

# MSMS - 105

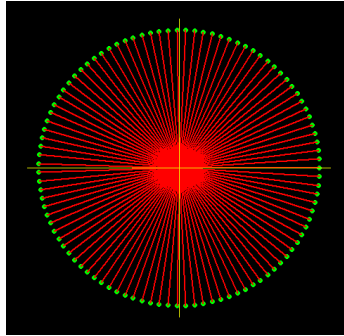
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## Assignment 04


❖ **Objective :** To create animated plots to get visual illustrations of different aspects of **Matrix Multiplication**.

⊕ **Theory :** Essence of matrix multiplication is best understood when it is seen as a linear transformation. The geometric interpretation of matrix multiplication provides insights into how matrices transform vectors of a vector space.

In the following we shall see different aspects of matrix multiplication. For best visualization experience, we have considered  $\mathbb{R}^2$  as our vector space. In each of the illustrations, we have taken 100 vectors originated at  $(0,0)$  and their tips together form a circle. We shall see how matrix multiplication changes the vectors and consequently the circular shape.

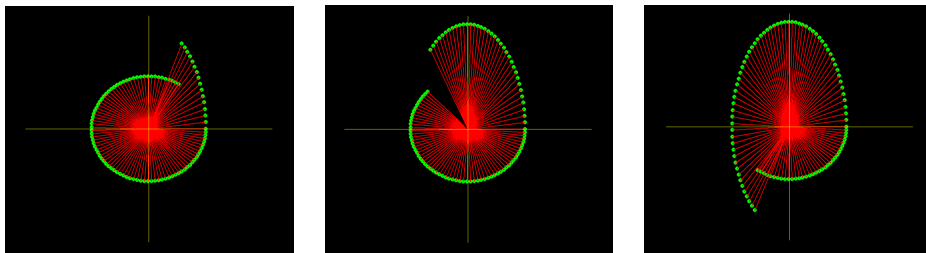


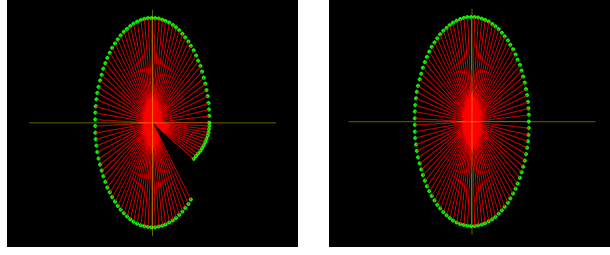
**Program to create the above plot is here.**


 **Scaling :** Pre-multiplying any vector  $\begin{bmatrix} a \\ b \end{bmatrix} \in \mathbb{R}^2$  by  $\begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix}$  scales the vector by a factor of  $s_x$  along  $x$ -axis and by a factor of  $s_y$  along  $y$ -axis.

Here we pre-multiply  $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$  with initial 100 vectors.

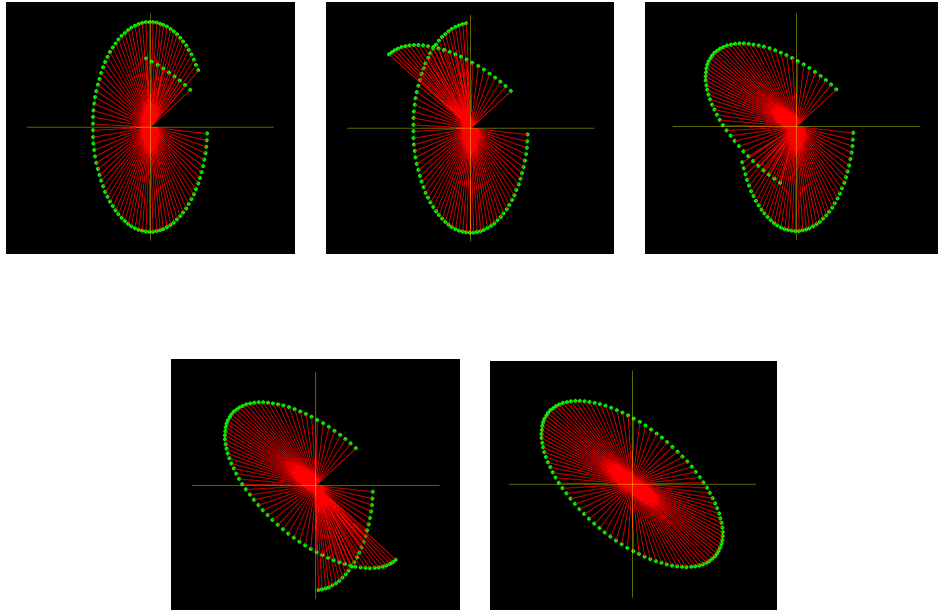
⊕ **Visualization :** **Program to create the following animation is here.**






 **Rotating** : Pre-multiplying any vector  $\begin{bmatrix} a \\ b \end{bmatrix} \in \mathbb{R}^2$  by  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  rotates the vector by an angle  $\theta$  anti-clockwise. Here we take  $\theta = \frac{\pi}{4}$  and rotate the above vectors by  $45^\circ$  anti-clockwise.

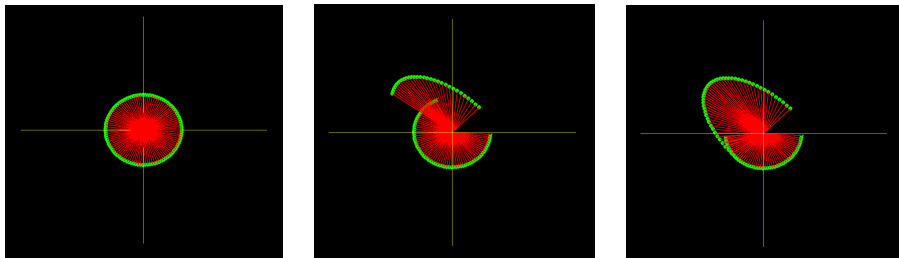
⊕ **Visualization** : [Program to create the following animation is here.](#)

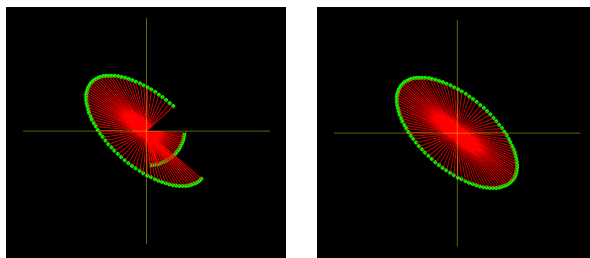



 **Composition of Transformation** : Multiplication of two matrices results in a matrix that represents the combination of their transformations. Above we first stretched the 100 vectors two times along  $y$ -axis and then rotated them  $45^\circ$  anti-clockwise. We can achieve the same by just pre-multiplying all the vectors by

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}_{\theta=\frac{\pi}{4}} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 0.7071068 & -1.414214 \\ 0.7071068 & 1.414214 \end{bmatrix}$$

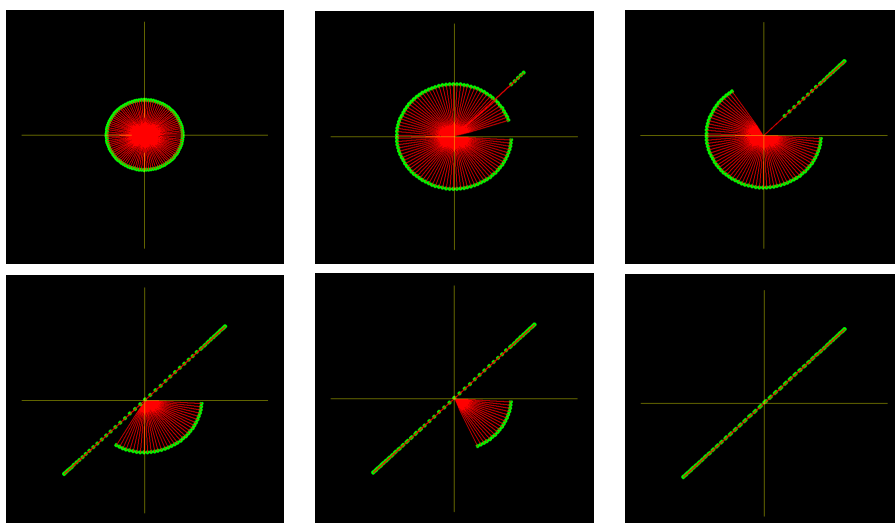
⊕ **Visualization** : [Program to create the following animation is here.](#)






 **Vector Spaces and Dimension** : Multiplying all the vectors of a vector space by a matrix of rank  $r$  creates a new vector space of dimension  $r$ . Here we pre-multiply all the 100 vectors by  $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  which has rank 1 and see how  $\mathbb{R}^2$  reduces to a straight line only.

➡ **Visualization** : [Program to create the following animation is here.](#)



 **Eigenvectors and Eigenvalues** : Eigenvectors are those special vectors that, under the linear transformation defined by a matrix, remain within their own span, being scaled by a value, positive or negative depending on change of direction, called corresponding eigenvalues.

In the **Scaling** example, observe that the vectors  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  get transformed to  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 2 \end{bmatrix}$  respectively but remain in their corresponding spans only. This makes  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  eigenvectors of  $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$  with corresponding eigenvalues 1 and 2.

➡ **Visualization** :

