

# Deep Learning Frameworks

Tokenization, RNN, GRU, Attention

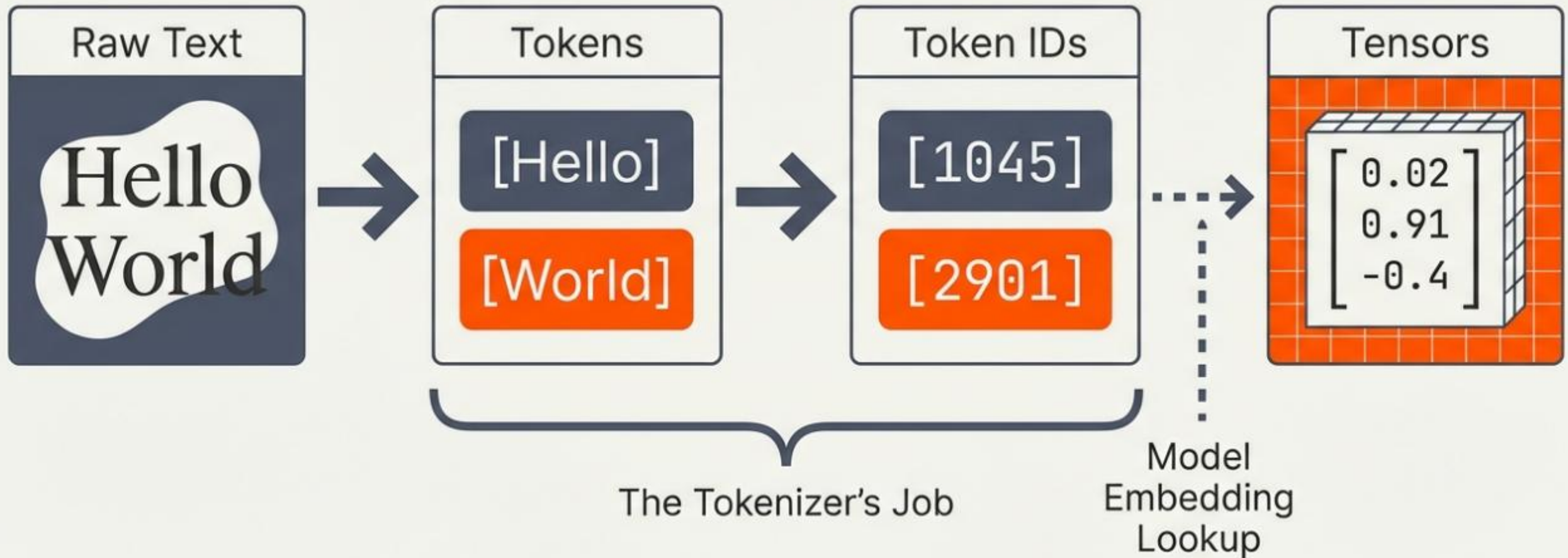
<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

# Challenges with Text Data

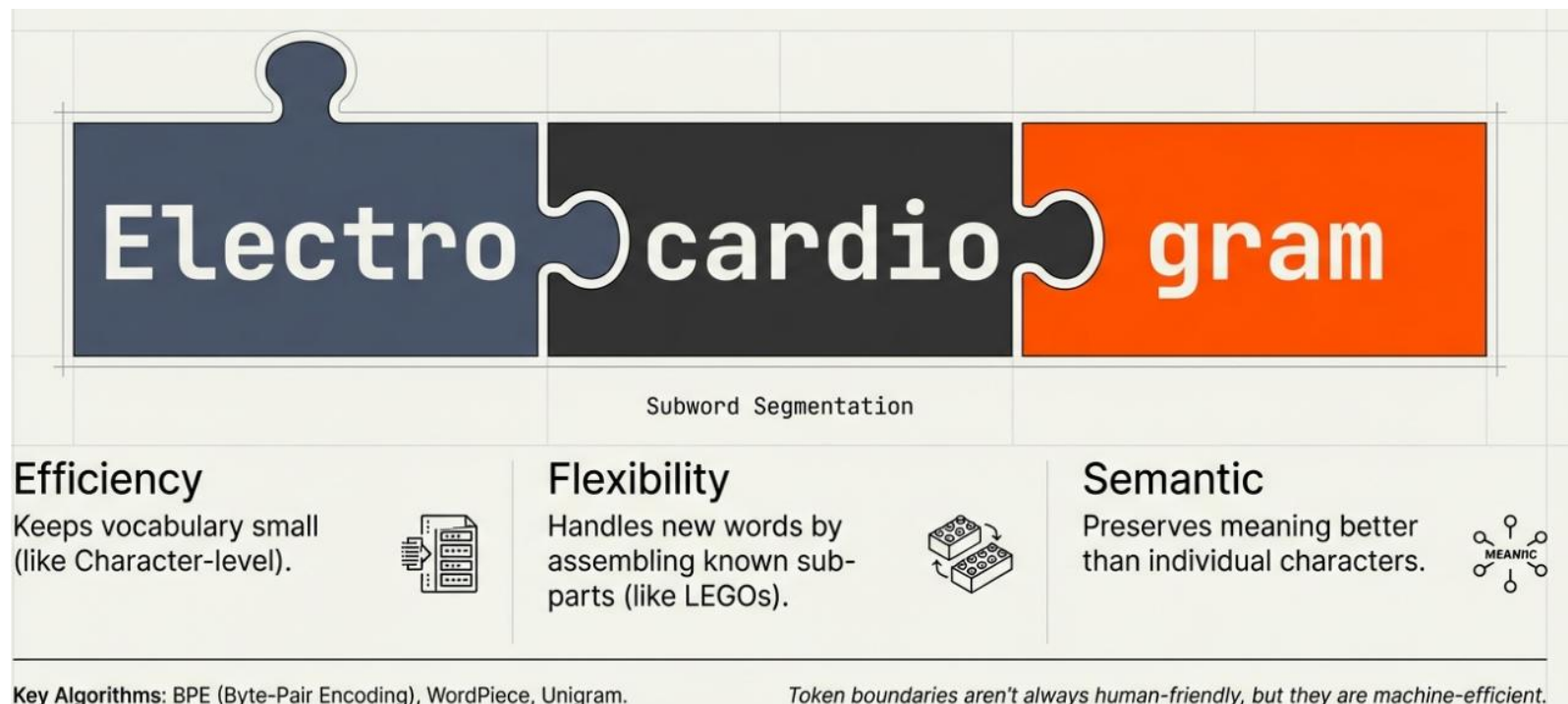
- Representing Text
- Varying Length

# Representing Text



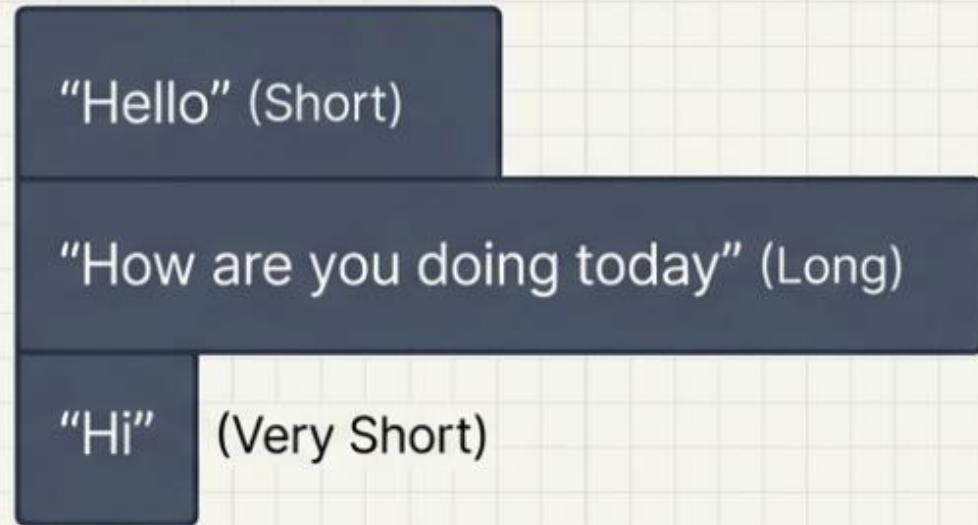
# Tokenization: Splitting the text input

- Word level: linguistic boundaries, vocab explosion, missing words
- Character Level: Limited Vocab, No unknowns, Sequence length
- Subword Level



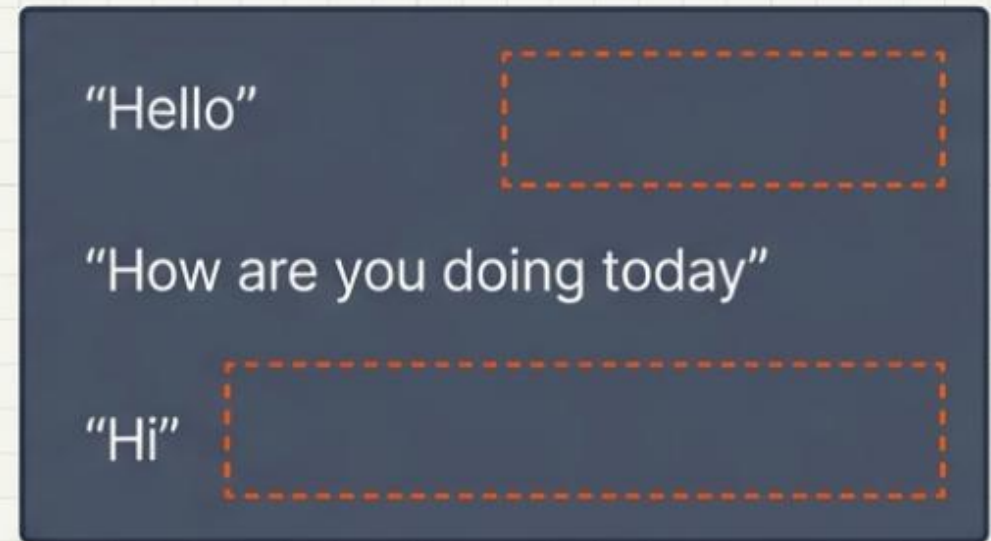
# Handling varying lengths

## Reality (Jagged Inputs)



Standardization  
Required

## Requirement (Tensor Shape)



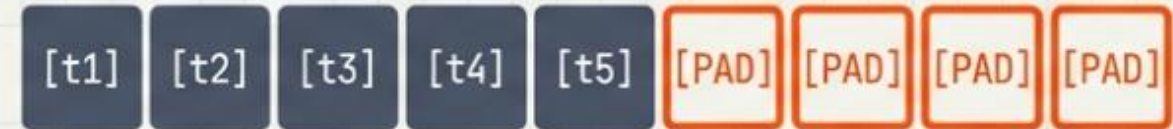
# Padding and Truncation

## Technique 1: Padding

Input



Output (Target Length 9)



The **[PAD]** tokens are filler for uniform length.

## Technique 2: Truncation

Input



Output (Max Length 10)



Exceeding tokens are cut to fit the limit.



# The Special Tokens Glossary

## <PAD>

### Padding

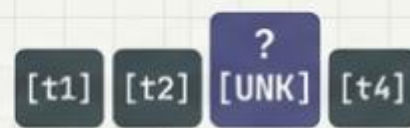
Fills empty space to maintain batch shape (rectangular constraint).



## <UNK>

### Unknown

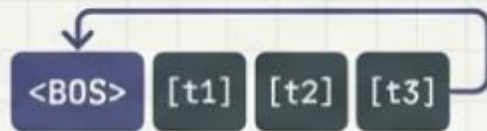
Represents out-of-vocabulary terms. Rare in modern subword models.



## <BOS> / <CLS>

### Begin-of-Sequence

Marks the start of input. Often holds sentence-level context.



## <EOS> / <SEP>

### End-of-Sequence

Marks the conclusion of a segment or sentence.



# Ways to Represent

- Integers [512>8]
- One hot [1 0 0] -> orange [0 1 0]-> car

An embedding maps each discrete token ID to a dense vector of fixed dimension  $d$ . These values are learnable parameters.

Old: One-Hot  
(Sparse)



New:  
Embedding  
(Dense)



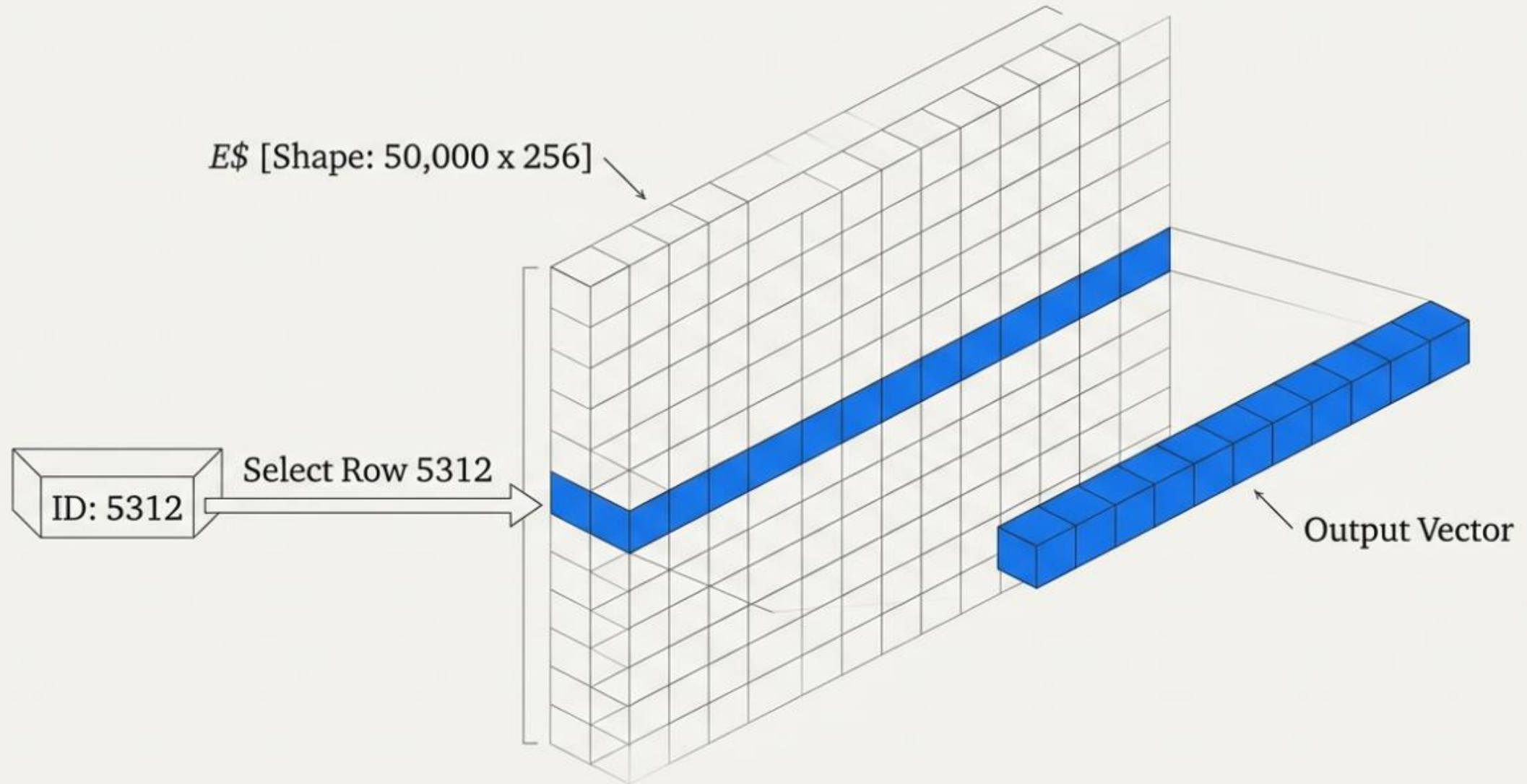
"cat" → [0.12, -0.33, 0.05, 0.91, -0.44 ...]

**Benefits:**

1. Compact ( $d \ll V$ )
2. Trainable Weights
3. Encodes Semantic Similarity



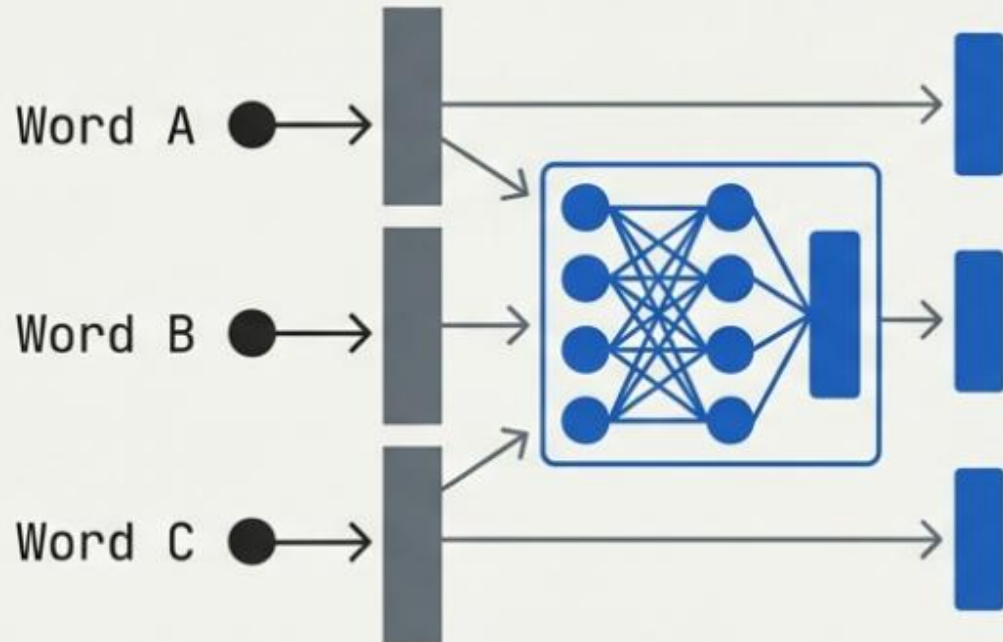
# nn.Embedding



# Sequence Matters

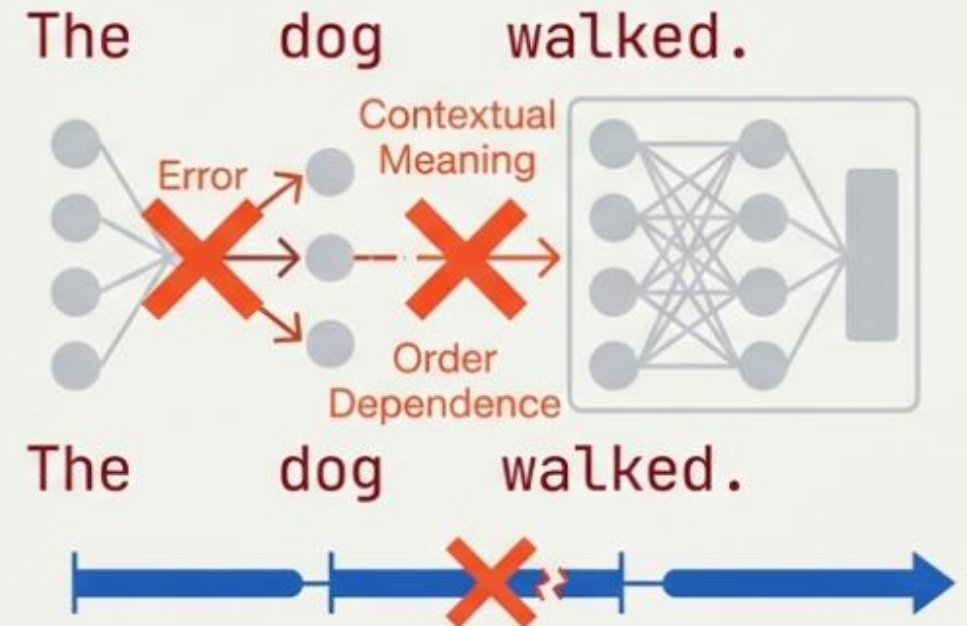
## The Gap

Standard feedforward networks treat inputs as independent events. They have no concept of “before” or “after.” A normal feedforward network cannot naturally “remember” what occurred in the previous step.

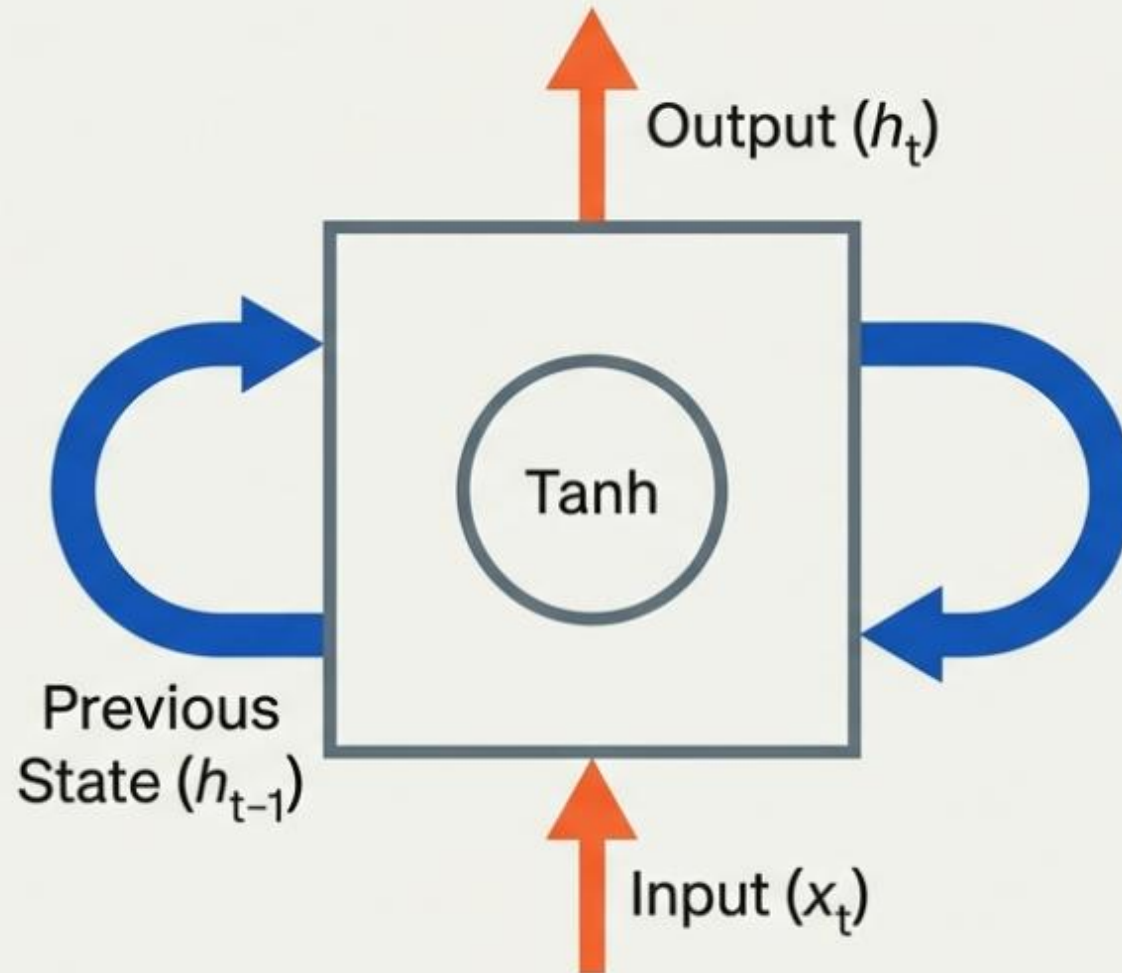


## The Reality

Real-world data, such as text and time-series, is defined by continuity. Its key attributes are: Variable length, Order dependence, and Contextual meaning.



# Recurrent Neural Network



**Concept:** The RNN processes tokens one step at a time while maintaining a 'hidden state' ( $h$ ) that acts as memory.

**Mechanism:** At time step  $t$ , the RNN combines two signals:

1. The Current Input ( $x_t$ );
2. The Previous Hidden State ( $h_{t-1}$ );

**Result:** A merger producing a new hidden state ( $h_t$ ) that carries the past into the present.

# State Update

**Sensory Weights:** The matrix processing the new input signal.

**Memory Weights:** The matrix processing the historical context ( $h_{t-1}$ ).

$$h_t = \tanh(W_{xh}x_t + W_{hh}h_{t-1} + b_h)$$

**Activation:** The non-linear function squashing values between -1 and 1.

**Bias:** The learnable offset.

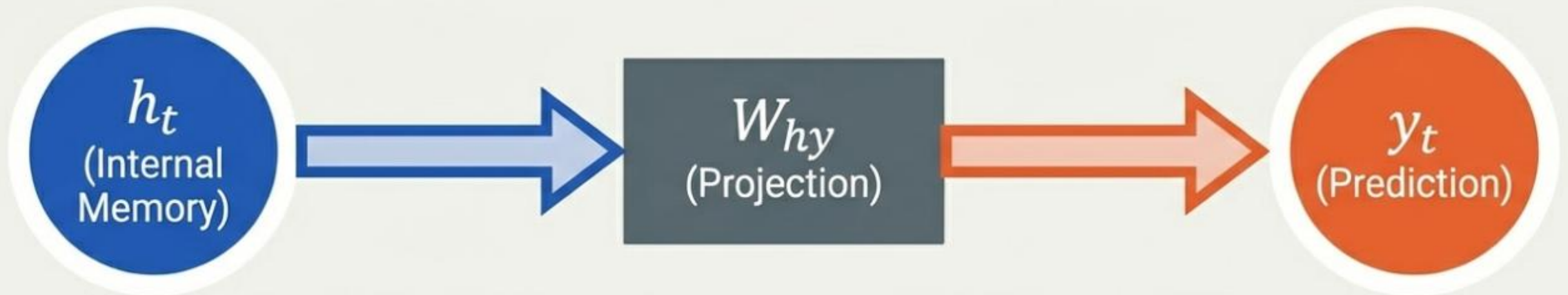
The new state is a weighted sum of immediate sensory data and historical context, fused mathematically by the tanh activation.



# Output

$$y_t = W_{hy}h_t + b_y$$

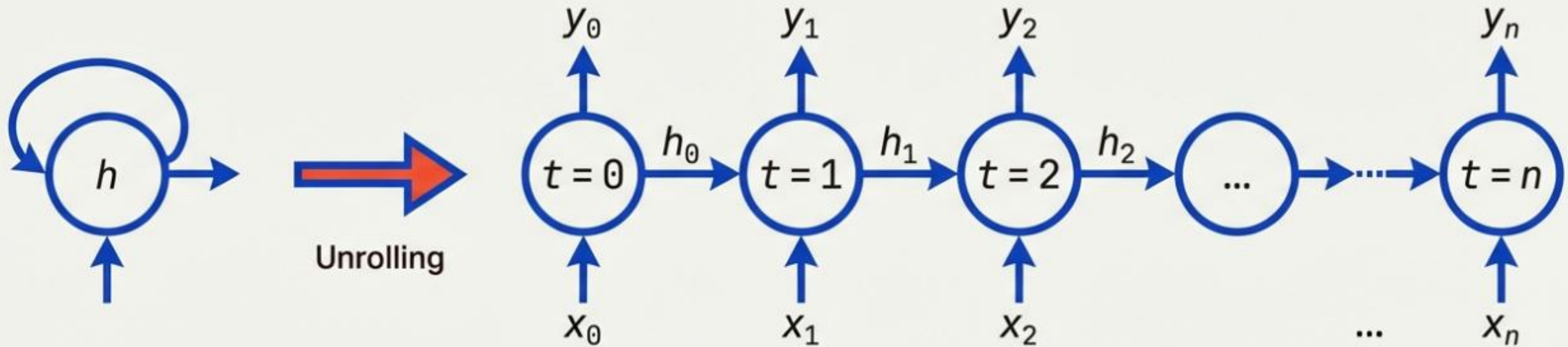
The hidden state  $h_t$  is internal memory. To get a prediction (like the next word), we project  $h_t$  through an output weight matrix ( $W_{hy}$ ).



Note: This output step is optional at intermediate steps, depending on the task topology.



# Unroll



The Abstraction

To train an RNN, we must visualize it not as a loop, but as a deep neural network where each layer corresponds to a time step. A sequence of 100 words is effectively a 100-layer deep network sharing the same weights.

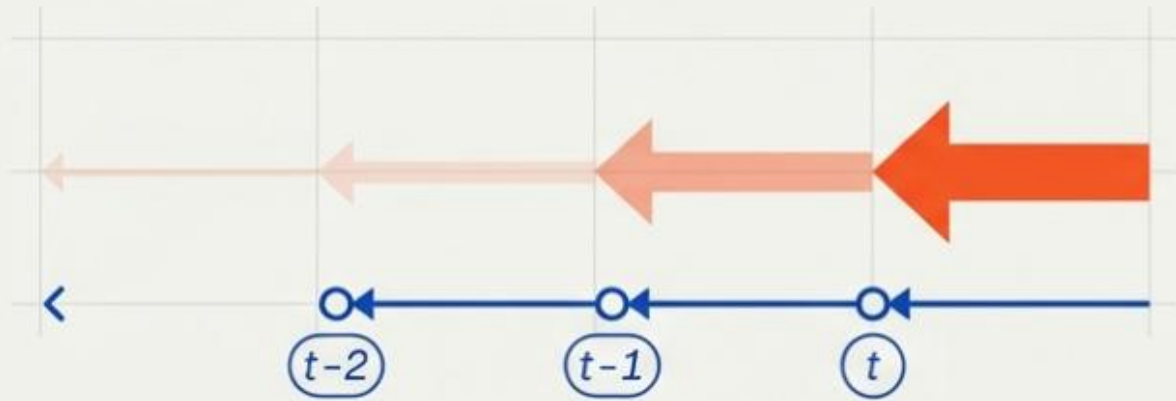
# Encoder

# Encoder - Decoder

# Instability in Long Term Dependencies

## The Vanishing and Exploding Gradient Problem

### Vanishing Gradients



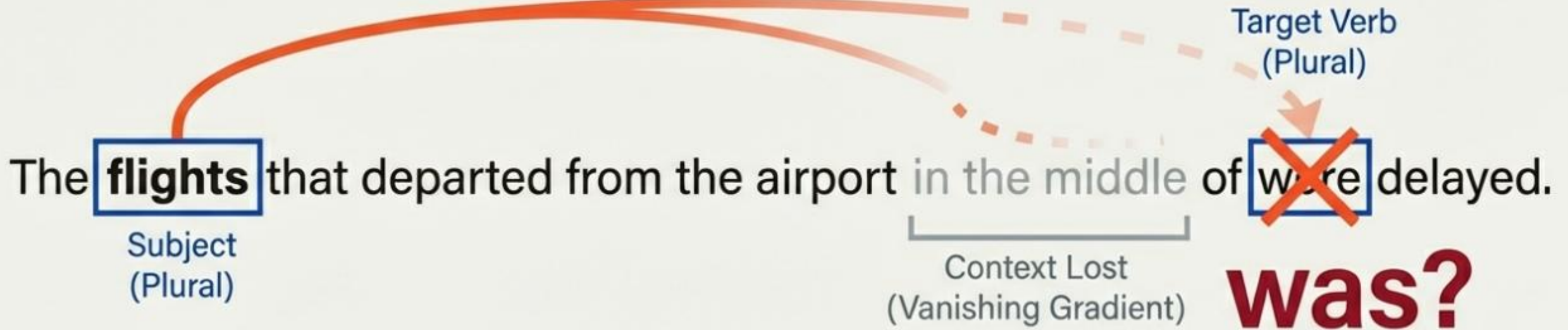
Cause: Gradients  $< 1$  multiplied many times.  
Effect: Signal shrinks to 0. The model “forgets” the beginning of the sequence.

### Exploding Gradients



Cause: Gradients  $> 1$  multiplied many times.  
Effect: Signal blows up. Training becomes unstable (NaN values).

# Synptoms of Memory Loss

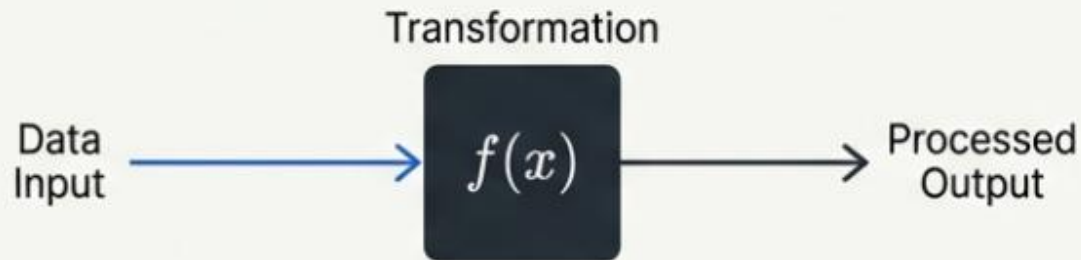


The Symptom: The model learns short-term dependencies well but fails at long contexts. Here, the RNN forgets the plural subject "flights" by the time it reaches the verb, potentially predicting the singular "was".



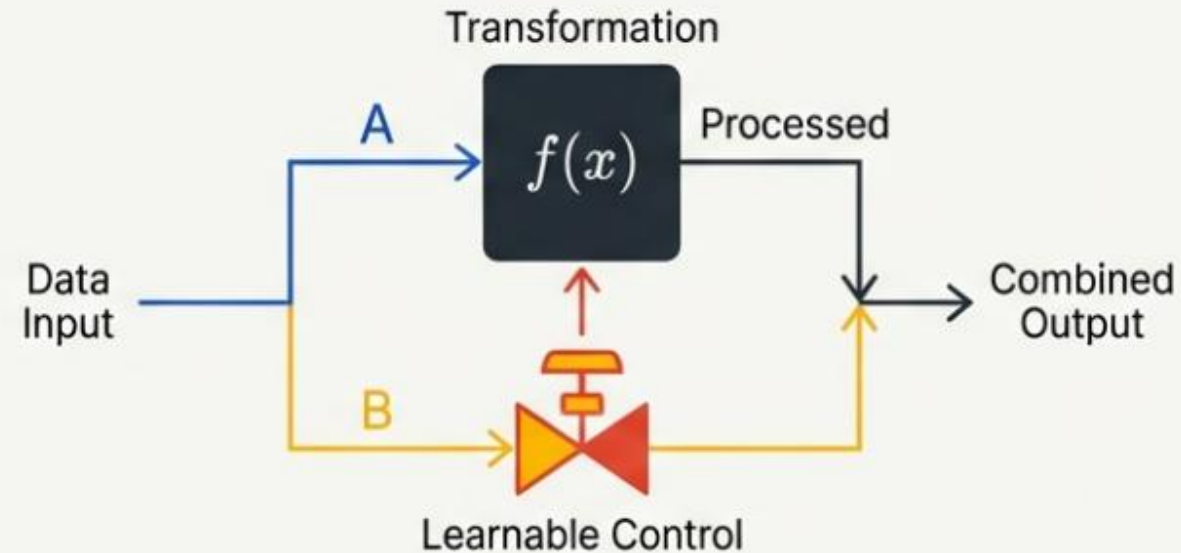
# Handling Long Term Dependencies

## Vanilla RNN Processing



Forced transformation at every step.

## Gated Recurrent Unit (GRU)

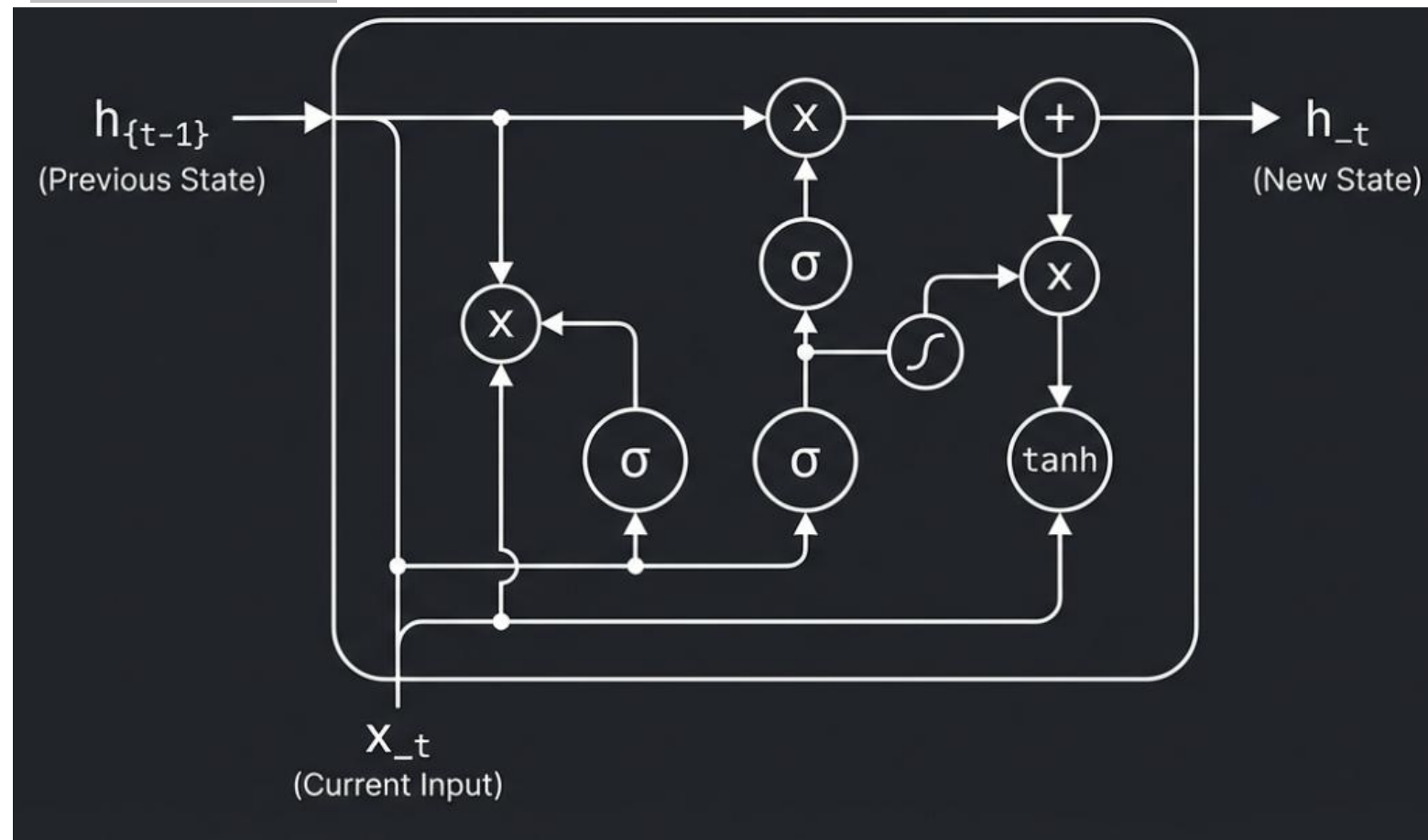


Data can bypass processing via the Highway.

**Core Concept:** Instead of forcing the model to rewrite its entire memory at every step, we add learnable **Gates** ( $z_t, r_t$ ). These differentiable knobs learn when to **Keep** existing memory, **Update** with new input, or **Ignore** irrelevant history. The GRU is a streamlined evolution of the LSTM, using only 2 gates instead of 3.

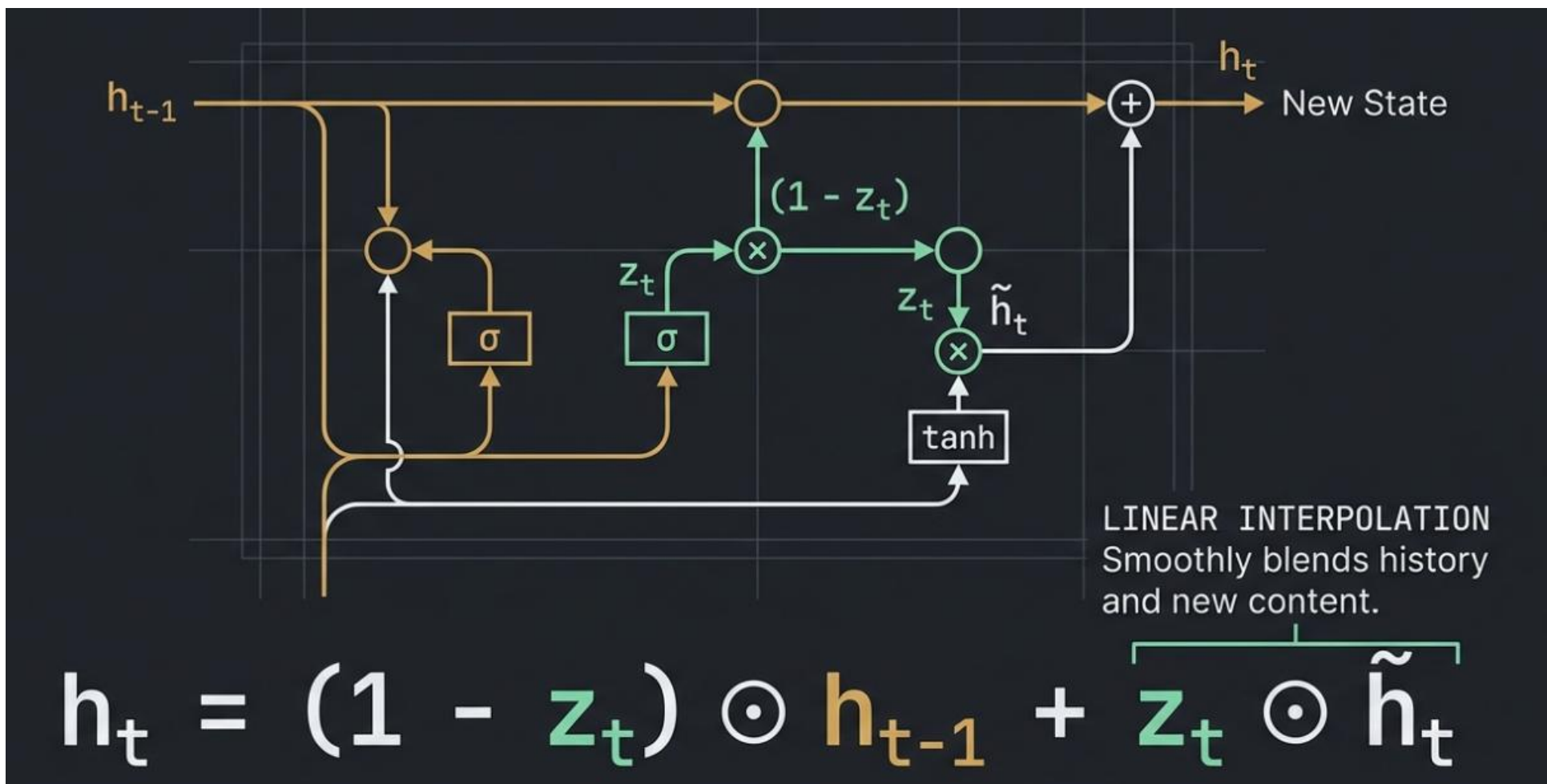
# GRU

The delivery was two days late and the box was torn. Customer support was slow to respond. Anyway, the Bluetooth earbuds paired instantly with my phone. The sound is clear, bass is decent, and the battery easily lasts 6–7 hours. I used them during a workout and the fit stayed secure.



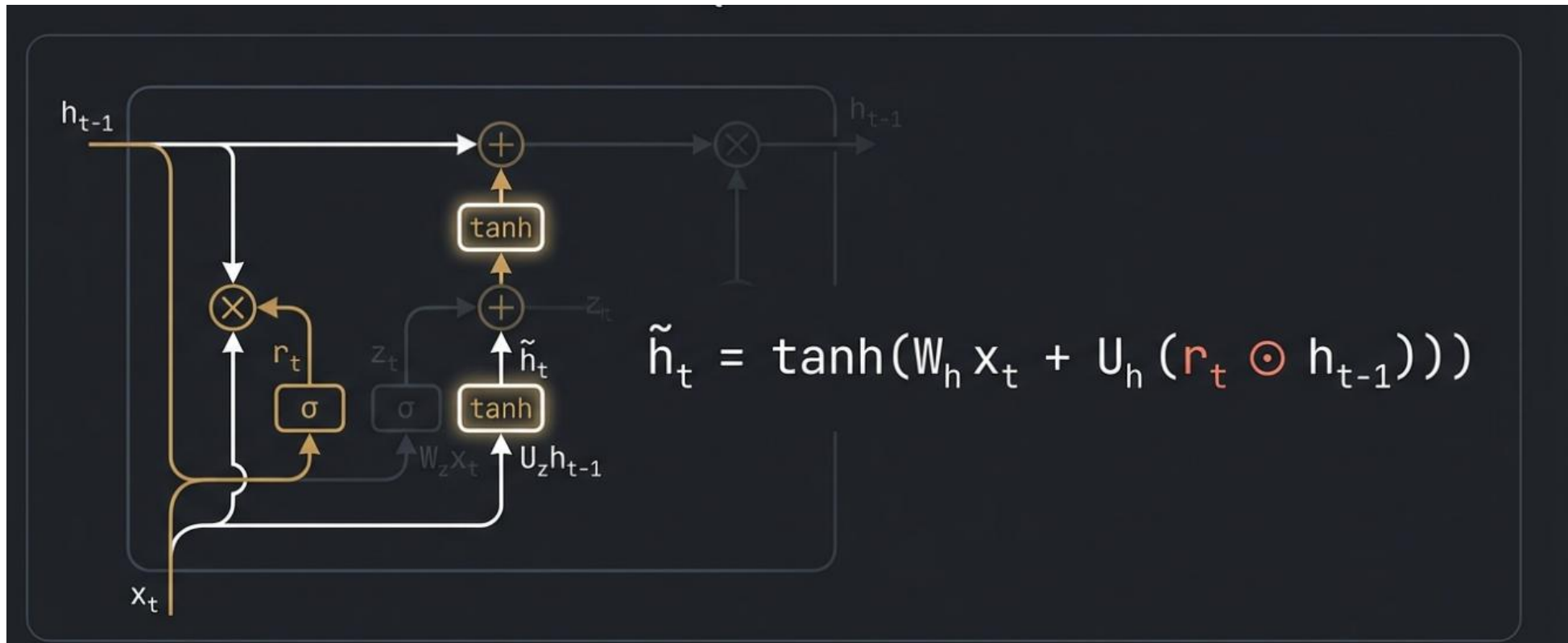
# Final State: How much should I keep vs replace?

The delivery was two days late and the box was torn. Customer support was slow to respond. Anyway, the Bluetooth earbuds paired instantly with my phone. The sound is clear, bass is decent, and the battery easily lasts 6–7 hours. I used them during a workout and the fit stayed secure.



# Candidate State

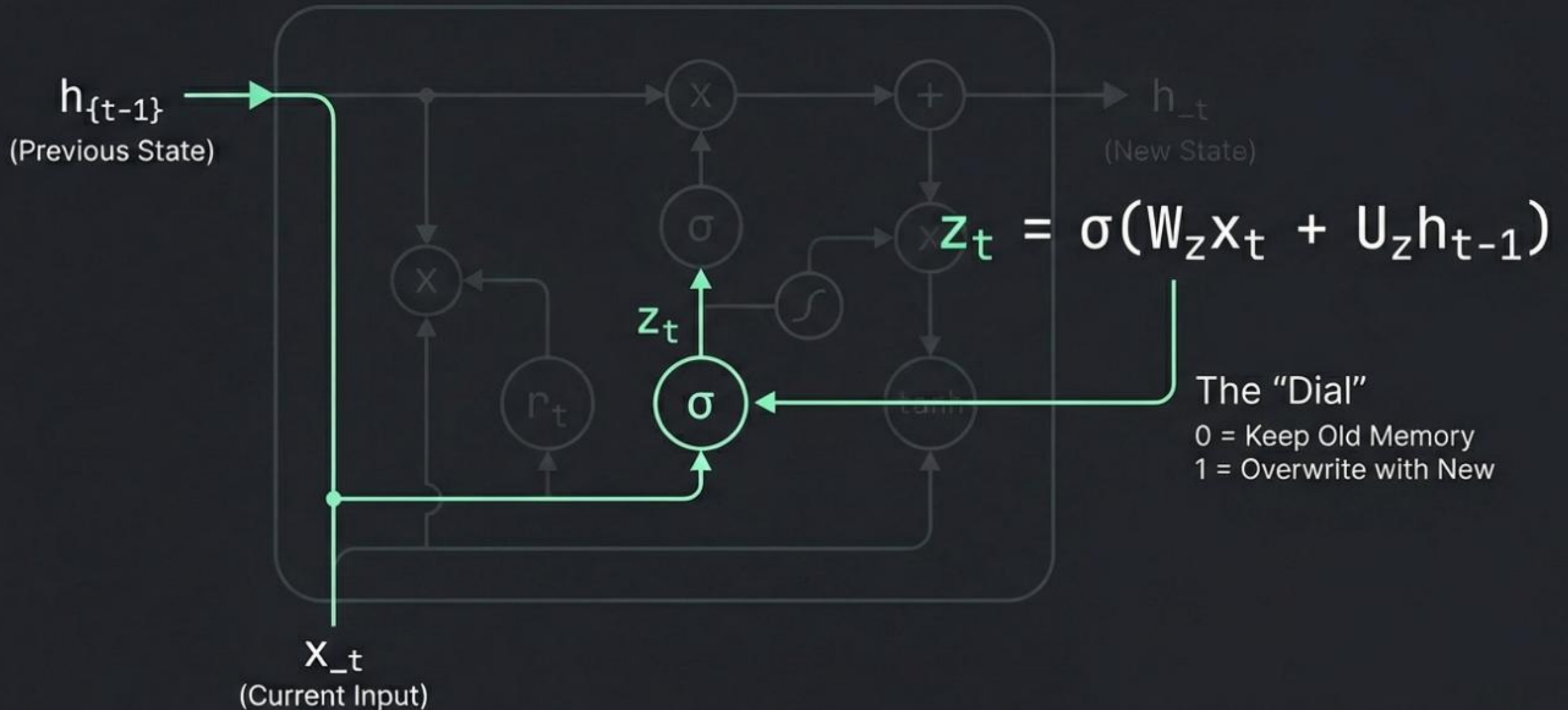
The delivery was two days late and the box was torn. Customer support was slow to respond. Anyway, the Bluetooth earbuds paired instantly with my phone. The sound is clear, bass is decent, and the battery easily lasts 6–7 hours. I used them during a workout and the fit stayed secure.



THE DRAFT

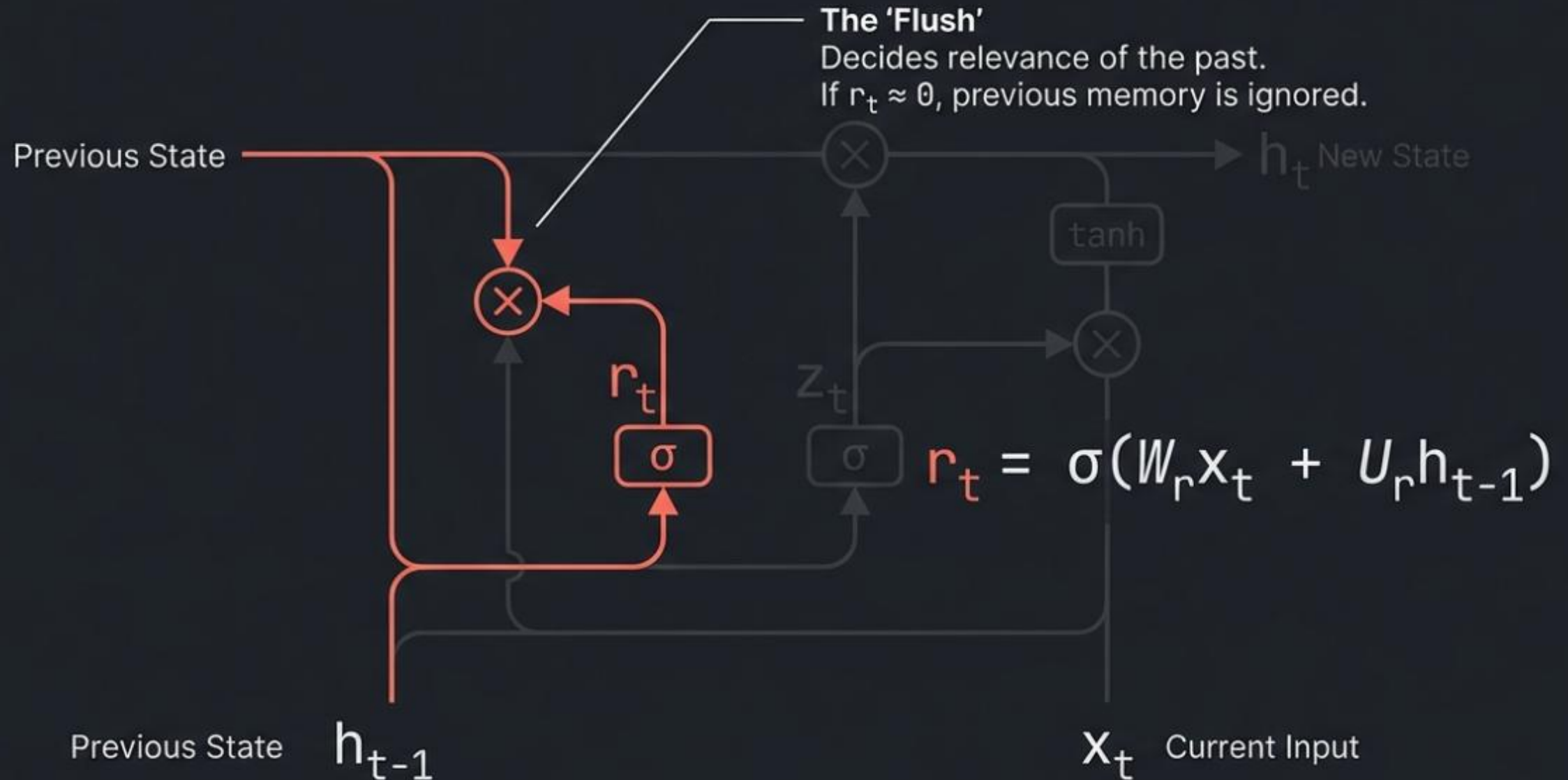
A proposal for the new state. It mixes current input with a selectively filtered history.

# Update Gate



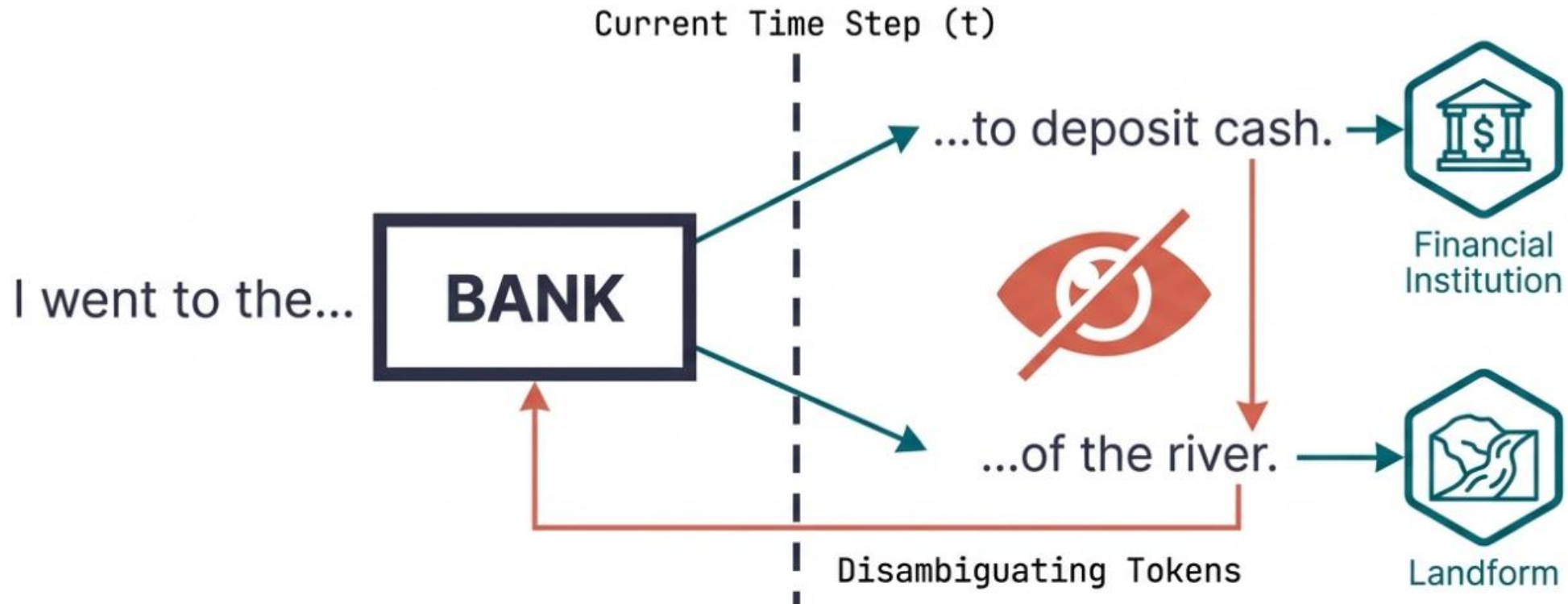


# Reset Gate

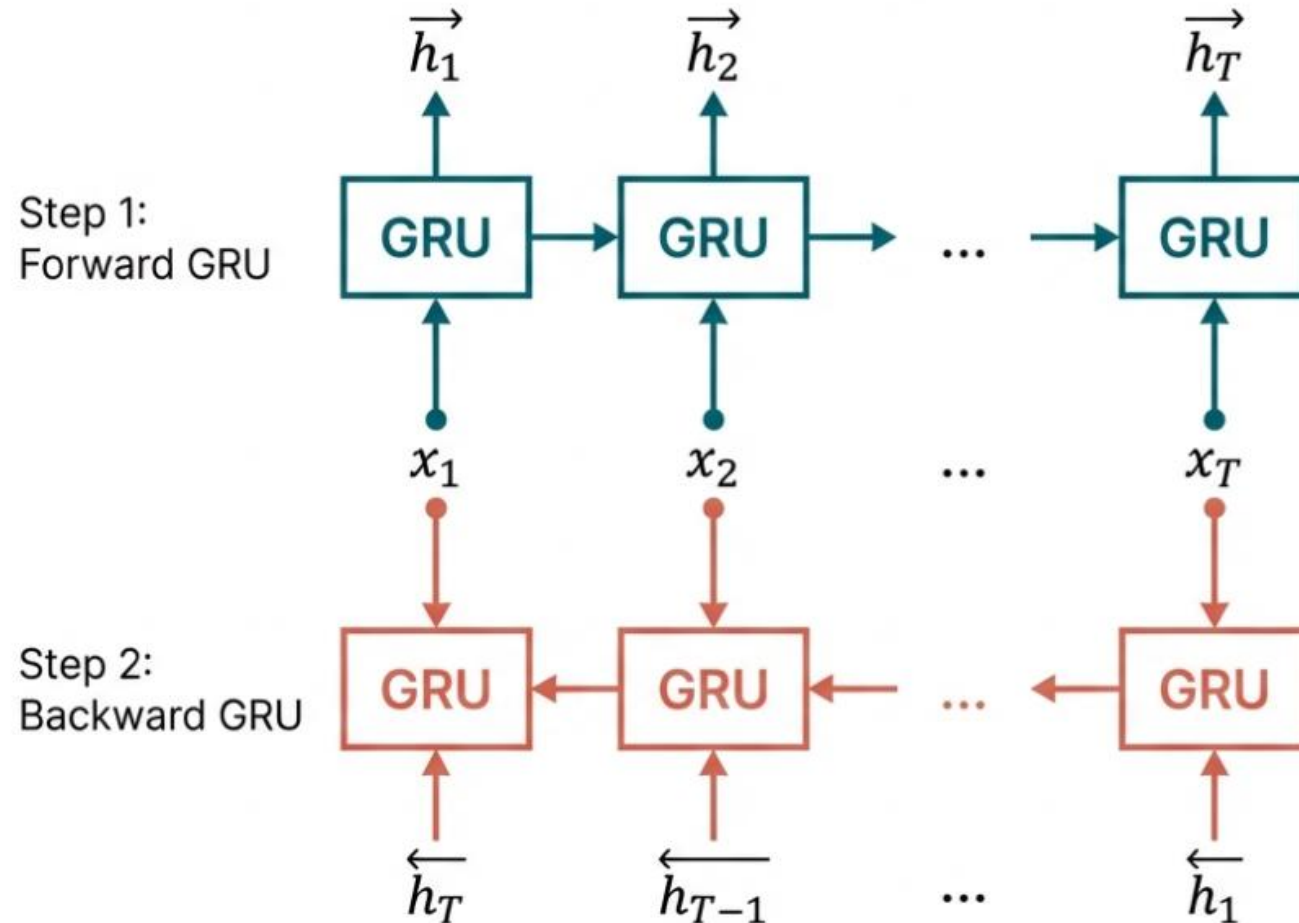


# Future gives the full picture

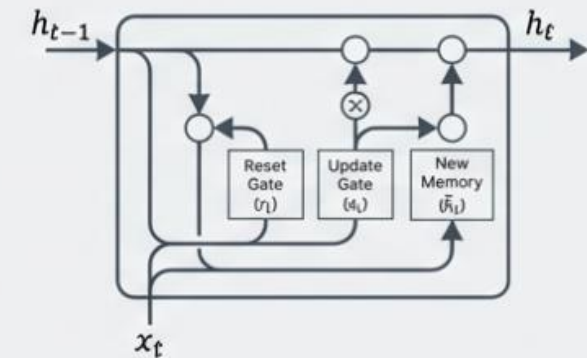
In sequence processing, the meaning of a specific token frequently depends on both its left (past) and right (future) context. Without the full picture, interpretation fails.



# Bi Directional GRU

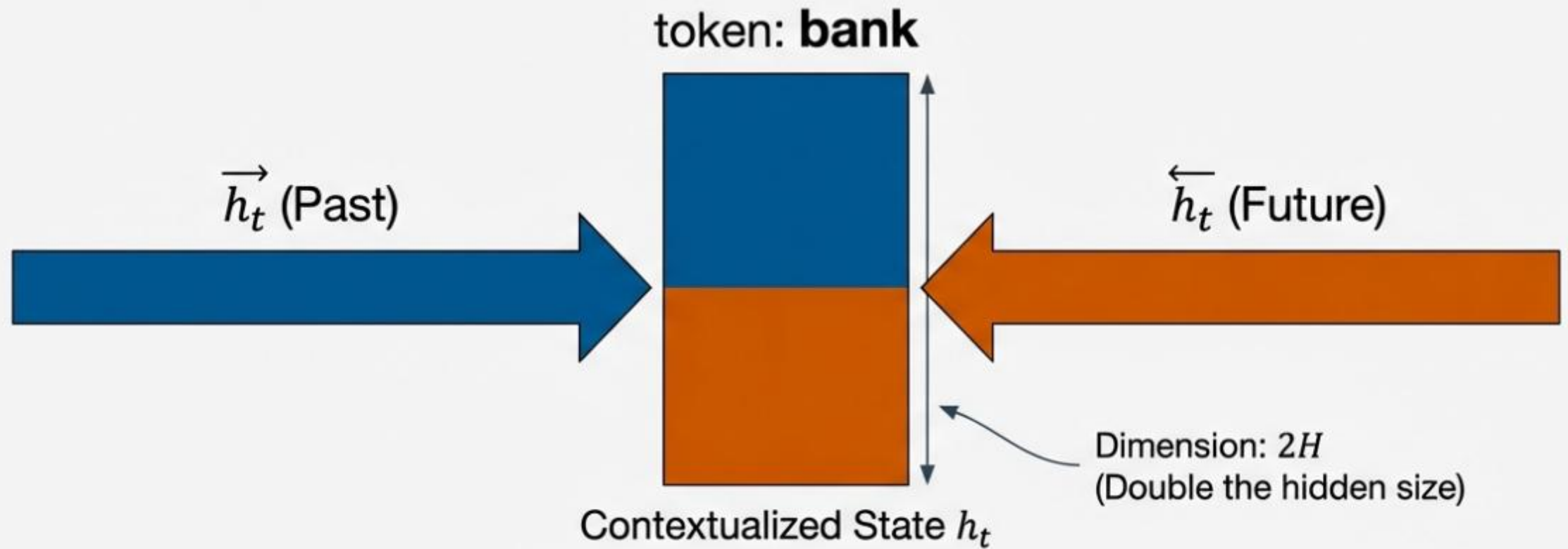


## Inside the GRU



Gates control information flow, deciding what to keep from the past and what to overwrite.

# Merging States from Both Direction



$$h_t = [\vec{h}_t ; \overleftarrow{h}_t] \text{ (Concatenation)}$$

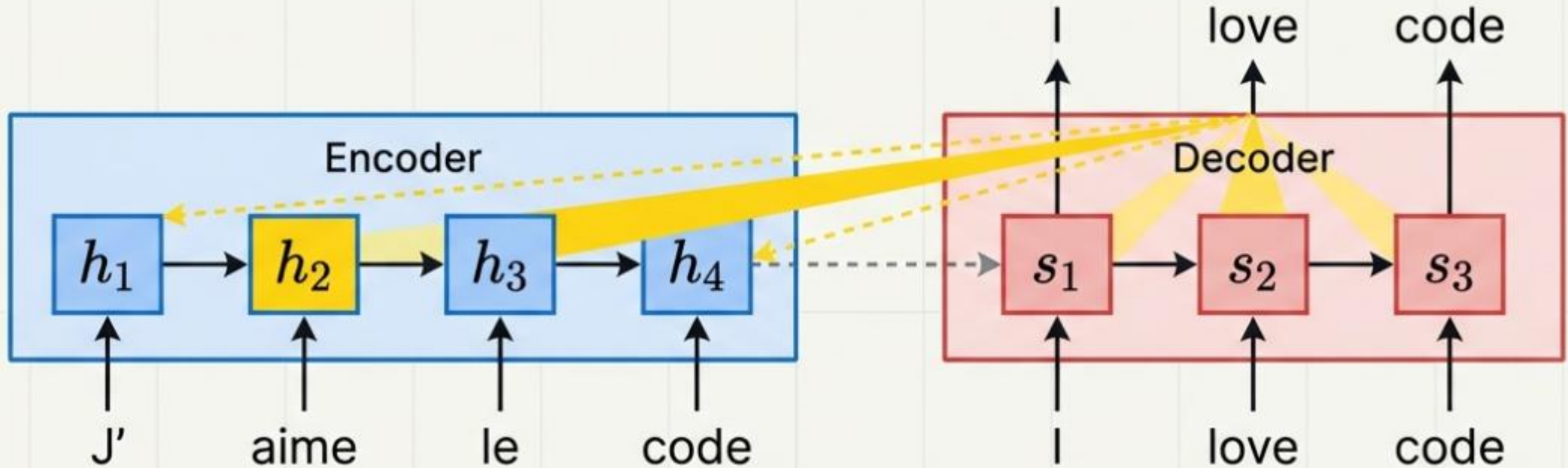
# Lab

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# Attention



**The Solution::** Instead of relying on a static summary, we allow the decoder to '**look back**' at the entire history of encoder states.

**Dynamic Context:** At every step of decoding, the model creates a unique context vector relevant *\*only\** to that specific moment.

# Approach

# Lab

<https://tinyurl.com/dlframeworks>

<https://github.com/sakharamg/DeepLearningFrameworks>

Thank You

# Appendix

	I	love	Py	Torch		
	8	450	9901	772		
Data IDs:	8	450	9901	772	0	0
Data Mask:	1	1	1	1	0	0
	0.015	0.874	...	...	0.331	
	0.452	-0.112	...	...	0.567	
	0.981	0.034	...	...	-0.229	
	-0.563	0.775	...	...	0.101	
	0.000	0.000	...	...	0.000	
	0.000	0.000	...	...	0.000	