CS754 Assignment-3

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Declaration: The work submitted is our own, and we have adhered to the principles of academic honesty while completing and submitting this work. We have not referred to any unauthorized sources, and we have not used generative AI tools for the work submitted here.

Question 2

Solution

0.1 Linear System Representation

The coded snapshot equation $E = \sum_{t=1}^{T} \mathbf{C}_t \odot \mathbf{F}_t$ can be rewritten as the linear system:

$$Ax = b$$

where:

1. \mathbf{x} is the **vectorized unknown video sequence**, formed by stacking the vectorized frames \mathbf{F}_t :

$$\mathbf{x} = egin{bmatrix} \mathrm{vec}(\mathbf{F}_1) \ \mathrm{vec}(\mathbf{F}_2) \ dots \ \mathrm{vec}(\mathbf{F}_T) \end{bmatrix} \in \mathbb{R}^{HWT imes 1}.$$

2. **b** is the **vectorized coded snapshot**:

$$\mathbf{b} = \operatorname{vec}(E) \in \mathbb{R}^{HW \times 1}.$$

3. **A** is the **measurement matrix** encoding the modulation by C_t . It is a block-diagonal matrix with horizontally concatenated diagonal matrices:

$$\mathbf{A} = \begin{bmatrix} \text{diag}(\text{vec}(\mathbf{C}_1)) & \text{diag}(\text{vec}(\mathbf{C}_2)) & \cdots & \text{diag}(\text{vec}(\mathbf{C}_T)) \end{bmatrix} \in \mathbb{R}^{HW \times HWT}.$$

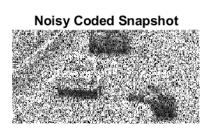
Each block diag($vec(\mathbf{C}_t)$) is a diagonal matrix whose entries are the vectorized binary code \mathbf{C}_t for frame t.







Figure 1: Original Frames for T = 3



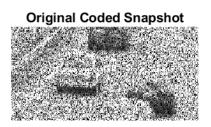


Figure 2: Encoded Snapshot for T = 3

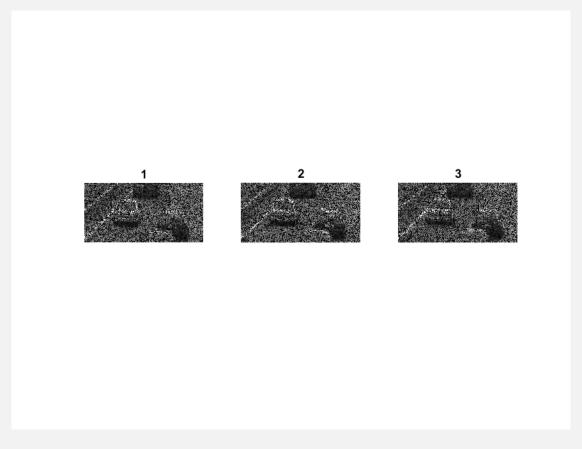


Figure 3: Reconstructed Frames for T = 3

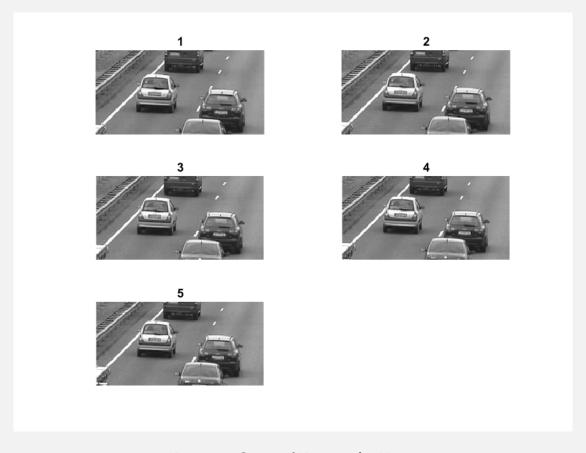


Figure 4: Original Frames for T = 5

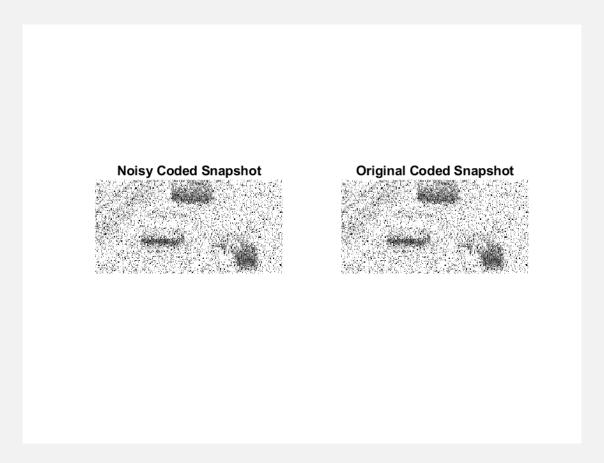


Figure 5: Encoded Snapshot for T = 5

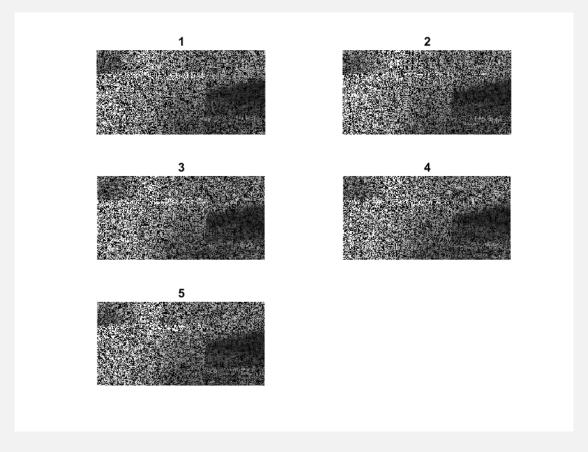


Figure 6: Reconstructed Frames for T = 5

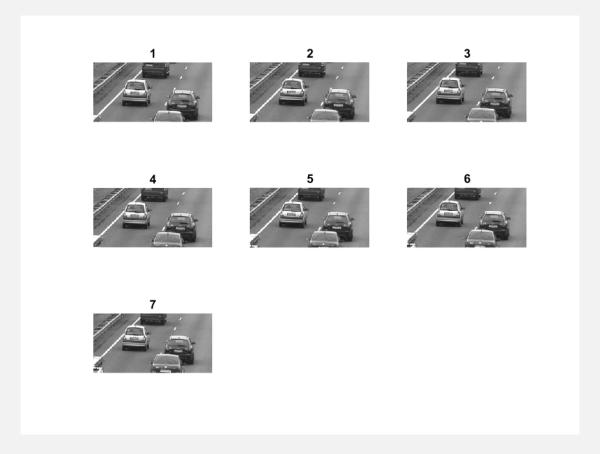


Figure 7: Original Frames for T = 7

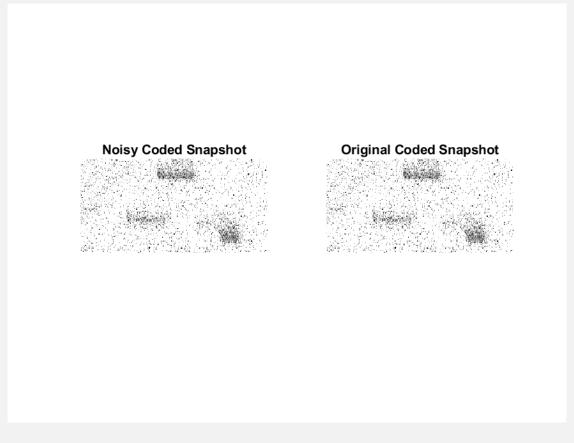


Figure 8: Encoded Snapshot for T = 7

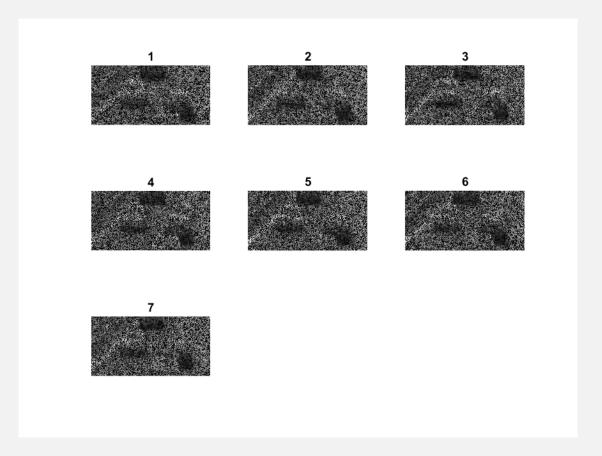
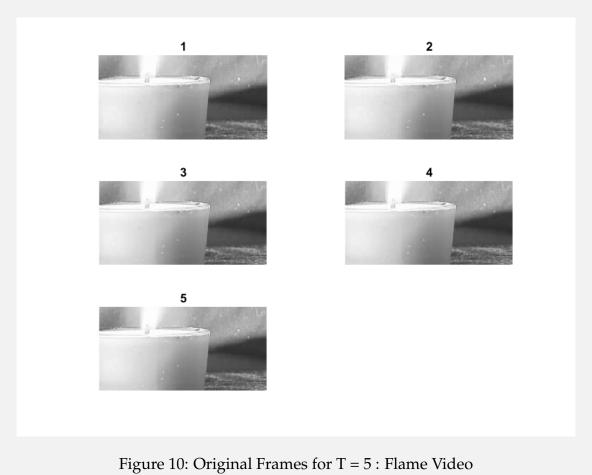


Figure 9: Reconstructed Frames for T = 7



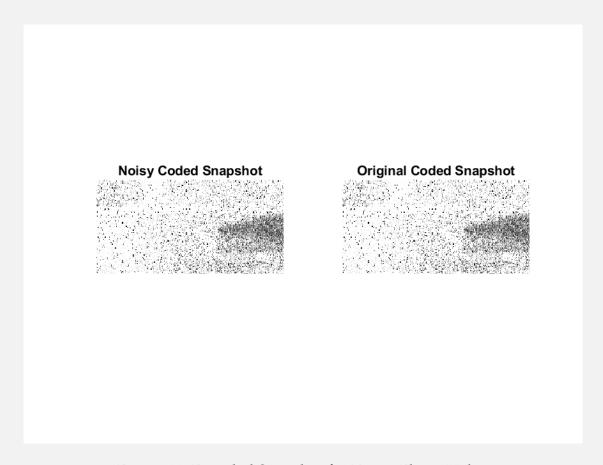


Figure 11: Encoded Snapshot for T = 5: Flame Video