

CS663 Assignment-5

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Question 5

Part (a)

We prove this via a contradiction. Consider an example where $N = 2$ and both P_1 and P_2 are square matrices.

Let $P_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ and $P_1 = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$.

The least square solution gives

$$\begin{aligned} R &= P_1 P_2^T (P_2 P_2^T)^{-1} \\ &= P_1 I^T (I I^T)^{-1} \\ &= P_1 \end{aligned}$$

It was given that R is an orthonormal matrix. Clearly P_1 is not orthonormal and hence $R = P_1$ is not a valid solution. Therefore using the least squares method does not give the right answer as it does not always give a solution which is orthonormal.

Part (b)

The objective is to find the orthonormal matrix R that minimises the square of the Frobenius norm of the error matrix E which equals $P_1 - RP_2$.

$$\begin{aligned} E(R) &= \|P_1 - RP_2\|_F^2 \\ \Rightarrow E(R) &= \text{Trace}((P_1 - RP_2)^T (P_1 - RP_2)) \\ &= \text{Trace}(P_1^T P_1 - (RP_2)^T P_1 - P_1^T (RP_2) + (RP_2)^T (RP_2)) \\ &= \text{Trace}(P_1^T P_1 - P_2^T R^T P_1 - P_1^T R P_2 + P_2^T R^T (R P_2)) \\ &= \text{Trace}(P_1^T P_1 + P_2^T R^T R P_2 - P_2^T R^T P_1 - P_1^T R P_2) \\ &= \text{Trace}(P_1^T P_1 + P_2^T P_2 - P_2^T R^T P_1 - P_1^T R P_2) \quad (R^T R = R R^T = I \text{ because } R \text{ is orthonormal}) \\ &= \text{Trace}(P_1^T P_1 + P_2^T P_2) - \text{Trace}(P_2^T R^T P_1) - \text{Trace}(P_1^T R P_2) \quad (\text{Because Trace is a linear operator}) \\ &= \text{Trace}(P_1^T P_1 + P_2^T P_2) - \text{Trace}((P_2^T R^T P_1)^T) - \text{Trace}(P_1^T R P_2) \quad (\text{Trace}(A) = \text{Trace}(A^T) \text{ for any square matrix } A) \\ &= \text{Trace}(P_1^T P_1 + P_2^T P_2) - \text{Trace}(P_1^T R P_2) - \text{Trace}(P_1^T R P_2) \\ &= \text{Trace}(P_1^T P_1 + P_2^T P_2) - 2\text{Trace}(P_1^T R P_2) \end{aligned}$$

Part (c)

As shown in the previous part $E(R) = \text{Trace}(P_1^T P_1 + P_2^T P_2) - 2\text{Trace}(P_1^T R P_2)$. Clearly for given P_1 and P_2 , the first term is fixed. Therefore to minimise $E(R)$ wrt R , the term $-2\text{Trace}(P_1^T R P_2)$ should be minimised ie, $\text{Trace}(P_1^T R P_2)$ should be maximised wrt R .

Part (d)

Now the goal is to maximise $\text{Trace}(P_1^T R P_2)$ wrt R . We will first show that for any two matrices $A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^{n \times m}$, $\text{Trace}(AB) = \text{Trace}(BA)$.

$$\begin{aligned} \text{Trace}(AB) &= \sum_{i=1}^m C_{ii} \text{ (where } C = AB) \\ \Rightarrow \text{Trace}(AB) &= \sum_{i=1}^m \left(\sum_{j=1}^n A_{ij} B_{ji} \right) \end{aligned} \quad (1)$$

Similarly,

$$\begin{aligned} \text{Trace}(BA) &= \sum_{j=1}^n D_{jj} \text{ (where } D = BA) \\ \Rightarrow \text{Trace}(BA) &= \sum_{j=1}^n \left(\sum_{i=1}^m B_{ji} A_{ij} \right) \end{aligned} \quad (2)$$

Clearly, the two double summations in the RHS of equation 1 and equation 2 are equal and can be obtained by simply reordering the summations. Therefore we have

$$\text{Trace}(AB) = \text{Trace}(BA) \quad (3)$$

We will also use the fact that the SVD of a square matrix $M = USV^T$ exists with U, V being orthonormal matrices and S being a diagonal matrix.

$$\begin{aligned} \text{Trace}(P_1^T R P_2) &= \text{Trace}(R P_2 P_1^T) \text{ (from equation 3)} \\ &= \text{Trace}(R U' S' V'^T) \text{ (where } P_2 P_1^T = U' S' V'^T \text{ is the SVD of } P_2 P_1^T) \\ &= \text{Trace}(S' V'^T R U') \text{ (again using the result from equation 3)} \\ &= \text{Trace}(S' X) \text{ (where } X = V'^T R U' \text{ and } S' \text{ is a diagonal matrix)} \end{aligned}$$

Part (e)

Since maximising $\text{Trace}(P_1^T R P_2)$ is the same as maximising $\text{Trace}(S' X)$ where S' is a diagonal matrix and $X = V'^T R U'$, we only need to determine the matrix X such that $S'_{11} X_{11} + S'_{22} X_{22}$ is maximised where S'_{11} and S'_{22} are the singular values of $P_2 P_1^T$.

We will now show that X is also orthonormal.

$$\begin{aligned} XX^T &= (V'^T R U') \cdot (V'^T R U')^T \\ &= (V'^T R U') \cdot (U'^T R^T V') \\ &= V'^T R (U' \cdot U'^T) R^T V' \\ &= V'^T R I R^T V', \text{ (since } U, V \text{ are orthonormal)} \\ &= V'^T R R^T V' \\ &= V'^T I V' \text{ (since } R \text{ is orthonormal)} \\ &= V'^T V' \\ &= I \\ \Rightarrow XX^T &= X^T X = I \\ \Rightarrow X_{11} X_{11} + X_{12} X_{12} &= 1 \text{ \& } X_{11} X_{21} + X_{12} X_{22} = 0 \\ \Rightarrow X_{21} X_{11} + X_{22} X_{12} &= 0 \text{ \& } X_{21} X_{21} + X_{22} X_{22} = 1 \\ \Rightarrow X_{11}^2 + X_{12}^2 &= 1 \\ \Rightarrow X_{21}^2 + X_{22}^2 &= 1 \\ \Rightarrow X_{11} X_{21} + X_{12} X_{22} &= 0 \end{aligned}$$

Since all entries of X are real numbers, $0 \leq X_{ij} \leq 1 \forall i, j \in [1, 2]$. We need to maximise $S'_{11}X_{11} + S'_{22}X_{22}$ and since S'_{11} and S'_{22} are positive values, we only need to maximise the values of X_{11} and X_{22} . Since $X_{11} \leq 1$ and $X_{22} \leq 1$ the maximum values X_{11} and X_{22} can take are 1. Hence,

$$\text{Trace}(S'X) = X_{11}S'_{11} + X_{22}S'_{22} \leq ((1)S'_{11} + (1)S'_{22}) = S'_{11} + S'_{22}$$

Therefore the matrix X is,

$$X = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

since $x_{11}^2 + x_{12}^2 = 1$ and $X_{11} = 1 \Rightarrow X_{12} = 0$, similarly $X_{21} = 0$. Hence we get $X = I_2$ for maximum value of $\text{Trace}S'X$

Part (f)

Since $X = I_2$ and $X = V'^T R U'$, we get

$$\begin{aligned} V'^T R U' &= I \\ \Rightarrow V' V'^T R U' U'^T &= V' I U'^T \\ \Rightarrow I R I &= V' U'^T \text{ (since } V' \text{ and } U' \text{ are orthogonal matrices)} \\ \Rightarrow R &= V' U'^T \end{aligned}$$

If X is the identity matrix $R = V' U'^T$.

Part (g)

If R is also a rotation matrix then $R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ for some $\theta \in \mathbb{R}$. This gives $\det(R) = \cos^2 \theta + \sin^2 \theta = 1$. However if R is not a rotation matrix then $\det(R) = 1, -1$. So the additional constraint imposed is $\det(R) = 1$.