## B.4 Chapter 4

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See the table below.

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2. 
$$\mathbf{A}^{\mathrm{T}} = \begin{bmatrix} 13 & 4 & -8 \\ 12 & 0 & 6 \\ -3 & -1 & 5 \\ 10 & -2 & 5 \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} 13 & 12 & -3 & 10 \\ 4 & 0 & -1 & -2 \\ -8 & 6 & 5 & 5 \end{bmatrix}$$

$$\mathbf{B}^{\mathrm{T}} = \begin{bmatrix} k_x & 0 & 0 \\ 0 & k_y & 0 \\ 0 & 0 & k_z \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} k_x & 0 & 0 \\ 0 & k_y & 0 \\ 0 & 0 & k_z \end{bmatrix}$$

$$\mathbf{C}^{\mathrm{T}} = \begin{bmatrix} 15 & 8 \\ -7 & 3 \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} 15 & -7 \\ 8 & 3 \end{bmatrix} \qquad \mathbf{D}^{\mathrm{T}} = \begin{bmatrix} a & g \\ b & h \\ c & i \\ d & j \\ f & k \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} a & b & c & d & f \\ g & h & i & j & k \end{bmatrix}$$

$$\mathbf{E}^{\mathrm{T}} = \begin{bmatrix} 0 & 1 & 3 \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} \qquad \mathbf{F}^{\mathrm{T}} = \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} x & y & z & w \end{bmatrix}$$

$$\mathbf{G}^{\mathrm{T}} = \begin{bmatrix} 10 & 20 & 30 & 1 \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} 10 \\ 20 \\ 30 \\ 1 \end{bmatrix} \qquad \mathbf{H}^{\mathrm{T}} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} \alpha & \beta & \gamma \end{bmatrix}$$

3. 
$$\mathbf{AB} = (4 \times 3)(3 \times 3) = 4 \times 3$$
  $\mathbf{AH} = (4 \times 3)(3 \times 1) = 4 \times 1$   $\mathbf{BB} = (3 \times 3)(3 \times 3) = 3 \times 3$   $\mathbf{BH} = (3 \times 3)(3 \times 1) = 3 \times 1$   $\mathbf{CC} = (2 \times 2)(2 \times 2) = 2 \times 2$   $\mathbf{DC} = (5 \times 2)(2 \times 2) = 5 \times 2$   $\mathbf{EB} = (1 \times 3)(3 \times 3) = 1 \times 3$   $\mathbf{EH} = (1 \times 3)(3 \times 1) = 1 \times 1$   $\mathbf{FE} = (4 \times 1)(1 \times 3) = 4 \times 3$   $\mathbf{FG} = (4 \times 1)(1 \times 4) = 4 \times 4$   $\mathbf{GA} = (1 \times 4)(4 \times 3) = 1 \times 3$   $\mathbf{GF} = (1 \times 4)(4 \times 1) = 1 \times 1$   $\mathbf{HE} = (3 \times 1)(1 \times 3) = 3 \times 3$   $\mathbf{HG} = (3 \times 1)(1 \times 4) = 3 \times 4$ 

4. (a) 
$$\begin{bmatrix} 1 & -2 \\ 5 & 0 \end{bmatrix} \begin{bmatrix} -3 & 7 \\ 4 & 1/3 \end{bmatrix} = \begin{bmatrix} (1)(-3) + (-2)(4) & (1)(7) + (-2)(1/3) \\ (5)(-3) + (0)(4) & (5)(7) + (0)(1/3) \end{bmatrix}$$
$$= \begin{bmatrix} -3 + (-8) & 7 + (-2/3) \\ -15 + 0 & 35 + 0 \end{bmatrix} = \begin{bmatrix} -11 & 19/3 \\ -15 & 35 \end{bmatrix}$$

(b) Not possible; cannot multiply a 2 × 2 matrix by a 1 × 2 vector on the right.

(c) 
$$\begin{bmatrix} 3 & -1 & 4 \end{bmatrix} \begin{bmatrix} -2 & 0 & 3 \\ 5 & 7 & -6 \\ 1 & -4 & 2 \end{bmatrix}$$
  

$$= \begin{bmatrix} (3)(-2)+(-1)(5)+(4)(1) & (3)(0)+(-1)(7)+(4)(-4) & (3)(3)+(-1)(-6)+(4)(2) \end{bmatrix}$$

$$= \begin{bmatrix} -6+(-5)+4 & 0+(-7)+(-16) & 9+6+8 \end{bmatrix} = \begin{bmatrix} -7 & -23 & 23 \end{bmatrix}$$

(d) 
$$\begin{bmatrix} x & y & z & w \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} x & y & z & w \end{bmatrix}$$

(e) Not possible; cannot multiply a 1 × 4 vector by a 2 × 1 vector.

$$(\mathbf{f}) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} = \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix}$$

(g) 
$$\begin{bmatrix} 3 & 3 \end{bmatrix} \begin{bmatrix} 6 & -7 \\ -4 & 5 \end{bmatrix} = \begin{bmatrix} (3)(6) + (3)(-4) & (3)(-7) + (3)(5) \end{bmatrix}$$
  
=  $\begin{bmatrix} 18 + (-12) & -21 + 15 \end{bmatrix} = \begin{bmatrix} 6 & -6 \end{bmatrix}$ 

(h) Not possible; cannot multiply a 3 × 3 matrix by a 2 × 3 matrix on the right.

5. (a) 
$$\begin{bmatrix} 5 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} (5)(1) + (-1)(0) + (2)(0) & (5)(0) + (-1)(1) + (2)(0) & (5)(0) + (-1)(0) + (2)(1) \end{bmatrix}$$

$$= \begin{bmatrix} 5 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} (1)(5) + (0)(-1) + (0)(2) \\ (0)(5) + (1)(-1) + (0)(2) \\ (0)(5) + (0)(-1) + (1)(2) \end{bmatrix} = \begin{bmatrix} 5 \\ -1 \\ 2 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} 5 & -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 5 & -3 \\ 1 & 7 & 1 \\ -2 & -1 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} (5)(2) + (-1)(1) + (2)(-2) & (5)(5) + (-1)(7) + (2)(-1) & (5)(-3) + (-1)(1) + (2)(4) \end{bmatrix}$$

$$= \begin{bmatrix} 10 + (-1) + (-4) & 25 + (-7) + (-2) & -15 + (-1) + 8 \end{bmatrix} = \begin{bmatrix} 5 & 16 & -8 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 5 & -3 \\ 1 & 7 & 1 \\ -2 & -1 & 4 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} (2)(5) + (5)(-1) + (-3)(2) \\ (1)(5) + (7)(-1) + (1)(2) \\ (-2)(5) + (-1)(-1) + (4)(2) \end{bmatrix} = \begin{bmatrix} 10 + (-5) + (-6) \\ 5 + (-7) + 2 \\ -10 + 1 + 8 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix}$$
(c)  $\begin{bmatrix} 5 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 7 & 2 \\ 7 & 0 & -3 \\ 2 & -3 & -1 \end{bmatrix}$ 

$$= \begin{bmatrix} (5)(1) + (-1)(7) + (2)(2) & (5)(7) + (-1)(0) + (2)(-3) & (5)(2) + (-1)(-3) + (2)(-1) \end{bmatrix}$$

$$= \begin{bmatrix} 5 + (-7) + 4 & 35 + 0 + (-6) & 10 + 3 + (-2) \end{bmatrix} = \begin{bmatrix} 2 & 29 & 11 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 7 & 2 \\ 7 & 0 & -3 \\ 2 & -3 & -1 \end{bmatrix} \begin{bmatrix} 5 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} (1)(5) + (7)(-1) + (2)(2) \\ (2)(5) + (-3)(-1) + (-1)(2) \end{bmatrix} = \begin{bmatrix} 5 + (-7) + 4 \\ 35 + 0 + (-6) \\ 10 + 3 + (-2) \end{bmatrix} = \begin{bmatrix} 2 \\ 29 \\ 11 \end{bmatrix}$$
(d)  $\begin{bmatrix} 5 & -1 & 2 \end{bmatrix} \begin{bmatrix} 0 & -4 & 3 \\ 4 & 0 & -1 \\ -3 & 1 & 0 \end{bmatrix}$ 

$$= \begin{bmatrix} (5)(0) + (-1)(4) + (2)(-3) & (5)(-4) + (-1)(0) + (2)(1) & (5)(3) + (-1)(-1) + (2)(0) \end{bmatrix}$$

$$= \begin{bmatrix} (5)(0) + (-1)(4) + (2)(-3) & (5)(-4) + (-1)(0) + (2)(1) & (5)(3) + (-1)(-1) + (2)(0) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & -4 & 3 \\ 4 & 0 & -1 \\ -3 & 1 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} (0)(5) + (-4)(-1) + (3)(2) \\ (4)(5) + (0)(-1) + (-1)(2) \end{bmatrix} = \begin{bmatrix} 0 & -4 + 6 \\ 20 + 0 + (-2) \\ -15 + (-1) + 0 \end{bmatrix} = \begin{bmatrix} 10 \\ 18 \\ -16 \end{bmatrix}$$
6. (a)  $((\mathbf{A}^T)^T)^T = \mathbf{A}^T$ 
(b)  $(\mathbf{B}\mathbf{A}^T)^T (\mathbf{C}\mathbf{D}^T) = ((\mathbf{A}\mathbf{B})^T)^T (\mathbf{C}\mathbf{D}^T) = (\mathbf{A}\mathbf{B}) (\mathbf{C}\mathbf{D}^T) = \mathbf{A}\mathbf{B}^T\mathbf{C}\mathbf{D}^T$ 
(c)  $((\mathbf{D}^T\mathbf{C}^T)(\mathbf{A}\mathbf{B})^T)^T = (((\mathbf{C}\mathbf{D}\mathbf{E})^T)^T (\mathbf{D}^T\mathbf{C}^T)^T) = (\mathbf{A}\mathbf{B}) (\mathbf{C}\mathbf{D}^T) = \mathbf{A}\mathbf{B}^T\mathbf{C}\mathbf{D}^T$ 
(d)  $((\mathbf{A}\mathbf{B})^T (\mathbf{C}\mathbf{D}^T)^T)^T = (((\mathbf{C}\mathbf{D}\mathbf{E})^T)^T ((\mathbf{A}\mathbf{B})^T)^T) = (\mathbf{C}\mathbf{D}\mathbf{E})(\mathbf{A}\mathbf{B})$ 

For each of the matrices M, interpret the rows of M as basis vectors after transformation.

= CDEAB

- (a) The basis vectors [1, 0] and [0, 1] are transformed to [0, −1] and [1, 0], respectively. Thus, M performs a 90° clockwise rotation.
- (b) The basis vectors [1, 0] and [0, 1] are transformed to  $\left[\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right]$  and  $\left[-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right]$ , respectively. Thus, **M** performs a 45° counterclockwise rotation.

- (c) The basis vectors [1, 0] and [0, 1] are transformed to [2, 0] and [0, 2], respectively. Thus, M performs a uniform scale, scaling both the x and y dimensions by 2.
- (d) The basis vectors [1, 0] and [0, 1] are transformed to [4, 0] and [0, 7], respectively. Thus, M performs a nonuniform scale, scaling the x dimension by 4 and the y dimension by 7.
- (e) The basis vectors [1, 0] and [0, 1] are transformed to [-1, 0] and [0, 1], respectively. Thus, M performs a reflection across the y axis, negating x values and leaving y values untouched.
- (f) The basis vectors [1, 0] and [0, 1] are transformed to [0, -2] and [2, 0], respectively. Thus, M is performing a combination of transformations: it is rotating clockwise by 90° and scaling both dimensions uniformly by 2. This can be confirmed by multiplying the appropriate matrices from parts (a) and (c), which perform these transformations individually:

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ 2 & 0 \end{bmatrix}.$$

8. 
$$\mathbf{M} = \begin{bmatrix} 0 & -b_z & b_y \\ b_z & 0 & -b_x \\ -b_y & b_x & 0 \end{bmatrix}$$
 This matrix is skew symmetric, as desired, since  $\mathbf{M}^{\mathrm{T}} = -\mathbf{M}$ .

- 0. (a) 3 (b) 1 (c) 4 (d) 2
- 10. The result vector element w<sub>i</sub> is the product of the ith row of M multiplied by the column vector v. To have w<sub>i</sub> = v<sub>i</sub> − v<sub>i−1</sub>, the ith row of M needs to capture the ith element of v, as well as the negative of the (i − 1)th element, but exclude all others. This means that

$$m_{ij} = \begin{cases} 1 & \text{if } j = i, \\ -1 & \text{if } j = i - 1, \\ 0 & \text{otherwise.} \end{cases}$$

Thus,

11. The result vector element w<sub>i</sub> is the product of the ith row of N multiplied by the column vector v. To have w<sub>i</sub> = \sum\_{j=1}^{i} v\_j, the ith row of N needs to capture all elements of v up to and including the ith element, but exclude all others. This means that

$$n_{ij} = \begin{cases} 1 & \text{if } j \le i, \\ 0 & \text{otherwise.} \end{cases}$$

Thus,

12.

- (a) Note that the structure of M causes the ith row of MN to be equivalent to the difference between the ith and (i − 1)th rows of N.
- (b) Note that the structure of N causes the ith row of NM to be equivalent to the sum of the first i rows of M.