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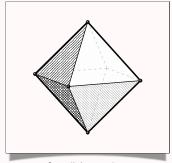
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feasible region

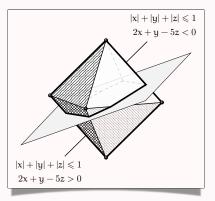
.

• Consider the hyperplane $F = \{(x, y, z) \mid 2x + y - 5z = c_0\}$

2

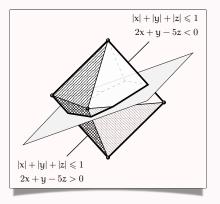
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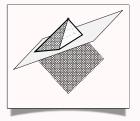
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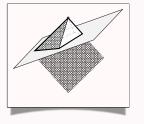
• What happens if we increase c_0 ?

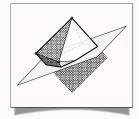
2

• Increasing $c_0 \Longrightarrow$ moving plane towards optimum

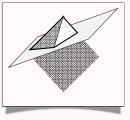


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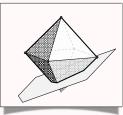




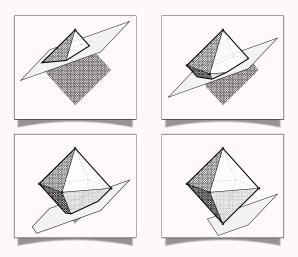
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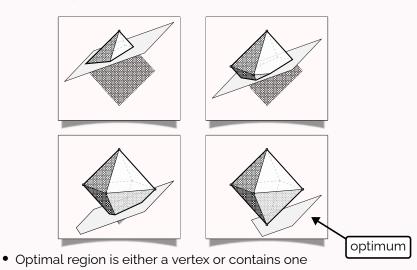




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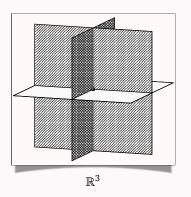
3

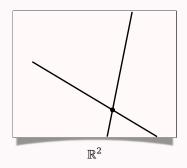
Finding a Vertex

• A vertex in \mathbb{R}^d is the intersection of d linearly independent hyperplanes

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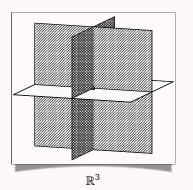
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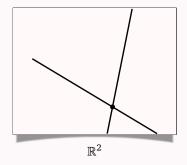




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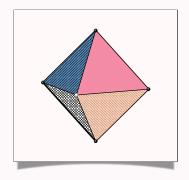
• In other words, a solution to a linear system

Example



$$x + y - z = 1$$

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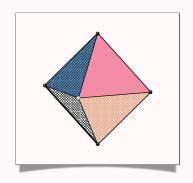


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The associated vertex is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

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 $\max_{x \in \mathbb{R}^{n \times 1}} \{ cx \mid Ax \leq b \}$

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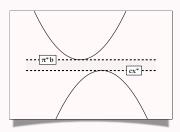
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- Both problems are deeply connected
 - In fact, the dual provides a certificate of optimality for primal solutions

Weak Duality

Theorem (Weak Duality)

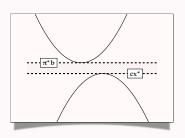
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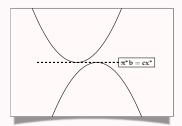


• Proof.
$$Ax \leq b \implies \underbrace{(\pi A)}_{c} x \leq \pi b$$
. \square

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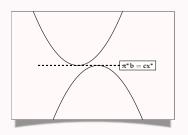
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- Proof is a little more elaborate
 - ► Requires Farkas' Lemma

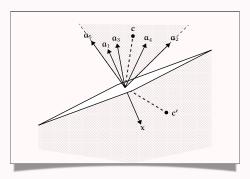
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 Provides conditions under which a system of inequalities is solvable



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$$\lambda \le 0$$

$$cx + \lambda(\delta - \varepsilon) > 0$$

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- Since ε was arbitrary, and it can be as close as possible to 0, we have that $cy = \delta$. \square

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- Besides, $cx = \pi b$ (that is, x and π are optimal) if and only if $\pi Ax = \pi b$. \square

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$$\begin{aligned} \min \pi_1 + \pi_2 + \pi_3 + \pi_4 + \pi_5 + \pi_6 + \pi_7 + \pi_8 \\ \text{s.t. } \pi_1 + \pi_2 + \pi_3 + \pi_4 - \pi_5 - \pi_6 - \pi_7 - \pi_8 &= 2 \\ \pi_1 + \pi_2 - \pi_3 - \pi_4 + \pi_5 + \pi_6 - \pi_7 - \pi_8 &= 1 \\ \pi_1 - \pi_2 + \pi_3 - \pi_4 + \pi_5 - \pi_6 + \pi_7 - \pi_8 &= -5 \\ \pi_1, \pi_2, \pi_3, \pi_4, \pi_5, \pi_6, \pi_7, \pi_8 &\geq 0 \end{aligned}$$

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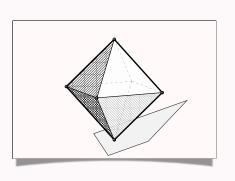
$$\pi_4, \dots, \pi_8 = 0$$

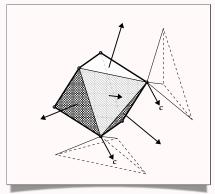
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- From Complementary Slackness, x is optimal as long as $x \ge 0$ and $\pi A < c$
 - ► The latter is equivalent to requiring positive reduced costs, that is, $\bar{c} = c \pi A = c (A_p^{-1}c_B)A \ge 0$