

**A REPORT  
ON  
DOOR SECURITY CONTROL**

**Submitted in partial fulfillment of the course  
INSTR F241 Microprocessors and Interfacing**

**Submitted by Group No. 106**

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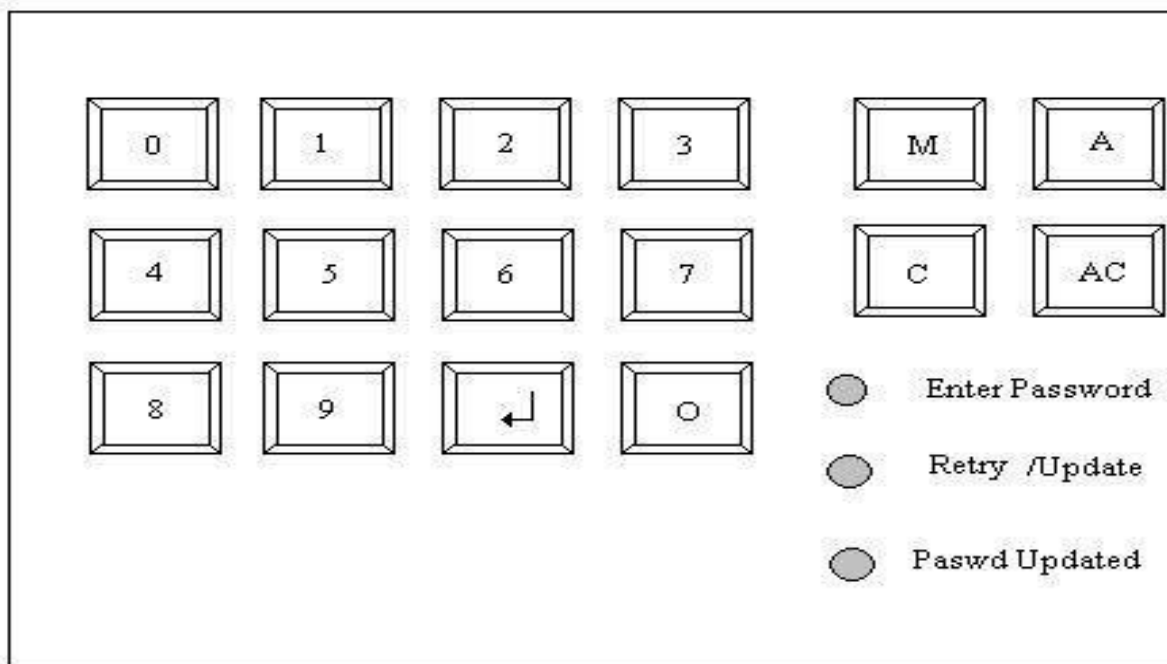
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## PROBLEM STATEMENT

**DESCRIPTION:** This system controls the opening and closing of a door based on password entry. If the password is correct the person can enter. Each person is given two chances to enter the correct password. On failure an alarm is sounded. Inside the room a button is available when the button is pressed the door opens for 1 Min, so that the person can leave the room.

**USER INTERFACE:** There are three sets of passwords:

- (1) User
- (2) Master
- (3) Alarm off



- The Master password is used by the security Personnel for updating Password of the day. Pressing the M button activates this mode. The system glows Enter Password LED asking the personnel to enter the password. The master password is a 16-digit value. The master is given only a single chance to enter the password. If authenticated, the retry/Update LED glows. If there is a failure in authentication the alarm is sounded. When the retry/ Update LED glows the user has to enter password of the day. This is 12-digit value. Once this value has been accepted by the system the Password Updated LED glows.
- User has to press the O key when he wants to enter the room. The Enter Password LED prompts the user to enter the password. The user is given C/AC option as well. If the first attempt fails, the RETRY LED glows. The user is allowed to re-enter password, on authentication door opens for a period of 1 Min. On Failure an ALARM is sounded.
- To Turn-off the Alarm the A button has to be pressed. Enter Password LED glows prompting user to enter the 14-digit password for turning of alarm, no retries are allowed. If authentication is successful then the alarm is turned off.
- To leave the room a button is available inside the room, when the button is pressed the door opens for 1 Minute so that the person can leave the room.
- LCD show the entry as asterisk when the password characters are entered.

## ASSUMPTIONS

- All operations are sequential and so, no two operations can be carried out at the same time.
- User cannot access the door lock system at the 24 hour mark. First, a user password needs to be set using the master mode and only then can the door lock be accessed.
- Once you have entered a mode, it is necessary to complete the entire procedure. Pressing any other mode buttons like M, O or A will not override the mode.
- In case of mistake in typing the password to turn down the alarm, the system will get locked in it's last state and to use it again, it is necessary to shutdown and restart the system.
- The 24 hour clock starts running as soon as we turn on the system.
- The Master Password and the Alarm Password have been hard coded in the system.

Master Password: 9999999999999999

Alarm Password: 9999999999999999

## LIST OF COMPONENTS USED

Sr. No.	Hardware Device	Description	Quantity
1.	8086	16 bit Microprocessor	1
2.	74LS373	Octal Latch	3
3.	74LS245	Transceiver	2
4.	7432	OR gate	6
5.	NOT	NOT gate	6
6.	2732	ROM	2
7.	6116	RAM	2
8.	74LS138	3-to-8 Decoder	1
9.	8255A	Programmable Peripheral Interface	2
10.	8253A	Programmable Interval Timer	2
11.	KEYPAD-PROJECT	Hex-keypad	1
12.	BUTTON	Button	1
13.	LM016L	16x2 LCD display	1
14.	BUZZER	Alarm	1
15.	LED-RED	Red LED	3
16.	MOTOR-STEPPER	Stepper Motor	1

17.	OMIH-SH-105D	Relay	1
18.	SW-SPDT-MOM	SPDT Switch	1
19.	ULN2003A	Darlington Transistor	1
20.	74LS241	Tri-state Buffer	1



## Memory Mapping

Size of 2732 (ROM) : 4k

ROM(even) : 00000h - 01FFEh (A0 = 0)

ROM (odd) : 00001h - 01FFFh (A0 = 1 )

[illegible]

Size of 6116 (RAM) : 2k

RAM(even) : FF000h - FFFFEh (A0 = 0)

RAM(odd) : FF001h - FFFFh (A0 = 1)

[illegible]

## I/O Mapping

Address of 8255-1 port-A	: 00h
Address of 8255-1 port-B	: 02h
Address of 8255-1 port-C	: 04h
Address of 8255-1 control register	: 06h
Control word of 8255-1	: 88h

Address of 8255-2 port-A	: 08h
Address of 8255-2 port-B	: 0Ah
Address of 8255-2 port-C	: 0Ch
Address of 8255-2 control register	: 0Eh
Control word of 8255-2	: 89h

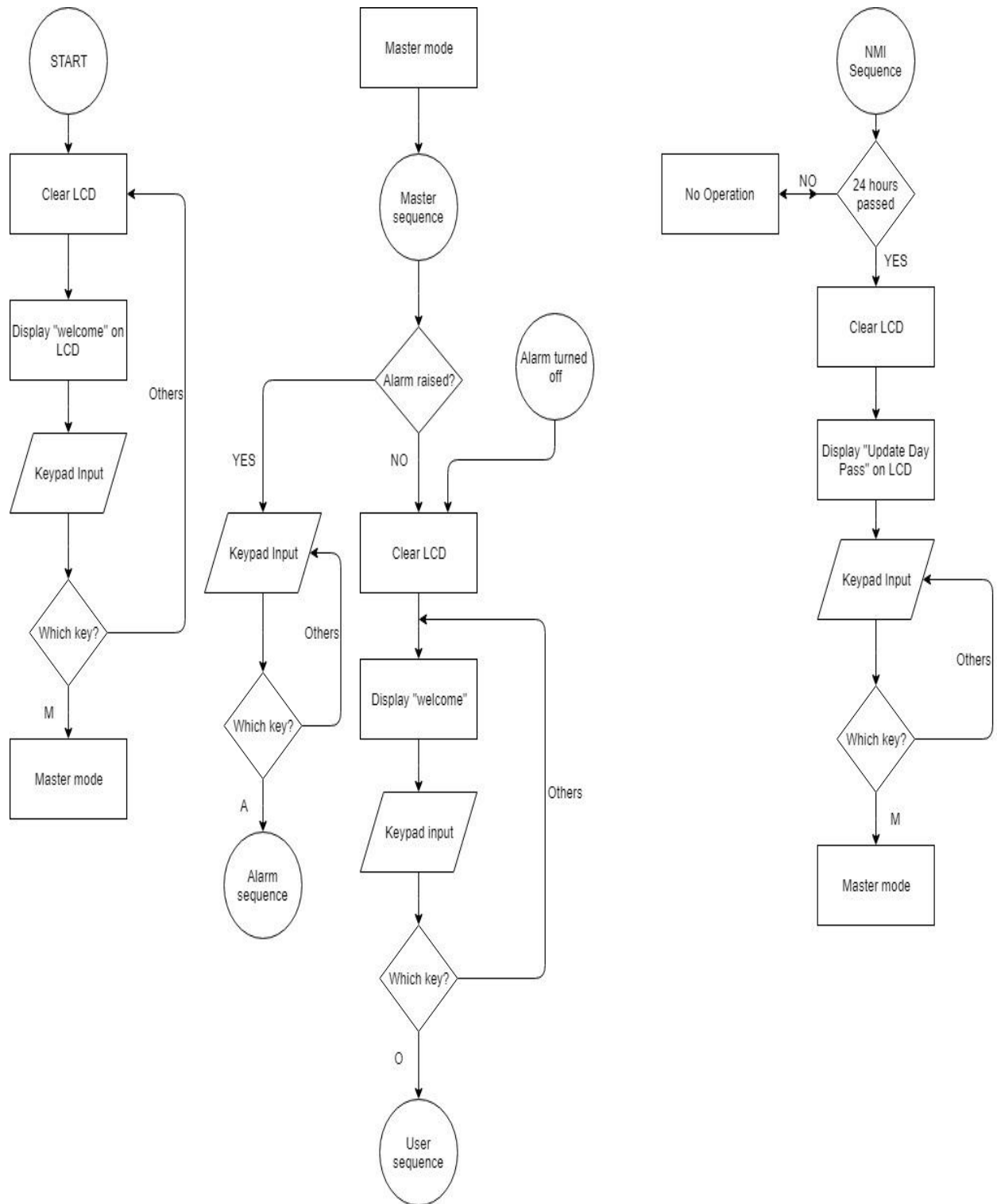
Address of 8253-1 count0	: 10h
Address of 8253-1 count1	: 12h
Address of 8253-1 count2	: 14h
Address of 8253-1 control register	: 16h
Control word of 8253-1 count0	: 36h
Control word of 8253-1 count1	: 56h
Control word of 8253-1 count2	: 92h

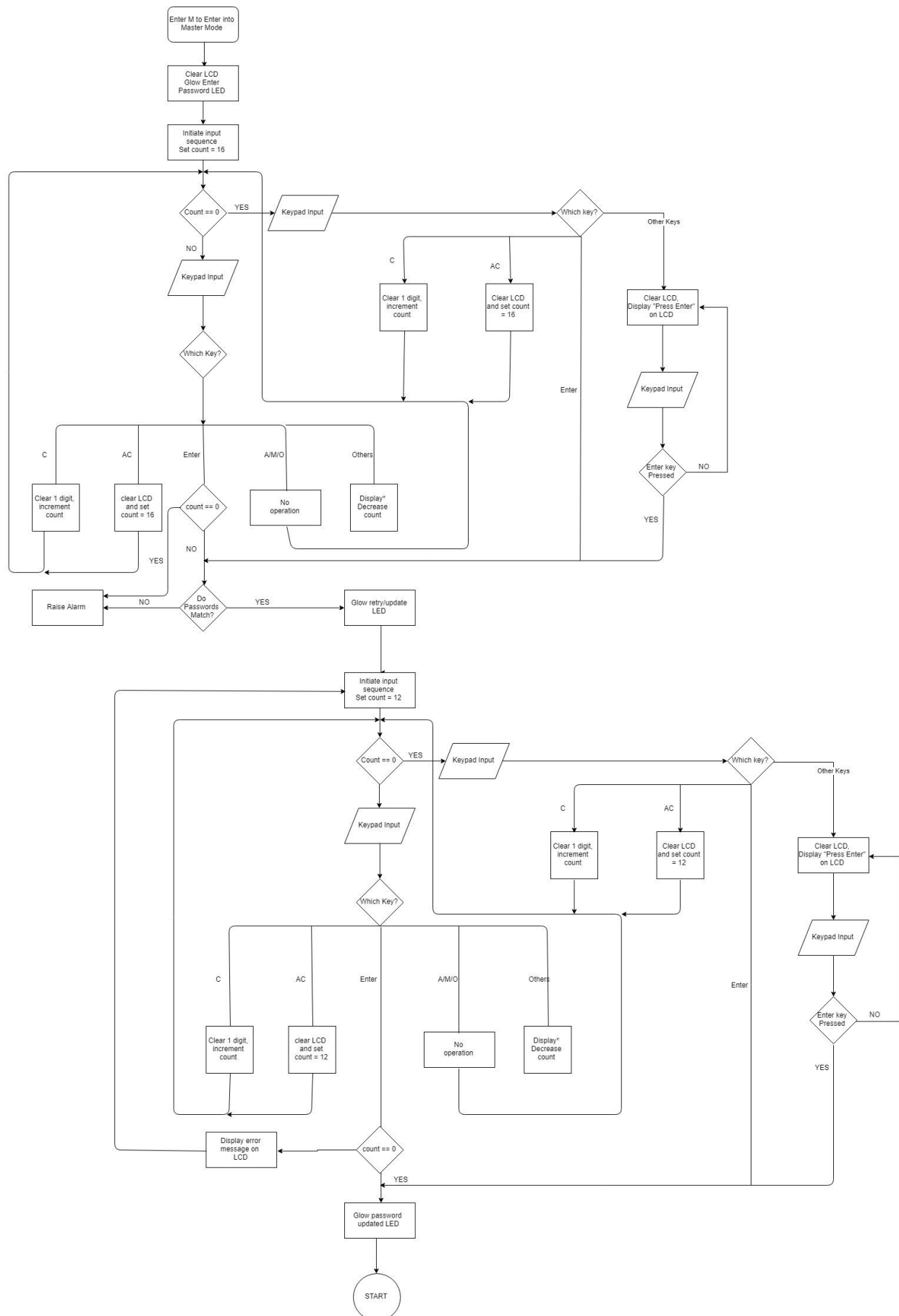
Address of 8253-2 count0	: 18h
Address of 8253-2 count1	: 1Ah
Address of 8253-2 count2	: 1Ch
Address of 8253-2 control register	: 1Eh
Control word of 8253-2 count0	: 34h
Control word of 8253-2 count1	: 5Ah
Control word of 8253-2 count2	: 94h

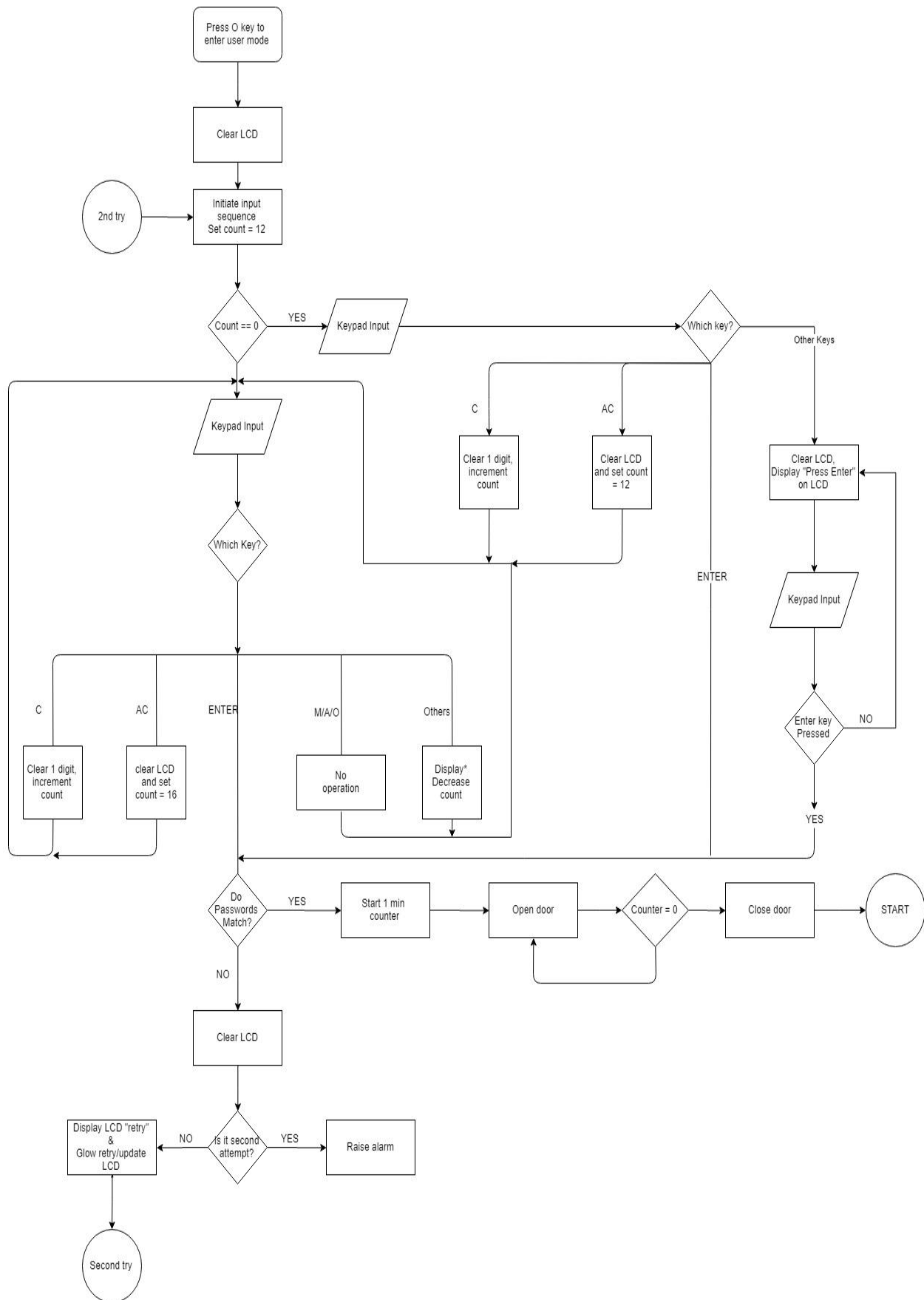
## IVT

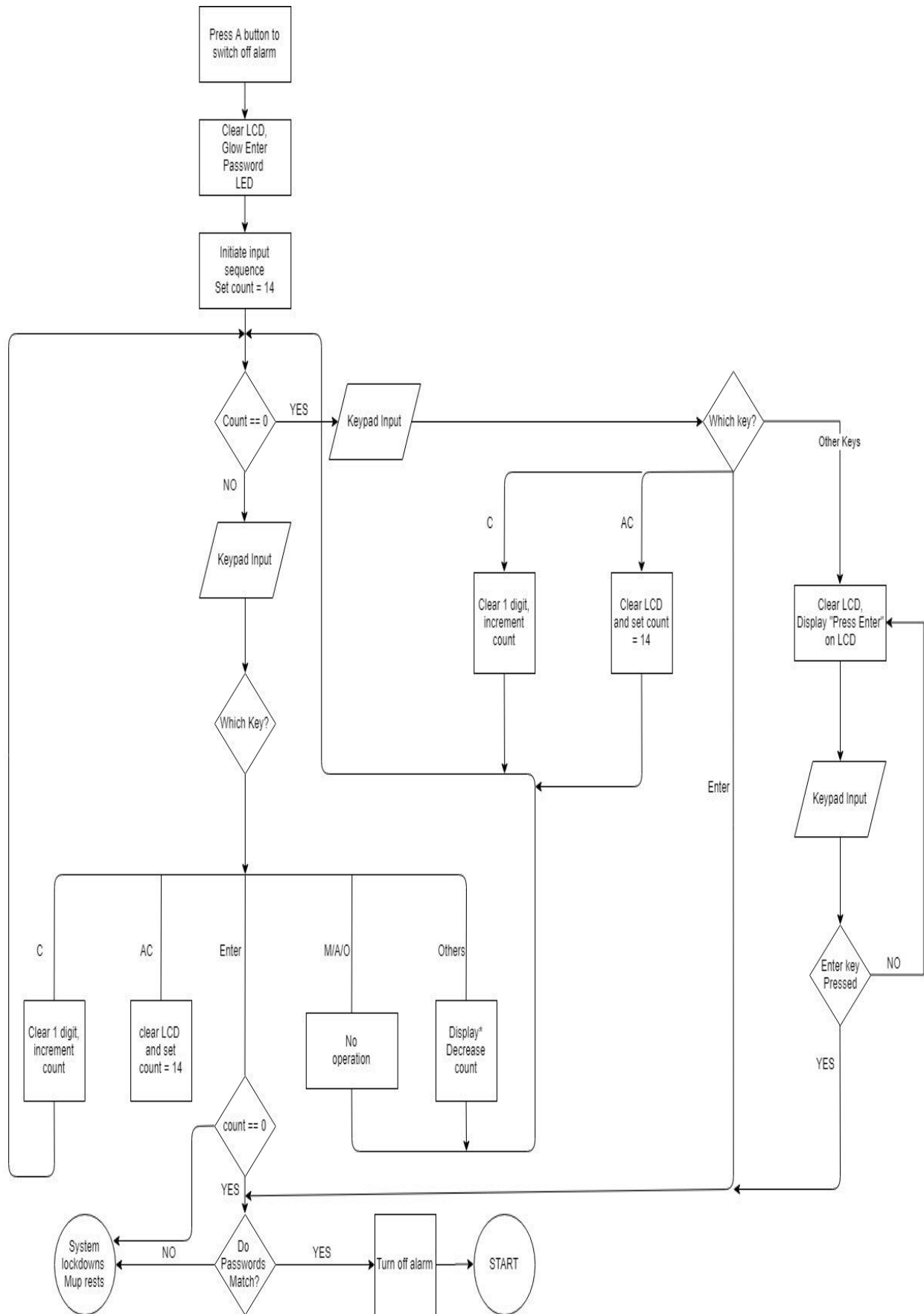
Interrupt Vector No.	Physical Address	Contains
INT 02h	00008h 0000Ah	IP2 CS2
INT 80h	00200h 00202h	IP128 CS128

# Flow-Chart of the System









## ALP Code

#make\_bin#

#LOAD\_SEGMENT=FFFFh#

#LOAD\_OFFSET=0000h#

#CS=0000h#

#IP=0000h#

#DS=0000h#

#ES=0000h#

#SS=0000h#

#SP=FFFEh#

#AX=0000h#

#BX=0000h#

#CX=0000h#

#DX=0000h#

#SI=0000h#

#DI=0000h#

#BP=0000h#

jmp st1  
db 5 dup(0)

;IVT entry for NMI (INT 02h)  
dw Nmi\_24hrtimer  
dw 0000  
db 500 dup(0)

;IVT entry for 80H  
dw Switch\_intR



```

dw    0000
    db    508 dup(0)
st1:   cli ;Clear IF, now initiliaze RAM

;intialize ds, es,ss to start of RAM
mov     ax,0200h
mov     ds,ax
mov     es,ax
mov     ss,ax
mov     sp,0FFFEH
; INITIALIZATION OF 8255,8253 BEGINS HERE

port_a1 equ 00h
port_b1 equ 02h
port_c1 equ 04h
creg1 equ 06h

port_a2 equ 08H
port_b2 equ 0Ah
port_c2 equ 0Ch
creg2 equ 0Eh

cnt0_1 equ 10h
cnt1_1 equ 12h
cnt2_1 equ 14h
creg3 equ 16h

cnt0_2 equ 18h
cnt1_2 equ 1Ah
cnt2_2 equ 1Ch
creg4 equ 1Eh

sti
    mov al,89h ; control word for 8255-2 I/O Mode, Port A - Mode 0,
o/p, PCU - i/p Port B - Mode 0, o/p, PCL - i/p
    out creg2,al

```

```
    mov al,88h ; control word for 8255-1 I/O Mode, Port A - Mode 0,  
o/p, PCU - i/p Port B - Mode 0, o/p, PCL - o/p  
    out creg1,al
```

```
    mov al,36h ;control word for 8253-1 counter 0 16bit count, Mode  
3, Bin  
    out creg3,al
```

```
    mov al,56h ;control word for 8253-1 counter 1 8bit LSB count, Mode  
3, Bin  
    out creg3,al
```

```
    mov al,92h ;control word for 8253-1 counter 2, 8bit LSB count,  
Mode 1, Bin  
    out creg3,al
```

```
    mov al,34h ;control word for 8253-2 counter 0 16bit count, Mode 2,  
Bin  
    out creg4,al
```

```
    mov al,5ah ;control word for 8253-2 counter 1 8bit LSB count, Mode  
5, Bin  
    out creg4,al
```

```
    mov al,94h ;control word for 8253-2 counter 2 8bit LSB count Mode  
2, Bin  
    out creg4,al
```

```
    mov al,50h ;load count lsb for 8253-1 counter 0 | Count value =  
50000(dec)  
    out cnt0_1, al
```

```
    mov al,0C3h ;load count msb for 8253-1 counter 0  
    out cnt0_1, al
```

```
    mov al,64h ;load count for 8253-1 counter 1 | Count value =  
100(dec)
```

out cnt1\_1, al

mov al,1eh ;load count lsb for 8253-1 counter 2 (1 minute Timer) |  
Count value = 30(dec)  
out cnt2\_1, al

mov al,0A0h;load count for 8253-2 LSB counter 0 (24 hour counter)  
| Count value = 64(dec)  
out cnt0\_2, al

mov al,-5h ;load count for 8253-2 MSB counter 0 (24 hour counter)  
out cnt0\_2, al

mov al,3 ;load count for 8253-2 counter 1 (Switch trigger counter)  
| Count value = 3(dec)  
out cnt1\_2, al

mov al,2 ;load count for 8253-2 counter 2 | Count value = 2(dec)  
out cnt2\_2, al  
;INITIALIZATION OF 8255,8253 ENDS HERE

mov al,00h ;default low output from 8255-2 upper port C  
out port\_c2, al

call DELAY\_20ms ;LCD INITIALIZATION BEGINS  
mov al,04h ;E=1 RW=0 RS=0 -> control write  
out port\_b1,al  
call DELAY\_20ms  
mov al,00h ;E=0 RW=0 RS=0 -> control write H-L transition  
out port\_b1,al

mov al,38h ;Initialization  
out port\_a1,al

mov al,04h ;E=1 RW=0 RS=0 -> control write

```

out port_b1,al
call DELAY_20ms
mov al,00h ;E=0 RW=0 RS=0 -> control write H-L transition
out port_b1,al
call DELAY_20ms
mov al,0Ch ;LCD ON, cursor ON, cursor blinking OFF
out port_a1,al
mov al,04h ;E=1 RW=0 RS=0 -> control write
out port_b1,al
call DELAY_20ms
mov al,00h ;E=0 RW=0 RS=0 -> control write H-L transition
out port_b1,al

```

```

mov al,06h ;move cursor right
out port_a1,al
call DELAY_20ms
mov al,04h ;E=1 RW=0 RS=0 -> control write
out port_b1,al
call DELAY_20ms
mov al,00h ;E=0 RW=0 RS=0 -> control write H-L transition
out port_b1,al
mov al,4ch
out port_a1,al
call DELAY_20ms ;LCD INITIALIZATION ENDS

```

```

mov ax,0200h ; Initialize DS
mov ds,ax

```

```

mov si,0000h
mov al,0bdh;hard coding pass-word ; 9999999999999999 (BD ->
Keyboard value)
mov [si],al

```

```

mov al,0bdh
mov [si+1],al

```

```

mov al,0bdh

```

mov [si+2],al

mov al,0bdh  
mov [si+3],al

mov al,0bdh  
mov [si+4],al

mov al,0bdh  
mov [si+5],al

mov al,0bdh  
mov [si+6],al

mov al,0bdh  
mov [si+7],al

mov al,0bdh  
mov [si+8],al

mov al,0bdh  
mov [si+9],al

mov al,0bdh  
mov [si+0ah],al

mov al,0bdh  
mov [si+0bh],al

mov al,0bdh  
mov [si+0ch],al

mov al,0bdh  
mov [si+0dh],al

mov al,0bdh  
mov [si+0eh],al

```
mov al,0bdh  
mov [si+0fh],al
```

```
add si,000fh  
inc si ; Update si to store future entry
```

```
mov al,0bdh;hard coding alarm pass-word ; 9999999999999999  
mov [si],al
```

```
mov al,0bdh  
mov [si+1],al
```

```
mov al,0bdh  
mov [si+2],al
```

```
mov al,0bdh  
mov [si+3],al
```

```
mov al,0bdh  
mov [si+4],al
```

```
mov al,0bdh  
mov [si+5],al
```

```
mov al,0bdh  
mov [si+6],al
```

```
mov al,0bdh  
mov [si+7],al
```

```
mov al,0bdh  
mov [si+8],al
```

```
mov al,0bdh  
mov [si+9],al
```

```
mov al,0bdh
mov [si+0ah],al
```

```
mov al,0bdh
mov [si+0bh],al
```

```
mov al,0bdh
mov [si+0ch],al
```

```
mov al,0bdh
mov [si+0dh],al
```

```
add si,000dh
inc si ;Update si to store future values
```

```
mov al,0ffh ; Switch off all LEDs
out port_a2,al
```

```
start: call clear_LCD
       call welcome_msg
```

```
       mov bp,00h
       call keypad_input
       cmp al,0bbh
       jz master_Mode
       jmp start
```

```
x6:   call clear_LCD
       call welcome_msg
       call keypad_input
       cmp al,0b7h
       jz User_Mode
       jmp x6 ;press valid key
```

```
master_Mode:
       call intm
```

```

    mov bp,0abcdh
    cmp ax,0abcdh
    jnz x6
x8:  call keypad_input
      cmp al,7Dh
      jz Alarm_Mode
      jnz x8

```

Alarm\_Mode:

```

    call inta
    cmp dh,6h
    jz start
    cmp dh,1h
    jz x6
    jmp x70

```

User\_Mode:

```

    call intu
    cmp ax,0abcdh
    jz x8
    jnz x6

```

x70:

```

stop: jmp stop

```

DELAY\_20ms proc

```

    MOV     CH,5
X4:  NOP
      NOP
      DEC  CH
      JNZ  X4

```

```

    RET

```

DELAY\_20ms endp

DELAY\_0.04s proc

```

    MOV cx,4fffh

```



```

        X17: NOP
            NOP
            DEC    cx
            JNZ    X17

```

```

        RET
DELAY_0.04s endp
DELAY_max proc

```

```

        MOV    cx,0ffffh
        X16: NOP
            NOP
            DEC    cx
            JNZ    X16

```

```

        RET
DELAY_max endp

```

```

enter_LCD proc
    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
    mov al,05h ;E=1 RW=0 RS=1 -> data write
    out port_b1,al
    call DELAY_20ms
    mov al,01h ;E=1 RW=0 RS=1 -> data write H-L transition
    out port_b1,al ;prints Space

```

```

    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints Space

```

```

    mov al,50h
    out port_a1,al

```

```
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints P
```

```
mov al,52h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints R
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,53h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints S
```

```
mov al,53h
out port_a1,al
call DELAY_20ms
```

```
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints S
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,4Eh
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints N
```

```
mov al,54h
out port_a1,al
call DELAY_20ms
mov al,05h
```

```
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints T
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,52h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints R
```

```
RET
enter_LCD endp
```

```
intm proc
```

```
call clear_LCD
mov al,0feh
out port_a2,al ;turns on enter password LED
mov cx,16
```

```
enter_16bit:
call keypad_input
cmp al,7eh ; Check if pressed 'C'
jz pressc
```

```

        cmp al,7bh ; Check if pressed 'AC'
        jz pressac
        cmp al,77h ; Check if pressed 'ENTER'
        jz press_enter
        cmp al,0bbh ;Check if pressed 'M'
        jz nop_master
        cmp al,0b7h ; Check if pressed 'U'
        jz nop_master
        cmp al,7dh ; Check if pressed 'A'
        jz nop_master
        mov [si],al
        CALL asterisk
        inc si
        dec cx
        jnz enter_16bit
disp_entermaster:
        call keypad_input
        cmp al,7eh
        jz pressc
        cmp al,7bh
        jz pressac
        cmp al,77h
        jz press_enter
asd:    CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h
        jz press_enter
        jnz asd

nop_master:    nop
               jmp enter_16bit
pressc:        call clear_1digit_LCD
               dec si
               inc cx
               jmp enter_16bit
pressac:

```

```

        CALL clear_LCD
        mov cx,16
        mov si,1eh          ;start of pass segment
        jmp enter_16bit
press_enter:
        CALL clear_LCD
        mov al,0ffh ; All LED off
        out port_a2,al
        cmp cx,0
        jz cmp_pass
        jmp raise_alarm

day_pass:
        mov si,002Eh
        mov al,0fdh ; Retry/Update is on
        out port_a2,al
        call DELAY_max
        call DELAY_max
        call DELAY_max
        call clear_LCD
        mov cx,12
enter_12bit:
        call keypad_input
        cmp al,7eh ;Check for 'C'
        jz presscd day
        cmp al,0bbh ;Check for 'M'
        jz nop_day
        cmp al,0b7h ;Check for U
        jz nop_day
        cmp al,7dh ;Check for A
        jz nop_day
        cmp al,7bh ;Check for AC
        jz pressac day
        cmp al,77h ;Check for ENTER
        jz press_enter day
        mov [si],al

```

```

        CALL asterisk
        inc si
        dec cx
        jnz enter_12bit
disp_enter:
        call keypad_input
        cmp al,7eh
        jz presscd day
        cmp al,7bh
        jz pressac day
        cmp al,77h
        jz press_enter day
asd1:
        CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h ;Check for ENTER
        jz press_enter day
        jnz asd1
nop_day:  nop
        jmp enter_12bit

presscd day:
        call clear_1digit_LCD
        dec si
        inc cx
        jmp enter_12bit
pressac day:
        CALL clear_LCD
        jmp day_pass
press_enter day:
        CALL clear_LCD
        mov al,0ffh
        out port_a2,al
        cmp cx,0
        jnz err_msg
        mov al,0fbh
        out port_a2,al

```

```

        call DELAY_max
        call DELAY_max

        mov al,0ffh
        out port_a2,al
        jz end_69h
err_msg:
        call error_msg
        jmp day_pass
cmp_pass:
        cld
        mov si,0000h
        mov di,001Eh
        mov cx,17
x5:      mov al,[si]
        mov bl,[di]
        dec cx
        jz day_pass
        cmp al,bl
        jnz raise_alarm
        inc si
        inc di
        jmp x5

raise_alarm:
        mov dh,5h
        mov al,0fh
        out port_a2,al
        mov ax,0abcdh
end_69h:
ret
intm endp

asterisk proc

```



```

        mov al,2Ah
        out port_a1,al
        call DELAY_20ms
        mov al,05h
        out port_b1,al
        call DELAY_20ms
        mov al,01h
        out port_b1,al ;prints *

```

```

ret
asterisk endp

```

```

clear_LCD proc
    mov al,00h
    out port_b1,al
    call DELAY_20ms
    mov al,01h                ;Clear Display
    out port_a1,al
    call DELAY_20ms
    mov al,04h
    out port_b1,al
    call DELAY_20ms
    mov al,00h
    out port_b1,al

```

```

RET
clear_LCD endp

```

```

keypad_input proc                ;SubR for keypad entry,al has unique
key input value.

```

```

x0:    mov al,00h
        out port_c1,al
x1:    in al, port_c1
        and al,0f0h
        cmp al,0f0h
        jnz x1
        CALL DELAY_20ms

```

```

        mov al,00h                ; Check for key press

```

```

out 04,al
x2:
in al, port_c1
and al,0F0h
cmp al,0F0h
jz x2
CALL DELAY_20ms

mov al,00h                                ; Check for key press
out 04,al
in al, port_c1
and al,0F0h
cmp al,0F0h
jz x2

mov al,0Eh                                ;Check for key press column 1
mov bl,al
out port_c1,al
in al, port_c1
and al,0f0h
cmp al,0f0h
jnz x3

mov al,0Dh                                ;Check for key press column 2
mov bl,al
out port_c1,al
in al, port_c1
and al,0f0h
cmp al,0f0h
jnz x3

mov al,0Bh                                ;Check for key press column 3
mov bl,al
out port_c1,al
in al, port_c1
and al,0f0h
cmp al,0f0h

```

jnz x3

mov al,07h  
mov bl,al  
out port\_c1,al  
in al,port\_c1  
and al,0f0h  
cmp al,0f0h  
jz x2

;Check for key press column 4

x3: or al,bl  
ret  
keypad\_input endp

inta proc  
mov al,00eh  
out port\_a2,al

mov cx,14  
mov si,3ah

;store the 16-bit entered pass

after the hard coded pass word  
enter\_14bit:

call keypad\_input  
cmp al,7eh  
jz pressc\_alarm  
cmp al,0bbh  
jz nop\_alarm  
cmp al,0b7h  
jz nop\_alarm  
cmp al,7dh  
jz nop\_alarm  
cmp al,7bh  
jz pressac\_alarm  
cmp al,77h  
jz press\_enter\_alarm

```

        mov [si],al
        CALL asterisk
        inc si
        dec cx
        jnz enter_14bit
disp_enteralarm:
        call keypad_input
        cmp al,7eh
        jz pressc_alarm
        cmp al,7bh
        jz pressac_alarm
        cmp al,77h
        jz press_enter_alarm
asd2:   CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h
        jz press_enter_alarm
        jnz asd2
nop_alarm: nop
        jmp enter_14bit
pressc_alarm:
        call clear_1digit_LCD
        dec si
        inc cx
        jmp enter_14bit
pressac_alarm:
        call clear_LCD
        mov cx,14
        mov si,3ah                ;start of pass segment
        jmp enter_14bit
press_enter_alarm:
        CALL clear_LCD
        mov al,0fh
        out port_a2,al
        cmp cx,0
        jz cmp_pass_alarm

```

```

                jnz x56
cmp_pass_alarm:
                cld
                mov si,10h
                mov di,3ah
                mov cx,14
                repe cmpsb
                cmp cx,00h
                jnz x56
                mov al,0ffh
                out port_a2,al
                add dh,1h
x56:
ret
intn endp

```

intu proc

```

                call clear_LCD
                mov dl,1

```

;flag for checking two inputs

```

                mov al,0feh
                out port_a2,al
                mov cx,12
                mov si,48h

```

;store the 12-bit entered pass

after the hard coded pass word  
enter\_12bitu:

```

                call keypad_input
                cmp al,7eh
                jz pressc_user
                cmp al,7bh
                jz pressac_user
                cmp al,0bbh
                jz nop_user
                cmp al,0b7h
                jz nop_user

```

```

        cmp al,7dh
        jz nop_user
        cmp al,77h
        jz press_enter_user
        mov [si],al
        CALL asterisk
        inc si
        dec cx
        jnz enter_12bitu
disp_enter_user:
        call keypad_input
        cmp al,7eh
        jz pressc_user
        cmp al,7bh
        jz pressac_user
        cmp al,77h
        jz press_enter_user
asd3:   CALL clear_LCD
        CALL enter_LCD
        call keypad_input
        cmp al,77h
        jz press_enter_user
        jnz asd3
nop_user:
        nop
        jmp enter_12bitu
pressc_user:
        call clear_1digit_LCD
        dec si
        inc cx
        jmp enter_12bitu
pressac_user:
        call clear_LCD
        mov cx,12
        mov si,48h
        jmp enter_12bitu
press_enter_user:

```

;start of pass segment

```
    mov al,0ffh
    out port_a2,al
    cmp cx,0
    jz cmp_pass_user
    jnz wrong_pass
```

```
cmp_pass_user:
    cld
    mov si,2eh
    mov di,48h
    mov cx,12
    repe cmpsb
    cmp cx,00h
    jnz wrong_pass
    jz open_door_user
```

```
wrong_pass :
    call clear_LCD
    mov si,48h
    mov cx,12
    cmp dl,0
    jz raise_alarm_user
    mov al,0fdh
    out port_a2,al
    call retry_msg
    call DELAY_max
    call DELAY_max
    call clear_LCD
    mov cx,12
    dec dl
    jmp enter_12bitu
```

```
raise_alarm_user:
    mov dh,0
    mov al,0fh
    out port_a2,al
    mov ax,0abcdh
    jmp end_70h
```

```
open_door_user:
    call open_door
```

```
end_70h:
```

```
ret
```

```
intu endp
```

```
ints proc
```

```
    call open_door
```

```
    ; CALL DELAY_0.04s
```

```
    ; mov al,00h
```

```
    ; out port_c2, al
```

```
ret
```

```
ints endp
```

```
open_door proc
```

```
    call clear_LCD
```

```
    mov al,8ah
```

```
    out port_b2,al
```

```
    call DELAY_20ms
```

```
    mov al,0ah
```

```
    out port_b2,al
```

```
x31:    in al, port_c2
```

```
    cmp al,0ffh
```

```
    jnz x31
```

```
    call DELAY_20ms
```

```
    call close_door
```

```
ret
```

```
open_door endp
```

```
close_door proc
```

```
    mov al,03h
```

```
    out port_b2,al
```



```
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max  
call DELAY_max
```

```
ret  
close_door endp
```

```
welcome_msg proc  
    mov al,0A0h  
    out port_a1,al  
    call DELAY_20ms  
    mov al,05h  
    out port_b1,al  
    call DELAY_20ms  
    mov al,01h  
    out port_b1,al ;prints Space  
  
    mov al,0A0h
```

```
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,57h
out port_a1,al
```

```
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints W
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,4Ch
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints L
```

```
mov al,43h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints C
```

```
mov al,4Fh
out port_a1,al
call DELAY_20ms
```

```
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints O
```

```
mov al,4dh
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints M
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
ret
welcome_msg endp
```

```
update_msg proc
    mov al,55h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints U
```

```
mov al,50h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints P
```

```
mov al,44h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints D
```

```
mov al,41h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints A
```

```
mov al,54h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints T
```

```
mov al,45h
```

```
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,50h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints P
```

```
mov al,41h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints A
```

```
mov al,53h
out port_a1,al
```

```
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints S
```

```
mov al,53h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints S
```

```
mov al,57h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints W
```

```
mov al,4Fh
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints O
```

```
mov al,52h
out port_a1,al
call DELAY_20ms
```

```
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints R
```

```
mov al,44h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints D
```

```
ret
update_msg endp
```

```
clear_1digit_LCD proc
    mov al,00h
    out port_b1,al
    call DELAY_20ms
    mov al,10h                ;shift left by 1
    out port_a1,al
    call DELAY_20ms
    mov al,04h
    out port_b1,al
    call DELAY_20ms
    mov al,00h
    out port_b1,al

    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
```



```
mov al,01h
out port_b1,al           ;prints Space
```

```
call DELAY_20ms
mov al,10h              ;shift left by 1
out port_a1,al
call DELAY_20ms
mov al,04h
out port_b1,al
call DELAY_20ms
mov al,00h
out port_b1,al
```

```
RET
clear_1digit_LCD endp
```

```
error_msg proc
    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints Space
```

```
    mov al,45h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints E
```

```
    mov al,4Eh
    out port_a1,al
```

```
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints N
```

```
mov al,54h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints T
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,52h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints R
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
```

```
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,31h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints 1
```

```
mov al,32h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints 2
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,44h
out port_a1,al
call DELAY_20ms
mov al,05h
```

```
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints D
```

```
mov al,49h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints I
```

```
mov al,47h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints G
```

```
mov al,49h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints I
```

```
mov al,54h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
```

```
call DELAY_20ms
mov al,01h
out port_b1,al ;prints T
```

```
mov al,53h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints S
```

```
RET
```

```
error_msg endp
```

```
retry_msg proc
    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints Space
```

```
    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints Space
```

```
    mov al,0A0h
    out port_a1,al
    call DELAY_20ms
```

```
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,0A0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,52h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints R
```

```
mov al,45h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,54h
out port_a1,al
call DELAY_20ms
mov al,05h
```

```
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints T
```

```
mov al,52h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints R
```

```
mov al,59h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Y
```

```
ret
retry_msg endp
```

```
updateday_msg proc
    mov al,55h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints U
```

```
mov al,50h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints P
```

```
mov al,44h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints D
```

```
mov al,41h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints A
```

```
mov al,54h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints T
```

```
mov al,45h
```



```
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints E
```

```
mov al,0a0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,44h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints D
```

```
mov al,41h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints A
```

```
mov al,59h
out port_a1,al
```

```
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Y
```

```
mov al,0a0h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints Space
```

```
mov al,50h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints P
```

```
mov al,41h
out port_a1,al
call DELAY_20ms
mov al,05h
out port_b1,al
call DELAY_20ms
mov al,01h
out port_b1,al ;prints A
```

```
mov al,53h
out port_a1,al
call DELAY_20ms
```

```
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints S
```

```
    mov al,53h
    out port_a1,al
    call DELAY_20ms
    mov al,05h
    out port_b1,al
    call DELAY_20ms
    mov al,01h
    out port_b1,al ;prints S
```

```
ret
```

```
updateday_msg endp
```

```
Nmi_24hrtimer:
```

```
    call clear_LCD
    call clear_1digit_LCD
    call updateday_msg
```

```
startnmi:
```

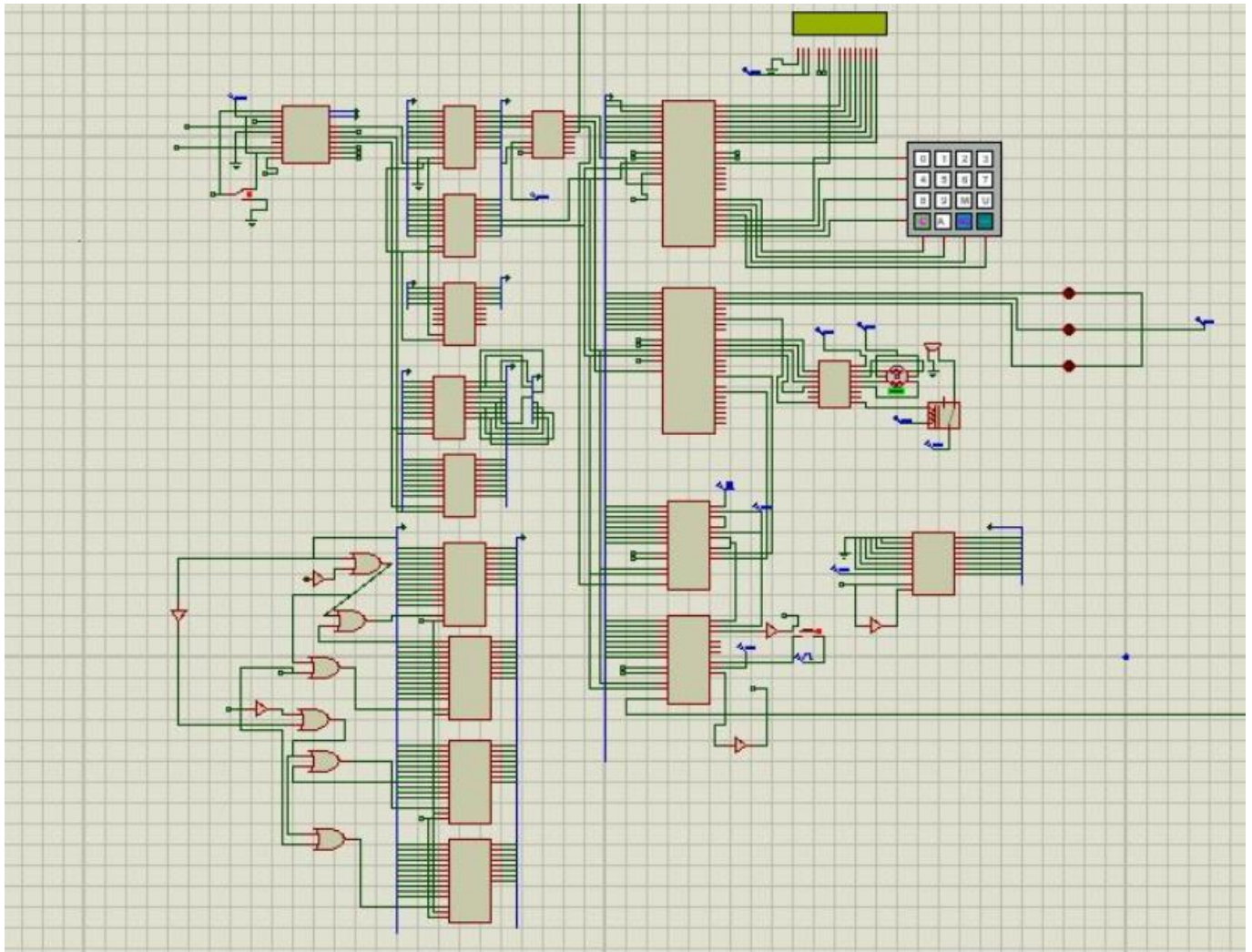
```
    call keypad_input
    cmp al,0bbh; Check for 'M'
    jz master_Mode
    jmp startnmi
```

```
iret
```

```
Switch_intR:
```

```
    call open_door
    sti
    cmp bp,0abcdh
    jz x6
    jnz start
```

## Complete Circuit Diagram



## References

- A 16x2 LCD display has been used. Following links were referred to understand its working:

<http://www.alldatasheet.com/view.jsp?Searchword=LMO16L>

<http://www.sakshieducation.com/Engineering/Story.aspx?cid=12&nid=96054>

- A 4x4 hex keypad has also been used.

<http://www.futurlec.com/Keypad4x4.shtml>

- A stepper motor and a Darlington transistor has been used.

<https://www.youtube.com/watch?v=8aLkXsh1O44>

<https://www.engineersgarage.com/electronic-components/uln2003-datasheet>