CS726 Programming Assignment – 2 Report

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Denoising Diffusion Probabilistic Models

Here are the results of unconditional DDPMs on various datasets (with respect to the number of time steps). We had fixed all other parameters (the best settings observed):

- lbeta=0.0001
- ubeta=0.02
- lr=0.0001 (so that training loss decreases across epochs)
- n_samples=10000
- $n_dim=2$ (for helix it is 3)
- batch_size=128 (to avoid CUDA memory errors and optimal results)
- epochs=40

Moons

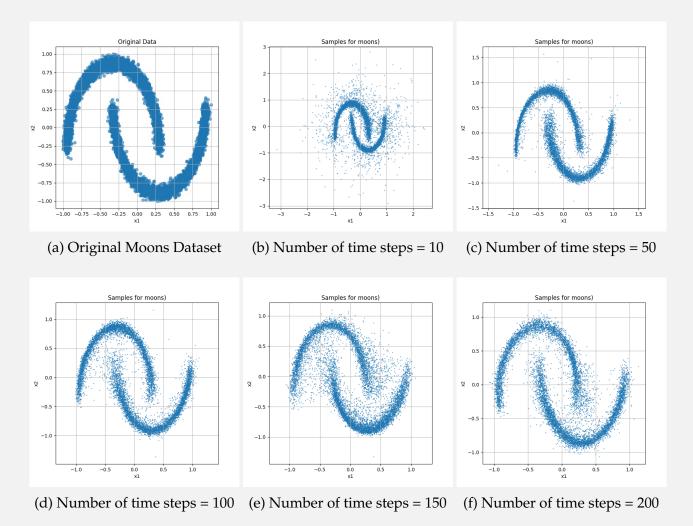


Figure 1: Moons Dataset

Here are the NLL values:

• *T* = 10: 1.048

• T = 50: 0.9599

• T = 100: 0.9519

• *T* = 150: 0.9218

• T = 200: 0.9321

As, we can see from both NLL values and the images, T = 150 performed the best.

Blobs

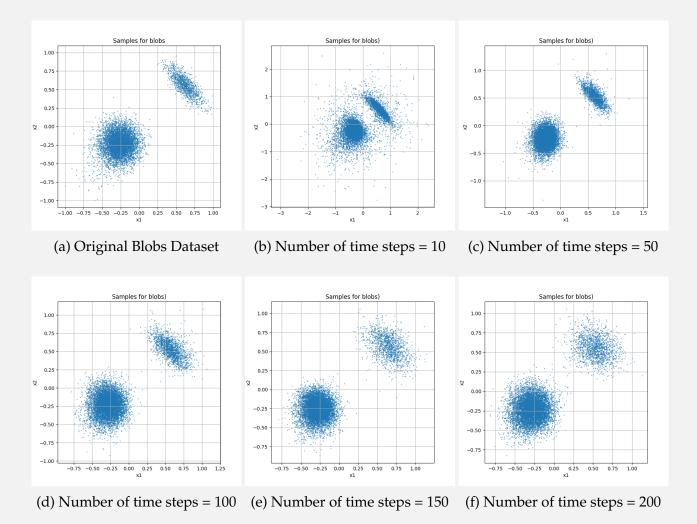


Figure 2: Blobs Dataset

Here are the NLL values:

• T = 10: 0.37

• *T* = 50: 0.0152

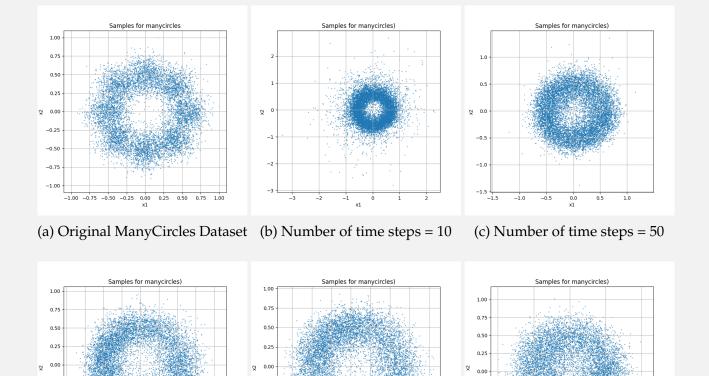
• T = 100: 0.0232

• T = 150: -0.0223

• T = 200: 0.0045

As, we can see from both NLL values and the images, T=150 performed the best. Moreover, there is a sudden decrease in NLL from 10 to 50, which shows the significant impact of increasing the number of time steps.

Many-Circles



(d) Number of time steps = 100

0.25 0.50 0.75 1.00

(e) Number of time steps = 150

0.25 0.50 0.75

-0.75 -0.50 -0.25 0.00

-0.25

(f) Number of time steps = 200

Figure 3: Many Circles Dataset

Here are the NLL values:

-1.00 -0.75 -0.50 -0.25 0.00

• T = 10: 0.75

• *T* = 50: 0.548

• T = 100: 0.545

• T = 150: 0.558

• T = 200: 0.522

As, we can see from both NLL values and the images, T = 200 performed the best.

Circles

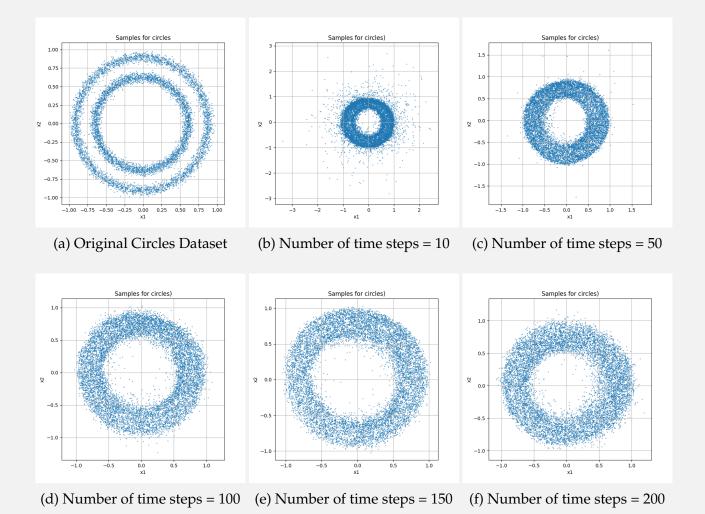
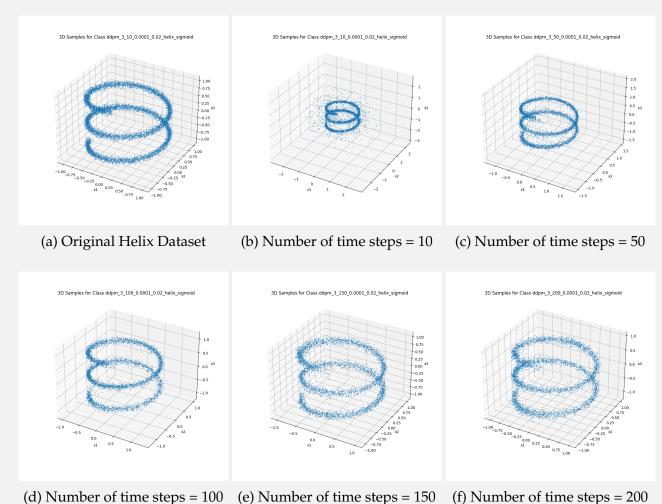


Figure 4: Circles Dataset

Here are the NLL values:

- *T* = 10: 1.081
- T = 50: 0.991
- *T* = 100: 0.9869
- *T* = 150: 1.004
- *T* = 200: 0.992

Helix



(e) Number of time steps = 150

(f) Number of time steps = 200

Figure 5: Helix Dataset

Here are the NLL values:

• *T* = 10: 1.6179

• *T* = 50: 1.514

• *T* = 100: 1.5198

• *T* = 150: 1.528

• *T* = 200: 1.528

As we can see from the images (and the NLL values), 50 performs the best.

Classifier-Free Guidance

Reward Guidance