

# Deep Learning Frameworks

Non-Linear Boundaries, Activation Functions, Backprop, Autograd,  
Dataset, DataLoader and Regularization

By Sakharam

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

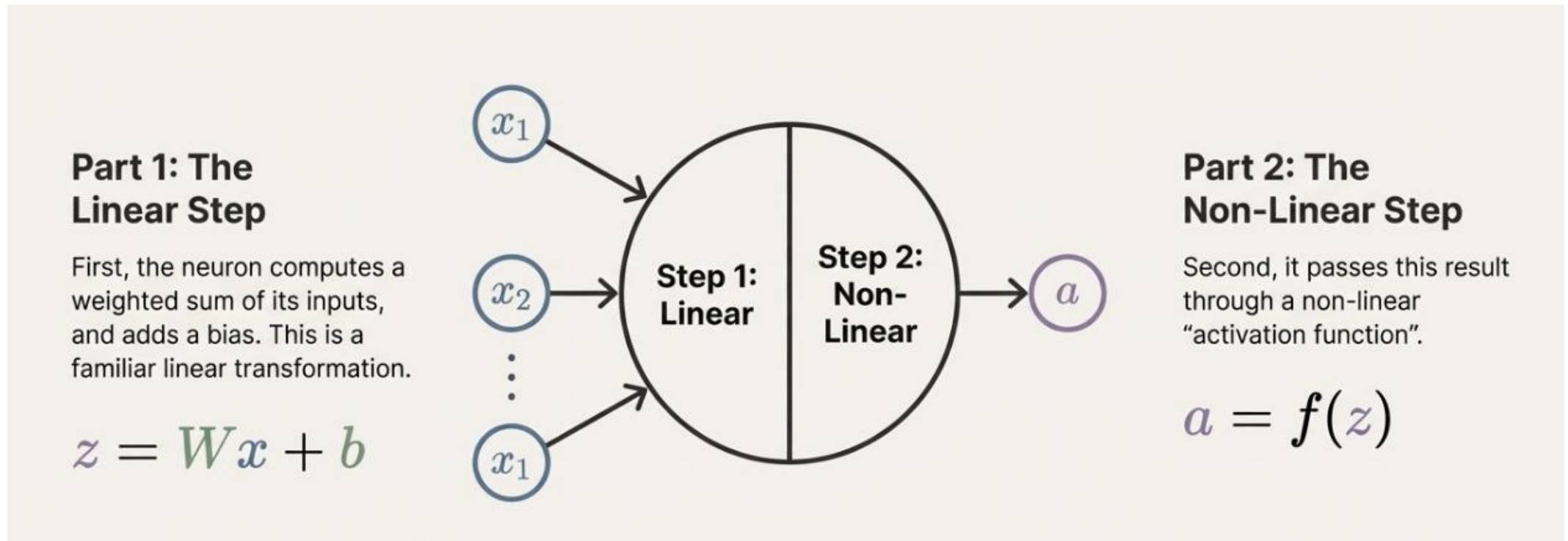
# Recap

- Computation Graph
- Tensor and Operations
- Toy Dataset – Initializing Tensors (Random, Zeroes, Ones)
- Neural Network – nn.Sequential
- Training Loop - Skeleton

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

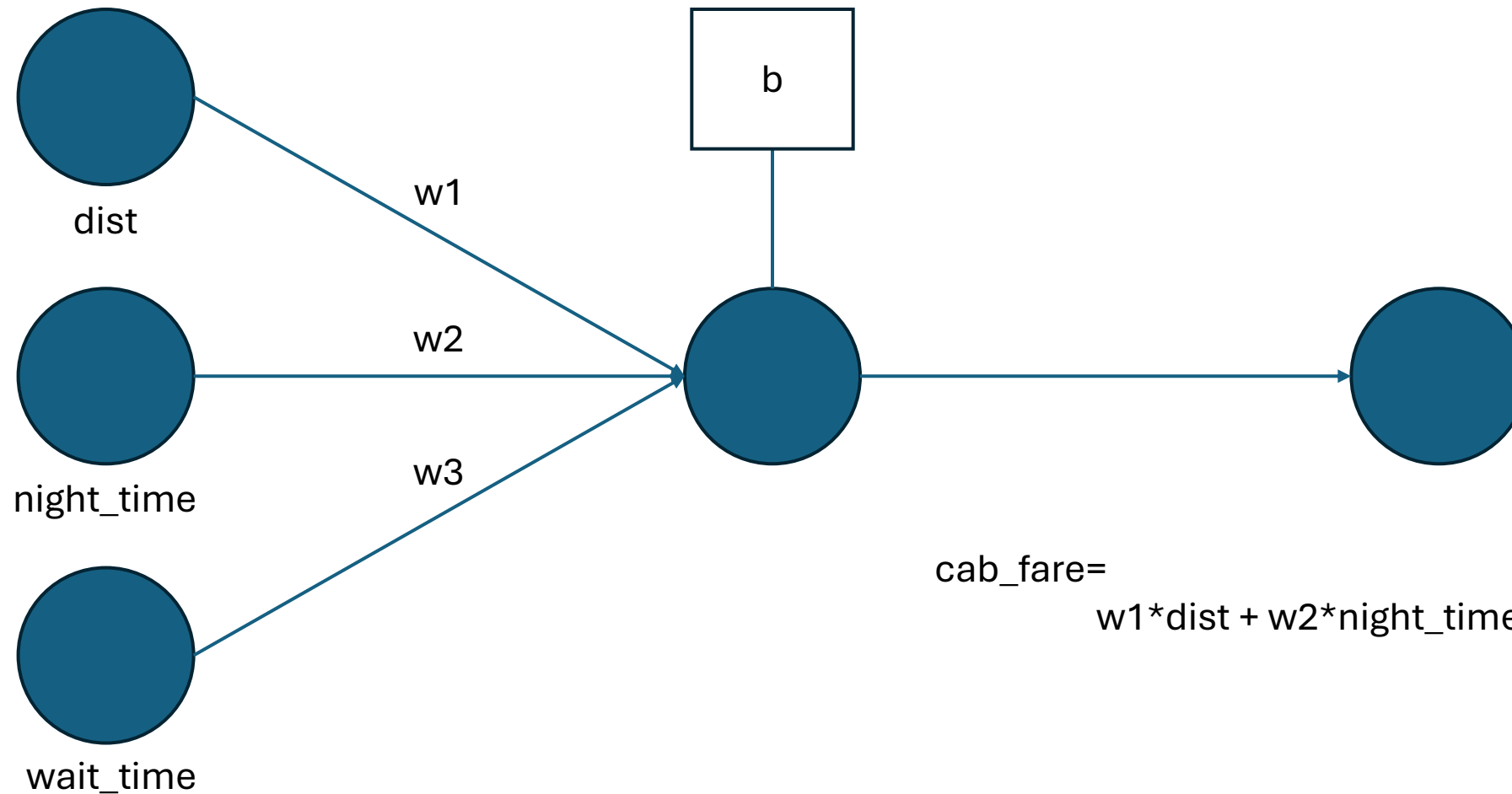
# Neuron: Building Block of Neural Network



<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Neural Network with Linear Neurons

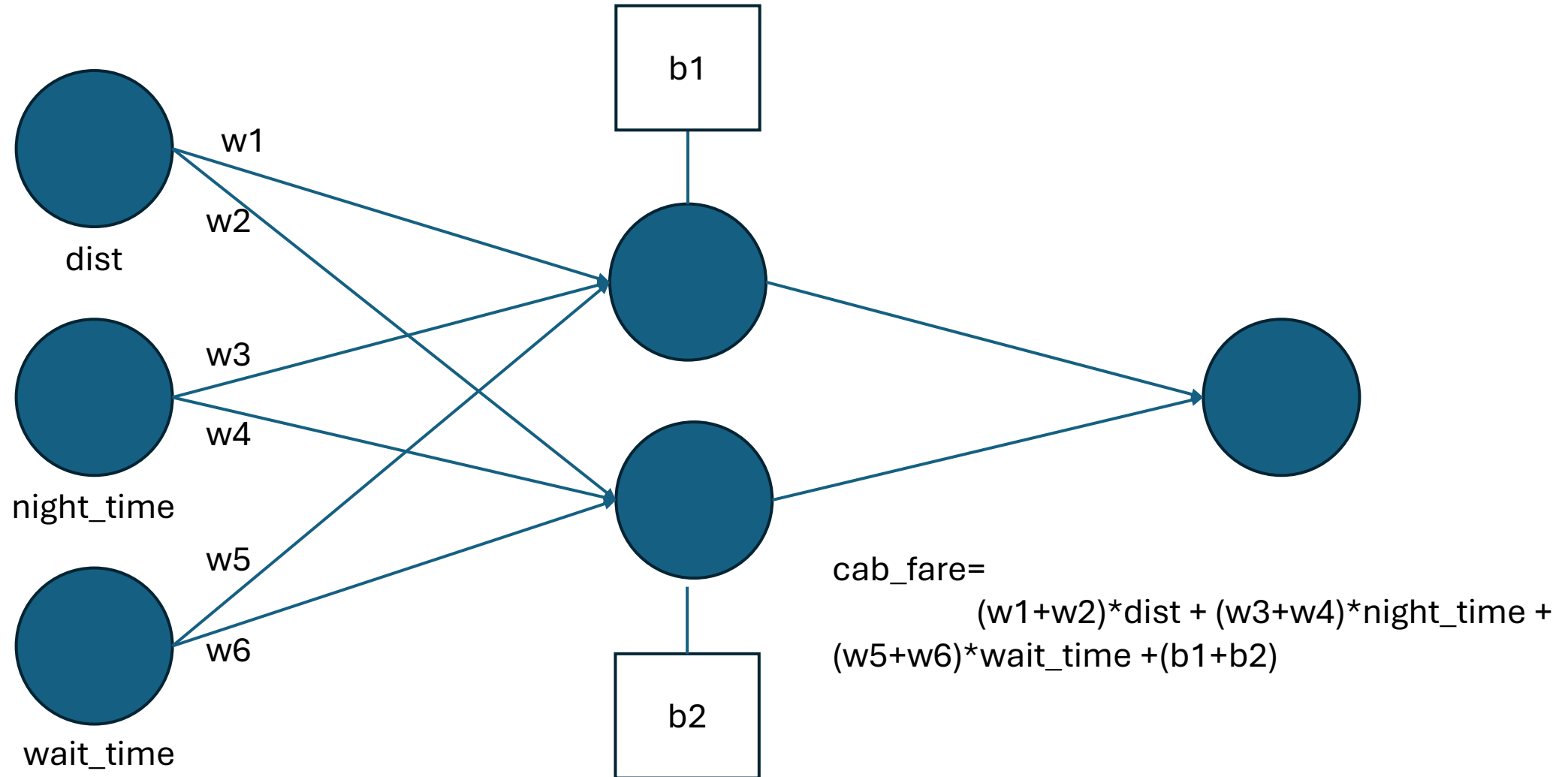


$$\text{cab\_fare} = w1 * \text{dist} + w2 * \text{night\_time} + w3 * \text{wait\_time} + b$$

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

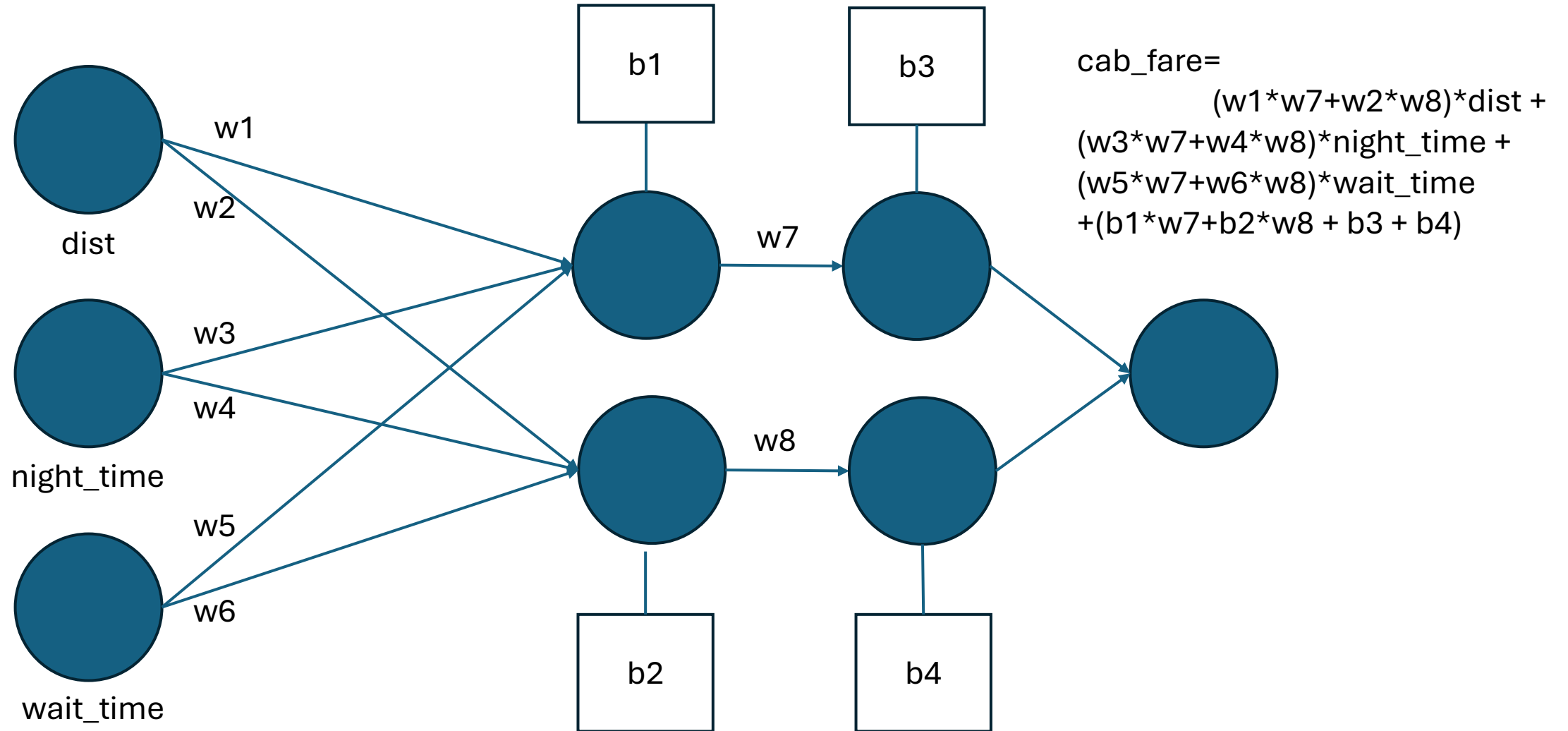
# Neural Network with Linear Neurons



<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

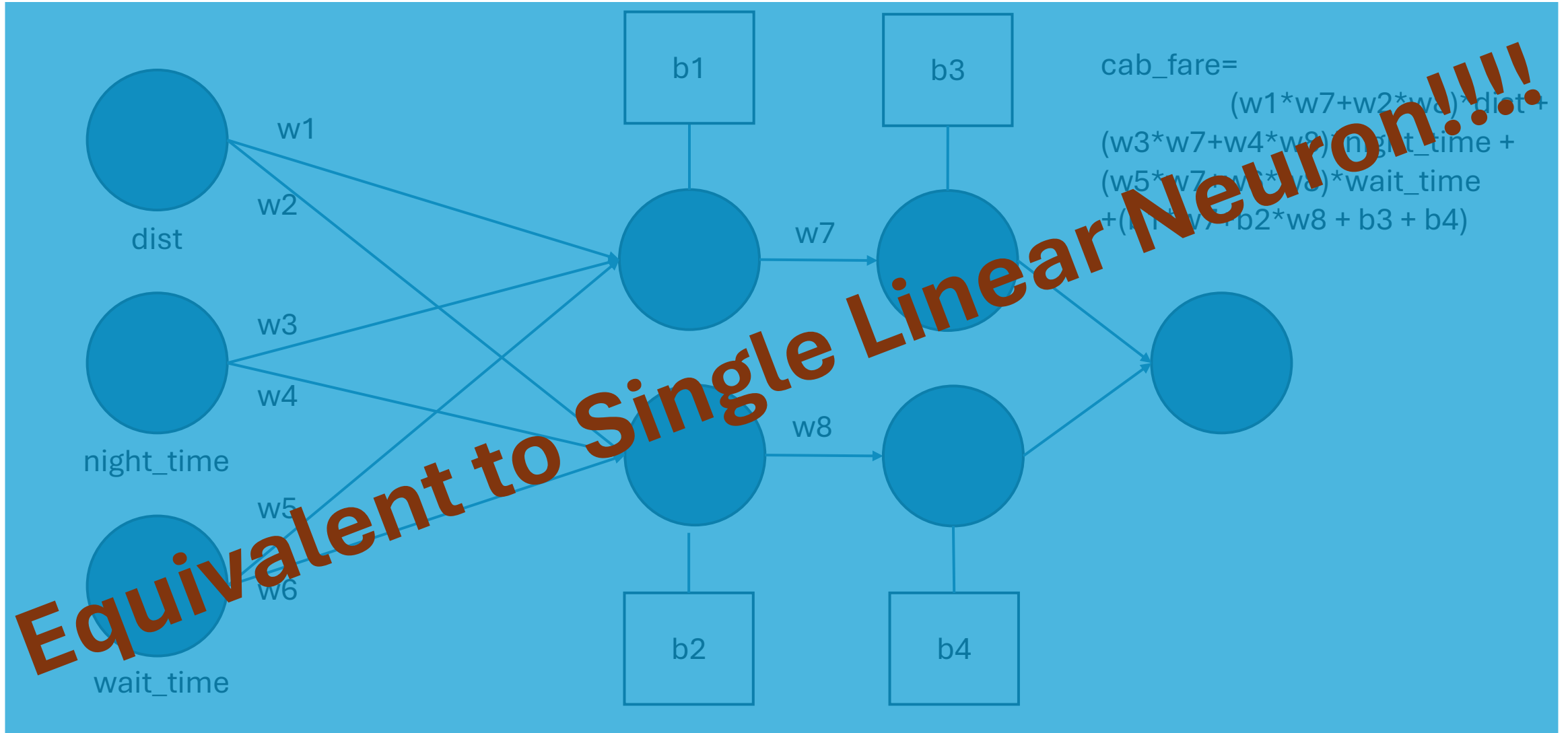
# Neural Network with Linear Neurons



<https://tinyurl.com/dlframeworks>

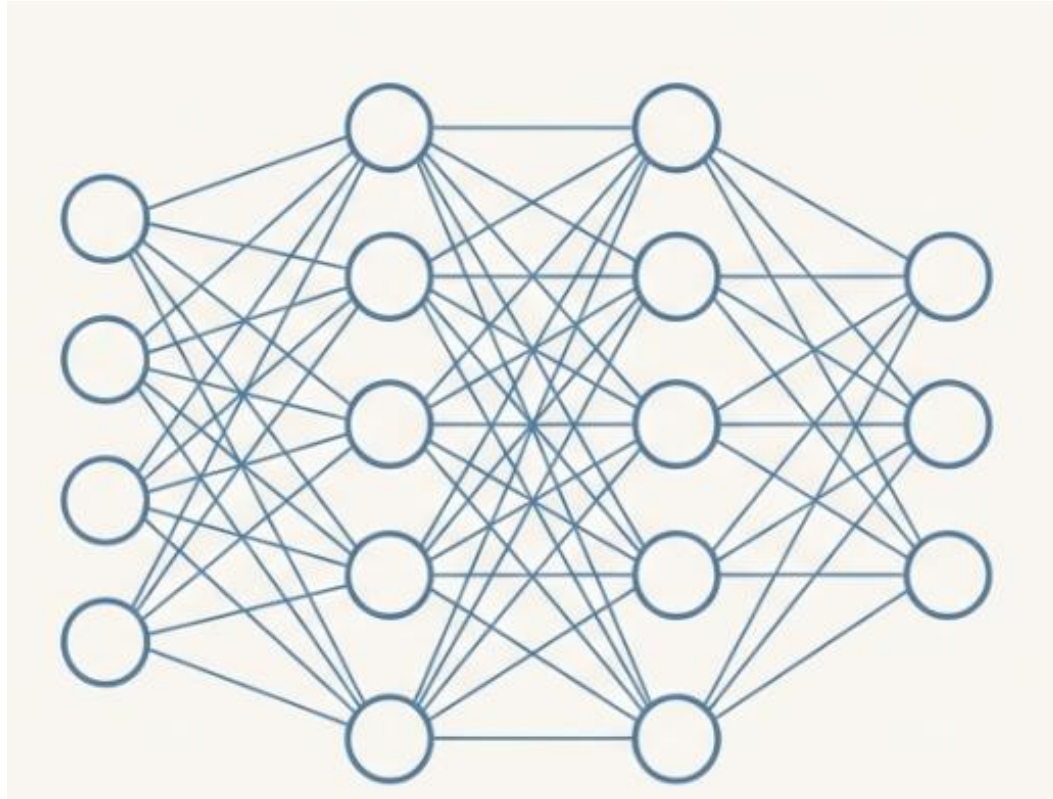
<https://github.com/sakharamg/DeepLearningFrameworks>

# Neural Network with Linear Neurons



# Neural Network with Linear Neurons

Still Linear

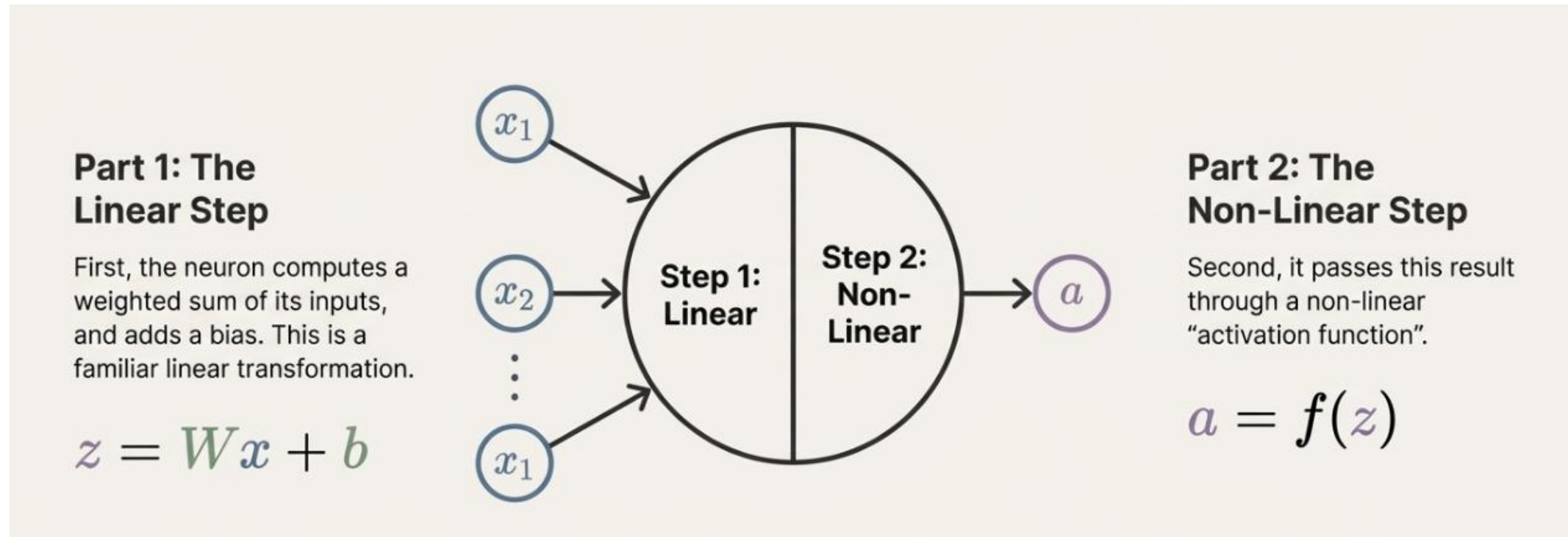


<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>



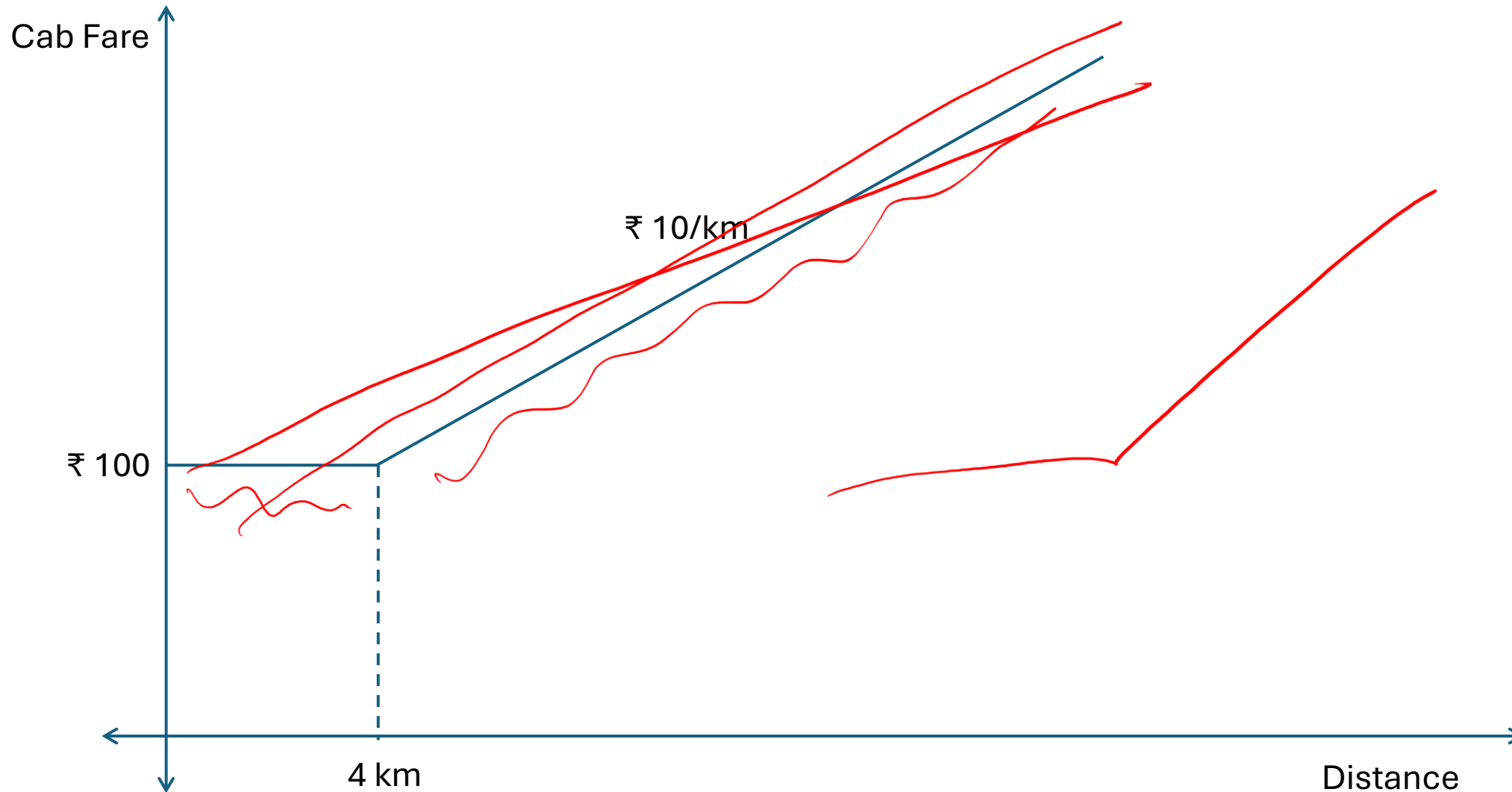
# Activation Functions – Non Linearity



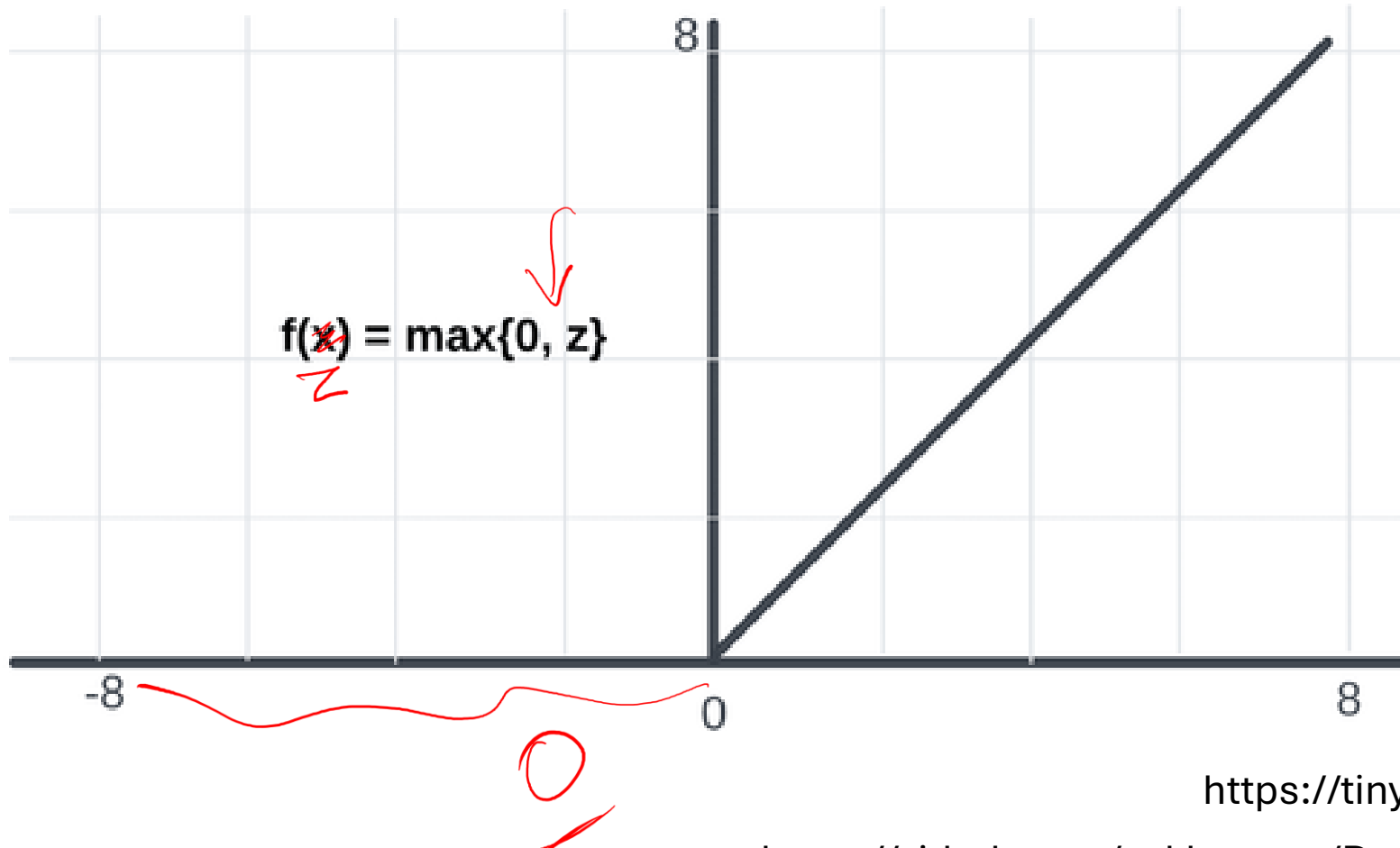
<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Towards Non Linearity – Handling Bends

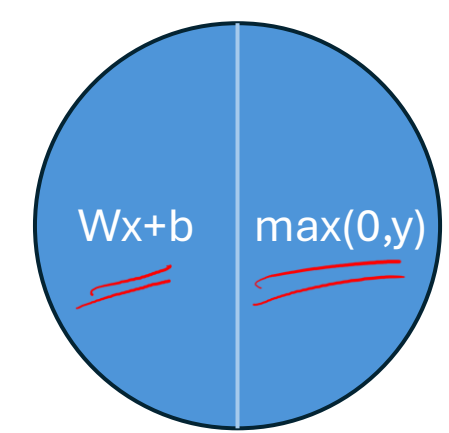
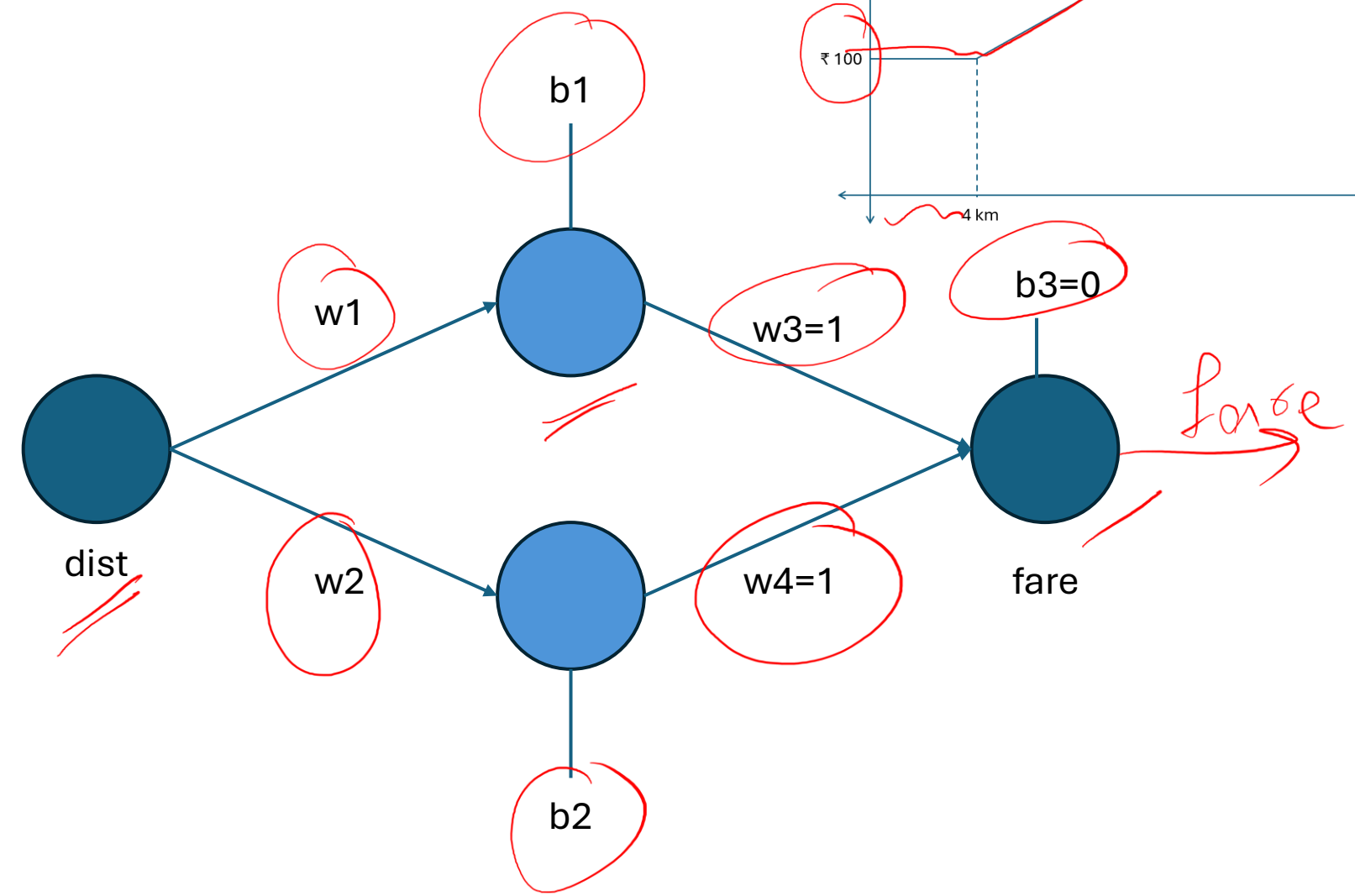
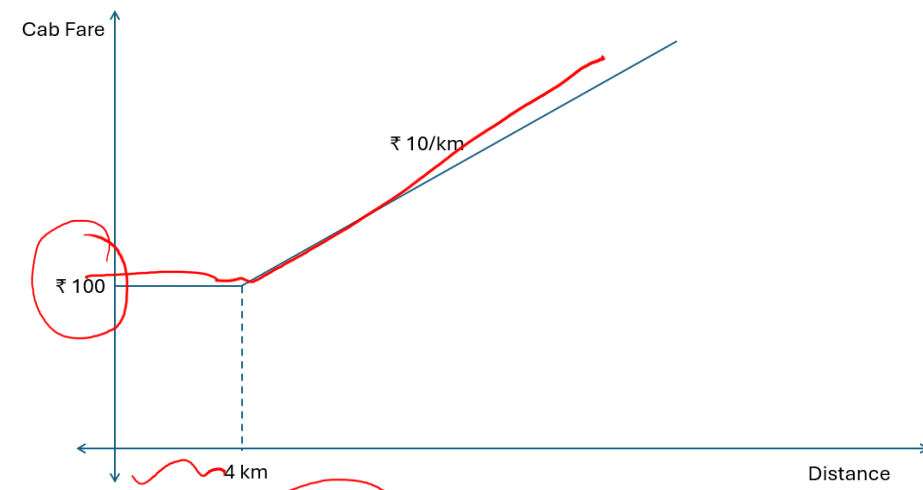


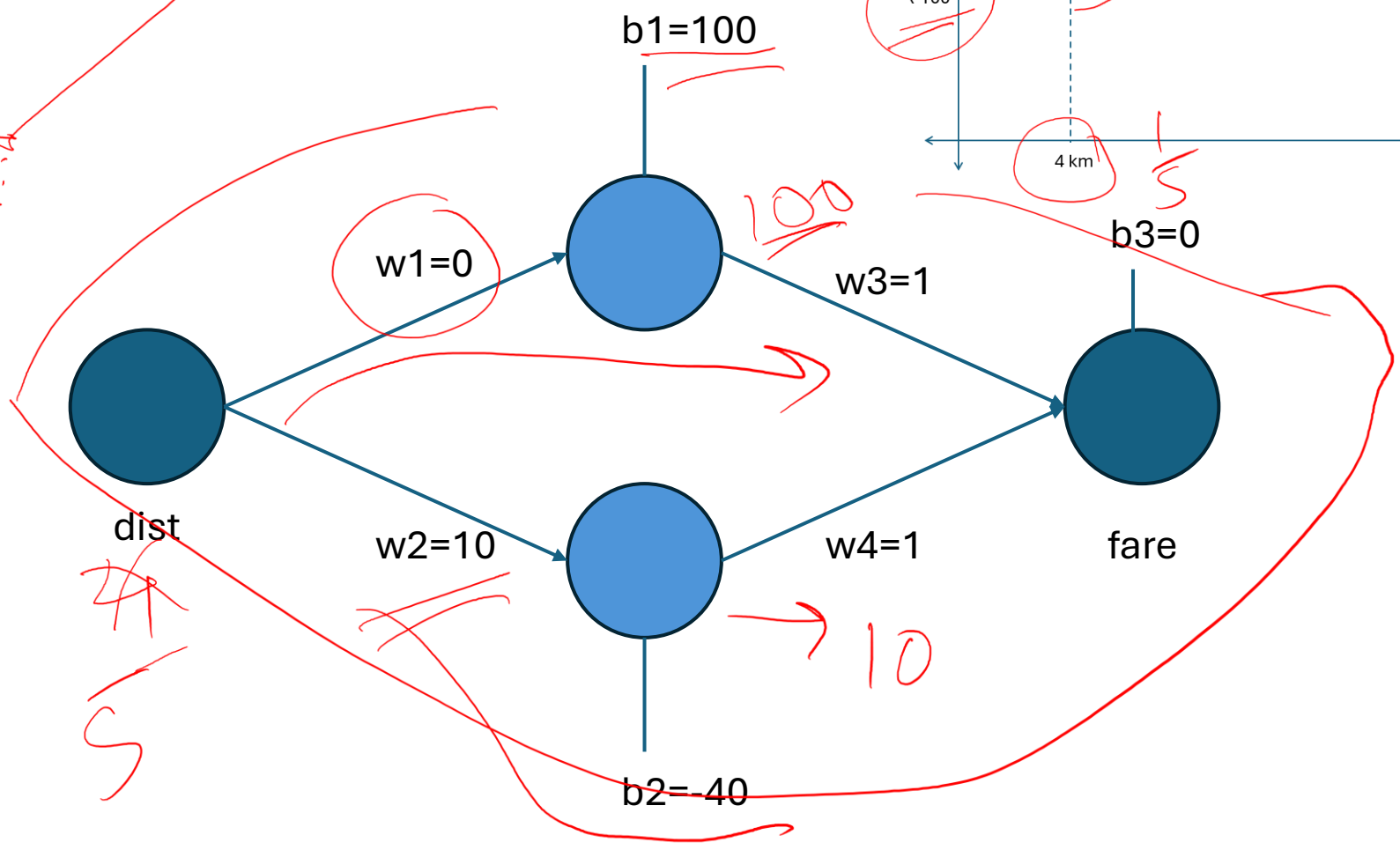
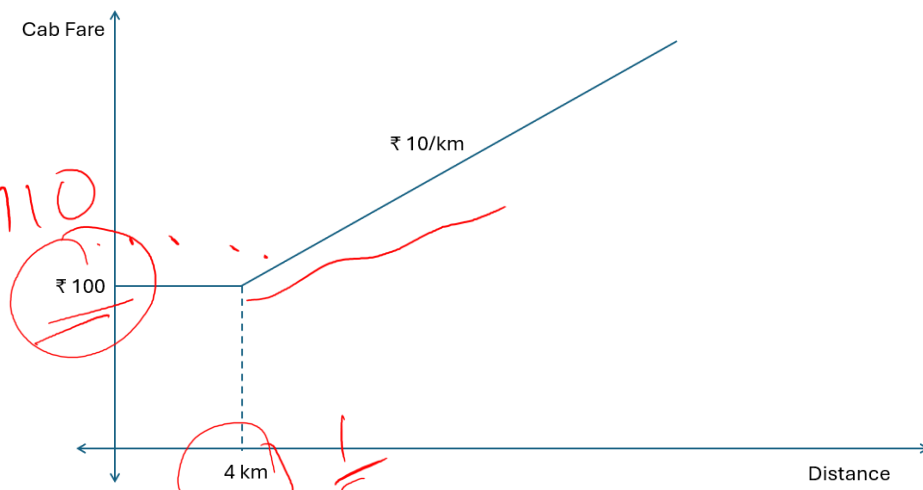
# ReLU



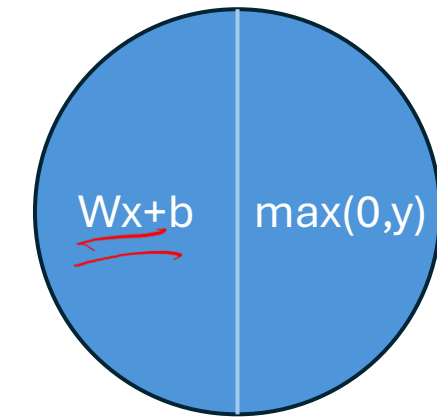
<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>





1  
2  
3  
4



# Classification

<https://playground.tensorflow.org/>

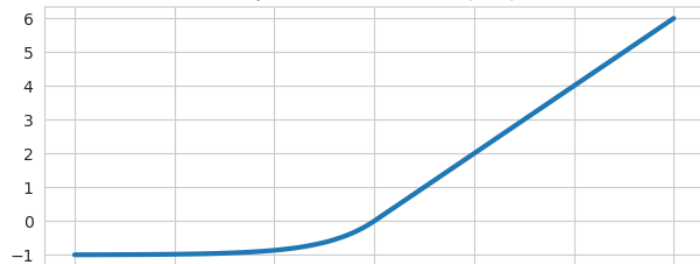


<https://tinyurl.com/dlframeworks>

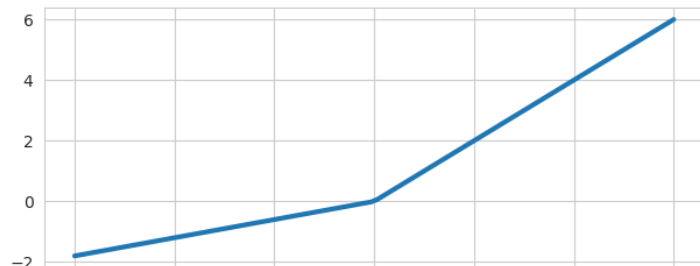
<https://github.com/sakharamg/DeepLearningFrameworks>

# Activation Functions

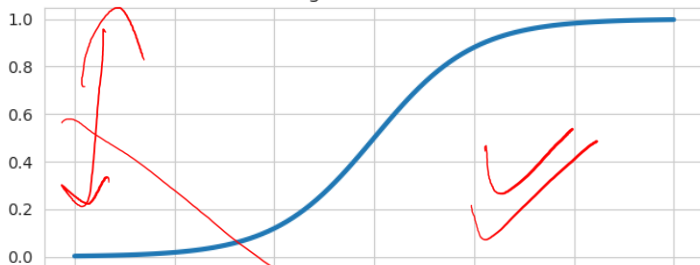
Exponential Linear Unit (ELU)



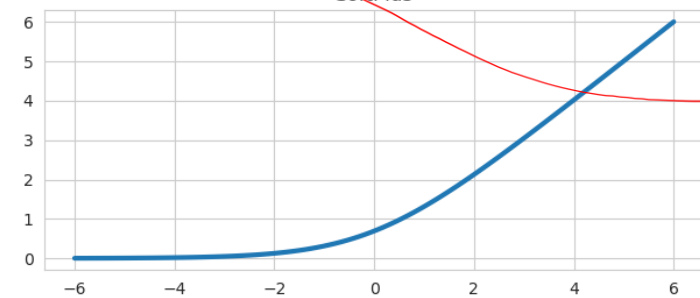
Parametric ReLU



Sigmoid Function



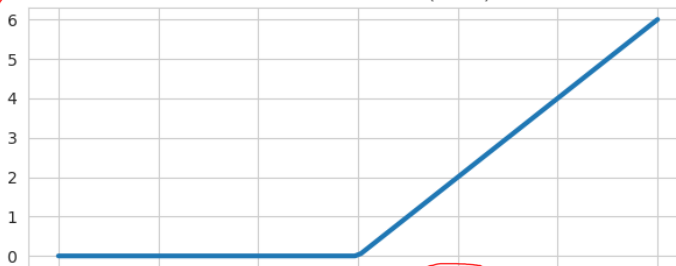
SoftPlus



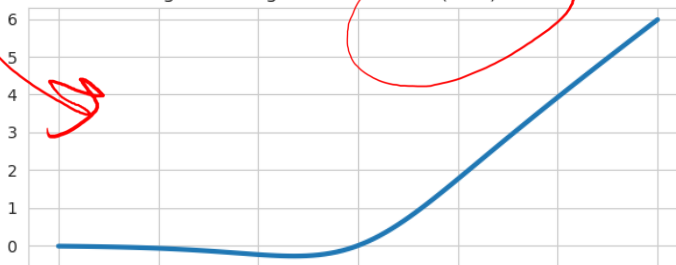
Gaussian Error Linear Unit (GELU)



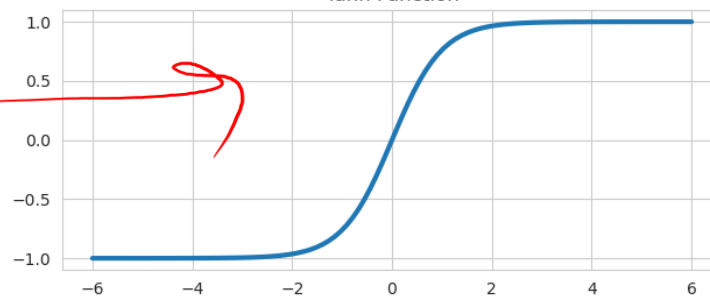
Rectified Linear Unit (ReLU)



Sigmoid-Weighted Linear Unit (SiLU) / Swish



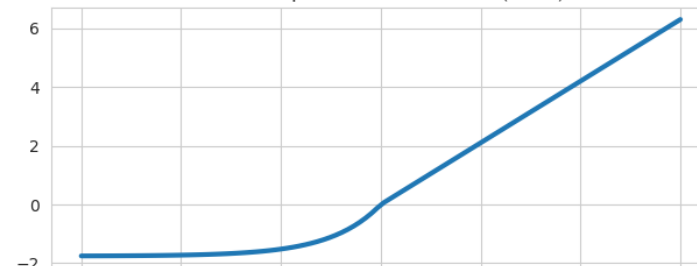
Tanh Function



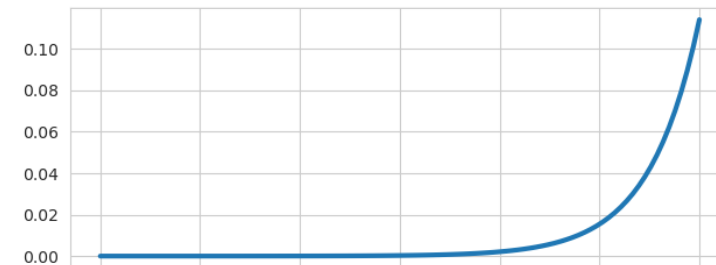
Leaky ReLU



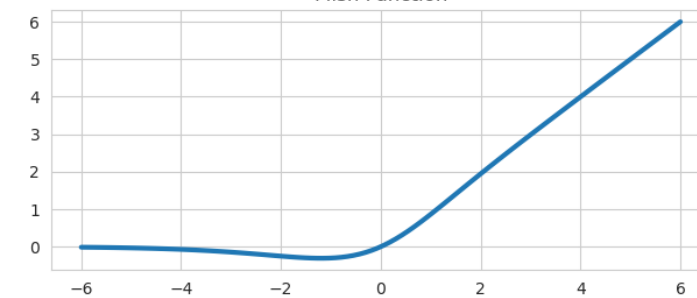
Scaled Exponential Linear Unit (SELU)



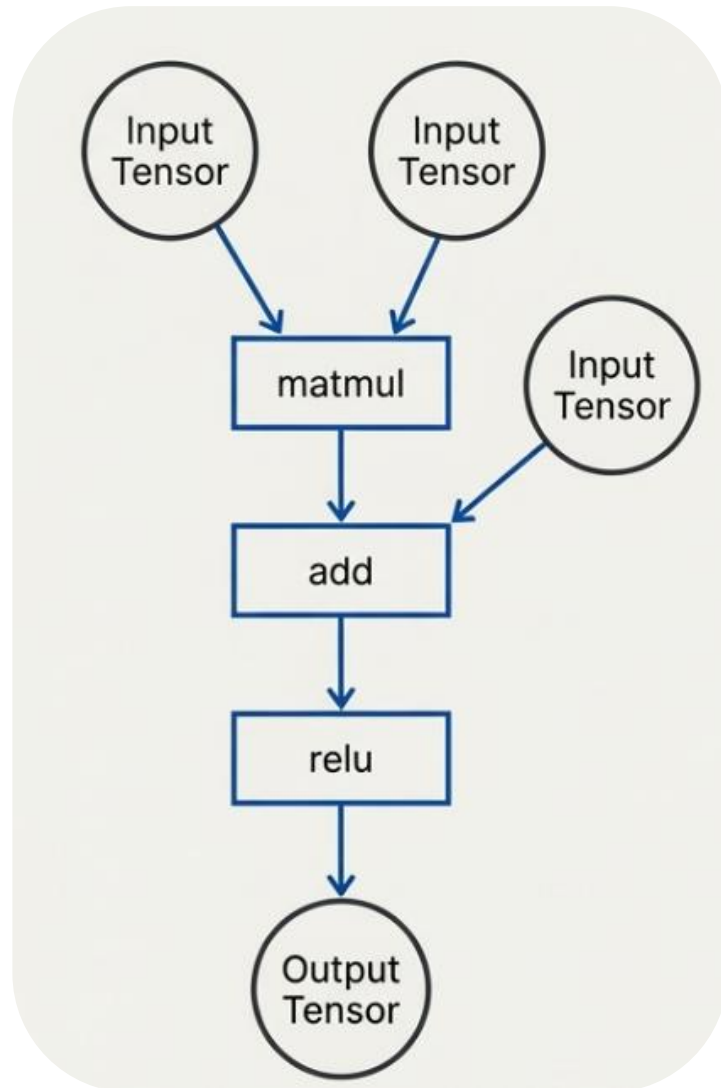
Softmax Function



Mish Function



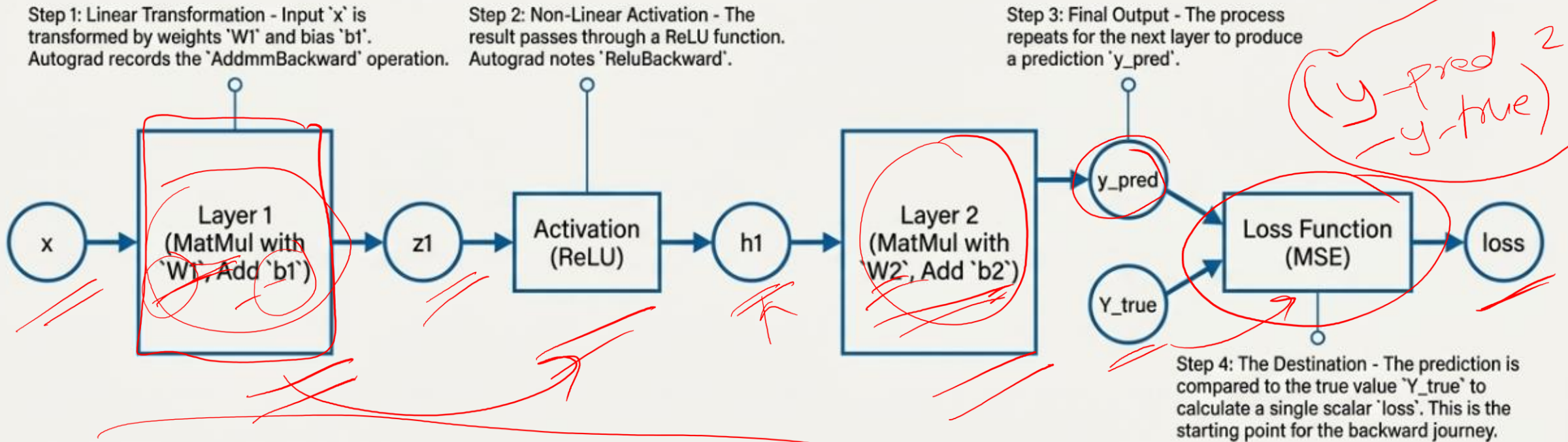
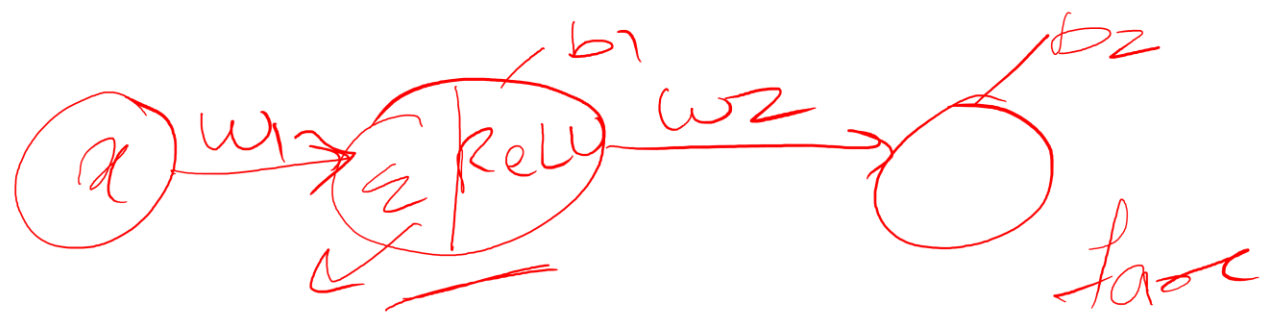
# Recap: Computation Graph



- **Eager Execution:** ops run immediately (no “compile step”)
- **Debugging = inspection:** print **shape** / **dtype** / **device** early
- **Core Primitives: Tensor + Autograd** → everything else builds on this



# Forward Pass



## What Happens During the Forward Pass?

The forward pass executes the model's operations sequentially to compute an output. Crucially, as this happens, PyTorch builds the dynamic computation graph in the background, linking each output tensor to its creating function via `grad_fn`. No gradients are calculated yet, but the 'map' is now complete.

# loss.backward()

## The Signal is Born

After the forward pass, we have a single scalar value: the loss. The entire goal of training is to minimize this value. To do this, we need to know how each parameter ( $W$ ,  $b$ ) affects the loss. This is the gradient.

The chain rule allows us to compute this:

If  $loss = f(y)$  and  $y = g(W)$ , then the gradient of the loss with respect to the weight  $W$  is:

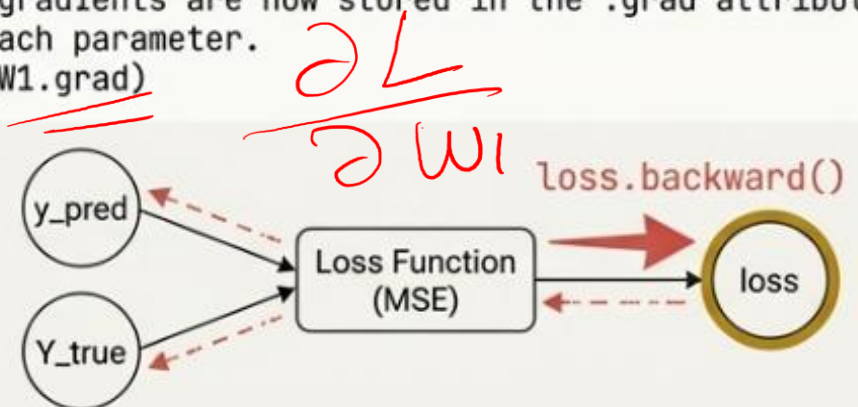
$$\frac{\partial loss}{\partial W} = \frac{\partial loss}{\partial y} * \frac{\partial y}{\partial W}$$

Think of it as assigning blame. The chain rule mathematically distributes the total error back through each operation that contributed to it.

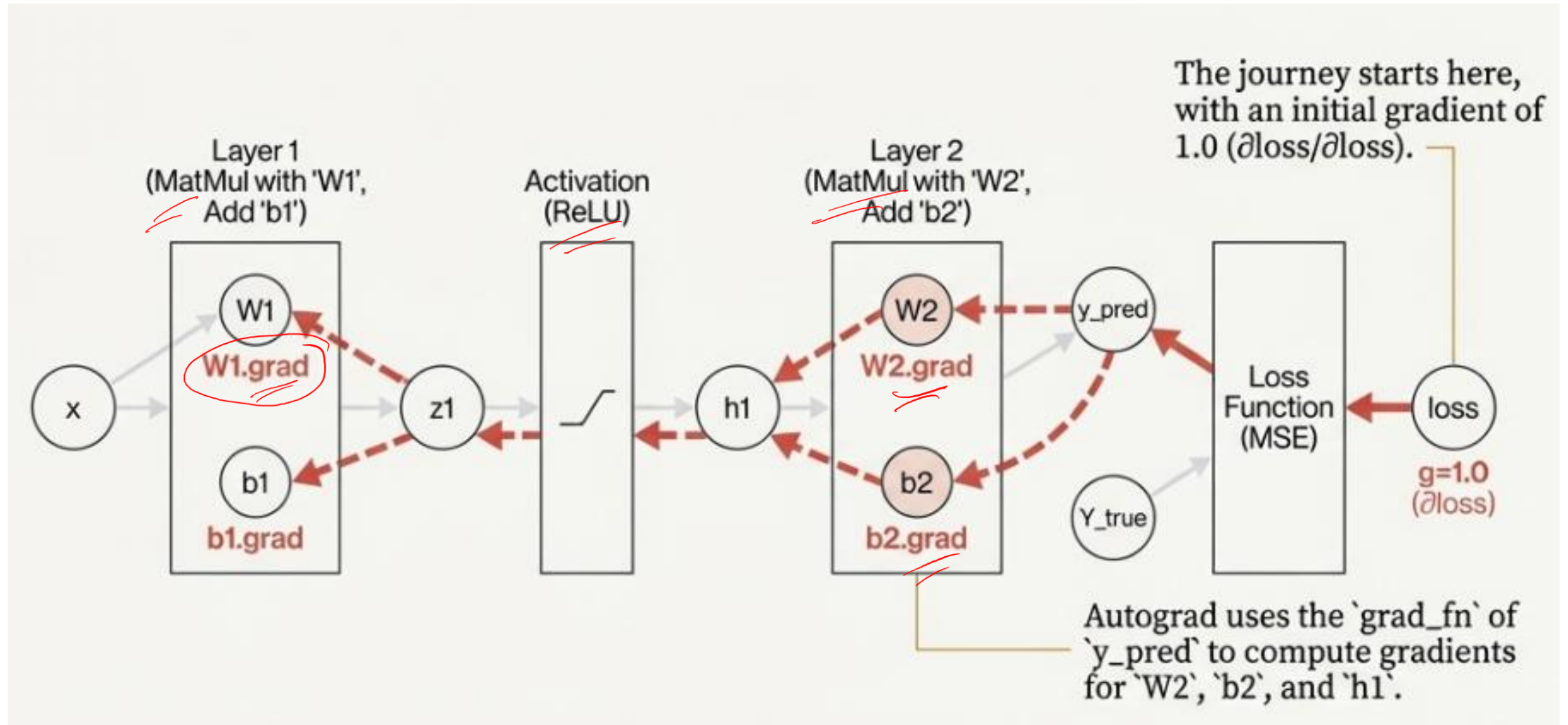
## The Trigger: `loss.backward()`

In PyTorch, the entire backpropagation process is triggered by a single command on the final loss tensor.

```
# After computing the final loss...  
loss = F.mse_loss(y_pred, Y_true)  
  
# This one line starts the journey home for the gradients.  
loss.backward()  
  
# The gradients are now stored in the .grad attribute  
# of each parameter.  
print(W1.grad)
```



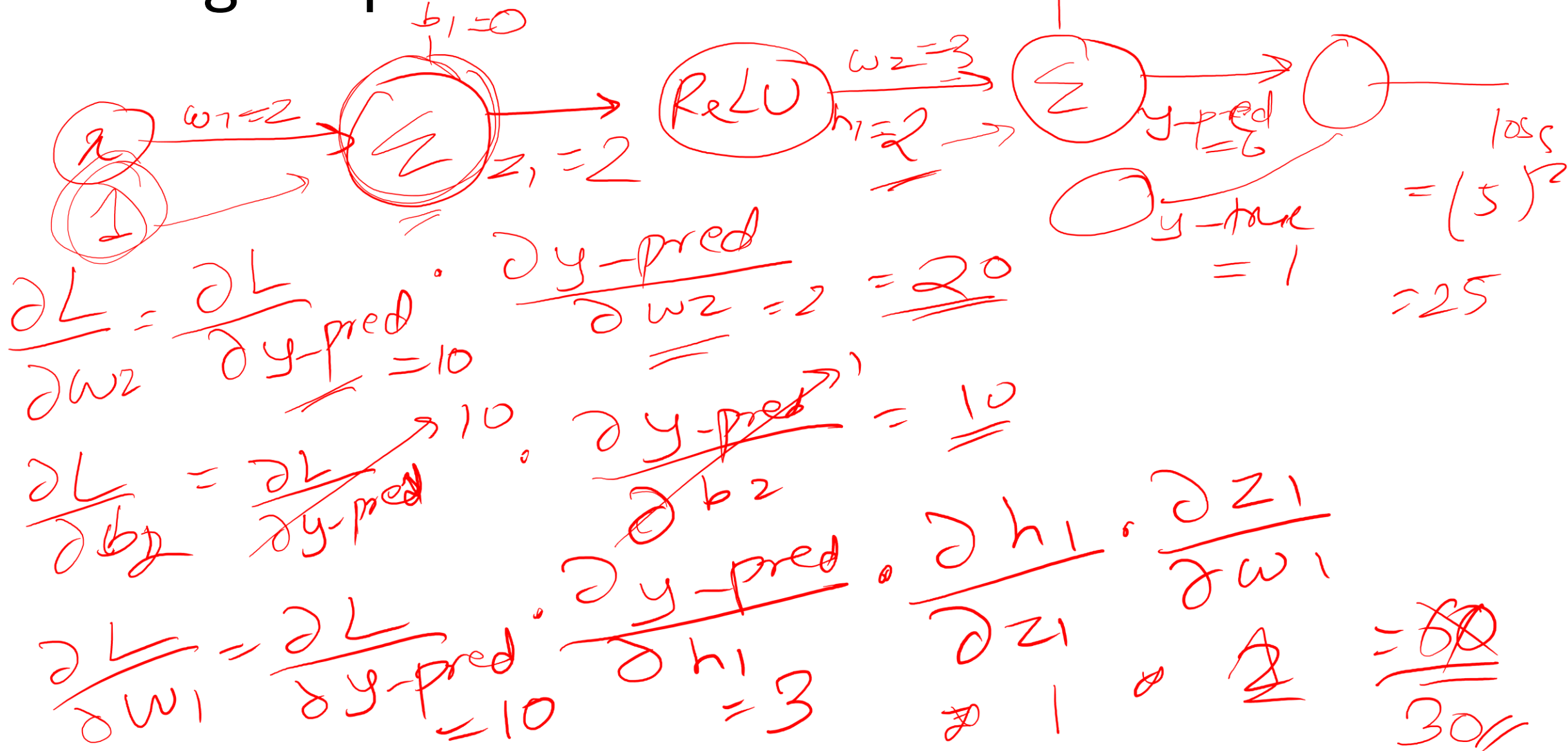
# Back Propagation





$$w = w - \lambda \frac{\partial L}{\partial w}$$

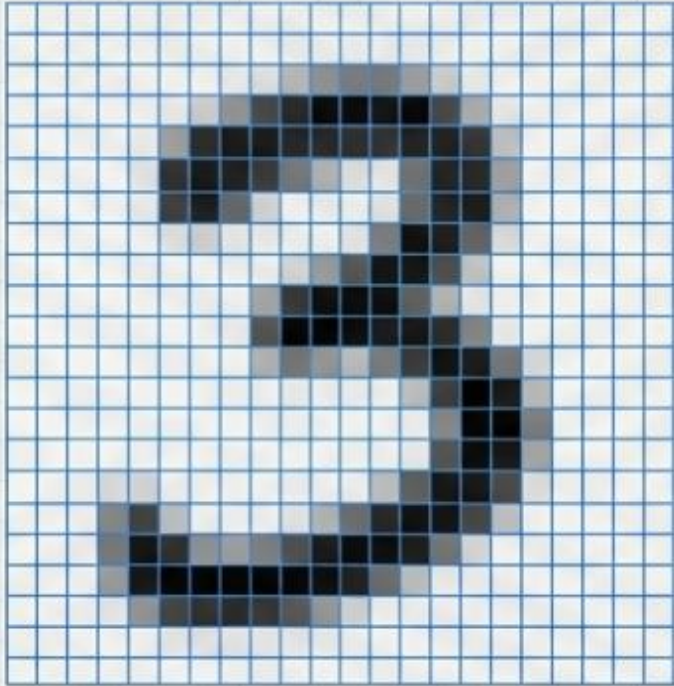
# Weight Updates



# Lab

# MNIST

INPUT



A 28x28 pixel grayscale image.

Tensor Shape: ``1 x 28 x 28``

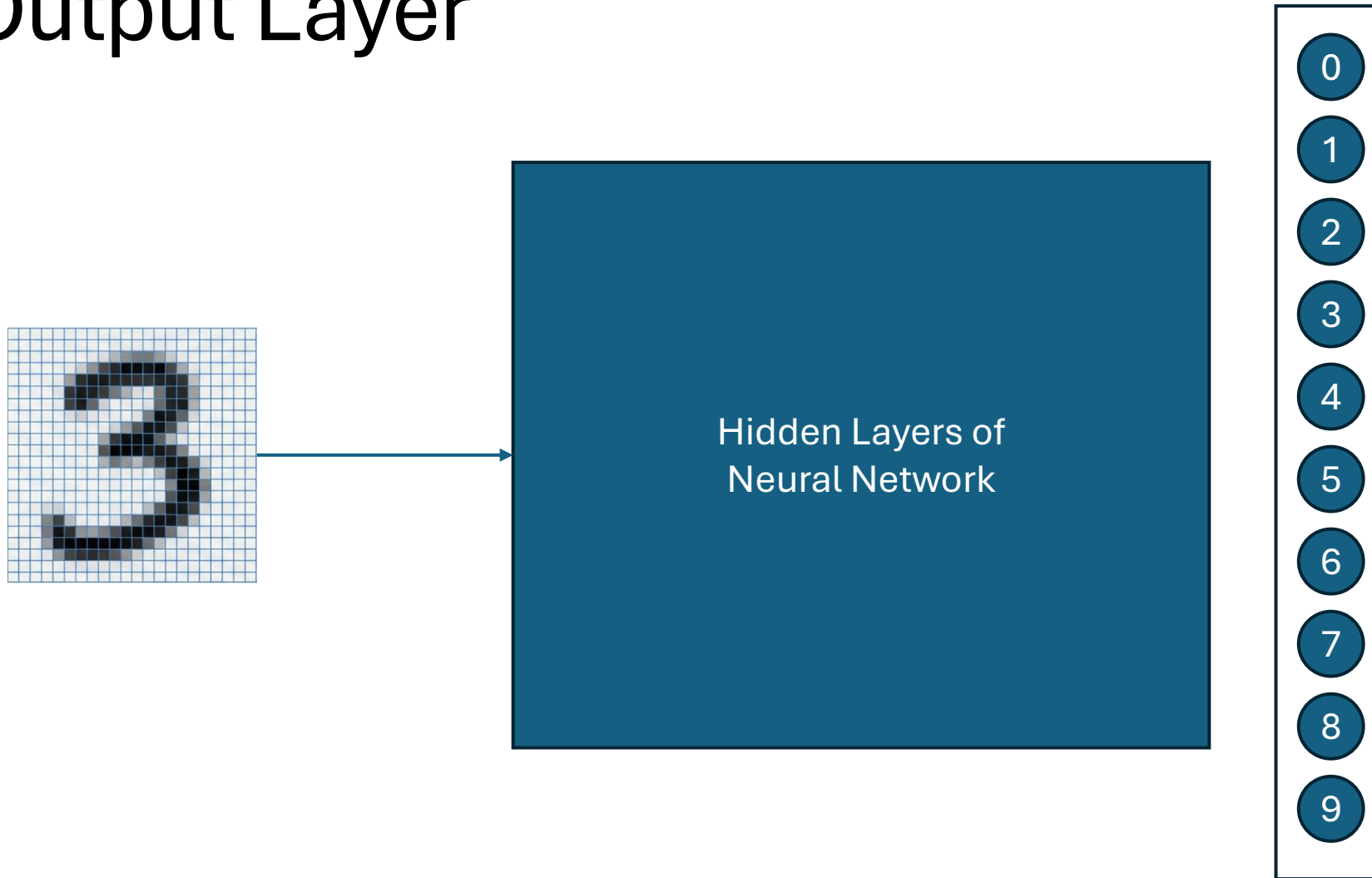
OUTPUT

0  
1  
2  
3  
4  
5  
6  
7  
8  
9

A prediction of the digit's class.

Classes: ``0, 1, 2, 3, 4, 5, 6, 7, 8, 9``

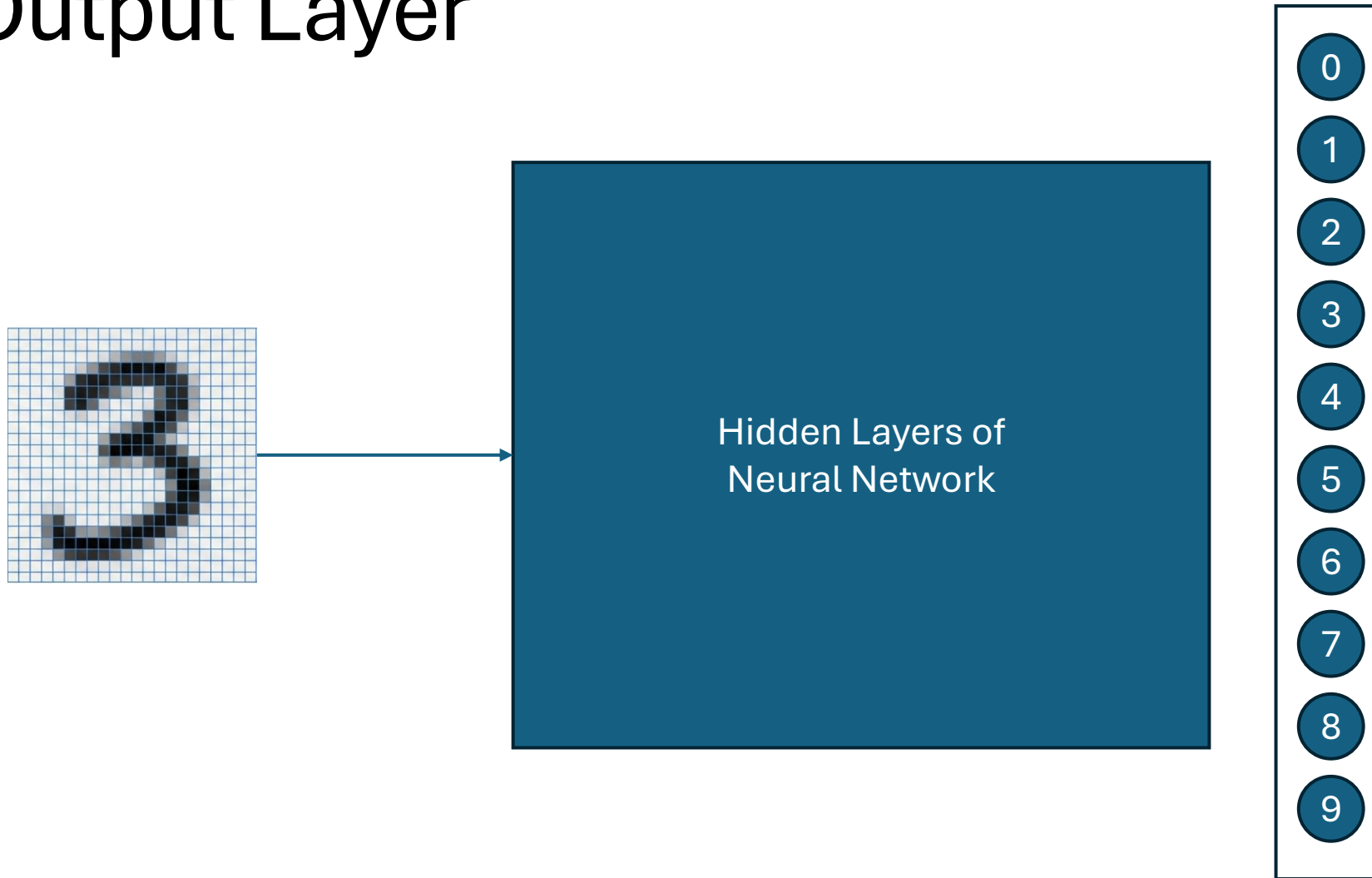
# Output Layer



<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

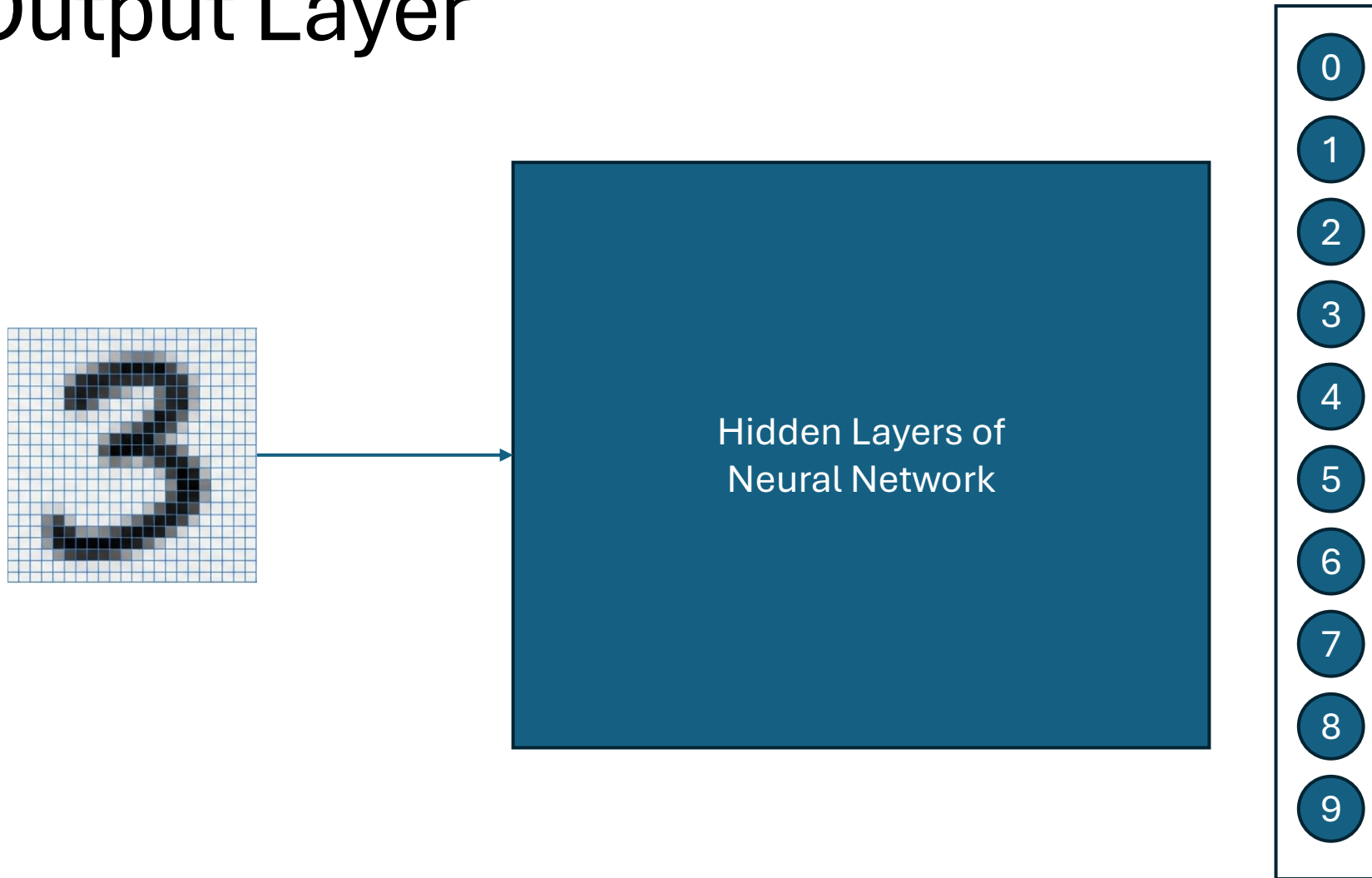
# Output Layer



10 Neurons

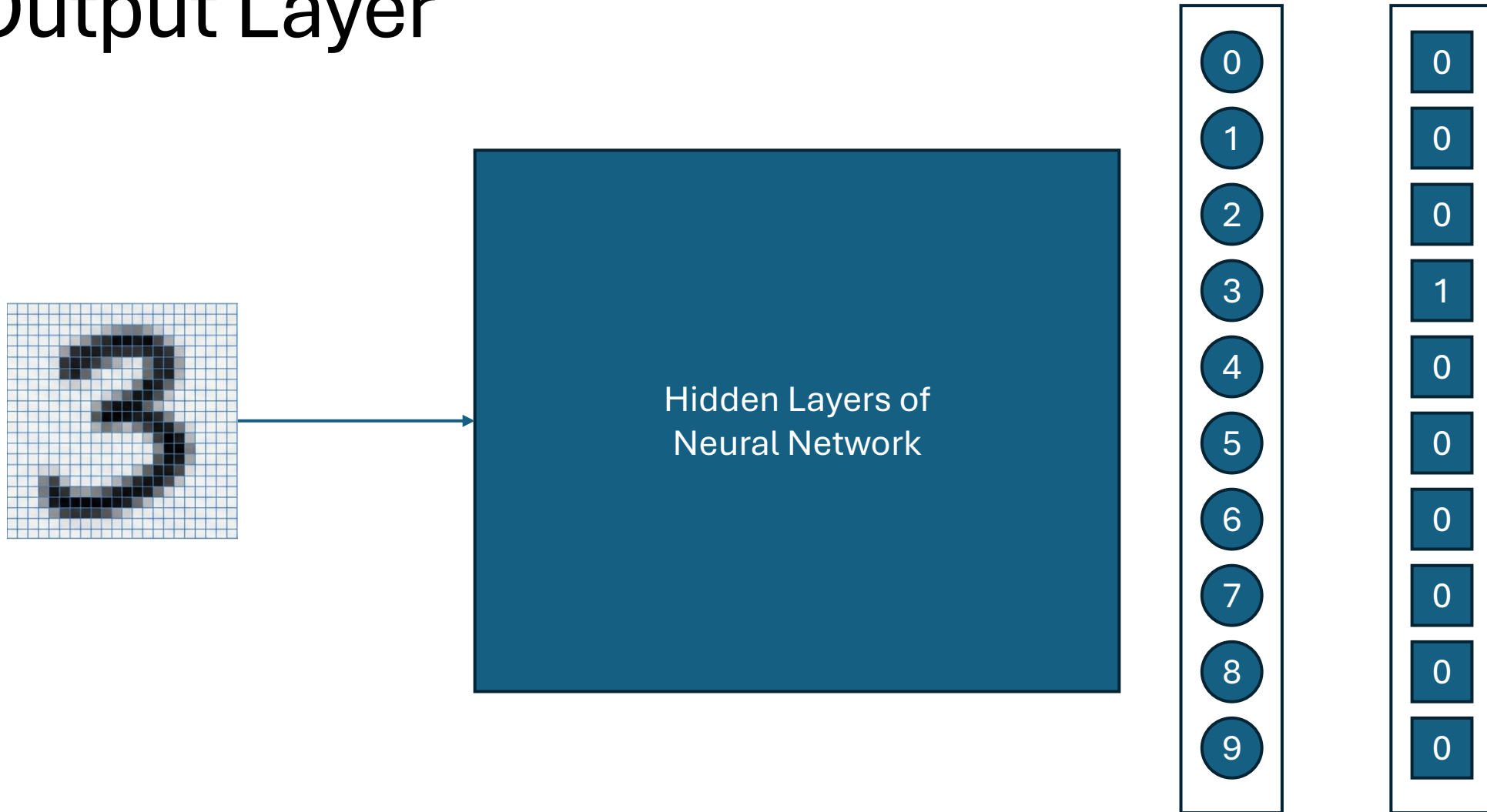


# Output Layer



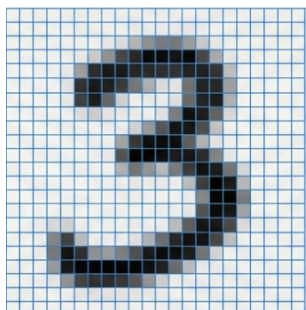
`nn.Linear( __ , 10)`

# Output Layer



`nn.Linear( __ , 10)`

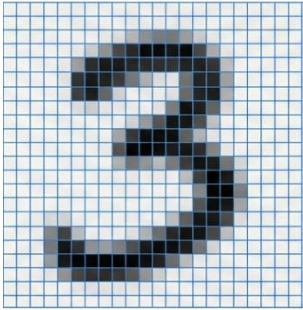
# Softmax



<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Softmax



Output Layer

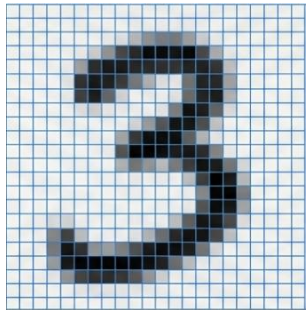
-0.7  
1.3  
-3.4  
**9.7**  
0.9  
-2.3  
0.1  
1.8  
4.1  
-1.2

Logits

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Softmax



Output Layer

-0.7  
1.3  
-3.4  
**9.7**  
0.9  
-2.3  
0.1  
1.8  
4.1  
-1.2

Logits

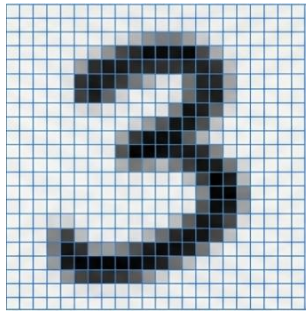
Softmax  
activation function

$$\frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Softmax



Output Layer

-0.7  
1.3  
-3.4  
**9.7**  
0.9  
-2.3  
0.1  
1.8  
4.1  
-1.2

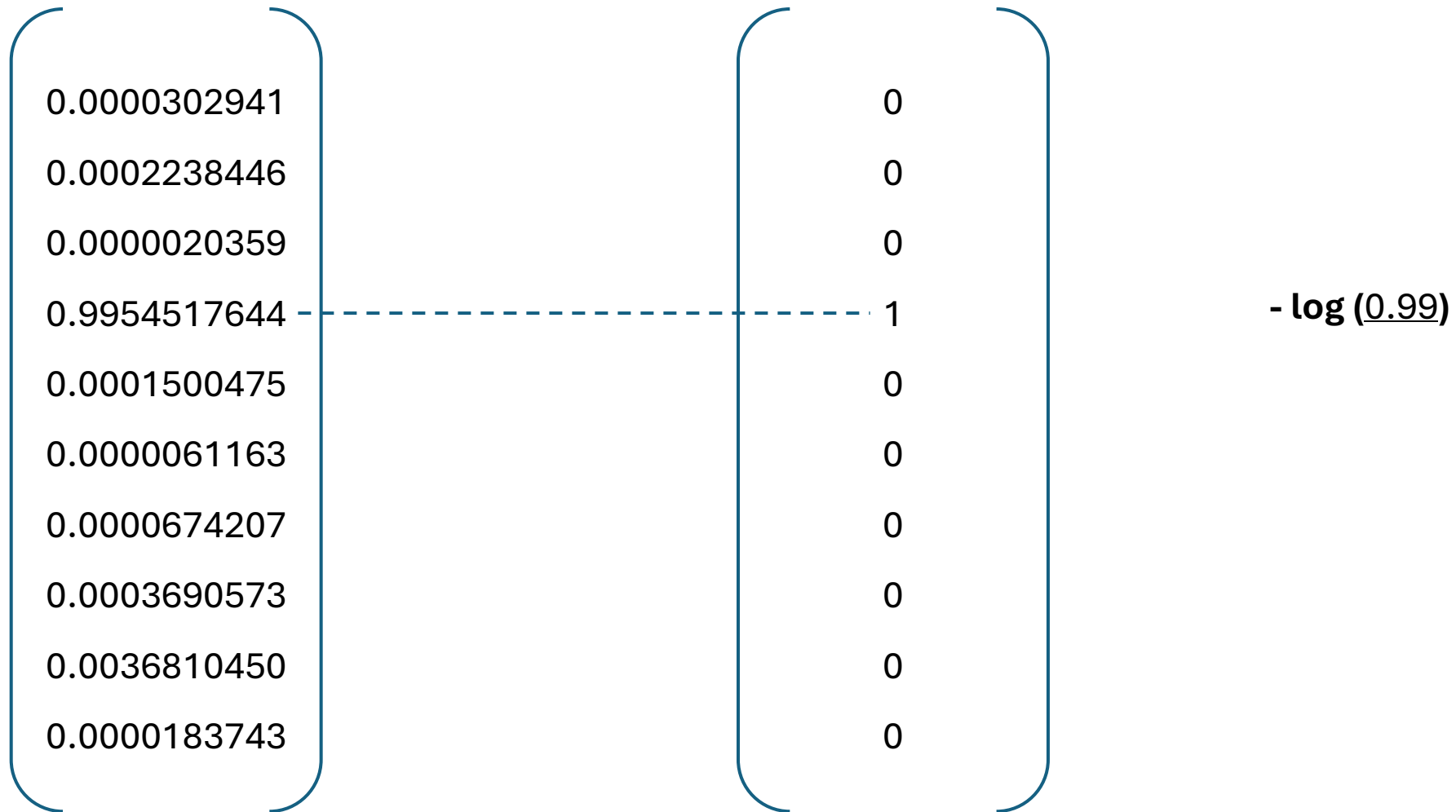
Logits

Softmax  
activation function

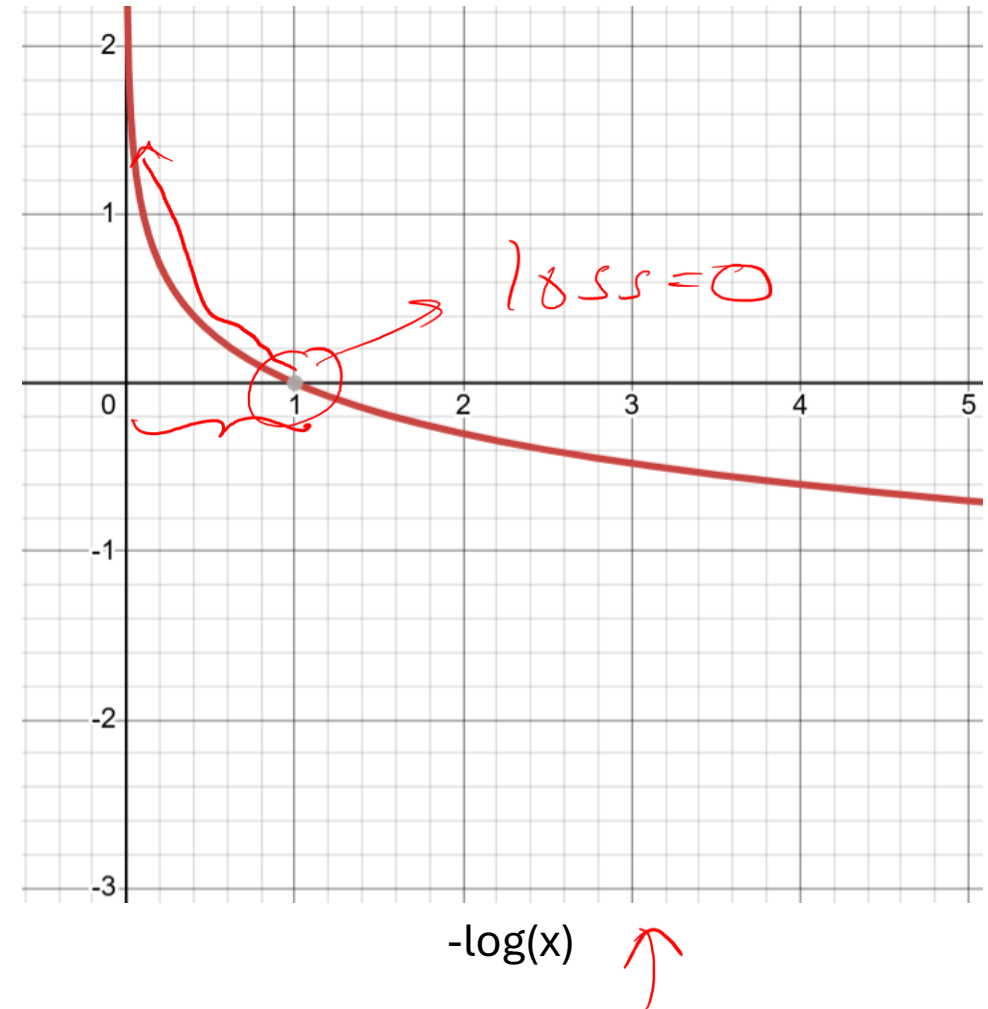
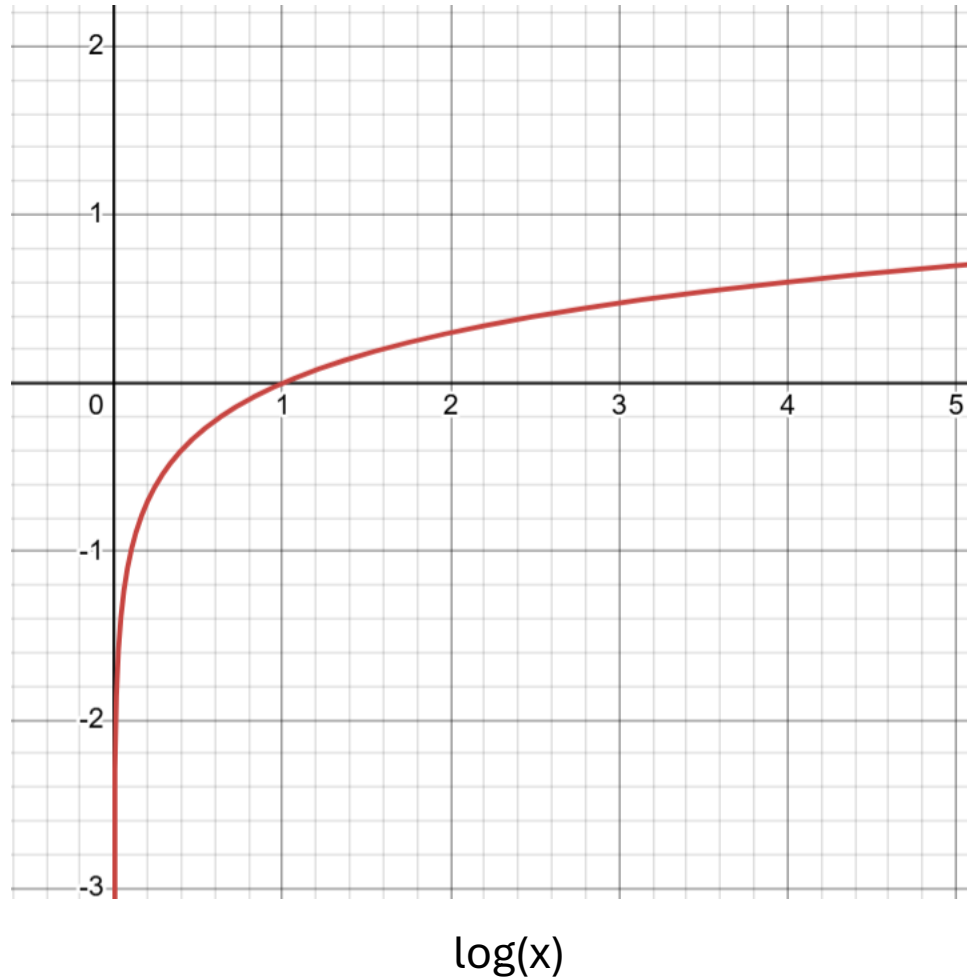
$$\frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

0.0000302941  
0.0002238446  
0.0000020359  
0.9954517644  
0.0001500475  
0.0000061163  
0.0000674207  
0.0003690573  
0.0036810450  
0.0000183743

# Negative Log Likelihood

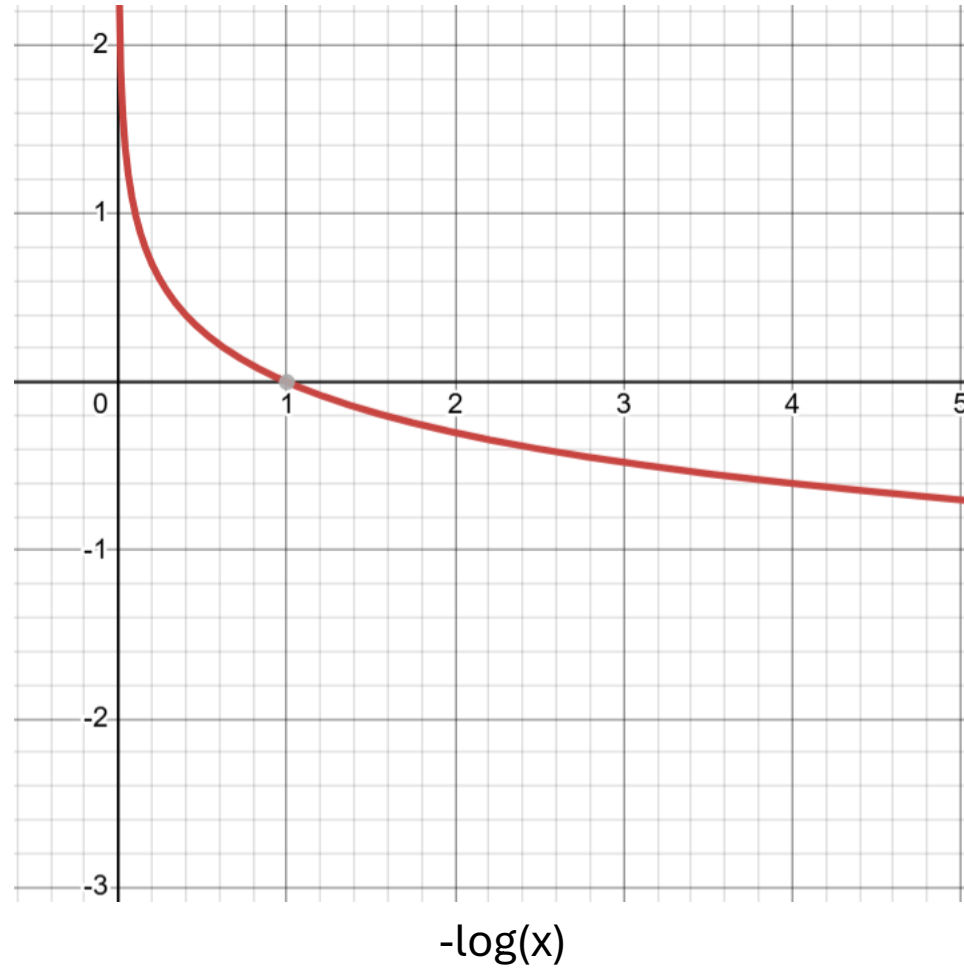


# Negative Log Likelihood





# Negative Log Likelihood



**Lesser Confidence -> More Penalty**

# Cross Entropy Loss *logsumexp*

*bof*  
 $e^{z_j} \rightarrow$

1.  $P = \text{log\_softmax}(\text{logits})$  ... Suppress Probabilities
2.  $\text{NLL}(\text{log\_P}) = -\log(P_{\text{true\_class}})$

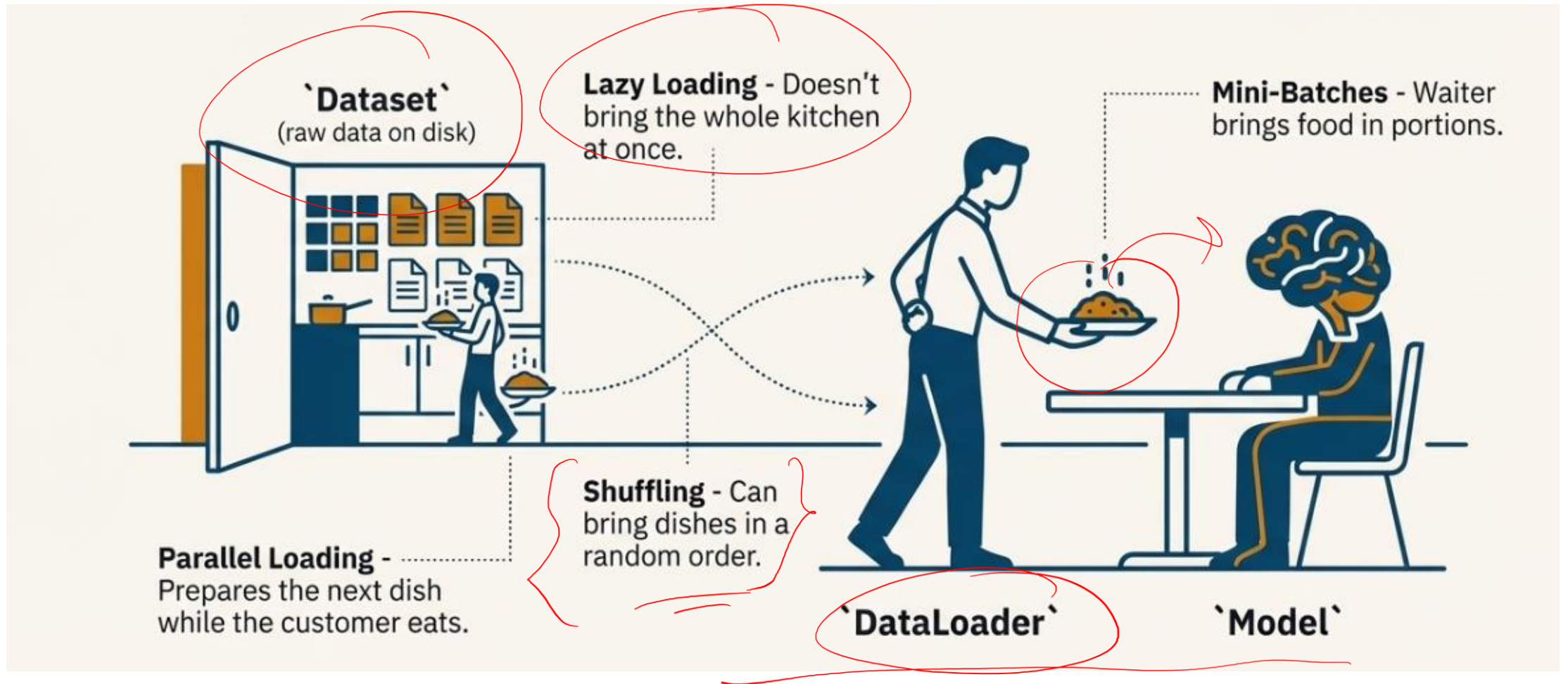
Softmax  
activation function

$$\frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

$$\text{log softmax}(z)_k = z_k - \log \sum_j e^{z_j}$$

- if logits are large (e.g., 80, 100),  $e^z$  can overflow to inf
- if logits are very negative (e.g., -80),  $e^z$  underflows to 0
- then  $\log(\text{softmax})$  becomes  $\log(0)$  or  $\log(\text{inf}) \rightarrow -\text{inf}/\text{inf}$ , NaNs, unstable gradients

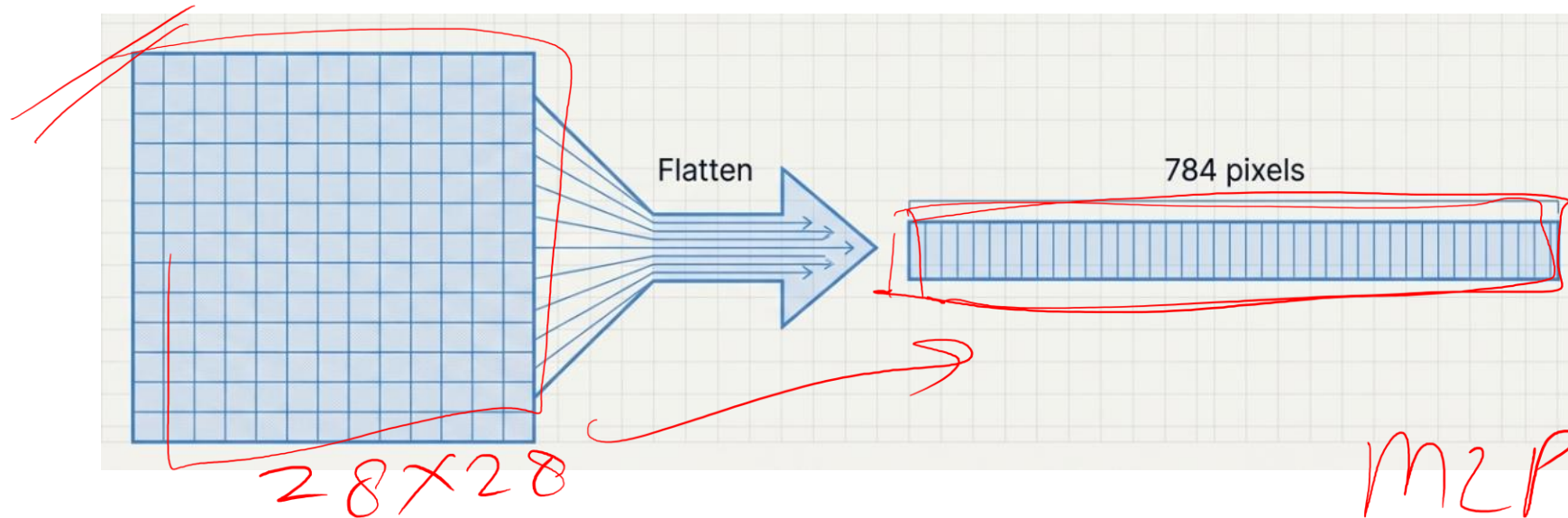
# DataLoader



<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Flatten



A 28x28 images contains 784 pixels.

MLP cannot process 2D spatial data directly. It requires a 1D vector as input.

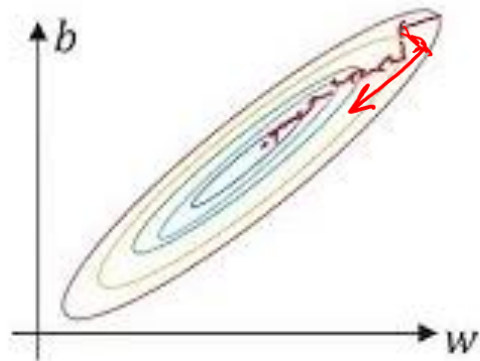
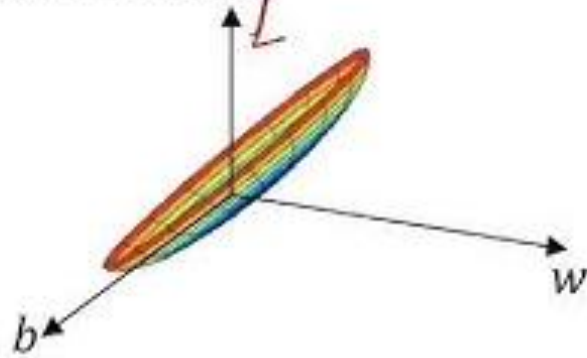
The first step in our model's logic must be to **Flatten** the  $(N, 1, 28, 28)$  image tensor into a  $(N, 784)$  vector.

<https://tinyurl.com/dlframeworks>

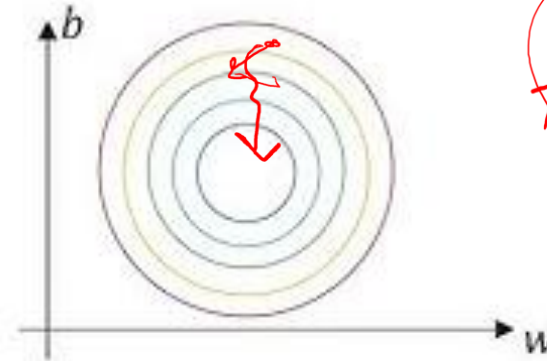
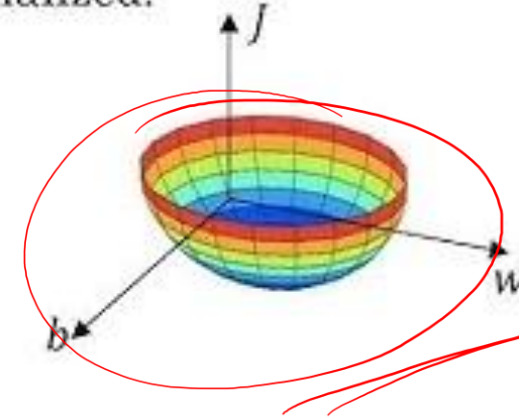
<https://github.com/sakharamg/DeepLearningFrameworks>

# Normalize()

Unnormalized:



Normalized:



Adam

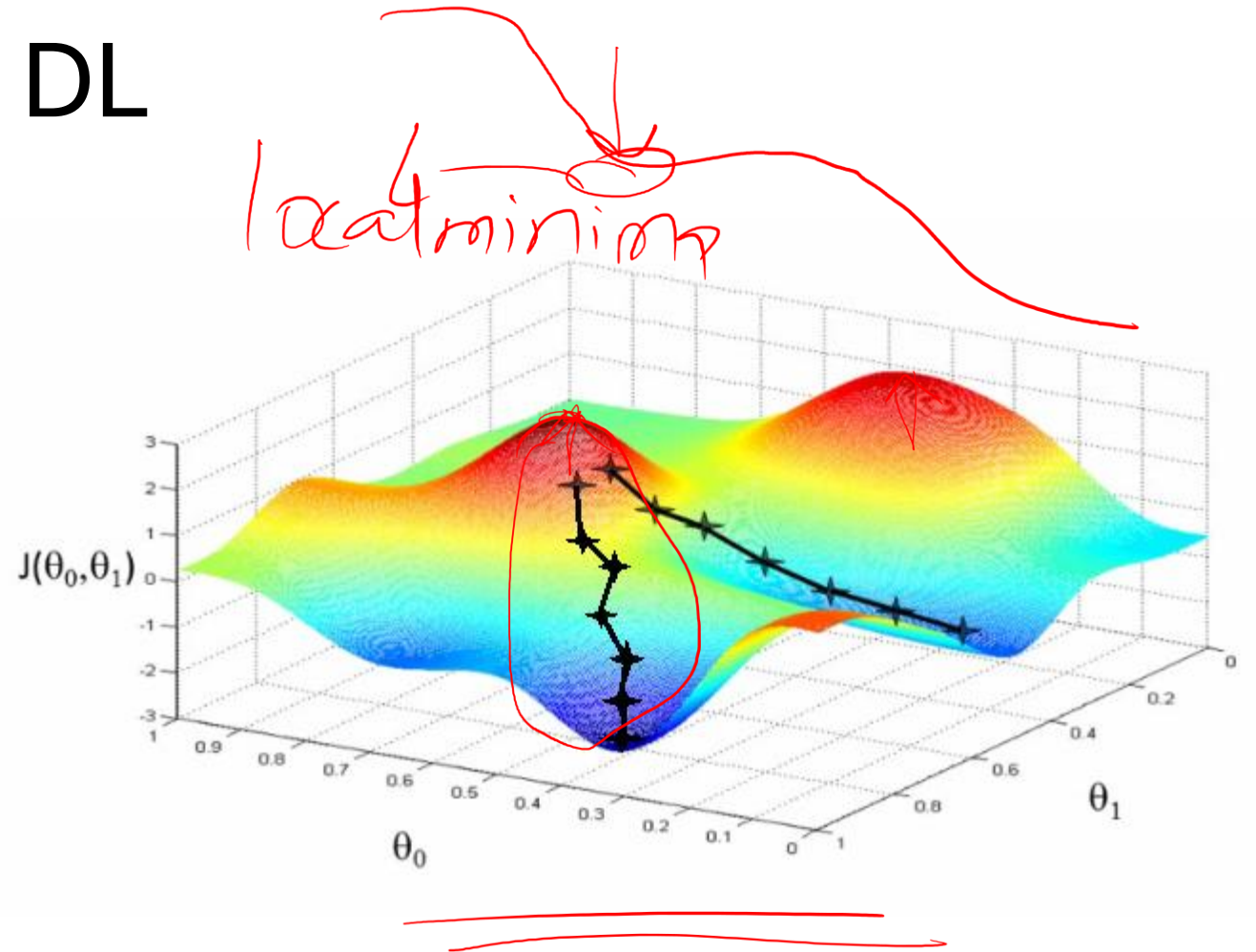
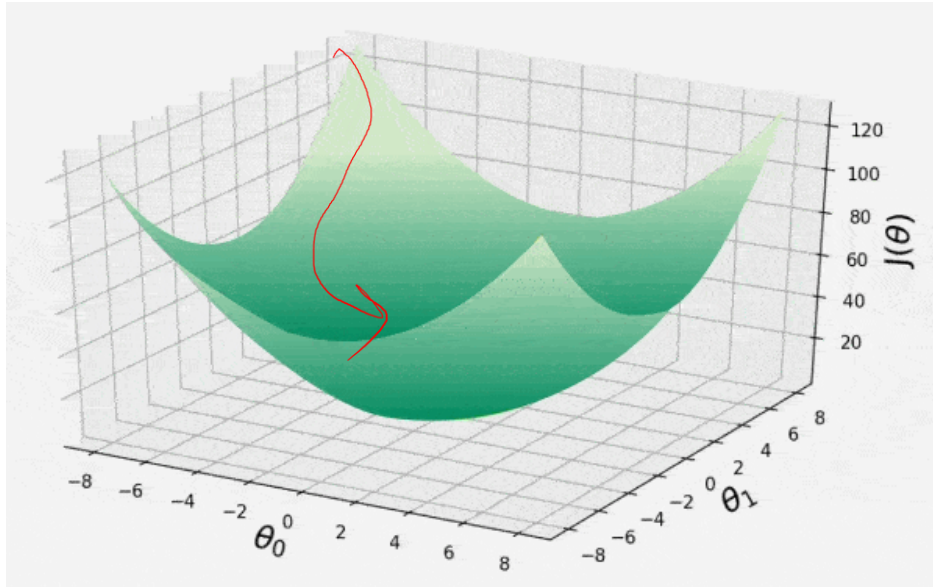
Source: DeepLearningAI (C2W1L09)

Andrew Ng

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Gradient Descend - DL



<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>



# Lab

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Regularization: Weight Decay and Dropout

Weight Decay: L2 Regularization

Dropout: Drop fraction of neurons

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>



# Weight Decay

$$L_{total} = L_{data} + \lambda \sum w^2$$

## Mechanism

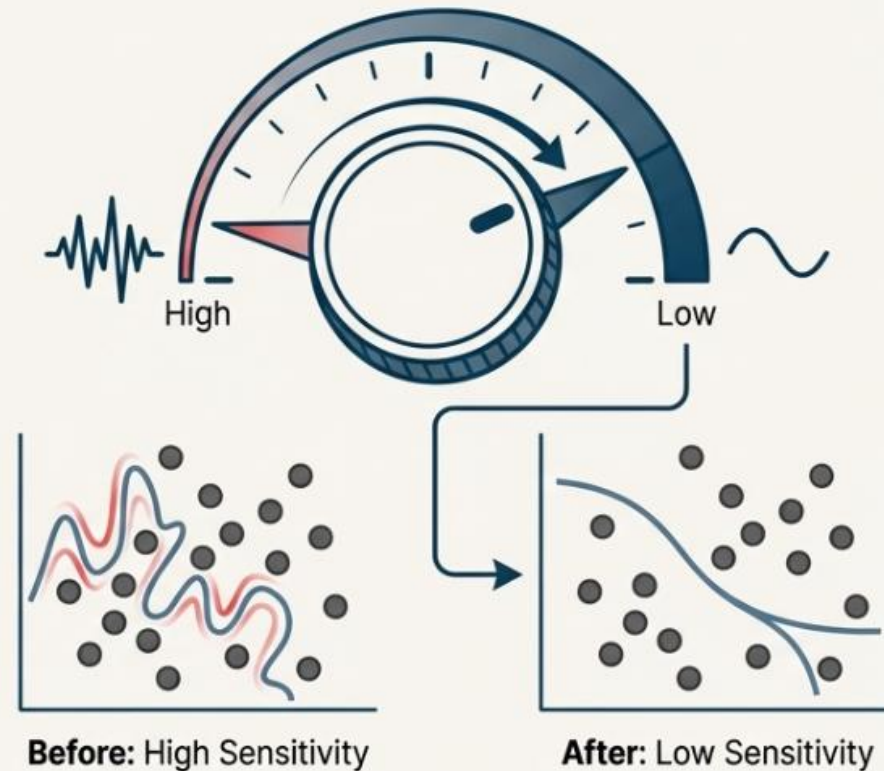
Adds a penalty term to the loss function proportional to the square of the weights ( $\lambda \sum w^2$ ). During training, this continuously pulls weights towards zero, making large weights “expensive.”

## Problem Solved

Prevents overly sharp and sensitive models. Large weights mean small input changes can cause large output changes.

## Intuition Analogy

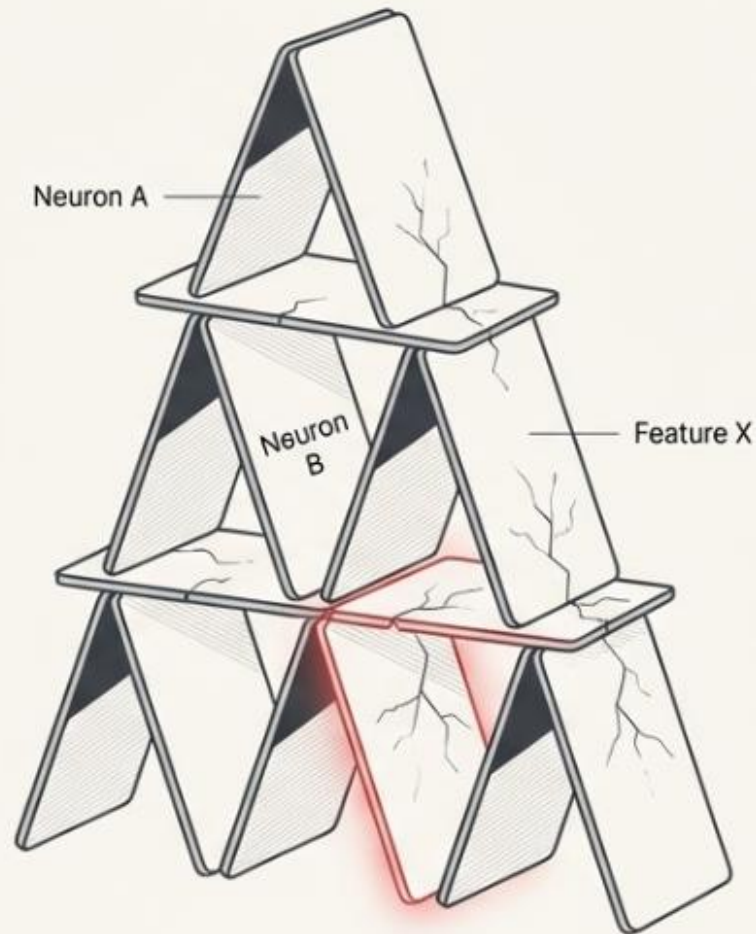
Think of a microphone's gain. High gain is sensitive and amplifies noise. Lowering the gain produces a clearer, more stable signal.



***“Use many small contributions, not a few dominant ones.”***

# Co-Adaptation

**Co-adaptation** creates entangled features. A neuron's output is only useful because another *\*specific\** neuron is present. Alone, its contribution is meaningless.

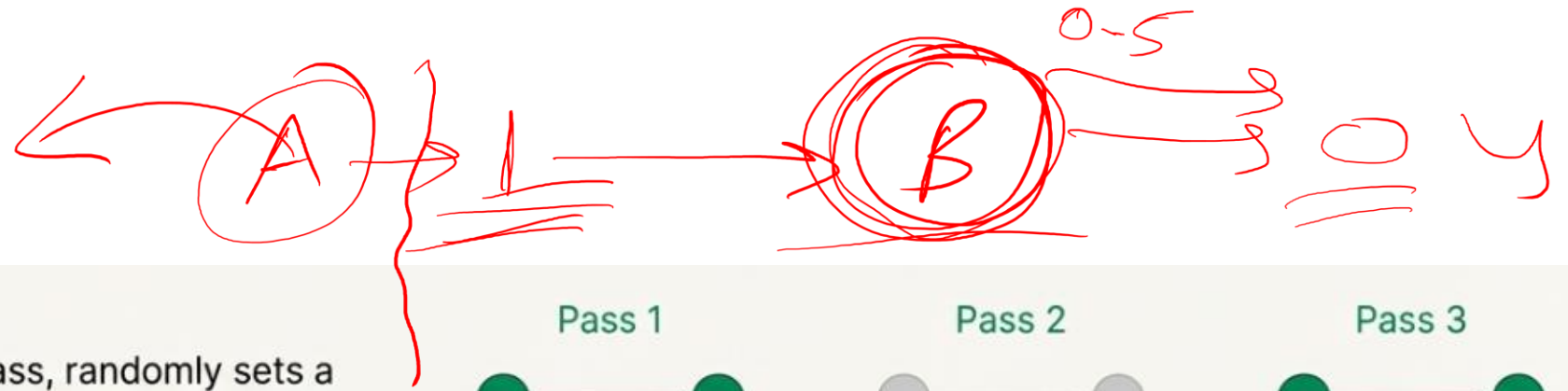


**Am I a Siberian Husky?**

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Dropout



## Mechanism

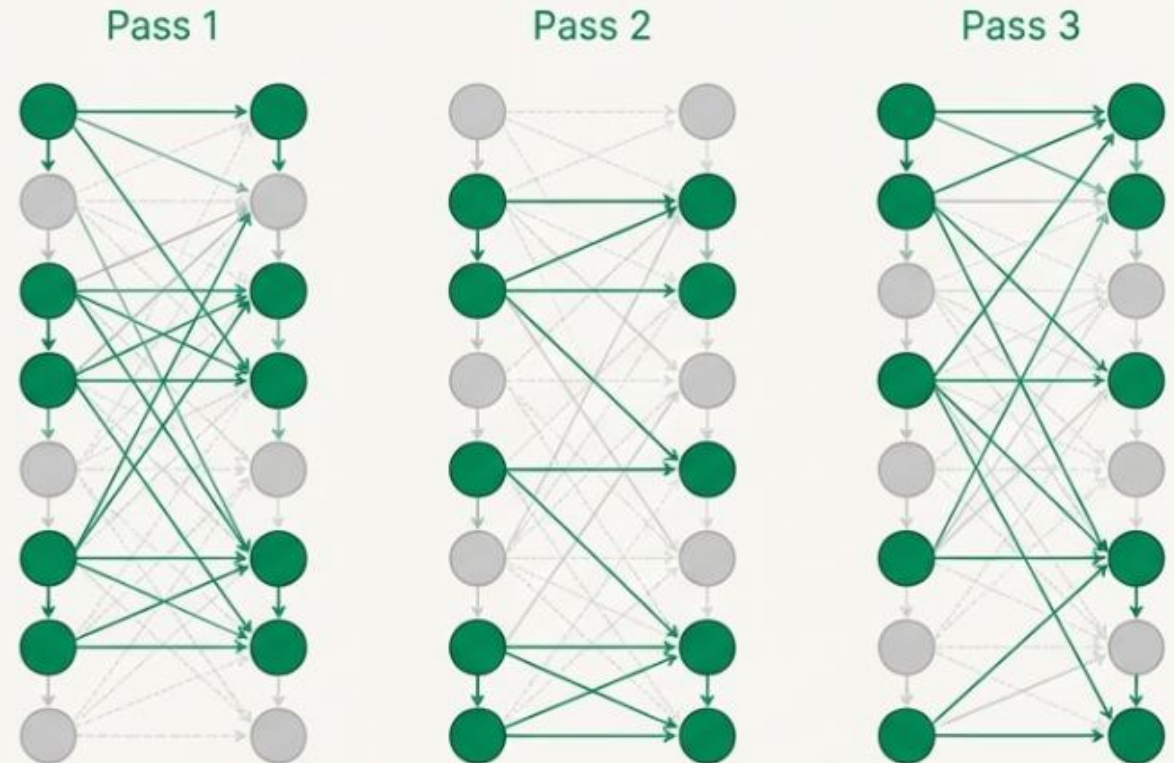
During each training pass, randomly sets a fraction of neuron activations to zero. This forces the network to function even with missing components. The network changes with every batch.

## Problem Solved

Directly targets fragile feature dependencies (co-adaptation).

## Intuition Analogy

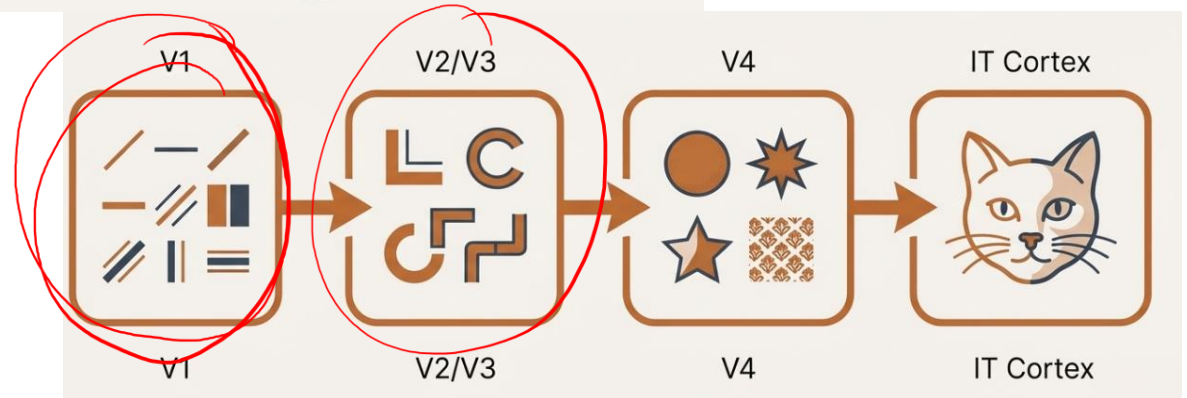
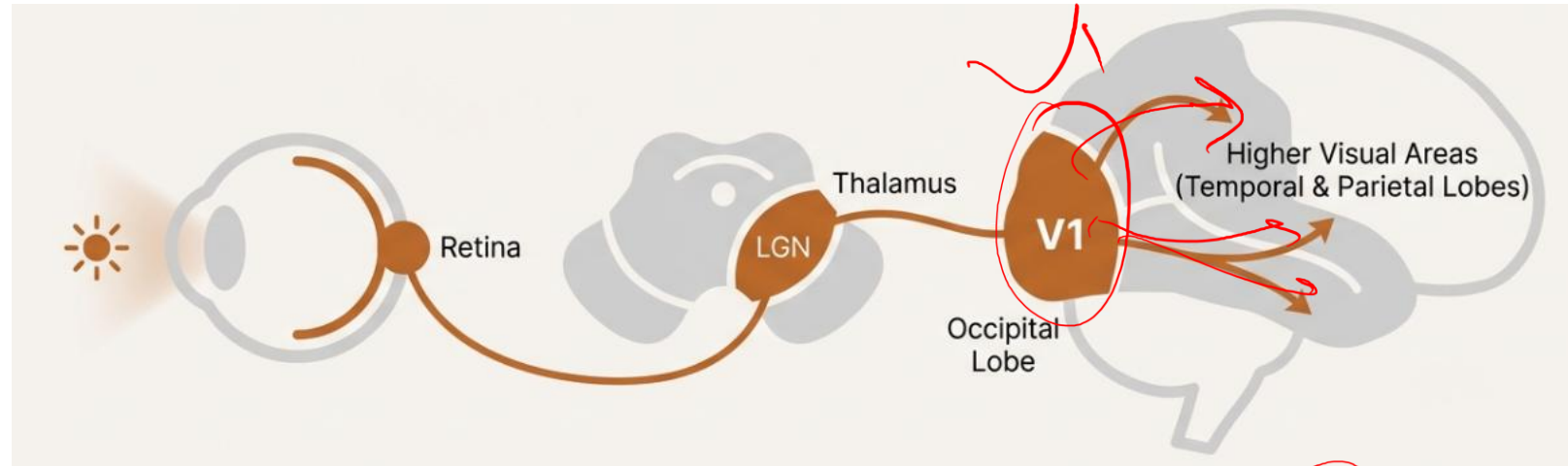
A team project where any member might be absent on any given day. To succeed, everyone must learn the full context instead of relying on one person.



> *“No neuron is guaranteed to exist — learn features that stand alone.”*



# How Brain Processes Images -> CNN



# Thank You

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

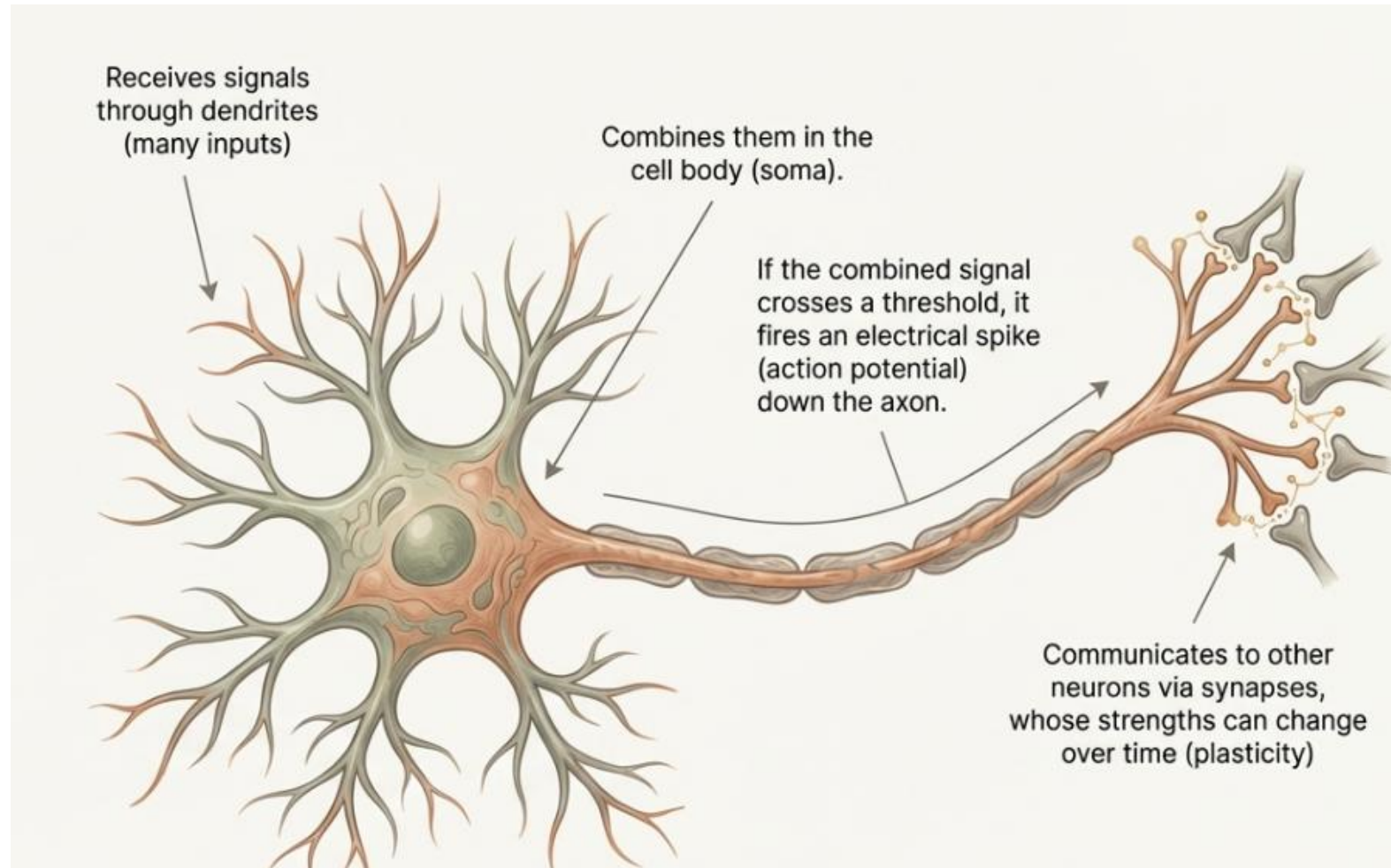
# Appendix







# Neuron in Brain



# Log Softmax

0.0000302941

0.0002238446

0.0000020359

0.9954517644

0.0001500475

0.0000061163

0.0000674207

0.0003690573

0.0036810450

0.0000183743

-10.4045575839

-8.4045584969

-13.1045725764

-0.0045586103

-8.8045586473

-12.0045532194

-9.6045584655

-7.9045586414

-5.6045585997

-10.9045576088