# CS726 - Advanced Machine Learning Programming Assignment 1

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#### 1 Triangulation

This step is implemented in the function triangulate\_and\_get\_cliques. We first check if the graph is already triangulated, using the function whether\_triangulated described below:

#### Algorithm 1 Check if Graph is already Triangulated

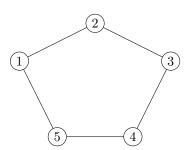
```
1: cycles \leftarrow Find all cycles in graph
2: for each cycle in cycles do
      if length of cycle \geq 4 then
3:
         if there is no shortcut (vertices connected by non-cycle edge) then
4:
5:
             return False
6:
          end if
      end if
8: end for
9: return True
```

If the graph is already triangulated, we directly proceed with extracting the maximal cliques. If the graph is not triangulated, we first triangulate it using the minimum degree heuristic, as described in the pseudocode below:

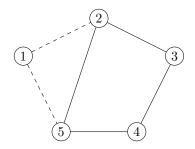
#### Algorithm 2 Triangulation Process

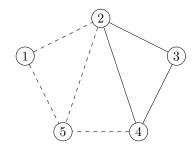
```
1: vertices_left ← Set of all vertices
2: while vertices_left is not empty do
      vertex ← Vertex in vertices_left with minimum degree
4:
      for each pair (i, j) of neighbours of vertex do
          if the graph does not contain an edge between i and j then
5:
             Add edge (i, j) to the original graph
6:
          end if
7:
      end for
8:
9:
      Remove vertex from vertices_left
      Update graph by removing vertex and updating degrees and edges
10:
11: end while
```

The figure below shows the run of the triangulation algorithm on an example graph:

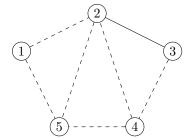


Step 1: Initial Graph

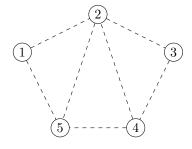




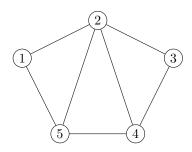
Step 2: Select 1, add (5,2), remove 1 Step 3: Select 5, add (4,2), remove 5



Step 4: Select 4, remove 4



Step 5: Select 2, remove 2



Final Triangulated Graph

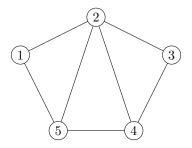
Once we obtain the triangulated graph, we extract the maximal cliques from it using the function get\_maximal\_cliques, which uses the Bron-Kerbosch algorithm described below:

#### Algorithm 3 Bron-Kerbosch Algorithm for Finding Maximal Cliques

```
1: procedure Bron_Kerbosch(current_clique, candidates, excluded, maximal_cliques)
       if candidates is empty and excluded is empty then
3:
          Add current_clique to maximal_cliques
4:
          return
       end if
5:
6:
       for each vertex v in candidates do
7:
          Bron_Kerbosch(current\_clique \cup \{v\},
                  candidates \cap Neighbors(v),
8:
                  excluded \cap Neighbors(v),
9:
                 maximal_cliques)
10:
          Remove v from candidates
11:
          Add v to excluded
12:
       end for
13:
14: end procedure
```

#### 2 Junction Tree Construction

This step is implemented in the get\_junction\_tree function. We use the maximal cliques obtained after the triangulation process to create the junction tree while maintaining the running intersection property. Each clique in this tree retains its assigned potential values. Consider the given triangulated graph:



Final Triangulated Graph

From the triangulated graph, we obtain the maximal cliques:

$$C_1 = \{1, 2, 5\}, \quad C_2 = \{2, 3, 4\}, \quad C_3 = \{2, 4, 5\},$$

The intersection sets are as follows:

$$C_1 \cap C_3 = \{2, 5\}, \quad |C_1 \cap C_3| = 2$$
  
 $C_1 \cap C_2 = \{2\}, \quad |C_1 \cap C_2| = 1$   
 $C_3 \cap C_2 = \{2, 4\}, \quad |C_3 \cap C_2| = 2$ 

We construct edges with weights corresponding to intersection sizes:

$$(C_1, C_3, 2), (C_3, C_2, 2), (C_1, C_2, 1)$$

Using Kruskal's algorithm:

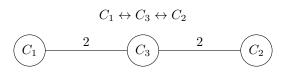
- 1. Sort edges:  $(C_1, C_3, 2), (C_3, C_2, 2), (C_1, C_2, 1).$
- 2. Add  $(C_1, C_3)$  (weight 2).
- 3. Add  $(C_3, C_2)$  (weight 2).

#### Algorithm 4 Constructing a Junction Tree from Maximal Cliques

```
Require: Set of maximal cliques C
Ensure: Junction tree satisfying the running intersection property
 1: Initialize an empty priority queue T
 2: for all pairs (C_1, C_2) in \mathcal{C} do
        Compute the intersection set S = C_1 \cap C_2
 4:
        if S \neq \emptyset then
            Compute weight w = |S|
 5:
           Push (-w, C_1, C_2) onto T (negative weight for max heap)
 6:
 7:
 8: end for
 9:
10: Initialize parent[C] = C and rank[C] = 0 for all C \in \mathcal{C}
11:
12: function FINDPARENT(C)
        if parent[C] \neq C then
13:
14:
           parent[C] \leftarrow FindParent(parent[C])
        end if
15:
        return parent[C]
16:
17: end function
18:
19:
    function Union(C_1, C_2)
        root_1 \leftarrow \text{FindParent}(C_1)
20:
        root_2 \leftarrow \text{FindParent}(C_2)
21:
        if root_1 \neq root_2 then
22:
23:
           if rank[root_1] > rank[root_2] then
               parent[root_2] \leftarrow root_1
24:
            else if rank[root_2] > rank[root_1] then
25:
               parent[root_1] \leftarrow root_2
26:
           else
27:
               parent[root_2] \leftarrow root_1
28:
29:
               rank[root_1] \leftarrow rank[root_1] + 1
30:
            end if
           return True
31:
        end if
32:
        return False
33:
    end function
34:
36: Initialize an empty set MST (Minimum Spanning Tree)
37: while T is not empty do
        Pop (w, C_1, C_2) from T
38:
        if UNION(C_1, C_2) then
39:
            Add edge (C_1, C_2) to MST
40:
        end if
41:
42: end while
43: return MST
```

4. Ignore  $(C_1, C_2)$  (weight 1) as it would form a cycle.

#### Final Junction Tree:



For any two cliques  $C_i$  and  $C_j$  containing the same variable X, all cliques along the unique path in the tree must contain X. This holds for all intersections.

## 3 Marginal Probability

Here is the pseudocode for sharing messages between the maximal cliques of the graph.

Firstly, we show how to calculate the Z value for the given graph.

#### **Algorithm 5** Computation of Partition Function Z

```
1: Arbitrarily root junction tree at C_{root}
2: Initialize dicionary clique_depths
3: Perform DFS from C_{root} to populate clique_depths
4: function SendMessage(C_{from}, C_{to})
       Compute separator set S = C_{from} \cap C_{to}
       Initialize message vector M of size 2^{|S|}
6:
7:
       Modify clique potential based on incoming messages
       for each state assignment in C_{from} do
8:
9:
          Compute corresponding separator index
           Aggregate message value
10:
       end for
11:
       Store message M(C_{from} \to C_{to})
12:
   end function
   for each clique from deepest to root do
       Send messages to parent cliques
15:
   end for
16:
   for each clique from root to leaves do
17:
       Send messages to child cliques
19: end for
20: Compute partition function Z using root clique potential and received messages
21: return Z
```

Here is the pseudocode for computing the marginal probabilities in the graphical model using message passing.

### ${\bf Algorithm~6~Computation~of~Marginal~Probabilities}$

```
1: Initialize adjacency list for junction tree
2: Retrieve partition function Z using previously computed values
3: Initialize marginal probability list M with zeros
4: for each variable X_i in the graphical model do
       Find a maximal clique C containing X_i
5:
       Extract the potential function for clique C
6:
       for each neighboring clique C' of C do
7:
           Compute separator set S = C \cap C'
8:
          Retrieve message M(C' \to C)
9:
          for each assignment in C do
10:
              Identify corresponding index in S
11:
12:
              Multiply message values with clique potential
          end for
13:
14:
       end for
       Compute marginal probability for X_i
15:
       Normalize values using Z
16:
17: end for
18: \mathbf{return}\ M
```