# THE UNIVERSITY OF MELBOURNE SCHOOL OF COMPUTING AND INFORMATION SYSTEMS COMP90038 ALGORITHMS AND COMPLEXITY

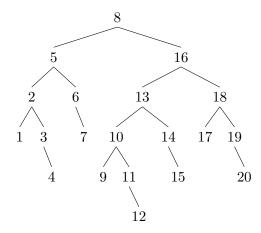
# Assignment 2, Semester 2, 2017

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### My Answers

#### Challenge 1

(1 mark)



# Challenge 2 (2 mark)

According to the following strategy, in the worst case, d = 6.

Now Dr. Luator have 2 detectors to use in the test, she could start the test from not level 1 but level 4. After the dropping the first detector, if it's safe, she should shift 4 levels and drop on level 8, if safe once again, shift to and drop on level 12, and so forth. When she reaches level 15 and there's no more room for a 4-level-shifting, Dr. Luator should drop the first detector on level 15. If the first detector remains safe in all these tests, then level 15 is the safe limit.

If the first detector breaks in any of the above tests, for example, on level 4, then she should drop the second detector in the brute force way from level 1 to level 3. Similarly, if the first detector, say, breaks on level

12, Dr. Luator should drop the second one in brute force way, starting from level 9 until level 11. The reason she starts from level 9 is that she already tested on level 8 and the first detector is safe, so all the levels before level 8 is ensured to be safe. If the second detector remains safe in the brute force way test, then the safe limit should be the latest drop of the first detector. If the second detector breaks, then the safe limit is the last drop of the second detector.

When using this startegy, in the worst case, the safe limit floor n should be 10, 11, 13, or 14, and the drop d should be 6.

```
Challenge 3
                                                                              (3 mark)
   1. 1: function F1(A[\cdot], B[\cdot], n, s)
               //Implement the worst-case running time of \Theta(n^2)
        3:
               //solution to the problem
               //Input: Sorted arrays A[\cdot], B[\cdot] each with n positive
        4:
               //integer keys, and a positive integer s
        5:
               //Output: The pair of indices (i, j) if A[i] + B[j] = s or
        6:
        7:
               //(0, 0) if no such pair exists
               for i \leftarrow 1 to n do
        8:
                   for j \leftarrow 1 to n do
       9:
                       if A[i] + B[j] = s then
       10:
                           return (i, j)
       11:
       12:
               return (0,0)
       1: function F2(A[\cdot], B[\cdot], n, s)
        2:
               //Implement the worst-case running time of \Theta(n \log n)
               //solution to the problem
        3:
               //Input: Sorted arrays A[\cdot], B[\cdot] each with n positive
        4:
               //integer keys, and a positive integer s
        5:
               //Output: The pair of indices (i, j) if A[i] + B[j] = s or
        6:
               //(0, 0) if no such pair exists
        7:
               for i \leftarrow 1 to n do
                                                    \triangleright Linear scan on the array A[\cdot]
        8:
                   lo \leftarrow 1
       9:
                   hi \leftarrow n
       10:
                   while lo \le hi do
       11:
                       j \leftarrow |(lo + hi)/2|
       12:
                                                 \triangleright Binary search on the array B[\cdot]
                       if B[j] = s - A[i] then
       13:
```

```
return (i, j)
       14:
                        if B[j] > s - A[i] then
       15:
                            hi \leftarrow j-1
       16:
                        else
       17:
                            lo \leftarrow j+1
       18:
               return (0,0)
       19:
       1: function F3(A[\cdot], B[\cdot], n, s)
                //Implement the worst-case running time of \Theta(n)
        3:
               //solution to the problem
               //Input: Sorted arrays A[\cdot], B[\cdot] each with n positive
        4:
               //integer keys, and a positive integer s
        5:
               //Output: The pair of indices (i, j) if A[i] + B[j] = s or
        6:
               //(0, 0) if no such pair exists
        7:
               i \leftarrow 1
        8:
               j \leftarrow n
        9:
               while i \leq n and j \geq 1 do
                                                   ▶ Linear scans on the two arrays
       10:
                    if A[i] + B[j] = s then
       11:
                        return (i, j)
       12:
                   if A[i] + B[j] < s then
       13:
                                       \triangleright ignore all keys before A[i] and A[i] itself
                        i \leftarrow i + 1
       14:
       15:
                    else
                        j \leftarrow j - 1
                                      \triangleright ignore all keys after B[j] and B[j] itself
       16:
               return (0,0)
       17:
Challenge 4
                                                                                (2 mark)
       1: function CanScreen(U[\cdot], V[\cdot], d)
                //Implement the algorithm which determines, given
               //two vectors \mathbf{u} and \mathbf{v}, whether \mathbf{u} screens \mathbf{v}.
        3:
               //Assuming that vectors \mathbf{u} and \mathbf{v} are arrays
        4:
               //Input: The vectors as array U[\cdot] and V[\cdot] with d dimensions
        5:
               //Output: Returns True iff u screens v
        6:
               MergeSort(U[\cdot])
        7:
               MergeSort(V[\cdot])
        8:
                                                                       \triangleright sort the arrays
               i \leftarrow 1
        9:
       10:
               j \leftarrow 1
```

```
11: while i \leq d and j \leq d do \triangleright Linear scans on the two arrays

12: if U[i] \leq V[j] then

13: return False

14: i \leftarrow i+1

15: j \leftarrow j+1

16: return True
```

Complexity Analysis: The worst case running time of Mergesort is  $\Theta(n \log n)$ . The comparisons of each items in the two arrays requires the linear scans on the two arrays, of which the worst-case running time is  $\Theta(n)$ . Hence, the worst-case time complexity of the algorithm is  $C(n) \in O(2n \log n + 2n) = O(n \log n)$ .

Challenge 5 (2 mark)

```
1: function MERGE(M_1, M_2): MultiwayTree
       if M_2 = void then
2:
           return M_1
3:
       if M_1 = void then
4:
           return M_2
5:
       M \leftarrow \mathbf{new} \ MultiwayTree
6:
7:
       if M_1.key > M_2.key then
           M.key \leftarrow M_1.key
8:
           M.subtrees \leftarrow Add ToList(M_2, M_1.subtrees)
9:
       else
10:
11:
           M.key \leftarrow M_2.key
           M.subtrees \leftarrow Add ToList(M_1, M_2.subtrees)
12:
13:
       return M
```

```
1: function MergePairs(L) : MultiwayTree
2:
        if L = \text{null then}
3:
            return void
        M_1 \leftarrow L.elt
        L_1 \leftarrow L.next
5:
        if L_1 = \text{null then}
6:
7:
            return M_1
8:
        M_2 \leftarrow L_1.elt
9:
        L_2 \leftarrow L_1.next
        return Merge(Merge(M_1, M_2), MergePairs(L_2))
10:
```

- 3. 1: function AddToList(M, L): TreeList
  - 2:  $R \leftarrow \mathbf{new} \ \mathit{TreeList}$
  - 3:  $R.elt \leftarrow M$
  - 4:  $R.next \leftarrow L$
  - 5: return R
- 4. 1: function Deletemax(M): MultiwayTree
  - 2: **if** M =**void then**
  - 3: Error ("Cannot delete from empty tree")
  - 4: **return** MERGEPAIRS(M.subtrees)
- 5. 1: **function** Insert(x, M): MultiwayTree
  - 2:  $M' \leftarrow \mathbf{new} \ MultiwayTree$
  - 3:  $M'.key \leftarrow x$
  - 4:  $M'.subtrees \leftarrow \mathbf{null}$
  - 5: **return** MERGE(M', M)