back**' at the entire history of encoder states.

**Dynamic Context:** At every step of decoding, the model creates a unique context vector relevant *\*only\** to that specific moment.

# Approach

# Lab

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

Thank You

# Appendix

I love Py Torch

8 450 9901 772

Data IDs:

8	450	9901	772	0
0	0	0	0	0

Data Mask:

1	1	1	1	0
0	0	0	0	0

0.015	0.874	...	...	0.331
0.452	-0.112	...	...	0.567
0.981	0.034	...	...	-0.229
-0.563	0.775	...	...	0.101
0.000	0.000	...	...	0.000
0.000	0.000	...	...	0.000