

# COMP90038

# Algorithms and Complexity

## Lecture 22: NP-completeness

(with thanks to Harald Søndergaard & Michael Kirley)

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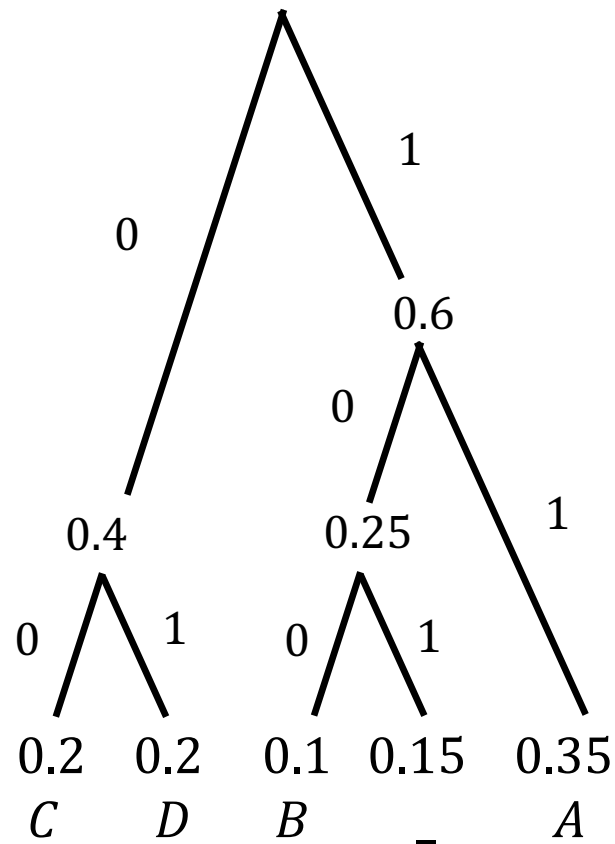
David Caro Building (Physics) 274

## Review from Lecture 21: Huffman Encoding

- Sometimes (for example for common English text) we may know the frequencies of letters fairly well.
- If we don't know about frequencies then we can still count all characters in the given text as a first step.
- But how do we assign codes to the characters once we know their frequencies?
- By repeatedly selecting the two smallest weights and fusing them.
- This is **Huffman's algorithm**—another example of a **greedy method**.
- The resulting tree is a **Huffman tree**.

# Review from Lecture 21: Huffman Encoding

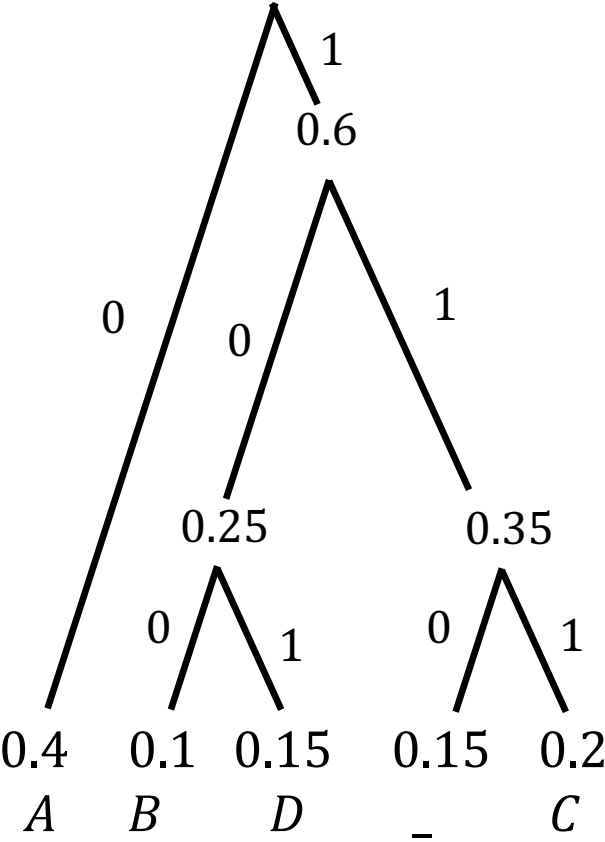
Symbol	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	–
Frequency	0.35	0.1	0.2	0.2	0.15
Codeword	11	100	00	01	101



# Review from Lecture 21: Huffman Encoding

Symbol	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	–
Frequency	0.4	0.1	0.2	0.15	0.15
Codeword	0	100	111	101	110

Encode *ABACABAD*:  
0100011101000101



Decode 100010111001010:

100	0	101	110	0	101	0
<i>B</i>	<i>A</i>	<i>D</i>	–	<i>A</i>	<i>D</i>	<i>A</i>

# Concrete Complexity

- We have been concerned with the analysis of algorithm's running times (best, average, worst cases).
- Our approach has been to give a bound for the **asymptotic** behaviour of running time, **as a function of input size**.
- For example, the quicksort algorithm is  $O(n^2)$  in the worst case, whereas mergesort is  $O(\log n)$ .

# Abstract Complexity

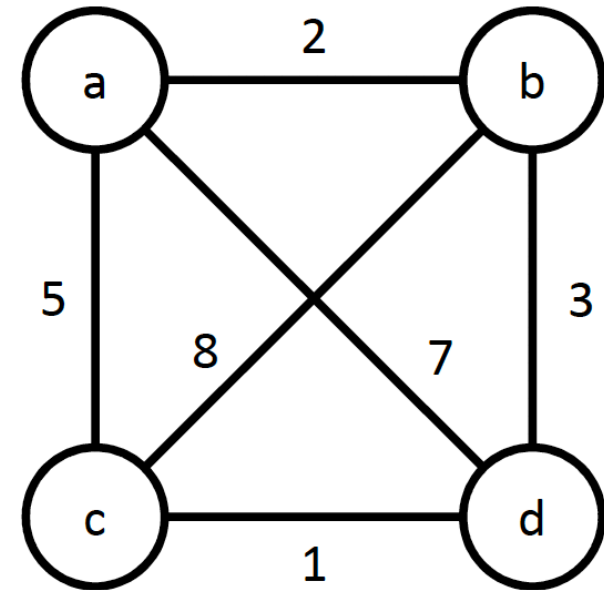
- **Complexity theory** instead asks:

*“What is the inherent difficulty of the **problem**?”*

- How do we know when we have come up with an algorithm which is **optimal** (in the asymptotic case).

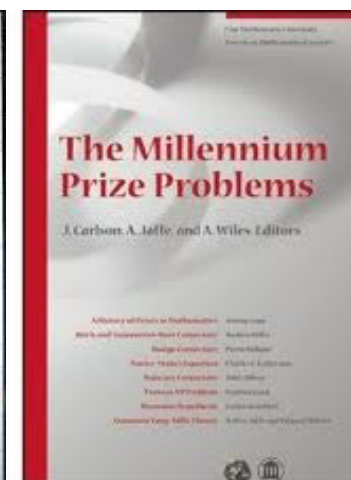
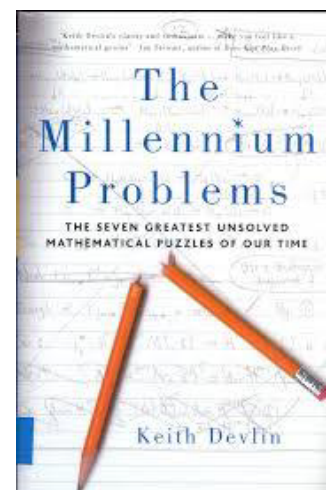
# Difficult Problems

- Which problems are difficult to solve?
- The travelling Salesman problem can be solved through brute force for very small instances
  - One solution is:  $a - b - d - c - a$
- However, it becomes very difficult as the number of nodes and connections increase.
  - The solution can be checked to determine if it is a good solution or not.



# Does $P=NP$ ?

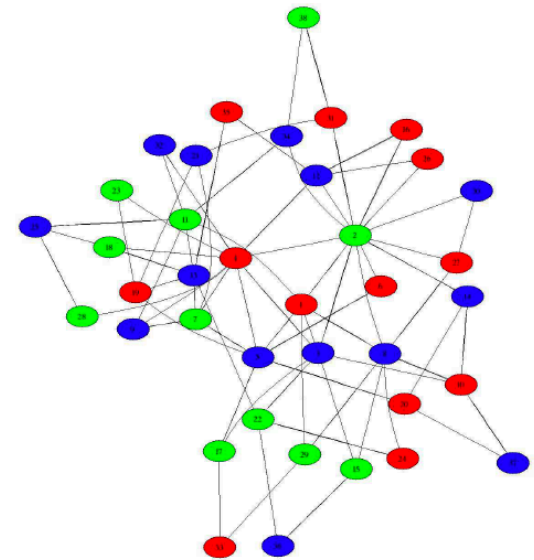
- The “**P versus NP**” problem comes from computational **complexity theory**.
- P means with polynomial time complexity
  - That is, algorithms that have  $O(\text{poly}(n))$
  - Sorting is a type of polynomial time problem
- NP means non-deterministic polynomial
  - The answer can be checked in polynomial time, but cannot find the answer in polynomial time for large  $n$ .
  - The TSP problem is an NP problem.
- This is the most important question in Computer Science





# Algorithmic Problems

- When we talk about a **problem** in computer science, we almost always mean a family of **instances** of a general problem.
- An **algorithm** for the problem has to work for all possible instances (inputs).
- Example: The **sorting** problem—an instance is a sequence of items.
- Example: The **graph  $k$ -colouring** problem—an instance is a graph.
- Example: **Equation solving** problems—an instance is a set of, say, linear equations.



## Easy and Hard Problems

- A path in a graph  $G$  is **simple** if it visits each node of  $G$  at most once.
- Consider this problem for undirected graphs  $G$ :

**SPATH**: Given  $G$  and two nodes  $a$  and  $b$  in  $G$ , is there a simple path from  $a$  to  $b$  of length **at most**  $k$ ?

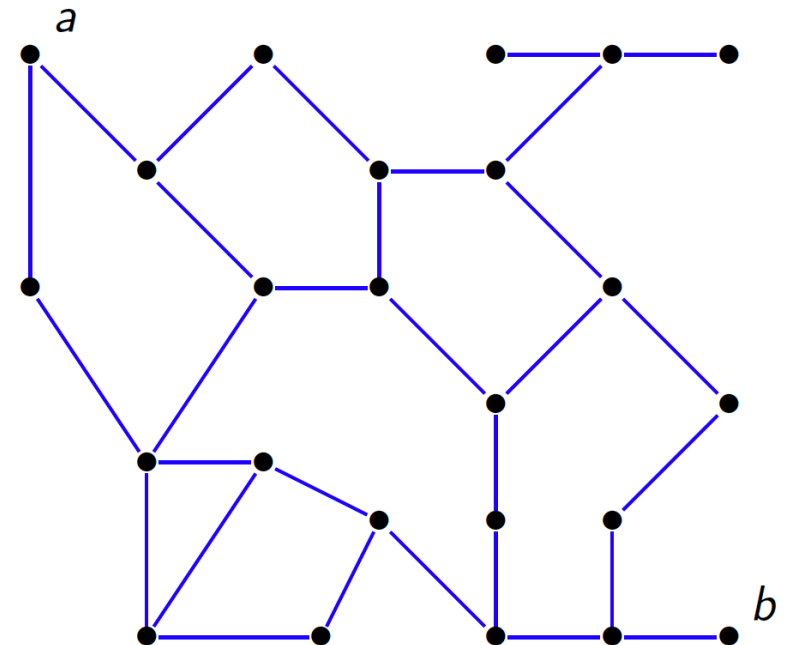
- And this problem:

**LPATH**: Given  $G$  and two nodes  $a$  and  $b$  in  $G$ , is there a simple path from  $a$  to  $b$  of length **at least**  $k$ ?

- If you had a large graph  $G$ , which of the two problems would you rather have to solve?

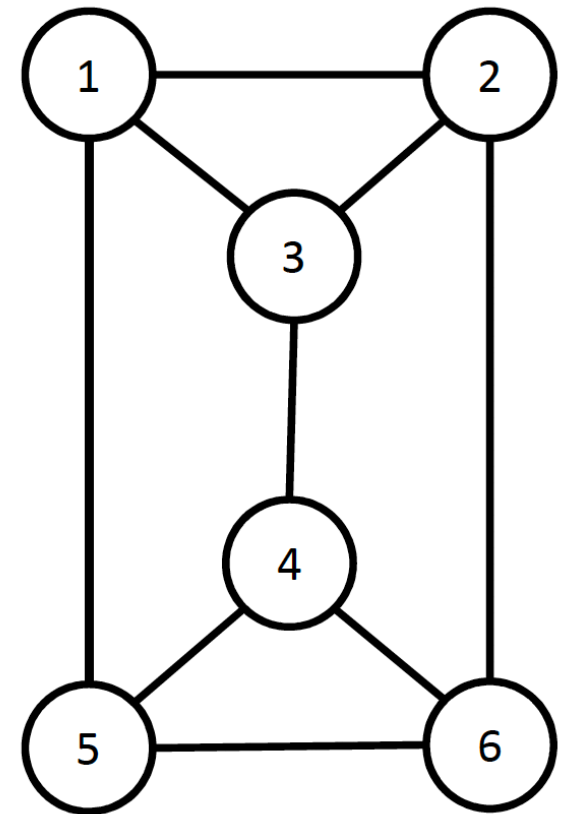
# Easy and Hard Problems

- There are fast algorithms to solve SPATH.
- Nobody know of a fast algorithm for LPATH.
- It is likely that the LPATH problem cannot be solved in polynomial time (But we do not know for sure).



## Easy and Hard Problems

- Two other related problems:
  - **EUL**: The **Eulerian** tour problem: in a graph is there a path which visits each **edge** of the graph once, returning to the origin?
  - **HAM**: The **Hamiltonian** tour problem: in a graph, is there a path which visits each **node** of the graph once, returning to the origin?
- Is the Eulerian tour problem P?
  - We just need to know whether the edge distribution is even.
- Is the Hamiltonian tour problem P?
  - No. As the number of nodes increases, the runtime becomes exponential.

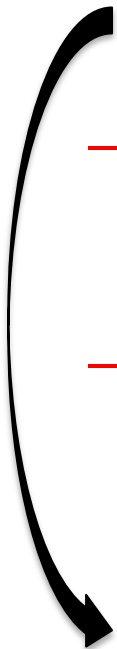


# Easy and Hard Problems

- Try to rank these problems according to inherent difficulty:
  - **SAT**: Given a propositional formula  $\varphi$ , is  $\varphi$  satisfiable?
  - **SUBSET-SUM**: Given a set  $S$  of positive integers and a positive integer  $t$ , is there a subset of  $S$  that adds up to  $t$ ?
  - **3COL**: Given a graph  $G$ , is it possible to colour the nodes of  $G$  using only three colours, so that no edge connects two nodes of the same colour?

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AND		
p	q	$p \wedge q$
F	F	F
F	T	F
T	F	F
T	T	T

Then  $OR = p \vee q$ , etc.

Satisfiable problem:  $\varphi = x_1 \vee \neg x_2 \wedge x_3 \vee \neg x_4$

Can we find an assignment of values (F or T) to the variables  $x_i$  that result in  $\varphi == T$ ?

# Polynomial-Time Verifiability

- SAT, SUBSET-SUM, 3COL, LPATH and HAM share an interesting property.
- If someone claims to have a solution (a “yes instance”) then we can quickly test their claim.
- In other words, these problems **seem hard to solve**, but the solutions allow for **efficient verification**. They are **polynomial-time verifiable**.
- That property is shared by a very large number of interesting problems in planning, scheduling, design, information retrieval, networks, games, ...
- To understand this concept, we need to talk about **Turing Machines**.

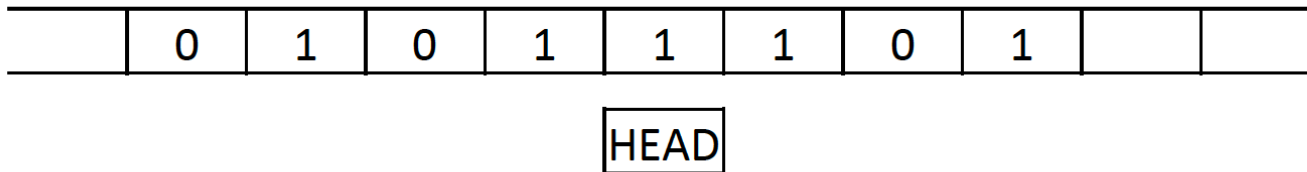
# Turing Machines

- Turing Machines are an **abstract model of a computer**.
- Despite their simplicity they appear to have the same **computational power** as any other computing device.
  - That is, any function that can be implemented in C, Java, Python, etc. can be implemented in a Turing Machine.
- Moreover, a Turing Machine is able to **simulate** any other Turing Machine.
  - This is known as the **universality** property.



# Turing Machines

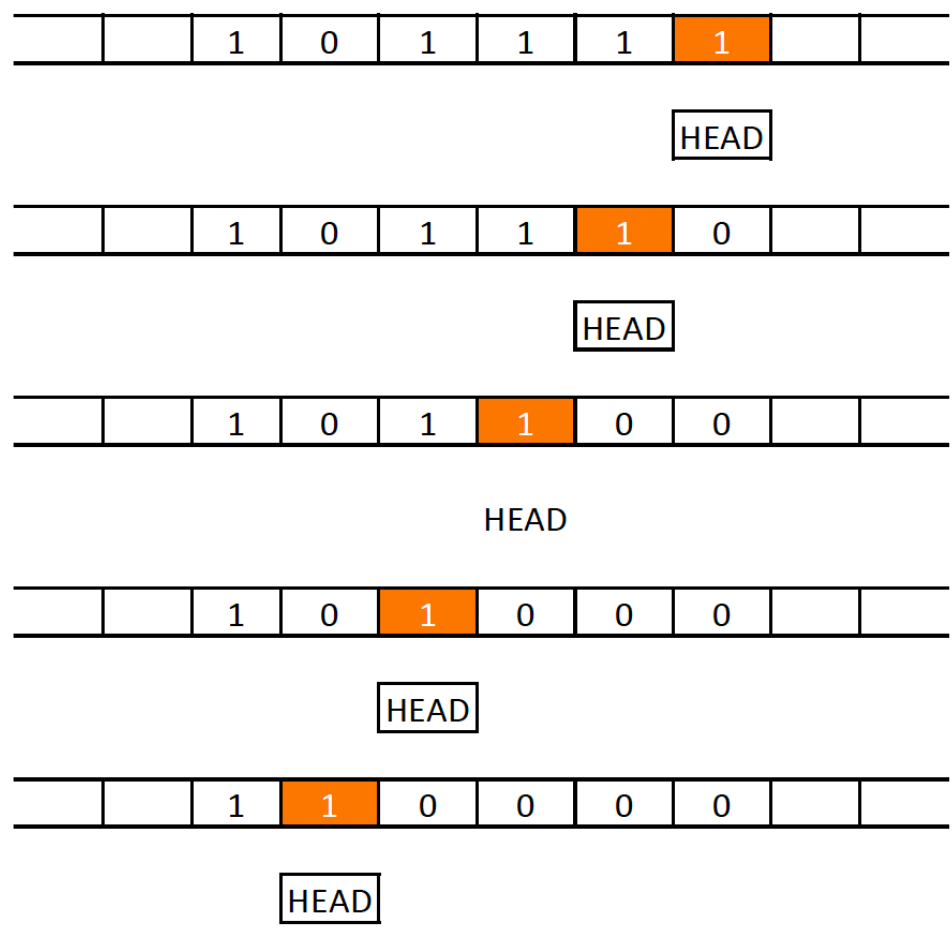
- A **Turing Machine** has an infinite tape through which it takes its input and perform its computations.
- It can:
  - Both read from and write to the tape,
  - Move either left or right over the tape.
- Whether the Turing Machine reads, write or moves left or right depends on a control sequence.



- The tape is unbounded in both directions.
- A Turing machine may fail to halt.

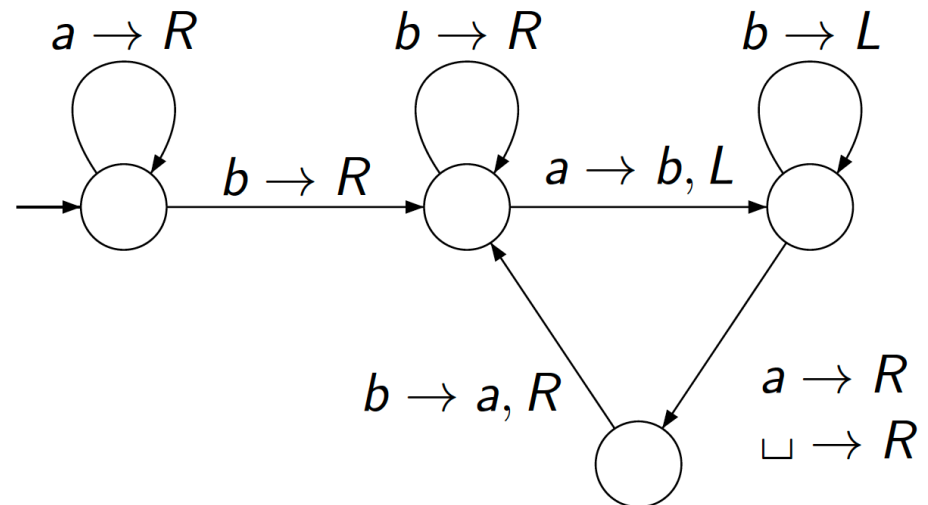
# Turing Machines: Example

- Let the control sequence be:
  - If read **1**, write **0**, go **LEFT**
  - If read **0**, write **1**, **HALT**
  - If read **\_**, write **1**, **HALT**.
- Alphabet is { **\_**, **0**, **1** }
- The input will be  $47_{10} = 101111_2$
- The output is  $48_{10} = 11000_2$
- The rules add one to a number.



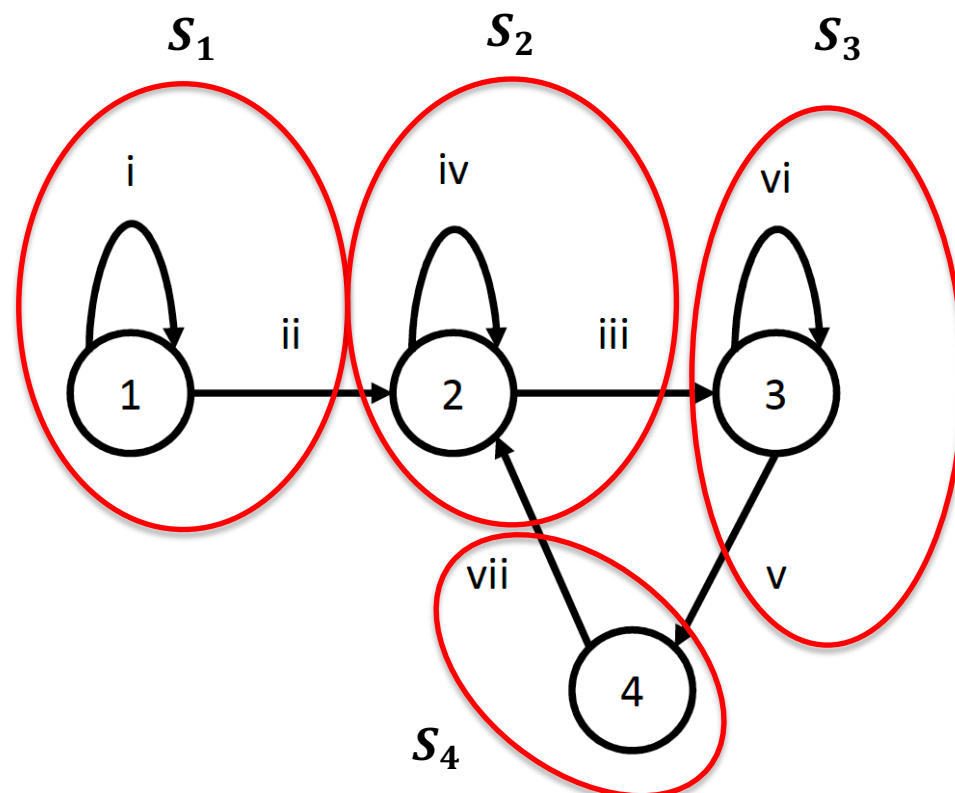
# Turing Machines: Complex Example

- This (halting) Turing machine sorts a sequence of *as* and *bs*.
- The tape alphabet is  $\{\sqcup, a, b\}$



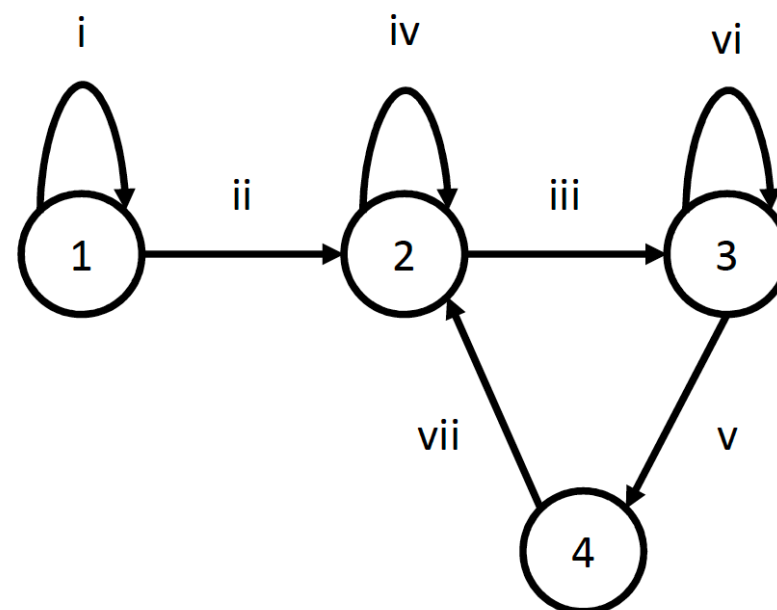
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- We will develop a state automaton:
  - If  $S_1$  and  $a$ , go **RIGHT**, stay in  $S_1$
  - If  $S_1$  and  $b$ , go **RIGHT**, go to  $S_2$
  - If  $S_2$  and  $a$ , write  $b$ , go **LEFT**, go to  $S_3$
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  - If  $S_3$  and  $a$  or  $\_$ , go **RIGHT**, go to  $S_4$
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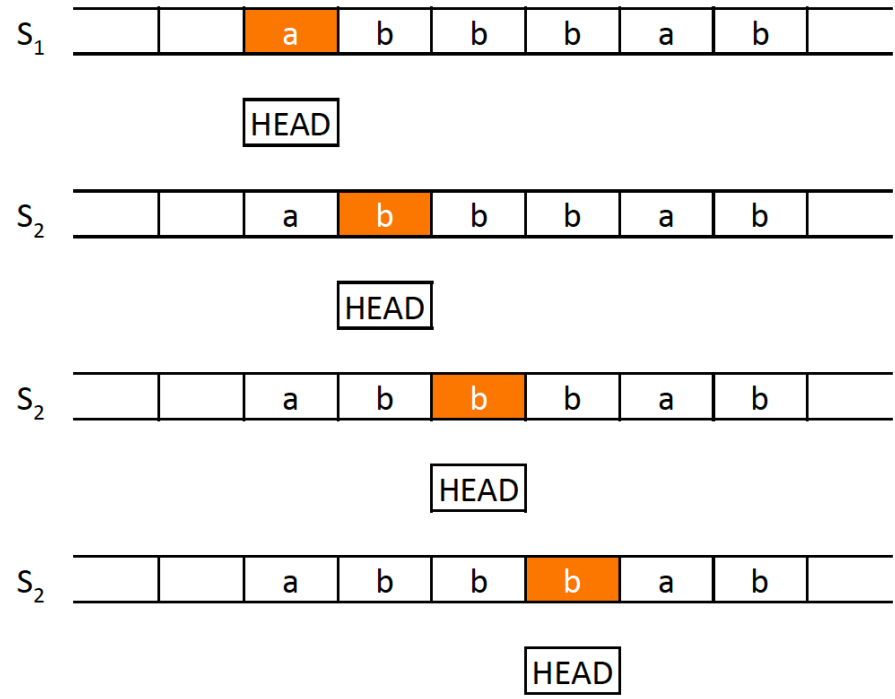
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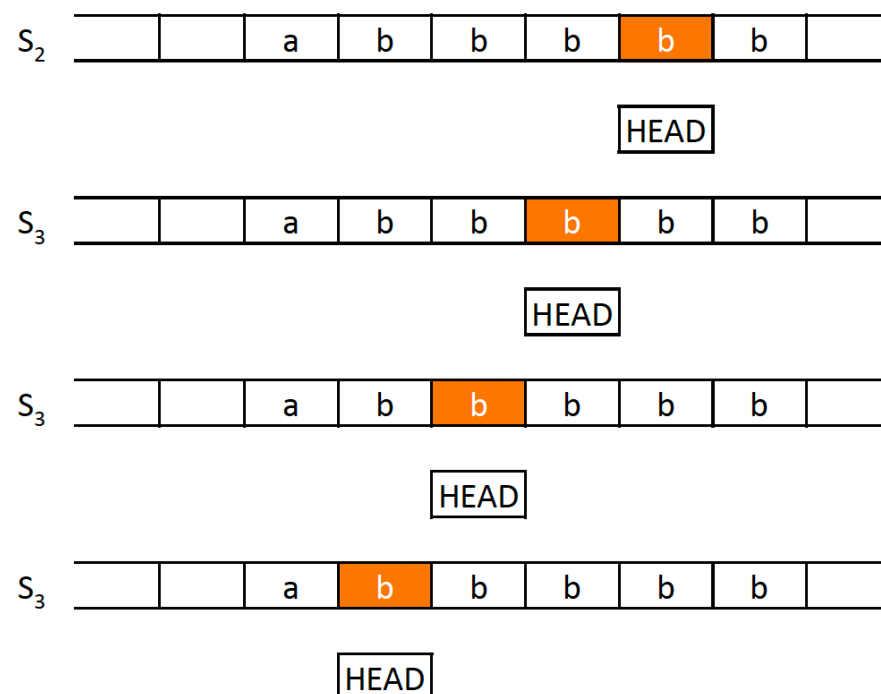
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  - ii. If  $S_1$  and *b*, go **RIGHT**, go to  $S_2$
  - iii. If  $S_2$  and *a*, write *b*, go **LEFT**, go to  $S_3$
  - iv. If  $S_2$  and *b*, go **RIGHT**, stay in  $S_2$
  - v. If  $S_3$  and *a* or  $\_$ , go **RIGHT**, go to  $S_4$
  - vi. If  $S_3$  and *b*, go **LEFT**, stay in  $S_3$
  - vii. If  $S_4$  and *b*, write *a*, go **RIGHT**, go to  $S_2$



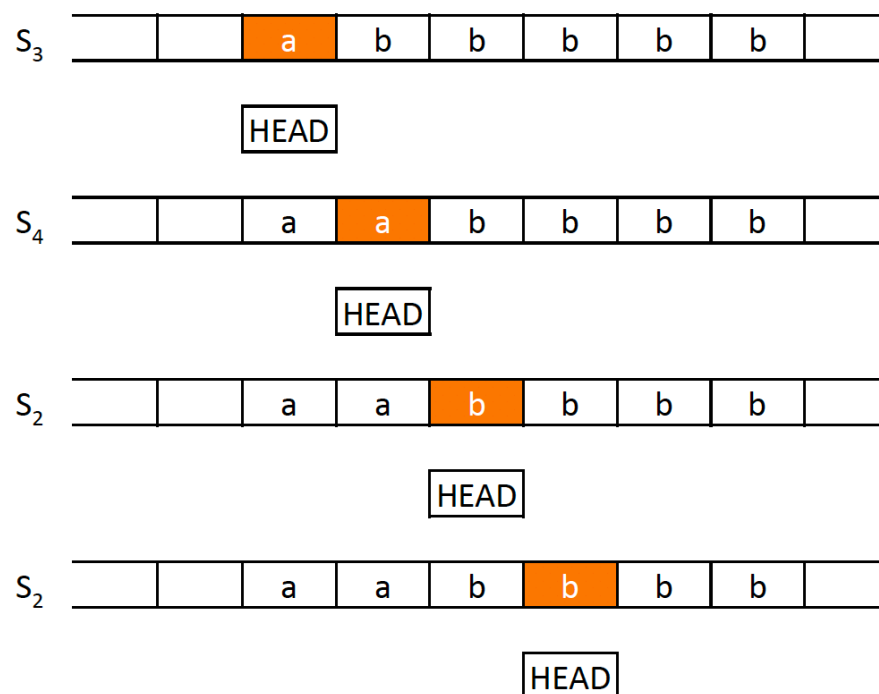
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# Non-Deterministic Turing Machines

- From now onwards we will assume that a Turing Machine will be used to implement **decision procedures**: algorithms with a YES/NO answer.
- One variant of the Turing Machine has a powerful **guessing** capability: If different moves are available the machine will favour a move that ultimately leads to a ‘yes’ answer.
- Adding this kind of **non-determinism** to the capabilities of Turing Machines does not change **what** Turing machine can compute, but it may have an impact of efficiency.
- What a non-deterministic Turing Machine can compute in polynomial time corresponds exactly to the class of polynomial-time verifiable problems.

# Non-Deterministic Turing Machines

- What a non-deterministic Turing Machine can compute in polynomial time corresponds exactly to the class of polynomial-time verifiable problems.
- **P** is class of problems solvable in polynomial time by a deterministic Turing Machine.
- **NP** is the class of problems solvable in polynomial time by a non-deterministic Turing Machine.
- Clearly  $P \subseteq NP$ .      Is  $P = NP$ ?

# Problem Reduction

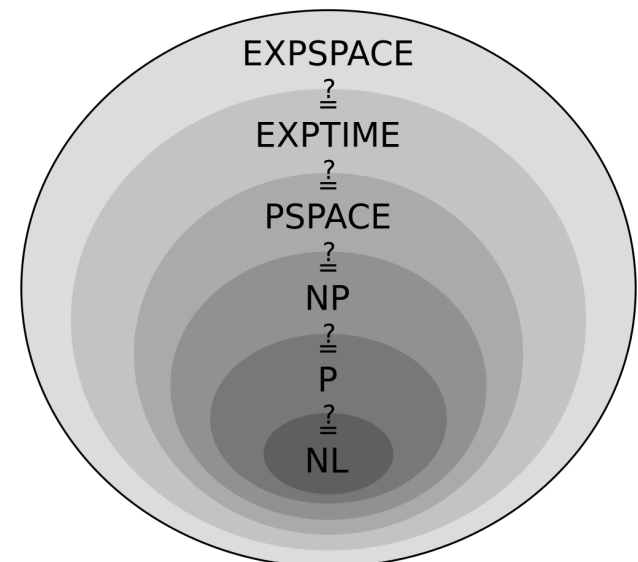
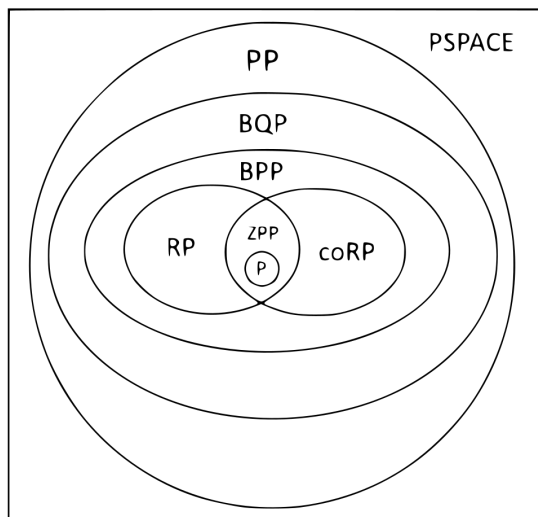
- The main tool used to determine the class of a problem is reducibility.
- A decision problem  $P$  is said to be **polynomially reducible** to a decision problem  $Q$ , if there exists a function  $t$  that transforms instances of  $P$  to instances of  $Q$  such that:
  - $t$  maps all yes instances of  $P$  to yes instances of  $Q$  and all no instances of  $P$  to no instances of  $Q$
  - $t$  is computable by a polynomial time algorithm.
- A decision problem  $D$  is said to be **NP-complete** if:
  - it belongs to class NP
  - Every problem in NP is polynomially reducible to  $D$ .

# NP-Complete Problems

- SAT, SUBSET-SUM, 3COL, LPATH and HAM, as well as thousands of other interesting and practically relevant problems have been shown to be NP-complete.
- This explains the continuing interest in NP-completeness and related concepts from complexity theory.
- For such problems, we do not know of solutions that are essentially better than exhaustive search.
- There are many other interesting complexity classes, including space complexity classes and probabilistic classes.

# Open Problems

- We do not know whether  $P=NP$ , and there are many other unsolved problems.
- We know that  $P \subseteq EXPTIME$ , that is, there are problems that can be solved in exponential time but provably not in polynomial time.
- We also know:
$$P \subseteq RP \subseteq NP \subseteq PSPACE \subseteq NPSPACE \subseteq EXPTIME$$
- But which of these inclusions are strict? (Some must be; all could be...)



# Dealing with NP-Completeness

- **Pseudo-polynomial problems** (SUBSET-SUM and KNAPSACK are in this class): Unless you have really large data, don't worry; for reasonably sized sets and numbers, the bad behaviour will not have kicked in yet.
- **Clever engineering** to push the boundary slowly: SAT solvers.
- **Approximation algorithms**: Settle for less than perfection.
- **Live happily** with intractability: Sometimes the bad instances never turn up in practice.

## Coming Up Next Week

- Special topic lecture on quantum computing
- Subject review