

# New estimator with larger sample size

2019-08-20

## Setting

### Functions

Let  $\rho(t) = 0.1$ , the piecewise example:

$$f(t, s) = \begin{cases} \exp(-t - s) & (t \leq s) \\ \rho \exp(-0.1t - 1.9s) & (t > s) \end{cases}$$

And

$$\begin{aligned} f(t) &= \frac{18}{19} \exp(-2t) + \frac{10}{19} \exp(-10t) \\ S(t) &= \frac{9}{19} \exp(-2t) - \frac{10}{19} \exp(-\rho t) \\ \psi(t) &= \exp(-2t) \\ S_x(t) &= \exp(-2t) \end{aligned}$$

The simulation:

- Generated dataset size: 1000
- Notation

True $S(t)$	Slud's estimator	Corrected Slud's estimator	$S(t)$ integral estimated by Riemann	$S(t)$ integral estimated by expectation
$S(t)$	$S_{p1}(t)$	$S_{p2}(t)$	$S_r(t)$	$S_e(t)$

All the estimators except KM were using the true value of  $\rho(t)$ , also  $S_x(t)$ .

### Mean absolute difference

KM estimator

```
round(mean(abs(s_est - S(t_est))),3)
```

```
## [1] 0.167
```

Slud's estimator

```
round(mean(abs(result2$s1 - S(t_est))),3)
```

```
## [1] 0.119
```

Corrected Slud's estimator

```
round(mean(abs(result2$s2 - S(t_est))),3)
```

```
## [1] 0.119
```

Integral estimated by Riemann

```
round(mean(abs(s_r - S(t_est))),3)
```

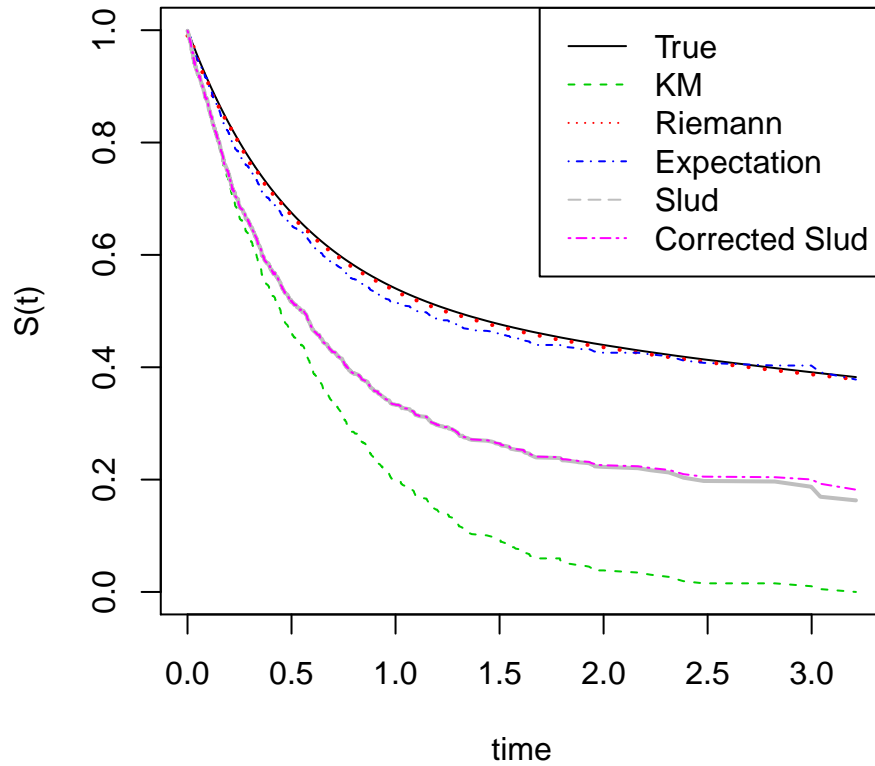
```
## [1] 0.005
```

Integral estimated by the expectation idea

```
round(mean(abs(s_e - S(t_est))),3)
```

```
## [1] 0.016
```

The plot



Why biased?

For KM estimator and Slud's estimator:

When  $\rho_i = 0$ , which means that  $f(t) = \psi(t) \rightarrow \int_0^\infty (t, s) ds = \int_t^\infty f(t, s) ds \rightarrow \int_0^t f(t, s) ds = 0$ . That is, when  $s < t$ ,  $f(t, s) = 0$ , there is no censoring.

$$S_{p1}(t) = \prod_{i=1}^{d(t)} \frac{n_i - 1}{n_i + \rho_i - 1} + \frac{1}{N} \sum_{k=1}^{d(t)} (\rho_k - 1) \prod_{i=k}^{d(t)} \frac{n_i - 1}{n_i + \rho_i - 1} = 1 - \frac{d(t)}{N}$$

$$S_{km}(t) = \prod_{i=1}^{d(t)} \frac{n_i - 1}{n_i}.$$

And if there is no censor,  $n_i = N - i$ ,  $\prod_{i=1}^{d(t)} \frac{n_i - 1}{n_i} = \prod_{i=1}^{d(t)} \frac{N - i - 1}{N - i} = \frac{N - 1 - d(t)}{N - 1} = 1 - \frac{d(t)}{N - 1}$ .

Therefore,  $S_{p1}(t) \approx S_{km}(t)$ . Since  $S_{km}(t)$  supposes independent, it is biased, and  $S_{p1}(t)$ ,  $S_{p2}(t)$  are also biased.

## How could we proof that the integral estimation method is unbiased?

I feel a little bit confused about how to proof the unbiased.

From Slud's paper, the  $S(t)$  has the unique expression:

$$S(t) = \exp\left[-\int_0^t \frac{\psi(s)\rho(s)}{Sx(s)} ds\right] \left(1 + \int_0^t \psi(s)\{\rho(s) - 1\} \exp\left[\int_0^s \frac{\psi(u)\rho(u)}{Sx(u)} du\right] ds\right) \quad (1)$$

And the integral term can be estimated as:

$$\begin{aligned} g(t) &\equiv \int_0^t \frac{\psi(s)\rho(s)}{Sx(s)} ds = \int_0^t \frac{\rho(s)}{Sx(s)} d\Psi(s) \\ &= \int_0^t \frac{\rho(s)}{Sx(s)} P(I=1) d\frac{\Psi(s)}{P(I=1)} \\ &= \int_0^t \frac{\rho(s)}{Sx(s)} P(I=1) d\Psi_c(s) \\ &\approx \frac{1}{N} \sum_{0 \leq s \leq t} \frac{\rho(s)}{Sx(s)} P(I=1) \equiv \hat{g}(t) \end{aligned}$$

where  $\Psi(t) = P(X < t, I=1) = P(X < t|I=1)P(I=1) = \Psi_c(t)P(I=1)$

Empirically, the  $\hat{g}(t)$  is the unbiased estimator of  $g(t)$ , i.e.  $E(\hat{g}(t)) = g(t)$

However, how could we say that  $E(\exp(-\hat{g}(t))) = \exp(-g(t))$ ? Based on Jensen's inequality,  $f(x) = \exp(-x)$  is a concave function. Then

$$E(\exp(-\hat{g}(t))) < \exp(-E(\hat{g}(t))) = \exp(-g(t))$$

Then how could we show it?