

# 1D Theta Simulation

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## 1 Data Generation

$$(M_i, R_i) = (\{M(p_i, \theta), R(p_i, \theta)\}) + \varepsilon_i$$

Where,

$$\varepsilon_i \sim N_2(0, \Sigma)$$

, independently for  $i = 1, \dots, n$ , where  $n$  is the number of NICER measurements.

For  $\{M(p_i, \theta), R(p_i, \theta)\}$ , consider the parametric relation:  $M^2 + R^2 = \theta$ , where  $\sqrt{\theta}$  could be thought of as the radius of the circle, and  $p_i$  as the angles (latent variables). Assuming a true value for  $\theta$  and  $p_i$ , the data is generated as:

```
1 sigma= 0.1; theta0=1.5; n= 100; p_true = runif(n,0,pi/2)
2 eps_m = rnorm(n,mean=0,sd=sigma)
3 eps_r = rnorm(n,mean=0,sd=sigma)
4 m = sqrt(theta0)*sin(p_true) + eps_m
5 r = sqrt(theta0)*cos(p_true) + eps_r
6 plot(m,r)
```

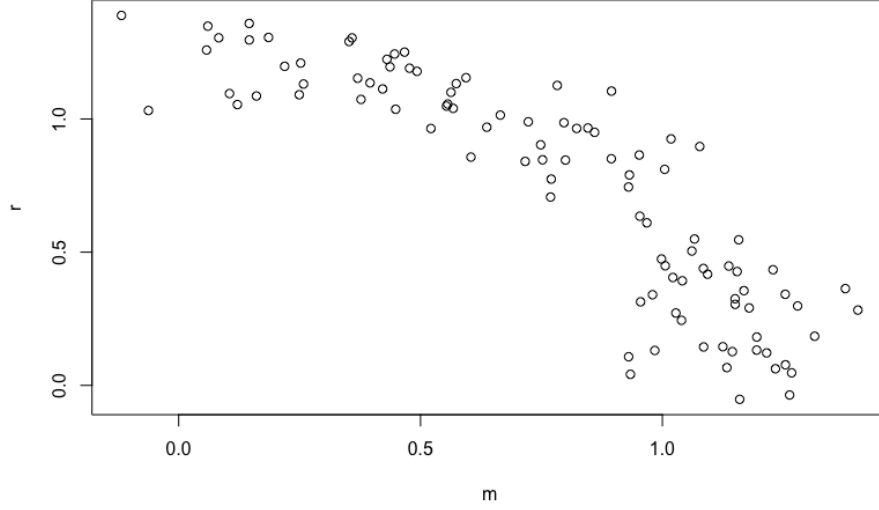


Figure 1: Data Generation

## 2 Bayesian Model Setup

Given the parametric equation, consider the Bayesian setup as:

$$\begin{aligned}
 (M_i, R_i) \mid p_i, \theta, \Sigma &\sim \mathcal{N}_2 \left( \{ \sqrt{\theta} \sin(p_i), \sqrt{\theta} \cos(p_i) \}, \Sigma \right), \\
 p_i &\sim \text{Discrete\_uniform}(0, \frac{\pi}{2}), \\
 \theta &\sim \text{Discrete\_uniform}(0, 5), \\
 \Sigma &\sim \text{Inverse\_Wishart}(\nu = 2, \Psi = \text{diag}(2)).
 \end{aligned}$$

The likelihood and the full conditionals take the form:

$$\begin{aligned}
 P(\mathbf{M}, \mathbf{R} \mid \mathbf{p}, \theta, \Sigma) &= \prod_{i=1}^n \mathcal{N}_2(\{M(p_i, \theta), R(p_i, \theta)\}, \Sigma), \\
 P(\theta \mid \mathbf{M}, \mathbf{R}, \Sigma, \mathbf{p}) &\propto P(\mathbf{M}, \mathbf{R} \mid \theta, \Sigma, \mathbf{p}) \cdot P(\theta), \\
 P(\Sigma \mid \mathbf{M}, \mathbf{R}, \theta, \mathbf{p}) &\propto P(\mathbf{M}, \mathbf{R} \mid \theta, \Sigma, \mathbf{p}) \cdot P(\Sigma), \\
 P(p_i \mid \mathbf{M}, \mathbf{R}, \theta, \Sigma) &\propto \mathcal{N}_2(\{M(p_i, \theta), R(p_i, \theta)\}, \Sigma) P(p_i).
 \end{aligned}$$

### 3 Gibbs Sampling Algorithm

Step 1: Define the global variables and create a discrete grid for theta & p.

```
1 #Global Variables:
2     nreps= 500; nu=2; Psi = diag(2); N=200;
3     theta_L =0; theta_U=5
4     grid_theta = seq(theta_L, theta_U, length.out=N)
5     grid_p=seq(0, pi/2, length.out=N)
```

Step 2: Initialize p and sigma (Draw them from the prior distribution)

```
1 # Storage variables:
2     theta_store = numeric(nreps);
3     p_store = matrix(0,nrow=nreps,ncol=n);
4     Sigma_store = array(0,dim = c(2,2,nreps))
5 # Initialization:
6     p=sample(seq(0,pi/2, length.out=N), n, replace=T);
7     Sigma = rinvwishart(nu, Psi)
```

Step 3: Start the Gibbs Sampling loop and update theta first

```
1 for (iter in 1:nreps)
2 {
3     iSigma = solve(Sigma)
4     # Update theta
5     theta_prob_log= mapply(function(theta){res = rbind(m
6 - sqrt(theta)*sin(p),r - sqrt(theta)*cos(p));
7     -0.5*sum(diag(t(res)%%iSigma%%res))},grid_theta)
8     unnorm_prob = exp( theta_prob_log - max(theta_prob_log
9 ))
10    norm_prob = unnorm_prob / sum(unnorm_prob)
11    theta = sample(grid_theta, 1, prob = norm_prob)
12    theta_store[iter] = theta
```

Step 4: Update  $p_i$  values

```
1 for (iter in 1:nreps)
2 # Update p
3     for (i in 1:n)
4     {
5         p_prob_log= mapply(function(x){res = c(m[i] - sqrt(
6 theta)*sin(x),r[i] - sqrt(theta)*cos(x));
7         -0.5*res%%iSigma%%res},grid_p)
8         unnorm_prob = exp( p_prob_log - max(p_prob_log))
9         norm_prob = unnorm_prob / sum(unnorm_prob)
10        p_store[iter,i] = sample(grid_p, 1, prob = norm_prob
11    )
```

```

10     }
11     }
12     p = p_store[iter,]

```

Step 5: Update  $\Sigma$  values

```

1 #Update Sigma
2     res = rbind(m - sqrt(theta)*sin(p), r - sqrt(theta)*
3     cos(p)); S <- res%*%t(res)
4     # Updated parameters for inverse Wishart
5     nu_star = nu + n; Psi_star <- Psi + S
6     Sigma = rinvwishart(nu_star, Psi_star)
7     Sigma_store[, , iter] = Sigma

```

## 4 Simulation Diagnosis / Plots

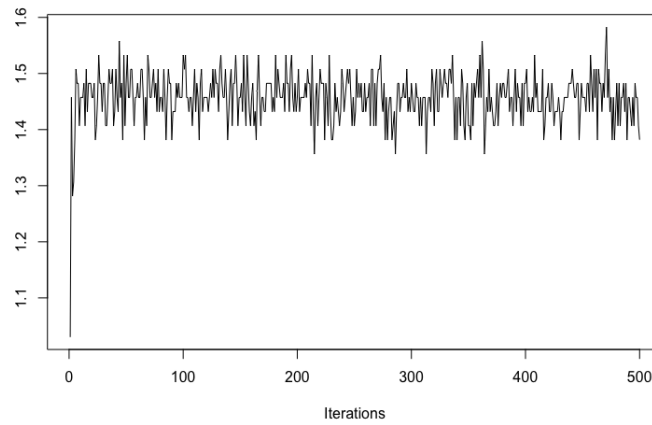


Figure 2: Trace for  $\theta$

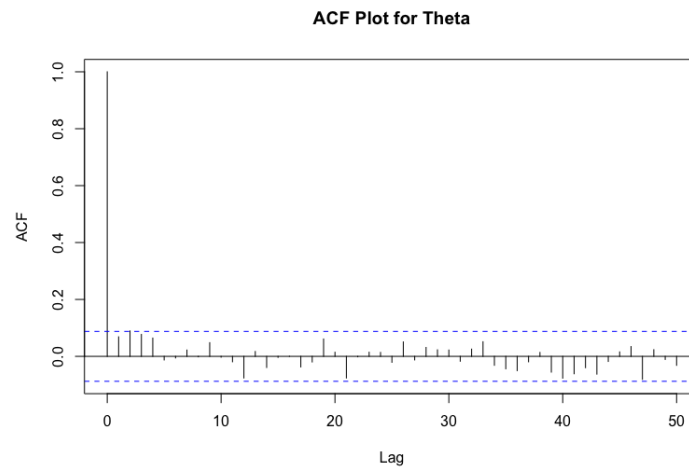


Figure 3: ACF for  $\theta$

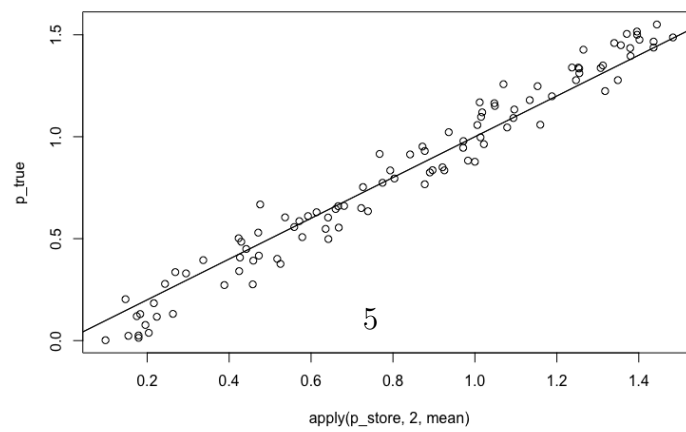


Figure 4:  $p_i$  estimates