

# Sakshi Shah

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## EDUCATION

### Master of Science in Mechanical Engineering

North Carolina State University || CGPA 4/4

Aug 2023 – May 2025

Raleigh, United States

Relevant Courses: Vibrations, Design of Electromechanical Systems, Industrial Automation, Optimization, Advanced Dynamics

### Bachelor of Technology (B.Tech.) in Mechanical Engineering

MKSSS's Cummins College of Engineering for Women || CGPA 8.5/10

Aug 2017 – Jun 2021

Pune, Maharashtra, India

Relevant Courses: Engineering Mathematics, Rigid Body Dynamics, Automation and Control Engineering, Avionics, Numerical Methods

## SKILLS

**Modelling and Analysis:** SOLIDWORKS | AutoCAD | Autodesk Inventor | ANSYS (Mechanical, Electronics) | Creo

**Planning and Manufacturing:** SAP PLM | Excel VBA | Power Apps | PreForm | UltiMaker Cura | Sheet Metal

**Programming:** MATLAB | Simulink | Python | Connected Components Workbench | ROS | PostgreSQL

## PROJECTS

### Visual Servo Control Using a 7-Link Kinova Gen 3 Robot Arm

Jan 2025 – May 2025

- Developed a **closed-loop control** system to track dynamic objects in **real-time** using an **eye-in-hand** camera, leveraging **Simulink**, **ROS**, and **OpenCV**. Integrated **forward and inverse kinematics** to compute real-time joint trajectories and incorporated dynamic modeling for accurate motion prediction.
- **Designed and fabricated** custom **End-of-Arm Tooling (EOAT)** in SolidWorks to stabilize the ultrasound probe and support a monocular camera.
- Implemented real-time **image processing** and **control algorithms (PID, MPC)** using **MATLAB** and **GStreamer**, reducing system latency and enhancing tracking precision.

### System Integration and Control of an Autonomous Conveyor System

Sep 2024 – Dec 2024

- Developed a **Flask/PostgreSQL web application** enabling remote access via **Modbus TCP/IP** and **MQTT**, for a **Micro800 PLC**-based color sorting system.
- **Integrated sensors and actuators**, reducing manual intervention by 50%.

### 2-Pole Electro-Permanent Magnet Clamp for Workpiece Holding

Sep 2024 – Nov 2024

- **Optimized** the design of an Electro-Permanent Magnetic Clamp using Magnetic Circuit Analysis (MCA) and Finite Element Method Magnetics (FEMM), **achieving a vertical reluctance force of 1460.1 lbf**.
- **Validated** FEMM data through 3D analysis in Ansys Electronics Desktop, **ensuring accurate force calculations and identifying potential saturation effects within the EPMC design**.

## PROFESSIONAL EXPERIENCE

### Research Assistant

Neuromuscular Controls and Rehabilitation Lab, North Carolina State University

Jan 2025 – May 2025

Raleigh, United States

- **Designed mechanical linkages in SOLIDWORKS** to enable lateral movement in a wearable exoskeleton.
- **Prototyped and 3D printed components** using Ultimaker for rapid iteration and testing.
- **Selected and integrated motors** to achieve smooth, precise actuation and enhanced user control.

### Process Development Intern

Tioga Cardiovascular

May 2024 – Aug 2024

Los Gatos, United States

- **Supported process development and R&D** to optimize manufacturing of the Luna TMVR product.
- **Designed SLA-printed fixtures** in SolidWorks and PreForm to improve vibration damping and validate the delivery system, incorporating Design for Manufacturing (DFM) principles.
- **Created detailed engineering drawings with GD&T** and authored controlled documents for testing and quality inspections. Participated in design reviews to ensure cross-functional alignment.

### Associate Engineer

Eaton

Aug 2021 – Jun 2023 | Pune, India

- **Managed 250+ customer orders** and streamlined the Engineering-to-Order (ETO) process, improving efficiency by **34%** using Continuous Improvement (DMAIC Six Sigma Certified) and automation tools (Python, VBA, Power Apps).
- **Executed Engineering Change Requests (ECRs)** and Sustaining Engineering projects, reducing labor hours and part variations by **96%** through drawing revisions, **BOM standardization in SAP PLM**, and improved documentation for medium-voltage regulators.
- **Realized \$100K in cost savings** through Design for Assembly (DFA) and Value Engineering (VAVE) initiatives.