AutonomousQuadruped

RoboDog

Team22

Start Date: 2023/6/19

Milestone Marker: 1

Rolling Increment 0

Milestone Description	Responsible Person	Start	Number of Days
General work	All	2023/7/13	18
Final Test and Debug	All	2023/7/13	7
Prepare documentation and Presentation	All	2023/7/17	14
State Machine	Yankun Wei	2023/6/19	9
Search Information	Yankun Wei	2023/6/19	4
Implementation: Node Statemachine	Yankun Wei	2023/6/22	6
Perception Pipeline	Yankun Wei, Hao Guo	2023/6/19	16
Search Information	Yankun Wei, Hao Guo	2023/6/19	5
Implementation: Node Perception	Yankun Wei, Hao Guo	2023/6/22	13
Depth to Pointcloud	Yankun Wei	2023/6/26	1
Pointcloud to voxelgrid	Hao Guo	2023/7/3	1
Path Planner	Shaoxiang Tan, Hanyu Li, Hao Guo	2023/6/19	27
Search Information	Shaoxiang Tan	2023/6/19	7
Determine the data format of path points	Shaoxiang Tan, Hanyu Li	2023/6/24	1
Implementation: Node Pathplanner	Shaoxiang Tan, Hanyu Li, Hao Guo	2023/6/24	22
Implementation in predefined voxelgrid	Shaoxiang Tan	2023/7/4	1
Implementation in voxelgrid from perception	Hanyu Li, Hao Guo	2023/7/13	1
Trajectory Planner	Hanyu Li, Yujie Guo	2023/6/19	27
Search Information	Hanyu Li, Yujie Guo	2023/6/19	7
Determine the data format of path points	Shaoxiang Tan, Hanyu Li	2023/6/24	1
Implementation: Node Trajectory Planner	Hanyu Li, Yujie Guo	2023/6/24	22
Implementation with predefined path points	Hanyu Li	2023/7/5	1
Implementation with path points from Pathplanner	Yujie Guo	2023/7/13	1
Position Controller	Hanyu Li, Yujie Guo	2023/6/19	27
Understand the control method	Hanyu Li, Yujie Guo	2023/6/19	7
Implementation with trajectory	Yujie Guo	2023/6/24	22

若要添加更多数据，请在此行上方插入新行