```
┌─────────────────────────────┐
│      view_frames Result     │
│                             │
│   Recorded at time: 209.621 │
└─────────────────────────────┘
```

world

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /camera_link_broadcaster
Average rate: 10.175
Buffer length: 4.914
Most recent transform: 209.655
Oldest transform: 204.741

panda_link0

camera_link

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link1

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link2

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link3

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link4

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link5

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link6

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_link7

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link8

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_hand

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

Broadcaster: /robot_state_publisher
Average rate: 50.0
Buffer length: 4.96
Most recent transform: 209.602
Oldest transform: 204.642

panda_leftfinger

panda_rightfinger