

# CS726 Programming Assignment – 2 Report

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## Denoising Diffusion Probabilistic Models

Here are the results of unconditional DDPMs on various datasets (with respect to the number of time steps). We had fixed all other parameters (the best settings observed):

- `lbeta=0.0001`
- `ubeta=0.02`
- `lr=0.0001` (so that training loss decreases across epochs)
- `n_samples=10000`
- `n_dim=2` (for helix it is 3)
- `batch_size=128` (to avoid CUDA memory errors and optimal results)
- `epochs=40`

## Moons

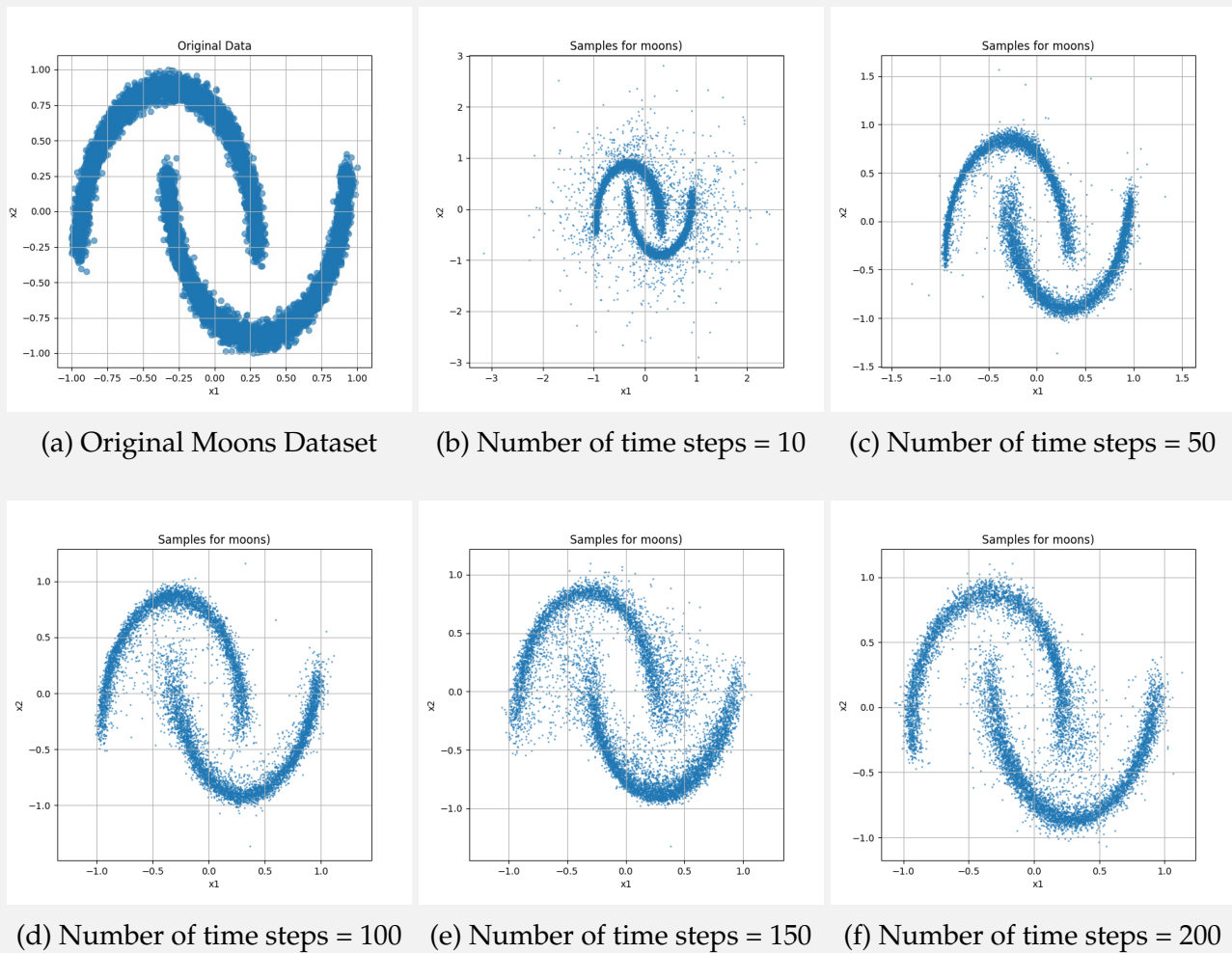


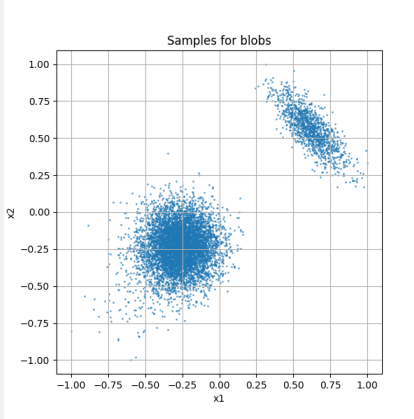
Figure 1: Moons Dataset

Here are the NLL values:

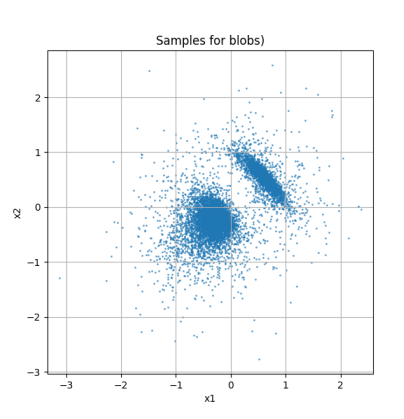
- $T = 10$ : 1.048
- $T = 50$ : 0.9599
- $T = 100$ : 0.9519
- $T = 150$ : 0.9218
- $T = 200$ : 0.9321

As, we can see from both NLL values and the images,  $T = 150$  performed the best.

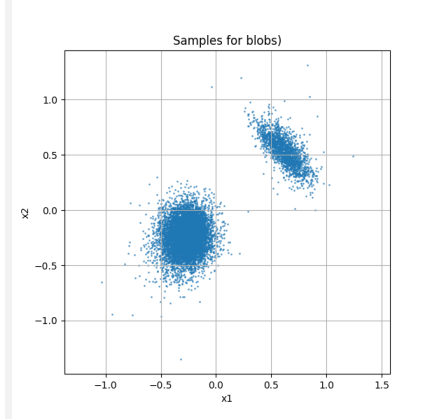
## Blobs



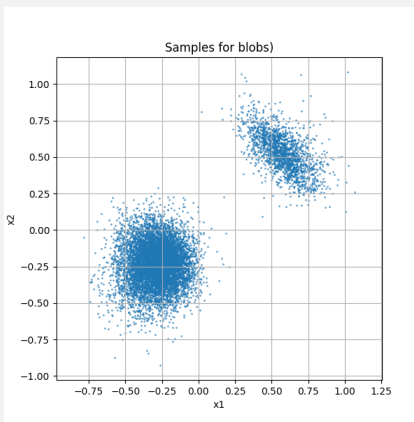
(a) Original Blobs Dataset



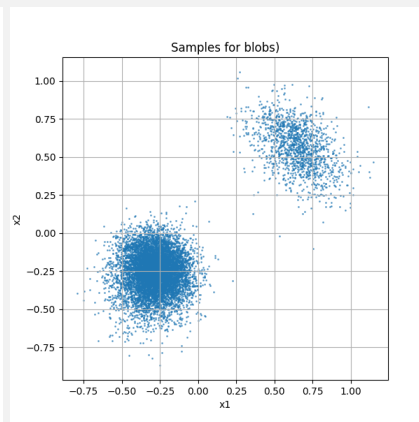
(b) Number of time steps = 10



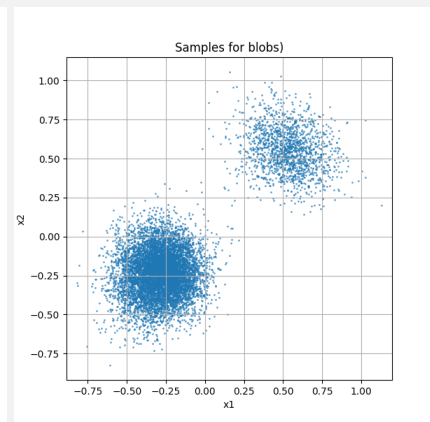
(c) Number of time steps = 50



(d) Number of time steps = 100



(e) Number of time steps = 150



(f) Number of time steps = 200

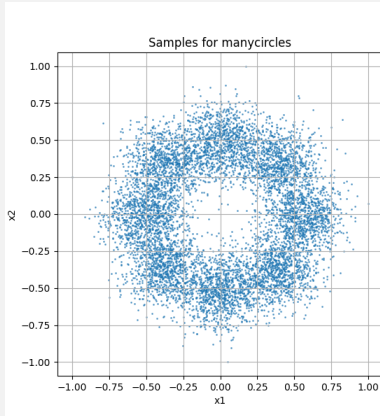
Figure 2: Blobs Dataset

Here are the NLL values:

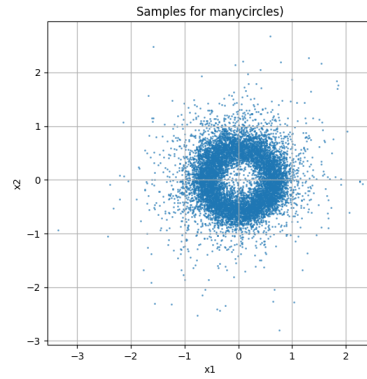
- $T = 10$ : 0.37
- $T = 50$ : 0.0152
- $T = 100$ : 0.0232
- $T = 150$ : -0.0223
- $T = 200$ : 0.0045

As, we can see from both NLL values and the images,  $T = 150$  performed the best. Moreover, there is a sudden decrease in NLL from 10 to 50, which shows the significant impact of increasing the number of time steps.

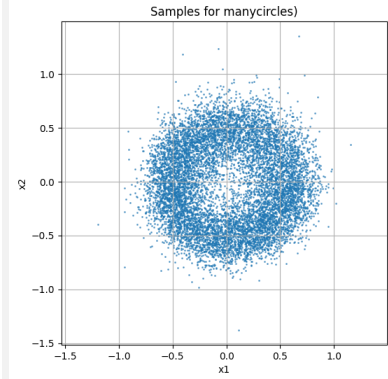
## Many-Circles



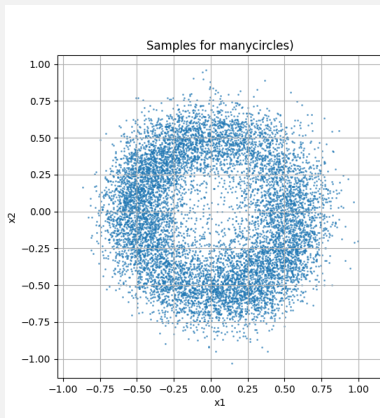
(a) Original ManyCircles Dataset



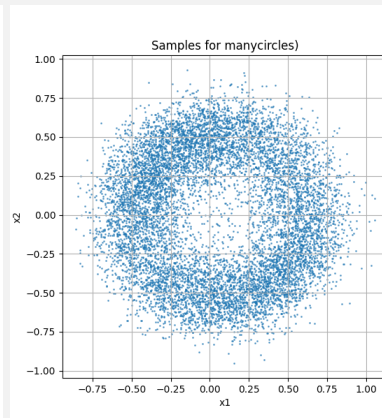
(b) Number of time steps = 10



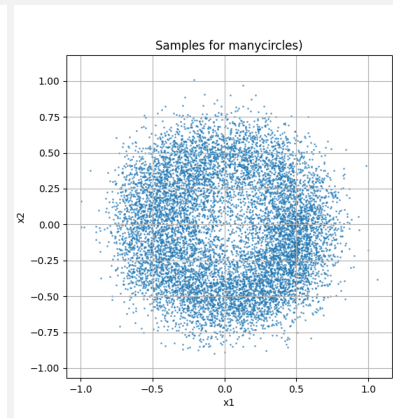
(c) Number of time steps = 50



(d) Number of time steps = 100



(e) Number of time steps = 150



(f) Number of time steps = 200

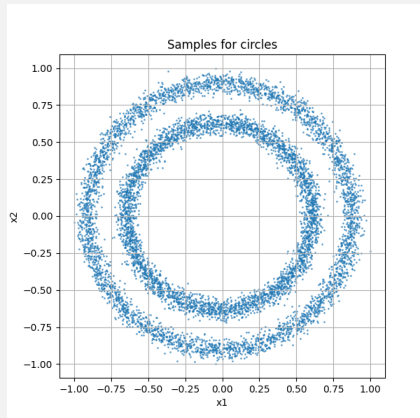
Figure 3: Many Circles Dataset

Here are the NLL values:

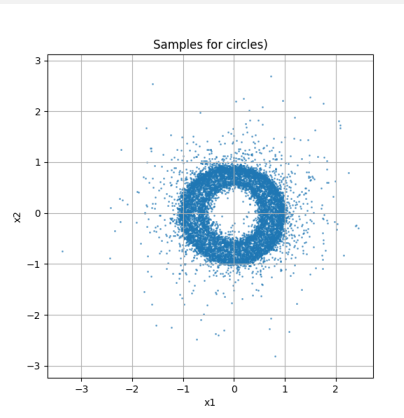
- $T = 10$ : 0.75
- $T = 50$ : 0.548
- $T = 100$ : 0.545
- $T = 150$ : 0.558
- $T = 200$ : 0.522

As, we can see from both NLL values and the images,  $T = 200$  performed the best.

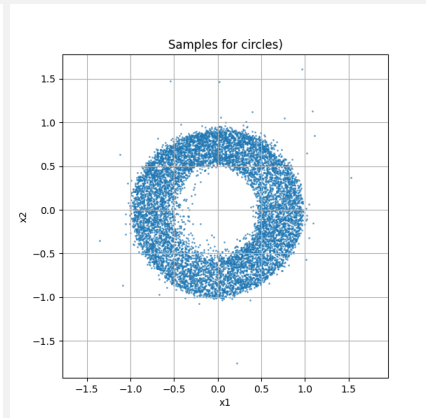
## Circles



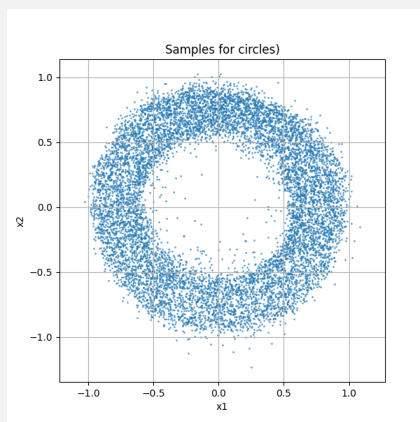
(a) Original Circles Dataset



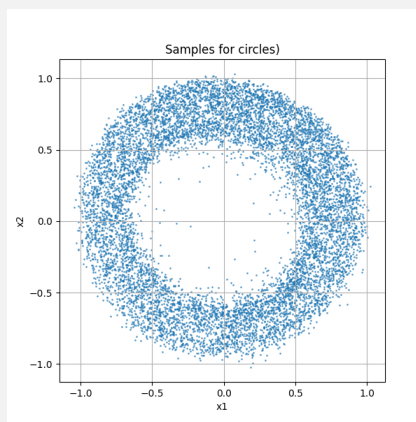
(b) Number of time steps = 10



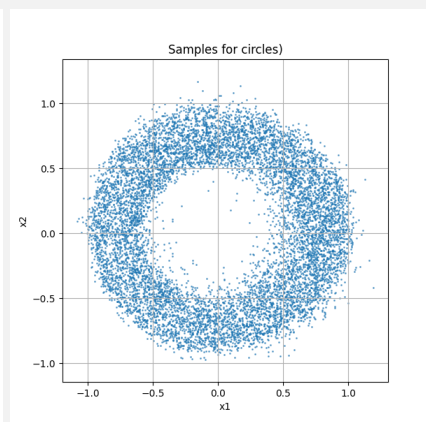
(c) Number of time steps = 50



(d) Number of time steps = 100



(e) Number of time steps = 150



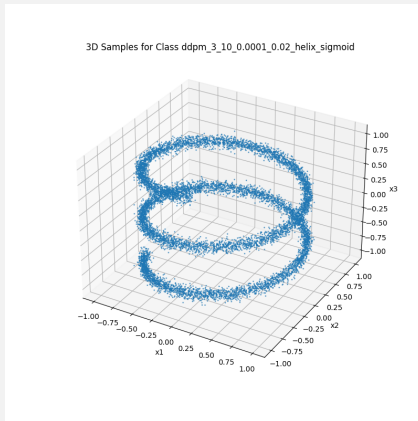
(f) Number of time steps = 200

Figure 4: Circles Dataset

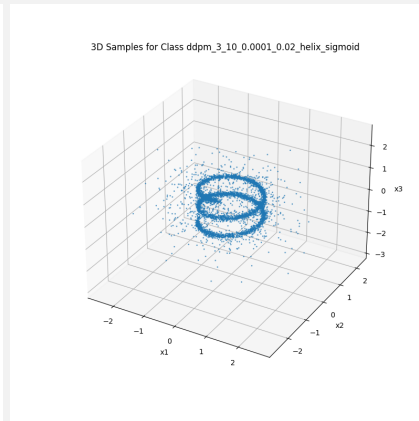
Here are the NLL values:

- $T = 10$ : 1.081
- $T = 50$ : 0.991
- $T = 100$ : 0.9869
- $T = 150$ : 1.004
- $T = 200$ : 0.992

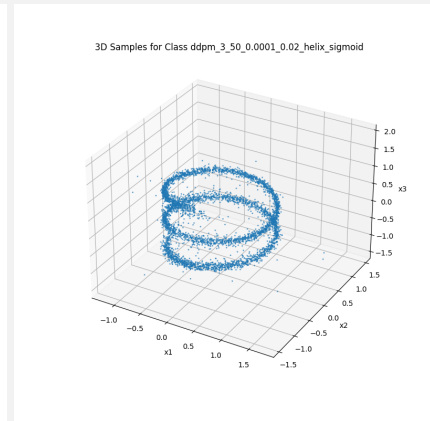
## Helix



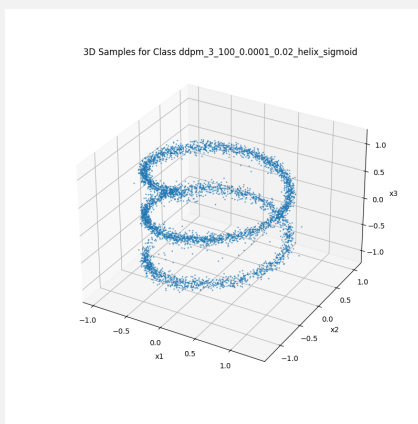
(a) Original Helix Dataset



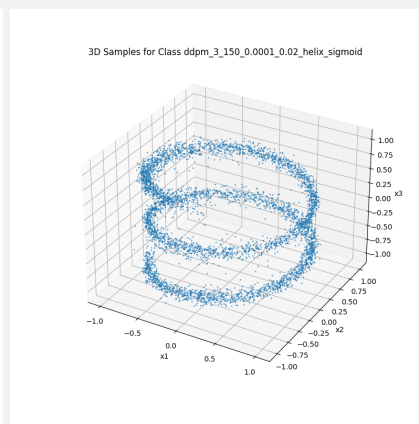
(b) Number of time steps = 10



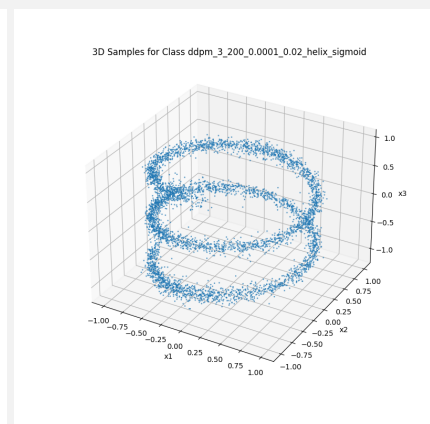
(c) Number of time steps = 50



(d) Number of time steps = 100



(e) Number of time steps = 150



(f) Number of time steps = 200

Figure 5: Helix Dataset

Here are the NLL values:

- $T = 10$ : 1.6179
- $T = 50$ : 1.514
- $T = 100$ : 1.5198
- $T = 150$ : 1.528
- $T = 200$ : 1.528

As we can see from the images (and the NLL values), 50 performs the best.

## Classifier-Free Guidance

### Difference between Guided Sampling and Conditional Sampling

In conditional sampling, we model  $p(x|y)$  directly, where  $y$  is a conditioning variable (like a class label). During generation, we sample from this conditional distribution to get samples that match the condition.

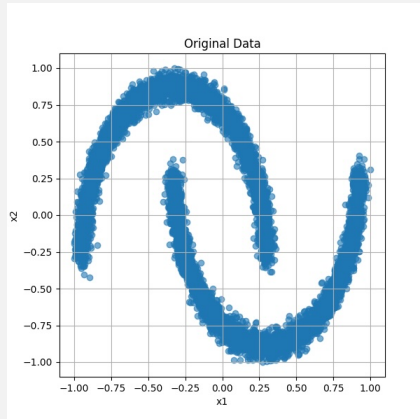
In guided sampling (specifically classifier-free guidance), we train two models: one conditional  $p(x|y)$  and one unconditional  $p(x)$ . During sampling, we interpolate between them with a guidance scale  $w$ :

$$\epsilon_{\theta}(x_t, t, y) = (1 + w) * \epsilon_{\theta}(x_t, t, y) - w * \epsilon_{\theta}(x_t, t)$$

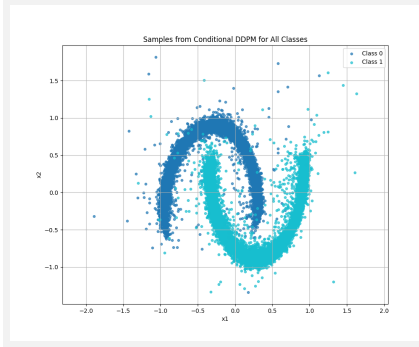
Firstly, guided sampling is more expensive in terms of computation required to train and sample points (almost double, since we are training two models, and using both of them to sample points). However, this guidance increases the impact of the conditioning information and can produce higher quality samples that better match the condition, but with a potential loss of diversity.

### Effect of guidance scale

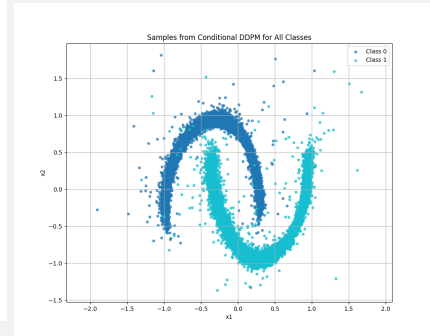
We sampled points using CFG on a variety of guidance scale values, here are the images from the moon dataset:



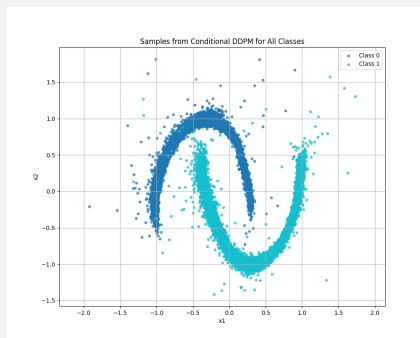
(a) Original Moons Dataset



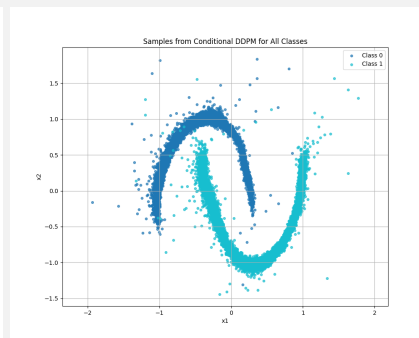
(b) Guidance Scale = 0 (Equivalent to Conditional Sampling)



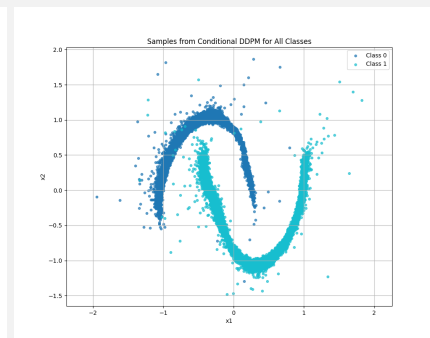
(c) Guidance Scale = 0.2



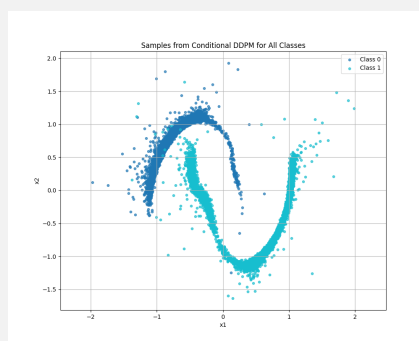
(d) Guidance Scale = 0.5



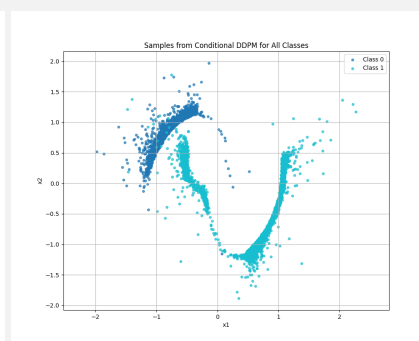
(e) Guidance Scale = 0.7



(f) Guidance Scale = 1.0



(g) Guidance Scale = 2.0



(h) Guidance Scale = 4.0

Figure 6: Moons - CFG



## Reward Guidance