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Title : Solve 8-puzzle problem using best first search.

Problem Statement :	Solve 8-puzzle problem using best first search.
Software Required :	Prolog
Theory :	When employing the best-first search algorithm to solve the 8-puzzle issue, a heuristic function is usually needed to direct the search. For this, the most popular best-first search algorithm is A* search. Here is a Prolog code that uses A* search to solve the 8-puzzle problem: % Define the initial state and the goal state initial state([1, 2, 3, 8, 0, 4, 7, 6, 5]). goal state([1, 2, 3, 8, 0, 4, 7, 6, 5]). % Define the heuristic function (Manhattan distance) heuristic(State, H) :- goal state(Goal),

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    find all(D, (nth1(I, State, Tile), nth1(I, Goal, Goal Tile), Manhattan(Tile, Goal Tile, D)), Distances),
    sum list(Distances, H).

Manhattan(X/Y, X1/Y1, D) :-
    D is abs(X - X1) + abs(Y - Y1).

% Operators to move tiles
move(State, New State) :-
    select(0, State, X, TempState),
    select(T, TempState, 0, NewTempState),
    append([X, T], NewTempState, NewState).

% Define a predicate to solve the puzzle using A*
solve_astar(InitialState, Actions) :-
    heuristic(InitialState, H),
    astar([(InitialState, [])], H, [], Actions).

astar([], _, _, []) :- !, fail.
astar(States, _, Visited, Actions) :-
    select((State, Actions), States, RestStates),
    goal_state(State),
    reverse(Actions, Actions).
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astar(States, H, Visited, Actions) :-
    select((State, Actions), States, RestStates),
    findall((NewState, [Move | Actions]),
        (move(State, Move), \+ member(Move, Visited), heuristic(Move, H1), H2 is H1 + length(Actions), NewState = (Move, [Move | Actions])),
        NewStates),
    append(NewStates, RestStates, AllStates),
    sort(AllStates, SortedStates),
    astar(SortedStates, H, [State | Visited], Actions).

% Entry point to solve the puzzle
solve_puzzle :-
    initial_state(InitialState),
    solve_astar(InitialState, Actions),
    write('Solution: '), nl,
    print_actions(Actions).

% Predicate to print the sequence of actions
print_actions([]).
print_actions([Action | Rest]) :-
    print_state(Action),
    print_actions(Rest).
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Conclusion:	% Predicate to print a single state print_state([A, B, C, D, E, F, G, H, I]) :- format('~d ~d ~d~n~d ~d ~d~n~d ~d ~d~n', [A, B, C, D, E, F, G, H, I]). % Start the solver :- solve_puzzle. This code finds the best solution to the 8-puzzle issue by combining the Manhattan distance heuristic with the A* search method. The search is guided by the heuristic predicate, which calculates the Manhattan distance between the current state and the objective state.