

Chapter. 6. Principle. of. Data. Reduction.

Principles. of. Data. Reduction:

1. Sufficient. Principle: Use. a statistic, that contain more. information about θ .
2. Likelihood. Principle: A function of parameters determined by data \Rightarrow what. Value. of θ . makes the observed data most. likely.
3. Equivalent. principle: Are. the. data reduction method processing, these. important. features.

Definition. Sufficient. Statistics

- A. Statistic $T(x)$ is sufficient. statistics for θ if conditional. distribution
of. sample. x . given the. value. of $T(x)$ does not depends on θ .

Example.: Sufficient. Statistics.

$\{x_i\}$ denotes number of accident. in NYC on a particular day

Assume. independent. with. Poission distribution.

$x_i \sim \text{Poission}(\lambda)$.

$$\begin{aligned} f(x|\lambda) &= f(x_1 \dots x_n | \lambda) \quad \text{Joint. PDF} \\ &= \frac{\lambda^{x_1} x_1}{x_1!} \cdot \frac{\lambda^{x_2} x_2}{x_2!} \cdots \frac{\lambda^{x_n} x_n}{x_n!} \\ &= \frac{\lambda^{\sum x_i}}{\prod x_i!} \end{aligned}$$

$T(x) = \sum_{i=1}^n x_i$. is the. sufficient. statistics.

Proof. $T(x) = \sum_{i=1}^n x_i$ is a sufficient. statistics. by. definition. of. Sufficient.

$$\begin{aligned} &P(x_1=x_1, x_2=x_2, \dots, x_n=x_n | T(x)=t) \\ &= \frac{P(x_1=x_1, \dots, x_n=x_n, T(x)=t)}{P(T(x)=t)} = \frac{P(x_1=x_1, \dots, x_n=x_n, \sum_{i=1}^n x_i=t)}{P(\sum_{i=1}^n x_i=t)} \\ &= \frac{P(x_1=x_1, \dots, x_n=x_n)}{P(\sum_{i=1}^n x_i=t)} \quad \text{Since. } \{x_1=x_1, \dots, x_n=x_n\} \subseteq \{T(x)=t\} \\ &\therefore \frac{e^{\lambda} \lambda^{x_1}, \dots, e^{\lambda} \lambda^{x_n}}{e^{\lambda} \lambda^{\sum_{i=1}^n x_i}} = \sim \text{independent. of. } \lambda. \end{aligned}$$

Theorem 6.6.2.

If $f(\underline{x}|\theta)$ is a joint PDF of \underline{x} and $g(t|\theta)$ is PDF or PMF of $T(\underline{x})$

Then, $T(\underline{x})$ is a sufficient statistic for θ , if, for every x in the sample

space, the ratio of $\frac{f(\underline{x}|\theta)}{g(T(\underline{x}))}$ is constant as a function of θ .

Proof:

$$P_\theta(X_1=x_1, \dots, X_n=x_n) = P_\theta(X_1=x_1, \dots, X_n=x_n, T(\underline{x})=t(\underline{x})). \quad \{x\} \subseteq \{T(\underline{x})\},$$

$$P_\theta(\underline{x}=\underline{x}) = P_\theta(\underline{x}=\underline{x}, T(\underline{x})=t(\underline{x})). \quad P_\theta(T(\underline{x})=t(\underline{x})).$$

$$\frac{P_\theta(\underline{x}=\underline{x})}{P_\theta(T(\underline{x})=t(\underline{x}))} = \underbrace{P_\theta(\underline{x}=\underline{x}, T(\underline{x})=t(\underline{x}))}_{\text{independent of } \theta, \text{ if } T(\underline{x}) \text{ is a sufficient statistic}},$$

Theorem: Factorization Theorem (LBB 6.6.2).

Let $f(\underline{x}|\theta)$ denote the joint PDF or PMF of \underline{x} . A statistic $T(\underline{x})$ is a sufficient statistic for θ , if there exists function $g(T(\underline{x}))$ and $h(\underline{x})$, s.t. for all sample points \underline{x} and all parameter points θ ,

$$f(\underline{x}|\theta) = g(T(\underline{x})|\theta) h(\underline{x}).$$

Proof = discrete case. prove both necessary & sufficient.

Suppose, $T(\underline{x})$ is a sufficient statistic. Choose $g(t|\theta) = P_\theta(T(\underline{x})=t)$ and $h(\underline{x}) = P(\underline{x}=\underline{x}, T(\underline{x})=t(\underline{x}))$. Because $T(\underline{x})$ is sufficient, the conditional probability, defining $h(\underline{x})$ does not depends on θ . Thus the choice of $h(\underline{x})$ & $g(t|\theta)$ is legitimate, and for this choice, we have

$$\begin{aligned} f(\underline{x}|\theta) &= P_\theta(\underline{x}=\underline{x}) \\ &= P_\theta(\underline{x}=\underline{x}, T(\underline{x})=t(\underline{x})). \\ &= P_\theta(T(\underline{x})=t(\underline{x})). \quad P_\theta(\underline{x}=\underline{x} | T(\underline{x})=t(\underline{x})). \\ &= g(T(\underline{x})|\theta) h(\underline{x}) \end{aligned}$$

The above exhibited the factorization theorem. We also see from the last,

two. (lines above). That.

$P_\theta(T(x)=T(x)) = g(T(x)|\theta)$. so, $g(T(x)|\theta)$ is PDF or PMF of $T(x)$.

Now, we assume factorization theorem exists. let $g(T|\theta)$ be the PMF of $T(x)$. Show that $T(x)$ is sufficient. We examine the ratio. $\frac{f(x|\theta)}{g(T(x)|\theta)}$

Define $A_{T(x)} = \{y : T(y) = T(x)\}$. Then,

$$\frac{f(x|\theta)}{g(T(x)|\theta)} = \frac{g(T(x)|\theta) h(x)}{g(T(x)|\theta)} \quad \text{Since factorization theorem exists.}$$

$$= \frac{g(T(x)|\theta) h(x)}{\sum_{A_{T(x)}} f(y|\theta)} \quad (T(x) = \sum x_i, \begin{matrix} x_1=1 & x_1=2 \\ x_2=2 & x_2=1 \end{matrix})$$

$$P(T(x)) = f(x_1=1, x_2=2) + f(x_1=2, x_2=1).$$

$$= \frac{g(T(x)|\theta) h(x)}{\sum_{A_{T(x)}} g(T(x)|\theta) h(y)}$$

$$= \frac{g(T(x)|\theta) h(x)}{g(T(x)|\theta) \sum_{A_{T(x)}} h(y)} \quad \text{Since } T \text{ is constant on } A_{T(x)}$$

$$= \frac{h(x)}{\sum_{A_{T(x)}} h(y)} \quad \sim \text{not depends on } \theta.$$

Since the ratio does not depends on θ . by theorem b.2.2.

$T(x)$ is a sufficient statistics for θ .

Various Version of this proved by Fisher & Savage.

See "Testing Statistical Hypothesis" by F. Lehman

Also see Billingsley, Dell for general frameworks.

Example: Poisson. Re-visit.

$$f(x_1, \dots, x_n) = \frac{e^{-nx} \cdot \frac{n}{x_1} x_1^{x_1} \cdots \frac{n}{x_n} x_n^{x_n}}{\sum_{i=1}^n x_i!} = h(x) e^{-nx} \cdot \frac{n}{\sum_{i=1}^n x_i} \left\{ \begin{array}{l} \sum_{i=1}^n x_i \text{ is a sufficient statistics.} \\ \Rightarrow \text{one-to-one function.} \\ \frac{1}{n} \sum_{i=1}^n x_i = \bar{x} \text{ is also a sufficient statistics.} \end{array} \right.$$

This form holds for any distribution in general.

Example: Uniform distribution. German Tank Problem

Use Serial number on tank to estimate total number of tank. θ

Set. $\{x_i\} \sim$ uniform distribution

$$f(x|o) = \frac{1}{o} \text{ for } x = 1, 2, \dots, o.$$

Select. n . serial. number without replacement We will have C_n^o possible samples. each with. DPF $\frac{1}{C_n^o}$

$$\begin{aligned} f(x|o) &= \frac{1}{C_n^o} \cdot I(1 \leq x_1 \leq o, 1 \leq x_2 \leq o \dots 1 \leq x_n \leq o), \\ &= (C_n^o)^{-1} \cdot I(\max(x_i) \leq o). \\ &= (C_n^o)^{-1} \cdot I(x_{(n)} \leftarrow \text{n}^{\text{th}} \text{ order statistic.}) \end{aligned}$$

Let. $h(x) = 1$. by. factorization theorem.

$X_{(n)}$ is a sufficient statistic for o .

However, $E[X_{(n)}] < o$. so. it's a biased sufficient statistic

So. it need. to be. rescaled. to get. the. unbiased. estimator.

Note: Sufficient statistics. with. extreme value statistics.

Typically, in examples where support. of. distribution. depends on some unknown parameters (e.g. uniform $(0, o)$) The. sufficient. statistics. will involve some. extreme order statistics.

Example: Sufficient Statistics. for. Normal. distribution.

$\{x_i\} \sim N(\mu, \sigma^2)$. Both. μ & σ^2 are. unknown.

$$\begin{aligned} f(x|\mu, \sigma^2) &= (2\pi\sigma^2)^{-\frac{n}{2}} (\sigma^2)^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \right\} \\ &= (2\pi\sigma^2)^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x} + \bar{x} - \mu)^2 \right\} \\ &= (2\pi\sigma^2)^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x})^2 + n(\bar{x} - \mu)^2 + 2 \sum_{i=1}^n (x_i - \bar{x})(\bar{x} - \mu) \right\} \\ &= (2\pi\sigma^2)^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x})^2 + n(\bar{x} - \mu)^2 \right\}, \quad S^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2 \\ &= (2\pi\sigma^2)^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2\sigma^2} (n-1)S^2 + n(\bar{x} - \mu)^2 \right\}. \end{aligned}$$

By. factorization. Theorem. $T(x) = (\bar{x}, S^2)$ are. sufficient. statistics for (μ, σ^2) .

Example: Sufficient Statistics for Multi-variate Normal distribution.

$$\tilde{x}_i = \begin{pmatrix} x_{i1} \\ \vdots \\ x_{ip} \end{pmatrix} \sim N(\bar{x}, \Sigma).$$

$$\begin{aligned}
 f(x_1, x_2, \dots, x_n | \mu, \Sigma) &= (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2} \sum_{i=1}^n (\tilde{x}_i - \bar{x})' \Sigma^{-1} (\tilde{x}_i - \bar{x}) \right\} \\
 &= (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2} \text{tr} \left(\sum_{i=1}^n (\tilde{x}_i - \bar{x})' \Sigma^{-1} (\tilde{x}_i - \bar{x}) \right) \right\} \\
 &= (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2} \sum_{i=1}^n \text{tr} \left(\Sigma^{-1} (\tilde{x}_i - \bar{x})' (\tilde{x}_i - \bar{x}) \right) \right\} \\
 &= (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2} \text{tr} \left(n \Sigma^{-1} \sum_{i=1}^n (\tilde{x}_i - \bar{x})' (\tilde{x}_i - \bar{x}) \right) \right\} \\
 &= (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2} \text{tr} \left(n \Sigma^{-1} (\tilde{x} - \bar{x} + \bar{x} - \bar{x})' (\tilde{x} - \bar{x} + \bar{x} - \bar{x}) \right) \right\} \\
 &= (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{n}{2}} \exp \left\{ -\frac{1}{2} \text{tr} \left(n \Sigma^{-1} (\tilde{x} - \bar{x})' (\tilde{x} - \bar{x}) \right) \right\} \\
 &\quad \text{Since } \Sigma^{-1} = 0.
 \end{aligned}$$

By factorisation theorem, (\tilde{x}, \bar{x}) are sufficient statistics for (μ, Σ) .

Definition: Minimal Sufficient Statistics.

A sufficient statistic, $T(x)$ is called minimal sufficient statistic

if, for any other sufficient statistic, $T'(x)$, $T'(x)$ is a function of $T(x)$.

Theorem - Minimal Sufficient Statistics - 6.2-13.

Let, $f(x|\theta)$ be the PDF or PDF of a sample x . Suppose there exists a function $T(x)$ s.t. for every two sample points x & y , the ratio of $\frac{f(x|\theta)}{f(y|\theta)}$ is constant as function of θ , iff. $T(x) = T(y)$. Then, $T(x)$ is a minimal sufficient statistic for θ .

Example: Minimal Sufficient Statistics for Normal distribution.

$$\{x_i\} \sim N(\mu, \sigma^2).$$

Let, $\{x_1\} \sim N(\bar{x}_1, s_1^2)$ & $\{x_2\} \sim N(\bar{x}_2, s_2^2)$, are two sample points.

Apply theorem 6.2.13.

$$\frac{f(x_1 | \mu, \sigma^2)}{f(x_2 | \mu, \sigma^2)} = \frac{\left(\frac{1}{2\sigma^2}\right)^{\frac{n}{2}} \exp\left\{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_{i2} - \mu)^2\right\}}{\left(\frac{1}{2\sigma^2}\right)^{\frac{n}{2}} \exp\left\{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_{i1} - \mu)^2\right\}} = \exp\left\{-\frac{1}{2\sigma^2} \left[\sum_{i=1}^n (x_{i2} - \mu)^2 - \sum_{i=1}^n (x_{i1} - \mu)^2 + \frac{n(\bar{x}_2^2 - \bar{x}_1^2)}{\sigma^2} \right] \right\}$$

is constant as function of (μ, σ^2) if $\bar{x}_1 = \bar{x}_2$, $s_1^2 = s_2^2$.

Proving that (\bar{x}, s^2) is minimal sufficient statistics for (μ, σ^2)

Note: Dimension of Minimal Sufficient Statistics

Dimension of Minimal Sufficient Statistics \geq Dimension of Θ .

Example: Dimension of minimal sufficient statistics \geq Dimension of Θ

$\{x_i\} \sim \text{Uniform}(\theta, \theta+1)$ where θ is one dimensional.

But, $(X_{(1)}, X_{(n)})$ is minimal sufficient statistic (\geq dimensional)

Note: Uniqueness of Minimal Sufficient Statistics.

If T_1 & T_2 are both minimal sufficient statistics. Then by definition, each of them is a measurable function of the other.

So, it's unique in the sense that they must be 1-to-1 function of each other.

Definition: Ancillary Statistics.

$S(x)$ is ancillary statistics if its distribution doesn't depend on θ .

Example: Ancillary statistics.

Suppose θ is a location parameter with CDF $F(x-\theta)$ F doesn't

depend on θ . (e.g. $\{x_i\} \sim N(\mu, 1)$ $F \sim \Phi$ ~ Standard Normal).

$\Rightarrow x_i = z_i + \theta$, where z_i is a standard normal.

When we look at the CDF of Range $R = X_{(n)} - X_{(1)}$.

$$\Pr(X_{(n)} - X_{(1)} \leq r) = \Pr(R \leq r) \quad \text{independent of } \theta$$

$$\Pr(z_{(n)} + \theta - z_{(1)} - \theta \leq r) = \Pr(\underline{z_{(n)} - z_{(1)}} \leq r),$$

We have R as an ancillary statistics for location family.

Similar results for scale parameter,

$X_1 = \frac{X_2}{\bar{X}_n}$, if we look at the ratio. Any statistic that.

depends on $\frac{X_1}{\bar{X}_n}, \frac{X_2}{\bar{X}_n}, \dots, \frac{X_m}{\bar{X}_n}$, is auxiliary statistic.

Note: Auxiliary statistics.

Auxiliary statistics in some cases gives information for inference on θ .

Definition: Complete Statistics, C & B, b.2.21,

let $f(x|\theta)$ be a family of PDF or PMF for a statistic $T(x)$. The family of probability distribution is called complete if $E_\theta(g(T)) = 0$, for all θ implies $P(g(T)=0) = 1$ for all θ . Equivalently, $T(x)$ is called complete statistic.

Example: Complete Statistics,

$\{x_i\} \sim N(98.6, 0.2)$ represent human body temperature

let $g(x) = x - 98.6$, $E[g(x)] = E[x - 98.6] = 0$.

$T(x) = \frac{1}{n} \sum_{i=1}^n x_i = \bar{x}$, if we don't assume that n is known.

We have $T(x) = \bar{x}$ as a complete statistic for $\mu \in \mathbb{R}$.

Note: Origin of the name of complete statistic.

A set of vector is complete if they span the whole space,

i.e. $V \in$ Vector Space. Then, \exists coefficients a_{ij} such that

if $v = a_1v_1 + \dots + a_pv_p$,

if $w \in$ Vector space & $\langle v, w_j \rangle = 0, j=1, 2, \dots, p \Rightarrow v = 0$.

Now consider a discrete example of complete statistic T .

$$E[g(T)] = 0 \Rightarrow \sum_{j=1}^p g(t_j) P_\theta(t_j) = 0 \Rightarrow g(w) = 0,$$

$$\Rightarrow (g(t_1), \dots, g(t_p)) \begin{pmatrix} P_\theta(t_1) \\ \vdots \\ P_\theta(t_p) \end{pmatrix} = 0 \Rightarrow \text{orthogonal}.$$

Thus, $P_{\sigma}(T_j) = \begin{pmatrix} P_{\sigma}(T_1) \\ \vdots \\ P_{\sigma}(T_p) \end{pmatrix}$ is complete, in vector-space, context.

Similarly, when T is continuous,

$$E[g(t)] = \int_{-\infty}^{+\infty} g(t) f(t) dt = 0.$$

\Rightarrow inner-product, in function space, is complete.

Example: Complete, statistic for Poisson distribution

$$\{x_i\} \sim \text{Poisson } (\lambda). \quad f(x|\lambda) = \frac{e^{-\lambda} \lambda^x}{x!}$$

$T(x) = \sum_{i=1}^n x_i$ is a sufficient statistic. $E[T(x)] = n\lambda$.

Suppose, there exists a measurable function g , s.t. $E[g(T(x))] = 0$, for all λ .

$$T(x) = S \sim \text{Poisson } (n\lambda).$$

$$\begin{aligned} E[g(s)] &= \sum_{s=0}^{\infty} g(s) P(S=s) \\ &= \sum_{s=0}^{\infty} g(s) \cdot e^{-n\lambda} \frac{(n\lambda)^s}{s!} \\ &= e^{-n\lambda} \cdot \sum_{s=0}^{\infty} \frac{g(s) n^s}{s!} \lambda^s = 0, \end{aligned}$$

$$\text{if } \sum_{s=0}^{\infty} \frac{g(s) n^s}{s!} \lambda^s = 0, \Rightarrow \frac{g(s) n^s}{s!} = 0 \Leftrightarrow g(s) = 0,$$

$$\text{Since, } s = 0, 1, 2, \dots \Rightarrow g(s) = 0.$$

Thus, S is a complete statistic.

We will see, using complete, $\frac{1}{n}S$, is the unbiased statistic for λ .

With, smallest variance

Theorem: Basu's theorem, C.B. 6.2.24

If, $T(x)$ is a complete & minimal sufficient statistic, then, $T(x)$ is independent of every ancillary statistic.

Proof = discrete case.

Let, $S(x)$ be ancillary statistic. Then $P(S(x)=s)$ does not depends on θ . Since, $S(x)$ is ancillary. Also, The conditional probability,

$$P(S(x)=s | T(x)=t) = P(X \in \{x : S(x)=s\} | T(x)=t).$$

does not depend on θ , because $T(x)$ is a sufficient statistic.

Thus we show that $S(x) \& T(x)$ are independent, it's sufficient to.

show that $P(S(x)=s | T(x)=t) = P(S(x)=s)$ for all possible values $t \in \mathbb{T}$. Now,

$$P(S(x)=s) = \sum_{t \in \mathbb{T}} P(S(x)=s | T(x)=t) \cdot P(T(x)=t).$$

Furthermore, since $\sum_{t \in \mathbb{T}} P(T(x)=t) = 1$. We can write.

$$P(S(x)=s) = \sum_{t \in \mathbb{T}} P(S(x)=s) P_{\theta}(T(x)=t).$$

Therefore, if we define the statistic $g(t) = P(S(x)=s | T(x)=t) - P(S(x)=s)$ the above two equations show that.

$$E(g(t)) = \sum_{t \in \mathbb{T}} g(t) P_{\theta}(T(x)=t) = 0 \text{ for all } \theta$$

Since $T(x)$ is a complete statistic, this implies that $g(t) = 0$ for all possible values $t \in \mathbb{T}$. Hence verified.

Lemma: Distribution of sufficient statistics in exponential family.

$\{x_i\}$ belongs to exponential family.

$$f(x|\theta) = h(x) c(\theta) \exp \left\{ \sum_{j=1}^k w(\theta_j) t_j(x_i) \right\}$$

Then $T(x) = \left(\sum_{j=1}^k t_1(x_i) \dots \sum_{j=1}^k t_k(x_i) \right)$ has a distribution also belongs to exponential family.

Theorem: Find Complete statistic in the exponential family.

Let $x_1 \dots x_n$ be iid observations from an exponential family with PDF or

$$PDF \text{ of the form } f(x|\theta) = h(x) c(\theta) \exp \left\{ \sum_{j=1}^k w(\theta_j) t_j(x) \right\}$$

where $\theta = (\theta_1, \theta_2, \dots, \theta_k)$. Then the statistic

$$T(x) = \left(\sum_{i=1}^n t_1(x_i) \dots \sum_{i=1}^n t_k(x_i) \right)$$
 is complete as long as the parameter space Θ contains a open set in \mathbb{R}^k .

Example 2. Poisson distribution.

We saw. $S = \sum_{i=1}^n X_i$ ~ complete & sufficient statistic.

$$f(x) = \frac{e^{-\lambda} \lambda^x}{x!} = \left(\frac{\lambda}{x}\right)^x \exp\{-\lambda + x\log\lambda - x\}.$$

$T(x) = \sum_{i=1}^n X_i$ is complete & sufficient statistic by theorem 6.2.25.

Theorem (Minimal Sufficient & Complete Statistics). (§ 13 6.2.28)

If a minimal sufficient statistic exists. Then any complete statistic is also a minimal sufficient statistic.

Definition: Likelihood Principle.

(Let. $f(x|\theta)$ denotes the joint PDF or DMF of sample $x = (x_1, \dots, x_n)$.

Then, given that $X=x$ is observed. The function of θ , defined by

$L(\theta|x) = f(x|\theta)$ is called likelihood function.

If X is a discrete random vector, then $L(\theta|x) = P_\theta(X=x)$, if we

compare the likelihood function at two parameter points and find that

$$P_{\theta_1}(X=x) = L(\theta_1|x) > L(\theta_2|x) = P_{\theta_2}(X=x)$$

Then, the sample we actually observed is more likely to occur if $\theta = \theta_1$.