Sakshi Shah

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PROFESSIONAL EXPERIENCE

Research Assistant

Jan 2025 – present | Raleigh, United States

Neuromuscular Controls and Rehabilitation Lab, North Carolina State University

- **Designing linkages** in **SOLIDWORKS** to incorporate lateral movement capability in a wearable exoskeleton.
- Prototyping and 3D printed parts using **Ultimaker**.
- Selected and **integrated motors** for smooth and precise actuation.

Process Development Intern

May 2024 - Aug 2024

Los Gatos, United States

Tioga Cardiovascular

- Supported **process development** and R&D in optimizing the **Luna TMVR** product's manufacturing process.
- Designed **SLA**-printed **fixtures** in **SolidWorks** and **Preform** to enhance vibration damping and test the delivery system.
- Refined engineering drawings for GD&T, managed approval requests for controlled documents, and ensured quality checks for injection-molded components, improving precision and reducing defects.

Associate Engineer

Aug 2021 – Jun 2023 | Pune, India

Eaton

- Managed 250 customer orders and optimized the Engineering-to-Order (ETO) process, increasing efficiency by 34% by using **CI** and **automation** tools (Certified in DMAIC Six Sigma).
- Supported the plant by executing Engineering Change Requests (ECRs) and Sustaining Engineering projects for the regulators team, standardizing processes, reducing labor hours, and reducing part variations by 96% through Part Drawing revisions, Bill of Materials (**BOM**) standardization in SAP PLM, and documentation.
- Reduced costs through Design for Assembly (**DFA**) and Value Analysis/Value Engineering (**VAVE**) projects worth \$100k.

Research Engineer (Co-op)

Sep 2020 – Apr 2021 | Pune, India

Bamboochi Bicycles

- Defined chassis design parameters and used MATLAB to model the drivetrain, evaluate stability, and analyze control responsiveness.
- Conceptualized the frame design, rendered and analyzed the frame in SOLIDWORKS, Fusion 360 and ANSYS Mechanical respectively, achieving a Fork flop of 150.43 N/rad and an Operational speed range of 2-12 m/s at 50 RPM.

PROIECTS

Visual Servo Control Using a 7-Link Kinova Gen 3 Robot Arm

Jan 2025 – present

- Developed a **closed-loop control** system to track dynamic objects in **real-time** using an **eye-in-hand** camera, leveraging MATLAB, Simulink, ROS, and OpenCV.
- Designed and fabricated custom End-of-Arm Tooling (EOAT) in SolidWorks to stabilize the ultrasound probe and support a monocular camera.

System Integration and Control of an Autonomous Conveyor System

Sep 2024 – Dec 2024

- Developed a Flask/PostgreSQL web application enabling remote access via Modbus TCP/IP and MOTT, for a Micro800 **PLC**-based color sorting system.
- **Integrated sensors and actuators**, reducing manual intervention by 50%.

2-Pole Electro-Permanent Magnet Clamp for Workpiece Holding

Sep 2024 – Nov 2024

- **Optimized** the design of an Electro-Permanent Magnetic Clamp using Magnetic Circuit Analysis (MCA) and Finite Element Method Magnetics (FEMM), achieving a vertical reluctance force of 1460.1 lbf.
- Validated FEMM data through 3D analysis in Ansys Electronics Desktop, ensuring accurate force calculations and identifying potential saturation effects within the EPMC design.

EDUCATION

Master of Science in Mechanical Engineering

North Carolina State University || CGPA 4/4

Aug 2023 - May 2025

Raleigh, United States

Vibrations, Design of Electromechanical Systems, Industrial Automation, Engineering Design Optimization

Bachelor of Technology (B.Tech.) in Mechanical Engineering

Aug 2017 – Jun 2021

MKSSS's Cummins College of Engineering for Women || CGPA 8.5/10

Pune, Maharashtra, India

Relevant Courses: Engineering Mathematics, Rigid Body Dynamics, Automation and Control Engineering, Avionics

SOFTWARE SKILLS

Modelling

SOLIDWORKS | AutoCAD | Autodesk Inventor | ANSYS Mechanical

Planning and Manufacturing

MATLAB | Simulink | Python | Connected Components Workbench |

ROS | PostgreSQL

Programming

SAP PLM | Excel VBA | Power Apps | PreForm | UltiMaker Cura