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## EXERCISE ROUND 2

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S-114.1100 COMPUTATIONAL SCIENCE

September 25, 2011

## Problem 1. Plots and conclusions

In exercise round 2 we studied polynomial interpolation. In problem 4, we tried to approximate the *serpentine curve*

$$f(x) = \frac{x}{1/4 + x^2}$$

using 13 equidistant nodes and again using 13 *Chebyshev nodes* which were calculated using

$$x_i = \frac{1}{2}(a + b) + \frac{1}{2}(b - a) \cos \left[ \left( \frac{i}{n} \right) \pi \right] \quad (0 \leq i \leq n).$$

The interval  $[a, b]$  used in both cases was  $[-2.02857, 2.02857]$ . In figure 1 is shown our function itself and the two approximations. As predicted, the approximation done using *Chebyshev nodes* is much better near the ends of our interval. However, as is shown in

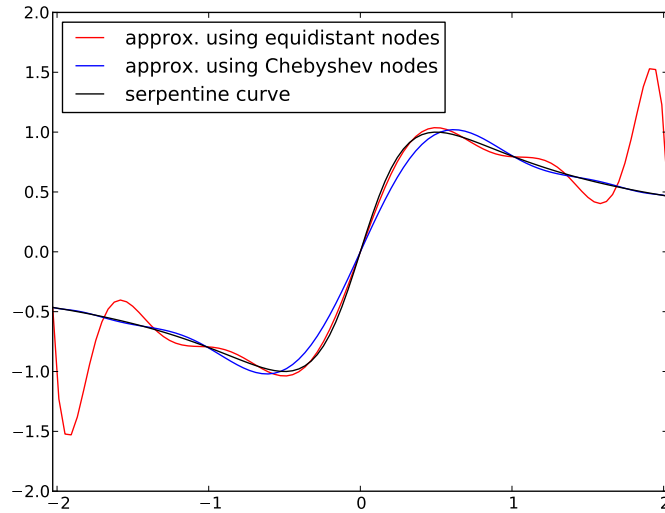


Figure 1: The serpentine curve and polynomial approximations

figure 2 which shows us the errors  $|p(x) - f(x)|$  calculated in 101 equidistant points in our interval, the error using *Chebyshev nodes* is actually larger near zero. We can not be satisfied with the results, as better ways can be found to approximate this curve.

We usually choose to use *Chebyshev nodes*, because they help to minimize the *Runge's phenomenon*: problem of oscillation at the edges of an interval when using polynomials of high degree. In the case of *serpentine curve*, approximation near the middle of the interval is also hard.

As seen in figure 1, shape of the *serpentine curve* is hard to approximate, even when using a polynomial of 12th degree. Better approximation might be possible if the points were chosen by hand. In this case, however, a good approximation could be done using natural cubic splines.

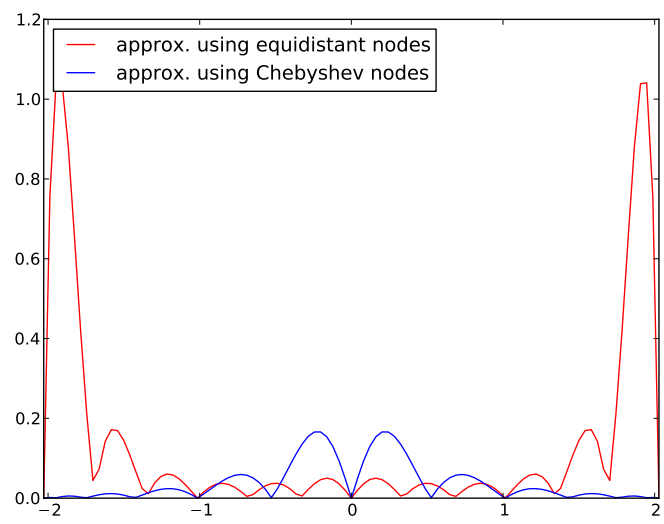


Figure 2: Errors of the polynomial approximations

## Appendix 1. Code

```
1 from __future__ import division
2 from pylab import *
3
4 def coefficients(n, x, y, a):
5     a=y;
6     for j in arange(1,n+1):
7         print j
8         for i in linspace(n,j,n-j+1):
9             a[i] = (a[i]-a[i-1])/(x[i]-x[i-j])
10    return a
11
12 def eval(n, x, t, a):
13     pt = a[n]
14     for i in linspace(n-1,0,n):
15         pt = pt * (t-x[i])+a[i];
16     return pt
17
18 def f(x):
19     return x/(1/4.0 + x**2)
20
21 def main():
22     col = ['r', 'b']
23     for k in range(2):
24         chebysnev = k
25         if(chebysnev==0):
26             x = linspace(-2.02857, 2.02857, 13)
27         else:
28             i = linspace(0,12,13)
29             x = 2.02857*cos(pi*i/12)
30
31     print "Hello!"
32     x_101 = linspace(-2.02857, 2.02857, 101)
33
34     y = f(x)
35     y_101 = f(x_101)
36     a = y
37     n = size(x)-1
38
39     a = coefficients(n,x,y,a)
40
41     y_eval = linspace(0,0,101)
42
```

```

43         for i in linspace(0,100,101):
44             y_eval[i] = eval(n,x,x_101[i],a)
45             plot(x_101,abs(y_eval-y_101), col[k])
46             #plot(x_101,y_eval, col[k])
47         #plot(x_101, y_101, 'k')
48         xlim(min(x_101),max(x_101))
49         #legend(('approx. using equidistant nodes','approx. using Chebyshev \
50 #nodes','serpentine curve'),loc=2)
51         legend(('approx. using equidistant nodes','approx. using Chebyshev \
52 nodes'),loc=2)
53         show()
54
55 if __name__ == "__main__":
56     main()

```